

## EE407 Process Control

### Experiment 5

1. Reverting back to actual temperature,

$$T(x, t) = T_e + (M - T_e) \operatorname{erfc}\left(\frac{x}{2\sqrt{\alpha t}}\right) \text{ for } x > 0 \text{ and } t > 0$$

For our case;

$$T(L, t) = T_e + (M - T_e) \operatorname{erfc}\left(\frac{L}{2\sqrt{\alpha t}}\right)$$

with given constants and  $T_e = 0$  ,for convenience, and  $M = 1$  for unit step input;  
The response can be seen at *Figure 1*. Source code for this part can be examined at **Appendix A**.

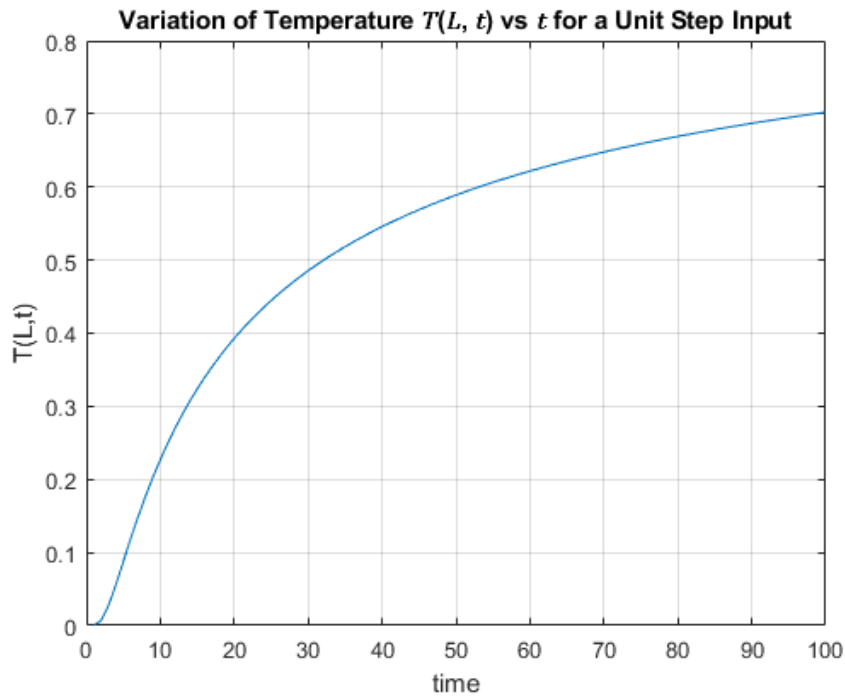


Figure 1: Variations of Temperature  $T(L,t)$  vs time

2. In general,

$$\frac{1}{\alpha} \frac{dT_r(t)}{dt} = \frac{T_{r-1}(t) - 2T_r(t) + T_{r+1}(t)}{(\Delta x)^2} \text{ for } r = 1, 2, \dots, n$$



$T_{n+1}$  can be assumed to be equal to  $T_n$  for  $n$  equations to solve for unknowns.

- for  $n=1$

$$\frac{1}{\alpha} \frac{dT_1(t)}{dt} = \frac{T_0(t) - 2T_1(t) + T_2(t)}{(\Delta x)^2}$$

where  $T_0$  is the input and  $T_1 = T_2$  assumption can be made.

Taking Laplace transforms of both sides, it can be found that;

$$\left( \frac{(\Delta x)^2}{\alpha} s + 1 \right) T_1(s) = T_0(s)$$

$$\frac{T_1(s)}{T_0(s)} = \frac{1}{\frac{(\Delta x)^2}{\alpha} s + 1}$$

it can be seen that the time constant of this equation is

$$\tau_1 = \frac{(\Delta x)^2}{\alpha} = 29.2002 \text{ seconds}$$

where  $\Delta x = L = 5 \text{ cm}$ .

Let us now find the circuit equivalent of this approximation. The circuit at at *Figure 2* seems a good fit. Let us now analyse this circuit and find its time constant. It is desired that the time constant of this circuit should at lest  $10^{-5}$  times of the approximation model.

