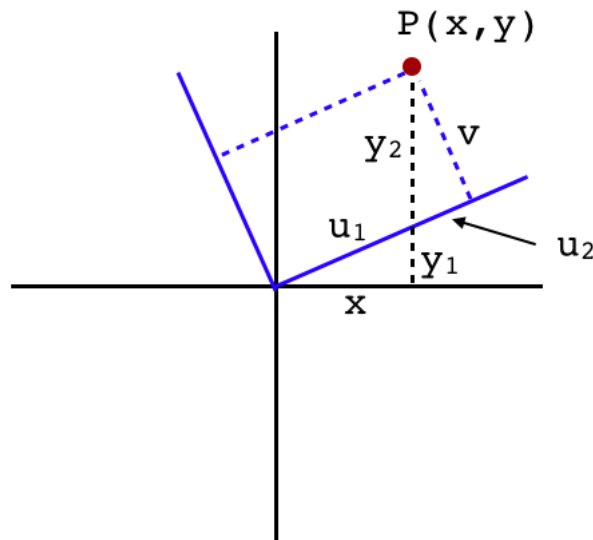


## Rotation of coordinates

I wanted to work on a derivation of the rotation of coordinates formulas. I've done it before in different ways, but I always have difficulties remembering those proofs. So here we will just fool around with the algebra a bit.



The setup is the usual one. We have a point  $P = (x, y)$  and we want to express the same point in terms of rotated coordinate axes. This means that we need to find the distances  $u$  and  $v$  that are the projections of the point onto the new axes. In the diagram, I express some distances in terms of two components:  $y = y_1 + y_2$  and  $u = u_1 + u_2$ .

The angle isn't marked explicitly, but let's call it  $\theta$ . We can write

immediately that

$$x = u_1 \cos \theta$$

$$y_1 = u_1 \sin \theta$$

Notice also that the second triangle with labeled sides is similar to the first. So we can also write

$$u_2 = y_2 \sin \theta$$

$$v = y_2 \cos \theta$$

Now we just play with the equations. We want a function giving  $u$

$$u = f(x, y, \theta)$$

Start with

$$u = u_1 + u_2$$

We have two equations involving  $u_1$ . Multiply the first by  $\cos \theta$

$$x \cos \theta = u_1 \cos^2 \theta$$

Multiply the second one by  $\sin \theta$

$$y_1 \sin \theta = u_1 \sin^2 \theta$$

If we add and then factor out  $\cos^2 \theta + \sin^2 \theta = 1$  we obtain:

$$u_1 = x \cos \theta + y_1 \sin \theta$$

We have that  $u_2 = y_2 \sin \theta$  so

$$u = u_1 + u_2$$

$$u = x \cos \theta + y_1 \sin \theta + y_2 \sin \theta$$

Factor out  $y_1 + y_2 = y$

$$u = x \cos \theta + y \sin \theta$$

$$v = f(x, y, \theta)$$

$$v = y_2 \cos \theta$$

$$v = (y - y_1) \cos \theta$$

$$v = y \cos \theta - y_1 \cos \theta$$

Go back to

$$x = u_1 \cos \theta$$

$$y_1 = u_1 \sin \theta$$

$$y_1 = \frac{x}{\cos \theta} \sin \theta$$

So

$$v = y \cos \theta - y_1 \cos \theta$$

$$v = y \cos \theta - \frac{x}{\cos \theta} \sin \theta \cos \theta$$

$$v = y \cos \theta - x \sin \theta$$

We can use the same equations to get expressions for  $x$  and  $y$ :

$$x = f(u, v, \theta)$$

$$u = u_1 + u_2$$

$$u = \frac{x}{\cos \theta} + y_2 \sin \theta$$

$$u = \frac{x}{\cos \theta} + \frac{v}{\cos \theta} \sin \theta$$

We multiply by  $\cos \theta$ :

$$u \cos \theta = x + v \sin \theta$$

$$x = u \cos \theta - v \sin \theta$$

and we have an expression for  $x$  in terms of  $u$  and  $v$  and  $\theta$ .

$$y = f(u, v, \theta)$$

$$\begin{aligned} y &= y_1 + y_2 \\ y &= u_1 \sin \theta + \dots \end{aligned}$$

Go back to the two equations involving  $y_2$

$$\begin{aligned} u_2 &= y_2 \sin \theta \\ v &= y_2 \cos \theta \end{aligned}$$

multiply by either  $\sin \theta$  or  $\cos \theta$  to obtain:

$$\begin{aligned} u_2 \sin \theta &= y_2 \sin^2 \theta \\ v \cos \theta &= y_2 \cos^2 \theta \end{aligned}$$

Add

$$u_2 \sin \theta + v \cos \theta = y_2(\sin^2 \theta + \cos^2 \theta) = y_2$$

Hence

$$\begin{aligned} y &= u_1 \sin \theta + y_2 \\ y &= u_1 \sin \theta + u_2 \sin \theta + v \cos \theta \\ y &= u \sin \theta + v \cos \theta \end{aligned}$$

And we have an expression for  $y$  in terms of  $u$  and  $v$  and  $\theta$ .

Notice the difference rotating from  $xy$  to  $uv$

$$\begin{aligned} u &= x \cos \theta + y \sin \theta \\ v &= -x \sin \theta + y \cos \theta \end{aligned}$$

while rotating from  $uv$  to  $xy$

$$x = u \cos \theta - v \sin \theta$$

$$y = u \sin \theta + v \cos \theta$$

The difference is a switch from minus to plus and plus to minus on the  $\sin \theta$  term. And the reason is simple, think of the latter rotation as being through the angle  $-\theta$ , then

$$\sin(-\theta) = -\sin \theta$$

$$\cos(-\theta) = \cos \theta$$

So in comparing rotations by angle  $\theta$  in the counter-clockwise and clockwise directions, the difference is just a change in sign for the sine term.

We said the difference rotating from  $xy$  to  $uv$

$$u = x \cos \theta + y \sin \theta$$

$$v = -x \sin \theta + y \cos \theta$$

As a check on our work, consider rotation by 90 degrees,  $\theta = \pi/2$ . We have  $\cos \theta = 0$  and  $\sin \theta = 1$ , so

$$u = y$$

$$v = -x$$

which is indeed a counter-clockwise rotation, matching the direction of rotation of the  $x, y$ -axes to  $u, v$  in our diagram.