Calculus of variations

Consider two points in the xy-plane (x_1, y_1) and (x_2, y_2) , and the paths that connect them. One path is the shortest path, namely a straight line. Our goal is to prove that.

There are many possible paths, any one of which we could try to write as y = f(x) or to use fewer symbols we write y = y(x).

As you know, any small element of the path ds is (by Pythagoras)

$$ds = \sqrt{dx^2 + dy^2}$$

Factoring out dx we get

$$ds = \sqrt{1 + (\frac{dy}{dx})^2} \ dx = \sqrt{1 + y'(x)^2} \ dx$$

The total path length is

$$L = \int_{x_1}^{x_2} \sqrt{1 + y'(x)^2} \, dx$$

The unknown is the function y = y(x). The principle is that we will find y(x) such that any infinitesimal change in y(x) makes no difference in the length, to first order. We say that such a path makes the integral stationary.

Fermat's principle

The problem can be made slightly harder by including some function f(x,y) under the integral. For example, consider the path taken by a light beam between two points. If the refractive index varies with position, then the path will not be a straight line. Instead, light takes the path that takes the *least time*.

time =
$$\int_1^2 dt = \int_1^2 \frac{ds}{v}$$

where v dt = ds and the velocity v = c/n so

time =
$$\int_{1}^{2} dt = \int_{1}^{2} \frac{ds}{v} = \frac{1}{c} \int_{1}^{2} n \, ds$$

n is a function n(x,y), and we substitute for ds:

time =
$$\frac{1}{c} \int_{x_1}^{x_2} n(x, y) \sqrt{1 + y'(x)^2} dx$$

Since for any parametrized curve (which is all we can really deal with), y = y(x), the function n(x, y) is really only dependent on x and this is a single integral over x.

generally

We will have some integral over x where the integrand is a function that depends on x, on y(x) and on y'(x) so we write

$$S = \int_{x_1}^{x_2} f[y(x), y'(x), x] dx$$

where y(x) is an unknown curve and we seek the y(x) which makes the integral stationary.

Let us denote the correct solution to the problem as y(x) and all the other "wrong" curves as Y(x) and then

$$Y(x) = y(x) + \eta(x)$$

 η is a term that contains all the extra length of a wrong path Y compared to the shortest path y. We are only interested in paths Y(x) that pass through the endpoints (x_1, y_1) and (x_2, y_2) . At those points η must be zero because Y = y there.

$$\eta(x_1) = \eta(x_2) = 0$$

As Taylor says, "there are infinitely many choices for the difference $\eta(x)$, for example we could choose $\eta = (x - x_1)(x - x_2)$ or $\sin [\pi(x - x_1)/(x_2 - x_1)]$."

The function η will have something that makes the difference in Y(x) – y(x). Let us parametrize those things that make the difference and factor them out into a parameter α so that

$$Y(x) = y(x) + \alpha \eta(x)$$

The integral S now depends on α . The curve y(x) is obtained by setting $\alpha = 0$. Our problem is now to make sure that $S(\alpha)$ is a minimum when $\alpha = 0$. We write

$$S(\alpha) = \int_{x_1}^{x_2} f[Y(x), Y'(x), x] dx$$
$$= \int_{x_1}^{x_2} f[y + \alpha \eta(x), y' + \alpha \eta'(x), x] dx$$

Notice that although η depends on x, α does not.

Next, we want to differentiate S with respect to α and set that derivative equal to zero. Differentiating the integrand:

$$\frac{\partial}{\partial \alpha} f \left[y + \alpha \eta(x), y' + \alpha \eta'(x), x \right] = \eta \frac{\partial f}{\partial y} + \eta' \frac{\partial f}{\partial y'}$$

I don't understand the previous step.

But given this

$$\frac{dS}{d\alpha} = \int_{x_1}^{x_2} \frac{\partial f}{\partial \alpha} dx$$
$$= \int_{x_2}^{x_2} (\eta \frac{\partial f}{\partial y} + \eta' \frac{\partial f}{\partial y'}) dx$$

This condition must be true for any choice of the path.

Now he says, we will rewrite the second term on the right using integration by parts.

$$\int_{x_1}^{x_2} \eta' \frac{\partial f}{\partial y'} dx = \eta(x) \frac{\partial f}{\partial y'} \Big|_{x_1}^{x_2} - \int_{x_1}^{x_2} \eta(x) \frac{d}{dx} \frac{\partial f}{\partial y'} dx$$

Because $\eta(x_1) = \eta(x_2) = 0$, the first term is zero and we have then:

$$\int_{x_1}^{x_2} \eta' \, \frac{\partial f}{\partial y'} \, dx = -\int_{x_1}^{x_2} \eta(x) \frac{d}{dx} \, \frac{\partial f}{\partial y'} \, dx$$

Substitute back into the derivative and set it equal to zero:

$$\int_{x_1}^{x_2} \eta(x) \left(\frac{\partial f}{\partial y} - \frac{d}{dx} \frac{\partial f}{\partial y'}\right) dx = 0$$

Since this must be true for any choice of $\eta(x)$, the term in parentheses must be zero (at least if the functions involved are continuous functions, and our examples will be). So we have finally

$$\frac{\partial f}{\partial y} = \frac{d}{dx} \frac{\partial f}{\partial y'}$$

which is the Euler-Lagrange equation.

examples