



February 26 - March 04 Weekly Report

1 Progress

- Detailed lane detection tests are done for different obstacles on the path as in *Figure 1*.

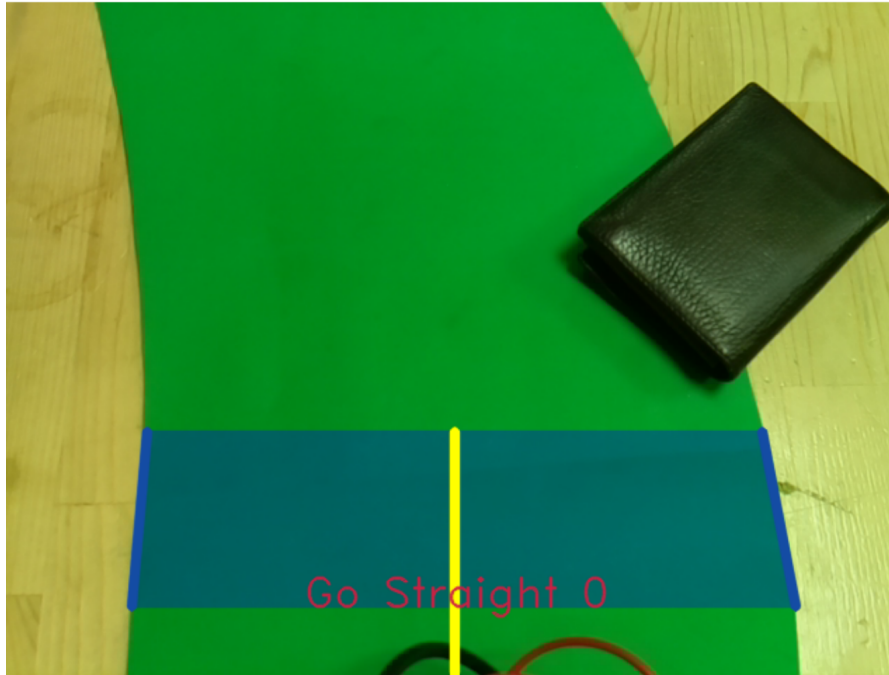


Figure 1: Possible Problem on the Path and the Algorithm Output

- 3D drawing of the vehicle is done as in *Figure 2*.
- Step response of the vehicle is tried to be obtained. Unfortunately, this test failed.
- Distance sensors are deployed on Raspberry Pi and tested.
- Critical Design Review Report is partially written.



2 Plans

- Obtaining step response with new chassis.

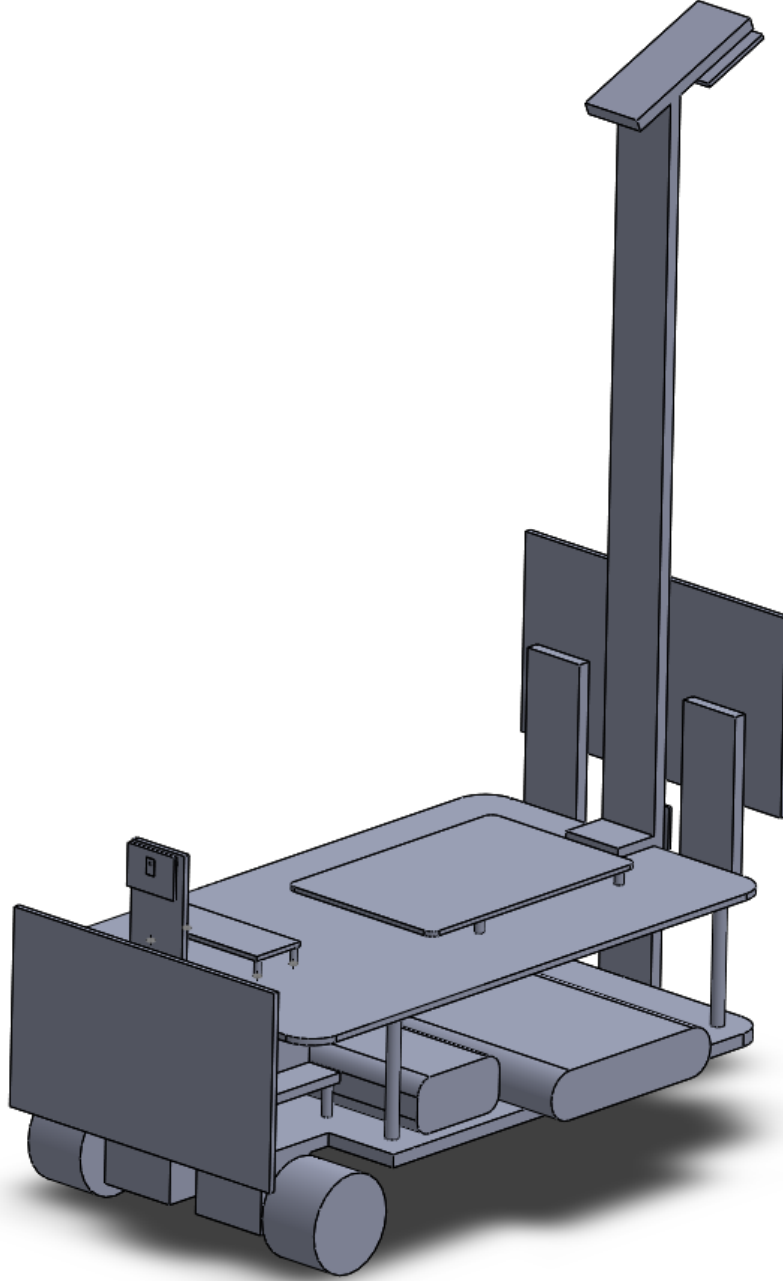


Figure 2: 3D Drawing of the Vehicle

