

SIDDHARTH JAIN

+1 (623) 326-7382 tellsiddh@asu.edu [linkedin.com/in/tellsiddh/](https://www.linkedin.com/in/tellsiddh/) github.com/tellsiddh www.tellsiddh.com

EDUCATION

Arizona State University, Tempe, USA

Expected May 2024

Master of Science, Robotics and Autonomous Systems

GPA: 3.78/4

Relevant Coursework: Reinforcement Learning, Deep Learning, Optimal Control, Multi-Robot Systems

D. J. Sanghvi College of Engineering, Mumbai, India

May 2022

Bachelor of Engineering, Mechanical

GPA: 8.74/10

Relevant Coursework: Structured Programming Approach, Industrial Electronics, Robotics, Machine Design

TECHNICAL SKILLS

Languages	Python, C++, Embedded C, MATLAB & Simulink, SQL, PowerShell
Software	Docker, ROS2, Gazebo, Solidworks, Linux, Arduino IDE, Altium, Microsoft Office
Frameworks	Tensorflow, Scikit-Learn, PyTorch, React Native, FreeRTOS
Cloud Services	AWS IoT Core, Lambda, Timestream, DynamoDB, S3 Buckets
Hardware	Semtech SX12xx, NRF BLE, ESP32, SAMD21, Arm Cortex-M, ATmega, Raspberry Pi
Protocols	SPI, I2C, CAN Bus, UART, ZigBee, LoRa, Wi-Fi, BLE, MQTT

WORK EXPERIENCE

Embedded Systems Engineer

Oct 2022 – Present

Enterprise Technology

Tempe, AZ

- Engineered a UHF full mesh protocol with AES Encryption for ASU cart tracking using embedded C++, LoRa, MQTT, and AWS IoT Core. Developed a BLE mesh network on ESP32 for SOS signals with React-Native on Android and iOS.
- Authored AWS Lambda functions with API Gateways and Timestream for real-time location capture, demonstrating system-cloud interoperability using Python and JavaScript.
- Optimized mpu9250 with deep sleep acceleration-based interrupt, extending IoT-based cart tracker battery life to 3 years.

Graduate Student Researcher

Dec 2022 – Present

Bio-Inspired Robotics, Technology and Healthcare Lab

Tempe, AZ

- Engineered an advanced 3-axis linear cartesian robot, integrating a 6-axis load cell with a closed-loop controller. Developed primarily in python for embedded Linux environments, ensuring high precision testing results.
- Designed and fabricated gripper pads with curved textured surfaces using a Polydimethylsiloxane (PDMS) polymer to enable the LTI robot to perform friction-based mobility on curved surfaces irrespective of the material and surface texture.

Vice Captain

Mar 2019 – May 2021

DJS Kronos India

Mumbai, India

- Headed and co-founded the electric ATV team, also simulated the vehicle using Simulink, achieving a 17% increased efficiency.
- Engineered a DAQ system using GSM SIM 900 Module with Raspberry Pi Zero, transmitting sensor data efficiently through the ThingSpeak Communication Library, emphasizing cloud interoperability and embedded C++ proficiency.

ACADEMIC PROJECTS

Dexterous Manipulation with a Robotic Hand | Reinforcement Learning, Actor Critic, ROS, Python

- Analyzed on-policy methods like DAPG, Monte-Carlo return methods such as AWR, leading to a 20% increase in success with the Advantage Weighted Actor Critic for dexterous robotic manipulation by merging prior offline data with online tuning.
- Employed reinforcement learning and Python within a Linux environment, optimizing robotic skill acquisition of a 6 DoF Hand.

Self Balancing Platform | MATLAB & Simulink, Inverse Kinematics, PID Tuning

- Engineered a closed-loop PID controller for the Stewart platform with Simulink, achieving optimized ball motion stability by reducing Steady State Error through integral tuning. Optimized stability with a response time of 0.5 seconds.

UAV Line Follower Drone | MATLAB, Simulink, Edge Detection

- Developed a Line Follower function for the Parrot Mambo Mini-Drone, employing edge detection techniques to calculate the nearest edge and identifying specific HSV values of the track within 20 ms using Simulink. Achieving an accuracy of 95% across 40 tests.

Machine Learning for Fraud Detection | Python, TensorFlow, LSTM, Deep Learning, RNN, CUDA

- Analyzed machine learning algorithms for fraud detection on 1 million bank transactions using one-hot encoding in Python. Validated model variations through feature assessment and statistical evaluations, achieving 97.2% accuracy.

Dynamic Pathfinding in Complex Environments | Python, Matplotlib, Algorithm Design, Dynamic Programming

- Developed and analyzed dynamic pathfinding algorithms including A*, Dijkstra's, DFS, BFS, and Greedy Best-First Search using Python and Matplotlib. Metrics such as path length (24-25 steps) and time taken (0.0011 to 3.288 seconds) were considered, enabling navigation in environments with moving obstacles and visualizing efficiency and behavior.

Custom LoRa and Ethernet Communication Board | ESP32 S3, PCB Design, Embedded C, FreeRTOS

- Developed a board with Xtensa LX7 (32-bit, 240 MHz), RFM95W LoRa (915 MHz, 15 km range), and LAN8720 Ethernet.
- Designed a 4-layer PCB with 50-ohm impedance control for RF signal integrity and implemented firmware in Embedded C with FreeRTOS for concurrent communication tasks, OTA updates, and power management.

PATENTS

Steering Knuckle Joint for Double A-arm Suspension System — 378832-001

Design Of Single Stage Open Differential - Pending — 378831-001