

Advanced techniques for Integrals

Shankar has this example for the volume of a sphere of radius R . We compute the volume for the part of the hemisphere that is in the first quadrant. The surface is $f(x, y) = \sqrt{R^2 - x^2 - y^2}$ so the integral is

$$\int_0^R \int_0^{\sqrt{R^2 - y^2}} \sqrt{R^2 - x^2 - y^2} \, dx \, dy$$

There are several ways to approach this but what he does is an unusual trig substitution where the hypotenuse is $\sqrt{R^2 - y^2}$. The substitution is

$$\begin{aligned} x &= \sqrt{R^2 - y^2} \sin \theta \\ dx &= \sqrt{R^2 - y^2} \cos \theta \, d\theta \end{aligned}$$

(This integral is over the values of x with y *fixed*, it may be treated as a constant.) The integrand is

$$\sqrt{R^2 - x^2 - y^2} = \sqrt{R^2 - y^2} \cos \theta$$

When $x = 0 \rightarrow \theta = 0$, and when $x = \sqrt{R^2 - y^2} \rightarrow \theta = \pi/2$ so the inner integral becomes

$$\begin{aligned} \int_0^{\pi/2} \sqrt{R^2 - y^2} \cos \theta \sqrt{R^2 - y^2} \cos \theta \, d\theta \\ R^2 - y^2 \int_0^{\pi/2} \cos^2 \theta \, d\theta \end{aligned}$$

We've done this one many times. One form of the answer is

$$\frac{1}{2}(\theta - \sin \theta \cos \theta)$$

For any interval involving $n\pi/2, n \in \{0, 1, 2, \dots\}$, the second term disappears. So the result for $\theta = 0 \rightarrow \pi/2$ is just $\pi/4$.

The outer integral becomes then

$$\begin{aligned} & \frac{\pi}{4} \int_0^R (R^2 - y^2) dy \\ &= \frac{\pi}{4} \left(R^2 y - \frac{y^3}{3} \right) \Big|_0^R = \frac{\pi}{4} \frac{2}{3} R^3 \end{aligned}$$

But there are eight such regions, so the total volume is

$$8 \frac{\pi}{4} \frac{2}{3} R^3 = \frac{4}{3} \pi R^3$$

The point of this example is that use of $\sqrt{R^2 - y^2}$ as the hypotenuse is useful and allowed because y is constant, and it simplifies the bounds as well as the integral itself.

Gaussian integral

We've worked this out elsewhere, but let's take a look at the following, called the Gaussian integral:

$$\int_0^\infty e^{-ax^2} dx$$

Shankar calls this $I_0(a)$, that is, it is a function of a :

$$I_0(a) = \int_0^\infty e^{-ax^2} dx$$

and it is $I_0(a)$ because it is the zeroth version of a family of functions

$$I_n(a) = \int_0^\infty x^n e^{-ax^2} dx$$

For the version

$$I_0(a) = \int_0^\infty e^{-ax^2} dx$$

$$2I_0(a) = \int_{-\infty}^\infty e^{-ax^2} dx$$

there is a special trick to convert this to polar coordinates

$$4I_0(a)^2 = \int_{-\infty}^\infty e^{-ax^2} dx \int_{-\infty}^\infty e^{-ay^2} dy$$

Since the bounds of the x and y integrals are independent, as are the integrals themselves, we can turn this into the double integral

$$\begin{aligned} &= \int_{-\infty}^\infty \int_{-\infty}^\infty e^{-ax^2} e^{-ay^2} dx dy \\ &= \int_{-\infty}^\infty \int_{-\infty}^\infty e^{-a(x^2+y^2)} dx dy \end{aligned}$$

which can be converted to polar coordinates as

$$\begin{aligned} &= \int_0^{2\pi} \int_{-\infty}^\infty e^{-ar^2} r dr d\theta \\ &= 2\pi \int_0^\infty e^{-ar^2} r dr \\ &= 2\pi \left(-\frac{1}{2a} \right) (e^{-ar^2} \Big|_0^\infty) \end{aligned}$$

At the upper limit we get 0, and at the lower limit we get

$$e^{-\infty} - e^0 = 0 - 1 = -1$$

so the minus signs and the factors of two cancel and we have

$$4I_0(a)^2 = \frac{\pi}{a}$$

$$I_0(a) = \frac{1}{2}\sqrt{\frac{\pi}{a}}$$

For the rest of the family, the first one is easy

$$I_1(a) = \int_0^\infty x e^{-ax^2} dx$$

$$= -\frac{1}{2a}(e^{-ax^2} \Big|_0^\infty) = \frac{1}{2a}$$

We get an approach to the second one in the following way. Start with

$$I_0(a) = \int_0^\infty e^{-ax^2} dx$$

Differentiate with respect to a !

$$\frac{d}{da} \int_0^\infty e^{-ax^2} dx = \int_0^\infty \frac{\partial}{\partial a} e^{-ax^2} dx$$

$$= \int_0^\infty -x^2 e^{-ax^2} dx$$

For the left-hand side, we have

$$\frac{d}{da} \frac{1}{2}\sqrt{\frac{\pi}{a}} = -\frac{\sqrt{\pi}}{4} \frac{1}{a\sqrt{a}} = \frac{1}{4a}\sqrt{\frac{\pi}{a}}$$

So finally

$$\int_0^\infty x^2 e^{-ax^2} dx = \frac{1}{4a}\sqrt{\frac{\pi}{a}}$$