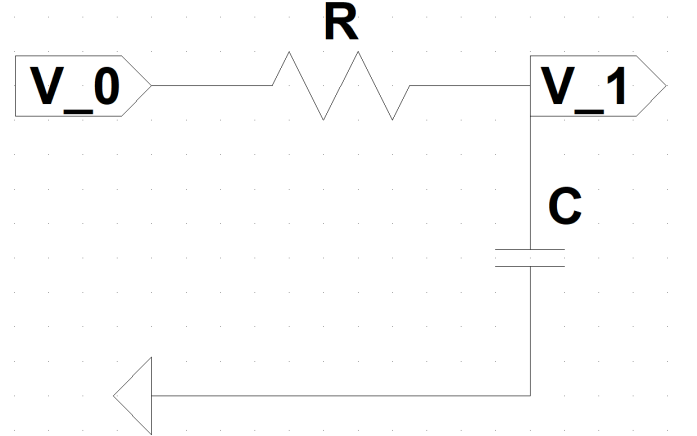


Figure 2: Circuit Equivalent of Lumped Approximation Model for  $n=1$

$$\frac{V_1(s)}{V_0(s)} = \frac{1}{1 + (RC)s}$$



$$\tau_c = RC = 10^{-5} \tau_1 = 2.92 \cdot 10^{-4}$$

Assuming  $C = 1 \mu F$

$R$  value can be found to be as  $292.002 \Omega$

- for  $n=2$ ;

$$\frac{1}{\alpha} \frac{dT_1(t)}{dt} = \frac{T_0(t) - 2T_1(t) + T_2(t)}{(\Delta x)^2}$$

$$\frac{1}{\alpha} \frac{dT_2(t)}{dt} = \frac{T_1(t) - 2T_2(t) + T_3(t)}{(\Delta x)^2}$$

where  $T_o$  is the input and  $T_2 = T_3$  assumption can be made.

Taking Laplace transform of both sides

Assume from now on  $A = \frac{(\Delta x)^2}{\alpha}$

$$(As + 2)T_1(s) = T_0(s) + T_2(s)$$

$$(As + 1)T_2(s) = T_1(s)$$

$$[(As + 2)(As + 1) - 1]T_2(s) = T_0(s)$$

$$\frac{T_2(s)}{T_0(s)} = \frac{1}{A^2 s^2 + 3As + 1} = \frac{1}{\tau_2^2 s^2 + 2\xi\tau_2 s + 1}$$

with  $\Delta x = L/2 = 2.5cm$

$$\tau_2 = A = \frac{(\Delta x)^2}{\alpha} = 7.3001 \text{ secs}$$

Desired time constant for circuit equivalent then  $\tau_{c2} = 10^{-5} \tau_2 = 7.3 \cdot 10^{-5} \text{ secs}$

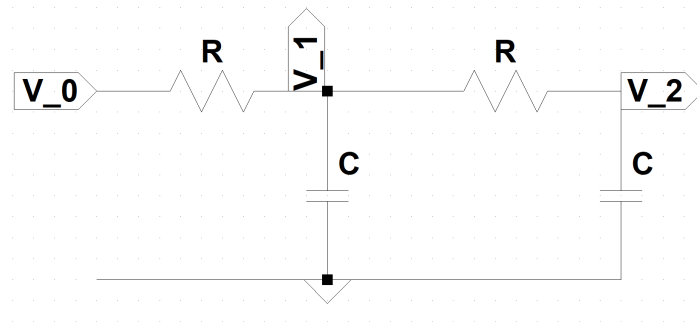


Figure 3: Circuit Equivalent of Lumped Approximation Model for  $n=2$



The transfer equation for the circuit at *Figure 3* can be found as

$$\frac{V_2(s)}{V_1(s)} = \frac{1}{(RC)^2 s^2 + 3(RC)s + 1} = \frac{1}{\tau_{c2}^2 s^2 + 2\xi\tau_{c2} + 1}$$

$$\tau_{c2} = RC = 7.3 \cdot 10^{-5} \text{ secs}$$

Assuming  $C = 1 \mu F$

$R$  value can be found to be as  $73.0005 \Omega$

- for  $n$ , the circuit model at *Figure 8* can be used

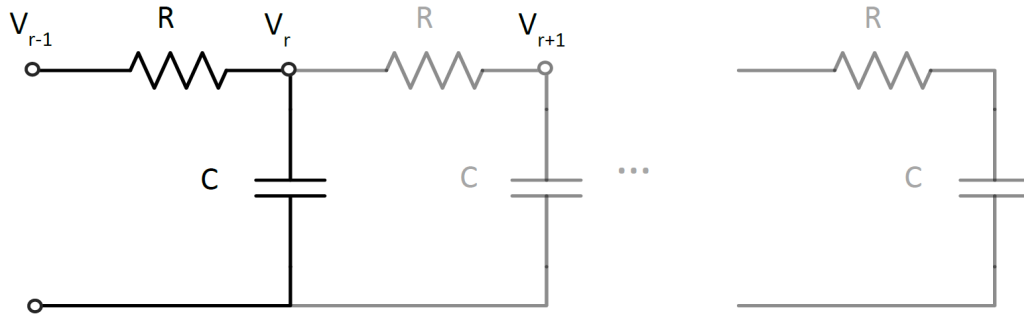


Figure 4: Simulation of the lumped approximate model

The pattern can be observed from the first two equations that found earlier for  $n = 1, 2$

