



Master 2 MoSIG

Advanced Software Modelling & Engineering

Lab: UML-RT

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Exercise 2

From the code of the traffic-light.rt file, we drew the following schemes, where Figure 1 represents the state machine and Figure 2 the capsule diagram.

timer.informEvery(UMLRTTimespec(5,0));

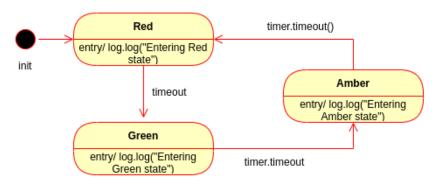


Figure 1: State machine

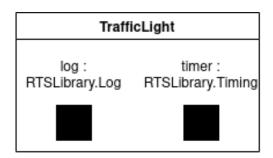


Figure 2: Capsule diagram

Regarding the timer part, we made the following changes:

```
state Red {
    entry log.log("Entering Red state");
        timer.informIn(UMLRTTimespec(5, 0));
}
state Green {
    entry log.log("Entering Green state");
        timer.informIn(UMLRTTimespec(5, 0));
}
state Amber {
    entry log.log("Entering Amber state");
```

```
timer.informIn(UMLRTTimespec(2, 0));
}
```

Exercise 3

From the code of the ping-pong.rt file, we drew the following schemes, where Figure 3 represents the state machine and Figure 4 the capsule diagram.

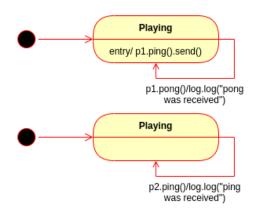


Figure 3: State machine

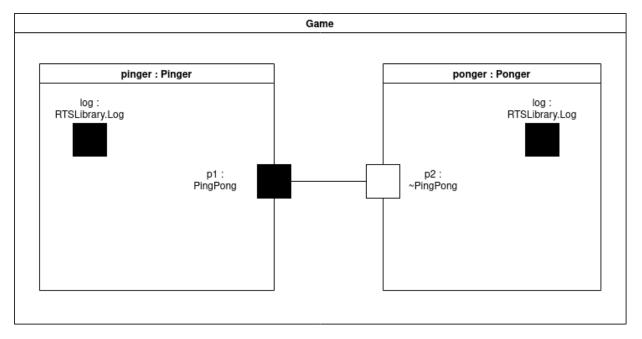


Figure 4: Capsule diagram

To produce an infinite trace of ping and pong messages, we did the following in the Ponger capsule:

Exercise 4

From the code of the traffic-light-with-replication.rt & led.rt files, we drew the following schemes, where Figure 6 represents the state machine and Figure ?? the capsule diagram.

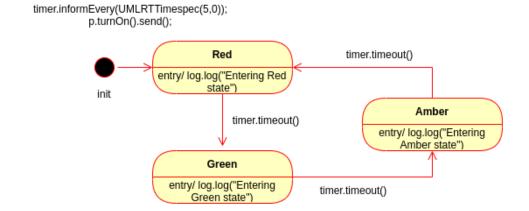


Figure 5: State machine

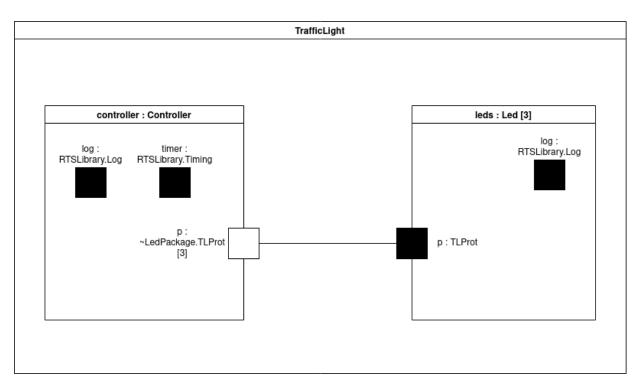


Figure 6: Capsule diagram

Exercise 6

To make use of two traffic lights at the same time, we simply added a new AssignementProtocol port and a new TrafficLight instance to the TestCapsule, where the connections are identical to the first one. Then we just assigned the GPIOs 12, 13 & 14 to the new port, and it worked.

For the synchronization part, we simply made sure that the two lights always start in different states (i.e. one initial \rightarrow red & one initial \rightarrow green) by creating two capsules TrLight1 and TrLight2. We set the durations to duration_{red} = duration_{amber} + duration_{green}, which ensures that the lights are synchronized.

All of these things are visible in the code files attached (Crossroad/cpp/cr.rt).