

velocity of the Earth's rotation is

$$\omega = \frac{2\pi}{24 \times 60 \times 60} = 7.27 \times 10^{-5} \text{ rad./s.} \quad (12.20)$$

It follows from Eq. (12.19) that

$$\begin{aligned} r_{\text{geo}} &= \left(\frac{G M_{\oplus}}{\omega^2} \right)^{1/3} = \left(\frac{(6.673 \times 10^{-11}) \times (5.97 \times 10^{24})}{(7.27 \times 10^{-5})^2} \right)^{1/3} \\ &= 4.22 \times 10^7 \text{ m} = 6.62 R_{\oplus}. \end{aligned} \quad (12.21)$$

Thus, a geostationary satellite must be placed in a circular orbit whose radius is *exactly* 6.62 times the Earth's radius.

12.6 Planetary orbits

Let us now see whether we can use Newton's universal laws of motion to derive Kepler's laws of planetary motion. Consider a planet orbiting around the Sun. It is convenient to specify the planet's instantaneous position, with respect to the Sun, in terms of the *polar coordinates* r and θ . As illustrated in Fig. 105, r is the radial distance between the planet and the Sun, whereas θ is the angular bearing of the planet, from the Sun, measured with respect to some arbitrarily chosen direction.

Let us define two unit vectors, \mathbf{e}_r and \mathbf{e}_θ . (A unit vector is simply a vector whose length is unity.) As shown in Fig. 105, the *radial* unit vector \mathbf{e}_r always points from the Sun towards the instantaneous position of the planet. Moreover, the *tangential* unit vector \mathbf{e}_θ is always normal to \mathbf{e}_r , in the direction of increasing θ . In Sect. 7.5, we demonstrated that when acceleration is written in terms of polar coordinates, it takes the form

$$\mathbf{a} = a_r \mathbf{e}_r + a_\theta \mathbf{e}_\theta, \quad (12.22)$$

where

$$a_r = \ddot{r} - r \dot{\theta}^2, \quad (12.23)$$

$$a_\theta = r \ddot{\theta} + 2 \dot{r} \dot{\theta}. \quad (12.24)$$

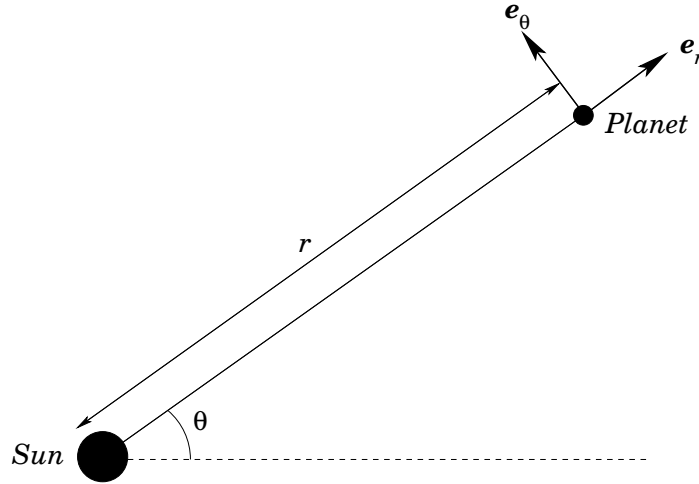


Figure 105: A planetary orbit.

These expressions are more complicated than the corresponding cartesian expressions because the unit vectors \mathbf{e}_r and \mathbf{e}_θ *change direction* as the planet changes position.

Now, the planet is subject to a single force: *i.e.*, the force of gravitational attraction exerted by the Sun. In polar coordinates, this force takes a particularly simple form (which is why we are using polar coordinates):

$$\mathbf{f} = -\frac{G M_\odot m}{r^2} \mathbf{e}_r. \quad (12.25)$$

The minus sign indicates that the force is directed towards, rather than away from, the Sun.

According to Newton's second law, the planet's equation of motion is written

$$m \mathbf{a} = \mathbf{f}. \quad (12.26)$$

The above four equations yield

$$\ddot{r} - r \dot{\theta}^2 = -\frac{G M_\odot}{r^2}, \quad (12.27)$$

$$r \ddot{\theta} + 2 \dot{r} \dot{\theta} = 0. \quad (12.28)$$

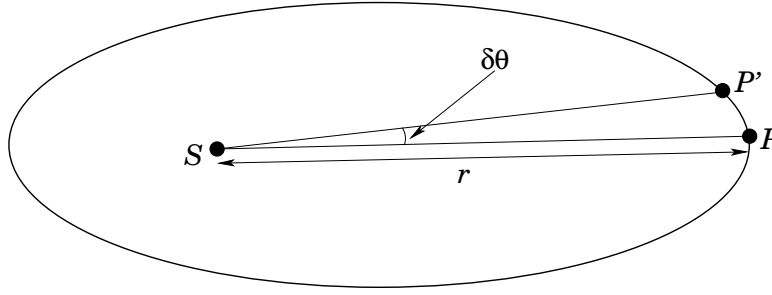


Figure 106: The origin of Kepler's second law.