$$\Delta x = \frac{L}{n}$$

$$\alpha = \frac{\lambda}{\rho c}$$

$$\tau_n = A = \frac{(\Delta x)^2}{\alpha}$$

$$\tau_{cn} = RC = \tau_n 10^{-5}$$

- for  $n=3$

$$\Delta x = \frac{L}{3}$$

$$\tau_3 = A = 3.2445 \text{ secs}$$



$$\tau_{c3} = RC = \tau_3 10^{-5} = 3.2445 \cdot 10^{-5} \text{ secs}$$

Assuming  $C = 1 \mu F$

$R$  value can be found to be as  $32.4447 \Omega$

- for  $n=5$

$$\Delta x = \frac{L}{5}$$

$$\tau_5 = A = 1.1680 \text{ secs}$$

$$\tau_{c5} = RC = \tau_5 10^{-5} = 1.1680 \cdot 10^{-5} \text{ secs}$$

Assuming  $C = 1 \mu F$

$R$  value can be found to be as  $11.6801 \Omega$

3. The responses can be examined below

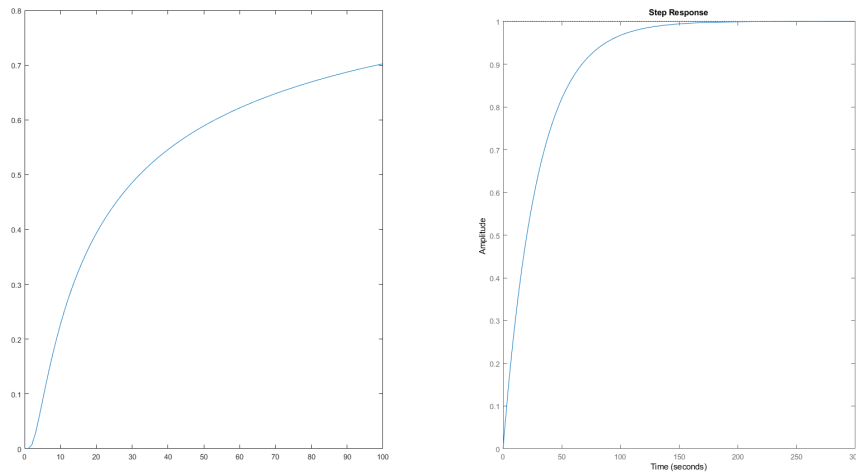


Figure 5: Step response of System and steps response pf its Lumped Parameter approximation for  $n=1$



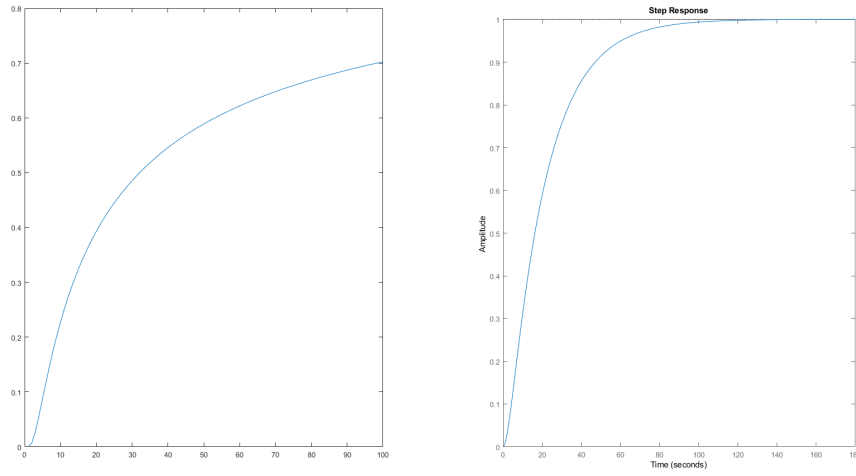


Figure 6: Step response of System and steps response pf its Lumped Parameter approximation for  $n=2$

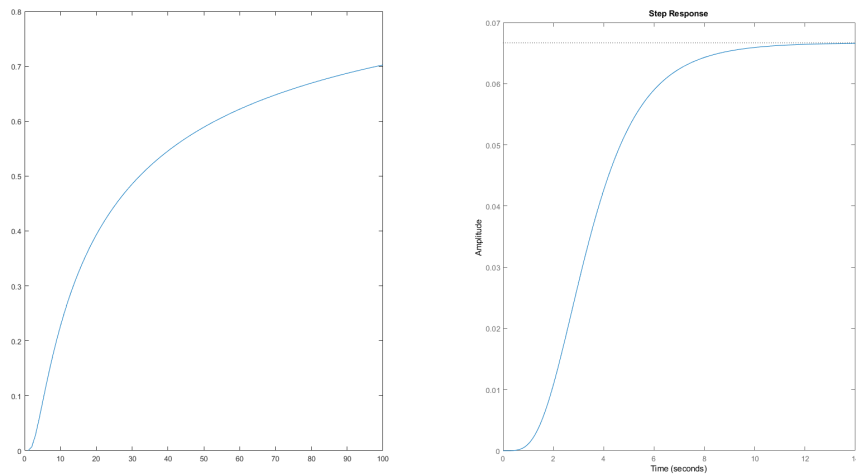


Figure 7: Step response of System and steps response pf its Lumped Parameter approximation for  $n=3$



