1 Paper Outline

I. Abstract

- A. Flatbed scanner alternative with improved resolution to digitizing tree cookies and cores
- B. Digital twins of samples is important for building data repositories and promoting replicable science
- C. Digitizing wood samples has limits to sample dimensions or lacks affordable implementations
- D. Current alternatives are very expensive (\$70,000USD), lack a high level of detail (printer scanners), or cannot scan cookies (CaptuRING)
- E. Tina is open source and able to be assembled with 3D printed parts, OpenBuilds parts kits, and hand tools

II. Introduction

- A. Tree ring science overview
 - i. **Lizzie add here**
 - ii. tree rings can help reconstruct past climates
 - iii. understanding tree growth mechanisms
- B. Development of scanning alternatives
 - i. beginning with ATRICS
 - ii. expensive Gigapixel
 - iii. DIY CaptuRING
- C. Main reasons to build this
 - i. further develop the affordable / open source alternatives for scientific equipment
 - ii. reduce the need for proprietary software such as PTGUI for image stitching
 - iii. allow a method to digitize cookies to have higher quality data than cores alone
 - iv. avoid size limitations to digitize tree cookies and cores
 - v. Digitizing wood samples for better data pooling / archiving
- D. Software can be used to help record annual growth
 - i. Coorecorder
 - ii. Various ML based methods that Sandy has researched

III. Materials and Methods

A. Hardware Design

- i. Cartesian gantry robot kit from OpenBuilds (ACRO system)
- ii. Camera
 - a. chose Raspberry Pi HQ Camera for C-mount lens options, ability to stream, cost effectiveness, and clear obscelescence statement
- iii. computer
 - a. NVIDIA Jetson Orin Nano for processing power in a light package, can connect to Raspberry Pi camera. Powerful enough to power a GUI and monitor display as well
 - b. NVMM Hardware accelerated video streaming reduces CPU load
- iv. 3D printed components
 - a. 3D printed parts from a Bambu X1C were designed to mount the lens and computer to the ACRO system
 - b. other parts such as a drag chain for cable management were also 3D printed
 - c. levelling tables were designed to allow for the cookie samples to be arranged orthogonally to the lens. Imperative to capturing in focus images across the entire cookie

B. Software Design

- i. image focusing
 - a. sample levelling is not perfect. At different points on the cookie, the Z-height of the gantry must vary to capture the in focus image. A routine was made to take multiple images at varied Z-heights. The image with the highest normalized variance score was chosen as the in focus image and is kept.
 - b. automatic PID control was implemented to adjust the initial Z-coordinate for each set of images to increase the probability of having an in focus image at each image set
- ii. grid traverse
 - a. The software traverses the entire surface area of the sample. Each row and column is overlapping with its adjacent row and column. Allowing for feature based image striching.
- iii. feature based image stitching
 - a. An implementation, Stitch2D, of feature based OpenCV image stitching was used. Edits to the code were made to allow for more memory efficient methods of stitching with the use of NumPy memory maps
- iv. user interface
 - a. A GUI was made to navigate the machine to samples, set the size of the sample and its center. After samples are set up the operation is passive.

IV. Results

- A. scans of cookies / cores
 - i. ultra high resolution scans (DPI 15,000 +)
 - ii. downscaled versions as high resolution is not necessary for all applications
 - iii. Digitization time as a function of surface area. Large cookies can scan only a portion of the cookie including the center and half of the rings.
 - iv. large surface areas can produce files that are inconveniently large
- B. File-size results in functional limits
 - i. max filesize for TIFF files is $2.5~\mathrm{GB}$
 - ii. other lossless filetypes for larger images are not compatible with standard image viewers
 - iii. workaround with NumPy memory maps and cropped viewing

V. Discussion (for MEE Only)

- A. strengths and opportunities
 - i. Ability to capture multiple cores / cookies simultaneously
 - ii. cost effective
 - iii. potential for automatic tree ring identification with iamge processing / ML
 - iv. potential for vessel counts for an entire ring
 - although final quality is only as good as the sample preparation
- B. opportunities for improvements
- C. Lenses
 - i. troubles with fixed aperature / non autofocusing / poorly manufactured lens
 - a. lack of control to increase sharpness
 - b. autofocusing with Z-axis movement is time consuming to do without image blur
 - c. poor lens manufacturing can lead to drastically different quality / lighting between the edges and center of an image
 - ii. good lens can increase sharpness and therefore stitching accuracy and ML inference
 - iii. obtain similar quality between the corner and center of the image
 - poor lens quality seemed to be the culprit of producing visible seams when stitching with larger field of view images

D. focus stacking

when a sample is microtomed, the vessels are hollow. The autofocusing algorithm can be confused from this

- E. Difficulty stitching with lower detail images, can't increase digitizing speed, must downscale high resolution images
- F. Autofocusing with hardware would significantly decrease the time to capture a cookie (using a professional camera)

VI. Conclusions (optional for MEE)

A.