Equation (12.28) reduces to

$$\frac{d}{dt} (r^2 \dot{\theta}) = 0, \quad (12.29)$$

or

$$r^2 \dot{\theta} = h, \quad (12.30)$$

where h is a *constant of the motion*. What is the physical interpretation of h ? Recall, from Sect. 9.2, that the angular momentum vector of a point particle can be written

$$\mathbf{l} = m \mathbf{r} \times \mathbf{v}. \quad (12.31)$$

For the case in hand, $\mathbf{r} = r \mathbf{e}_r$ and $\mathbf{v} = \dot{r} \mathbf{e}_r + r \dot{\theta} \mathbf{e}_\theta$ [see Sect. 7.5]. Hence,

$$\mathbf{l} = m r v_\theta = m r^2 \dot{\theta}, \quad (12.32)$$

yielding

$$h = \frac{l}{m}. \quad (12.33)$$

Clearly, h represents the *angular momentum* (per unit mass) of our planet around the Sun. Angular momentum is conserved (*i.e.*, h is constant) because the force of gravitational attraction between the planet and the Sun exerts *zero torque* on the planet. (Recall, from Sect. 9, that torque is the rate of change of angular momentum.) The torque is zero because the gravitational force is *radial* in nature: *i.e.*, its line of action passes through the Sun, and so its associated lever arm is of length zero.

The quantity h has another physical interpretation. Consider Fig. 106. Suppose that our planet moves from P to P' in the short time interval δt . Here, S

represents the position of the Sun. The lines SP and SP' are both approximately of length r . Moreover, using simple trigonometry, the line PP' is of length $r \delta\theta$, where $\delta\theta$ is the small angle through which the line joining the Sun and the planet rotates in the time interval δt . The area of the triangle PSP' is approximately

$$\delta A = \frac{1}{2} \times r \delta\theta \times r : \quad (12.34)$$

i.e., half its base times its height. Of course, this area represents the area swept out by the line joining the Sun and the planet in the time interval δt . Hence, the rate at which this area is swept is given by

$$\lim_{\delta t \rightarrow 0} \frac{\delta A}{\delta t} = \frac{1}{2} r^2 \lim_{\delta t \rightarrow 0} \frac{\delta\theta}{\delta t} = \frac{r^2 \dot{\theta}}{2} = \frac{h}{2}. \quad (12.35)$$

Clearly, the fact that h is a constant of the motion implies that the line joining the planet and the Sun sweeps out area at a *constant rate*: *i.e.*, the line sweeps equal areas in equal time intervals. But, this is just Kepler's second law. We conclude that Kepler's second law of planetary motion is a direct manifestation of *angular momentum conservation*.

Let

$$r = \frac{1}{u}, \quad (12.36)$$

where $u(t) \equiv u(\theta)$ is a new radial variable. Differentiating with respect to t , we obtain

$$\dot{r} = -\frac{\dot{u}}{u^2} = -\frac{\dot{\theta}}{u^2} \frac{du}{d\theta} = -h \frac{du}{d\theta}. \quad (12.37)$$

The last step follows from the fact that $\dot{\theta} = h u^2$. Differentiating a second time with respect to t , we obtain

$$\ddot{r} = -h \frac{d}{dt} \left(\frac{du}{d\theta} \right) = -h \dot{\theta} \frac{d^2 u}{d\theta^2} = -h^2 u^2 \frac{d^2 u}{d\theta^2}. \quad (12.38)$$

Equations (12.27) and (12.38) can be combined to give

$$\frac{d^2 u}{d\theta^2} + u = \frac{G M_{\odot}}{h^2}. \quad (12.39)$$

This equation possesses the fairly obvious general solution

$$u = A \cos(\theta - \theta_0) + \frac{G M_\odot}{h^2}, \quad (12.40)$$

where A and θ_0 are arbitrary constants.