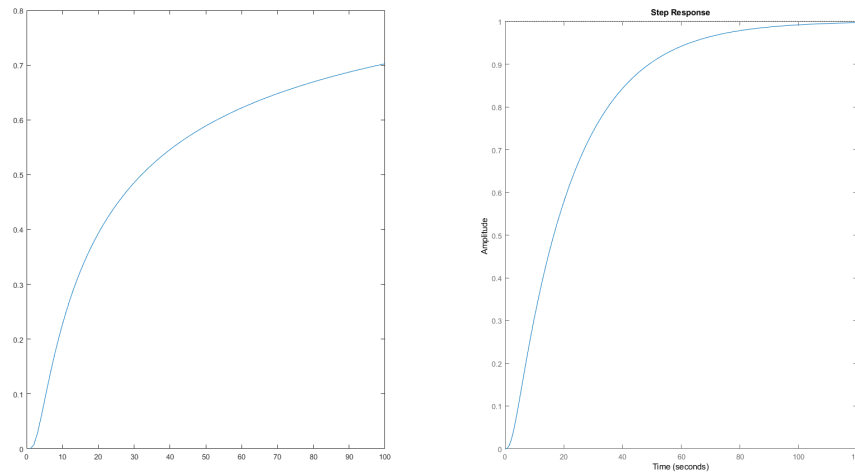


Figure 8: Step response of System and steps response pf its Lumped Parameter approximation for  $n=4$

## Appendices

### A Source Code for Matlab Part

```

1 %% %%%%%%%%%%% Q1 %%%%%%%%%%%
2 %% Var Declr.
3
4 L=5
5 A=4.9
6 p=2.7
7 k=0.497
8 c=0.215
9 a=k/(p*c)
10 Te=0
11 M=1
12 %% Calculation of the response
13 t=1:1:100
14 i=1
15 while (i < 101)
16     T(i)=Te+(M-Te)*erfc(L/(2*sqrt(a*i)))
17     i=i+1
18 end

```



```

19 %% Plotting the response
20 plot(t,T)
21 grid on
22 title('Variation of Temperature T(L,t) vs t for a Unit Step
      Input')
23 xlabel('time')
24 ylabel('T(L,t)')
25
26 %% %%%%%%%%%%% Q2 %%%%%%%%%%%
27 %% for n=1
28
29 tau1=(L^2)/(a)
30
31 taue=10^(-5)*tau1
32
33 C=10^-6
34
35 R=taue/C
36
37 %% for n=2
38 L2=L/2
39
40 tau2= (L2^2)/(a)
41
42 taue2=10^(-5)*tau2
43
44 C2=10^-6
45
46 R2=taue2/C2
47
48 %% for n=3
49 L3=L/3
50
51 tau3= (L3^2)/(a)
52
53 taue3=10^(-5)*tau3
54
55 C3=10^-6
56
57 R3=taue3/C3
58
59 %% for n=5

```





```

60 L5=L/5
61
62 tau5= (L5^2)/(a)
63
64 taue5=10^(-5)*tau5
65
66 C5=10^-6
67
68 R5=taue5/C2
69
70 %% %%%%%%%%%%% Q2 %%%%%%%%%%%
71 %% n=1
72
73 T1=tf([1],[tau1 1])
74
75 figure;
76 grid on
77 subplot(1,2,1)
78 plot(t,T)
79 subplot(1,2,2)
80 step(T1)
81
82 %% n=2
83
84 T2=tf([1],[tau2^2 3*tau2 1])
85
86 figure;
87 grid on
88 subplot(1,2,1)
89 plot(t,T)
90 subplot(1,2,2)
91 step(T2)
92
93 %% n=3
94
95 T3=tf([1],[tau3^3 5*tau3^2 7*tau3 1])
96
97 figure;
98 grid on
99 subplot(1,2,1)
100 plot(t,T)
101 subplot(1,2,2)

```



```
102 step(T3)
103
104 %% n=5
105 a=tf([tau5 2],[1])
106 b=tf([tau5 1],[1])
107 c= a^4*b-1
108
109 T5=1/c
110
111 figure;
112 grid on
113 subplot(1,2,1)
114 plot(t,T)
115 subplot(1,2,2)
116 step(T5)
```

