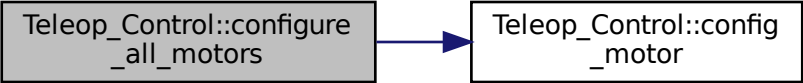


Teleop_Control::configure
_all_motors



```
graph LR; A[Teleop_Control::configure_all_motors] --> B[Teleop_Control::config_motor]
```

Teleop_Control::config
_motor