The above formula can be inverted to give the following simple orbit equation for our planet:

$$r = \frac{1}{A \cos(\theta - \theta_0) + G M_\odot / h^2}. \quad (12.41)$$

The constant θ_0 merely determines the orientation of the orbit. Since we are only interested in the orbit's *shape*, we can set this quantity to zero without loss of generality. Hence, our orbit equation reduces to

$$r = r_0 \frac{1 + e}{1 + e \cos \theta}, \quad (12.42)$$

where

$$e = \frac{A h^2}{G M_\odot}, \quad (12.43)$$

and

$$r_0 = \frac{h^2}{G M_\odot (1 + e)}. \quad (12.44)$$

Formula (12.42) is the standard equation of an *ellipse* (assuming $e < 1$), with the origin at a focus. Hence, we have now proved Kepler's first law of planetary motion. It is clear that r_0 is the radial distance at $\theta = 0$. The radial distance at $\theta = \pi$ is written

$$r_1 = r_0 \frac{1 + e}{1 - e}. \quad (12.45)$$

Here, r_0 is termed the *perihelion* distance (*i.e.*, the closest distance to the Sun) and r_1 is termed the *aphelion* distance (*i.e.*, the furthest distance from the Sun). The quantity

$$e = \frac{r_1 - r_0}{r_1 + r_0} \quad (12.46)$$

is termed the *eccentricity* of the orbit, and is a measure of its departure from circularity. Thus, $e = 0$ corresponds to a purely circular orbit, whereas $e \rightarrow$

Planet	e
Mercury	0.206
Venus	0.007
Earth	0.017
Mars	0.093
Jupiter	0.048
Saturn	0.056

Table 7: The orbital eccentricities of various planets in the Solar System.

1 corresponds to a highly elongated orbit. As specified in Tab. 7, the orbital eccentricities of all of the planets (except Mercury) are fairly small.

According to Eq. (12.35), a line joining the Sun and an orbiting planet sweeps area at the constant rate $h/2$. Let T be the planet's orbital period. We expect the line to sweep out the *whole area* of the ellipse enclosed by the planet's orbit in the time interval T . Since the area of an ellipse is $\pi a b$, where a and b are the *semi-major* and *semi-minor* axes, we can write

$$T = \frac{\pi a b}{h/2}. \quad (12.47)$$

Incidentally, Fig. 107 illustrates the relationship between the aphelion distance, the perihelion distance, and the semi-major and semi-minor axes of a planetary orbit. It is clear, from the figure, that the semi-major axis is just the mean of the aphelion and perihelion distances: *i.e.*,

$$a = \frac{r_0 + r_1}{2}. \quad (12.48)$$

Thus, a is essentially the planet's mean distance from the Sun. Finally, the relationship between a , b , and the eccentricity, e , is given by the well-known formula

$$\frac{b}{a} = \sqrt{1 - e^2}. \quad (12.49)$$

This formula can easily be obtained from Eq. (12.42).

Equations (12.44), (12.45), and (12.48) can be combined to give

$$a = \frac{h^2}{2 G M_\odot} \left(\frac{1}{1+e} + \frac{1}{1-e} \right) = \frac{h^2}{G M_\odot (1 - e^2)}. \quad (12.50)$$

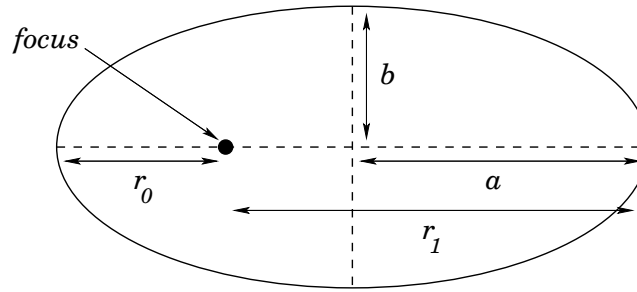


Figure 107: Anatomy of a planetary orbit.

It follows, from Eqs. (12.47), (12.49), and (12.50), that the orbital period can be written

$$T = \frac{2\pi}{\sqrt{GM_{\odot}}} a^{3/2}. \quad (12.51)$$

Thus, the orbital period of a planet is proportional to its mean distance from the Sun to the power $3/2$ —the constant of proportionality being the *same* for all planets. Of course, this is just Kepler’s third law of planetary motion.

Worked example 12.1: Gravity on Callisto

Question: Callisto is the eighth of Jupiter’s moons: its mass and radius are $M = 1.08 \times 10^{23}$ kg and $R = 2403$ km, respectively. What is the gravitational acceleration on the surface of this moon?

Answer: The surface gravitational acceleration on a spherical body of mass M and radius R is simply

$$g = \frac{GM}{R^2}.$$

Hence,

$$g = \frac{(6.673 \times 10^{-11}) \times (1.08 \times 10^{23})}{(2.403 \times 10^6)^2} = 1.25 \text{ m/s}^2.$$