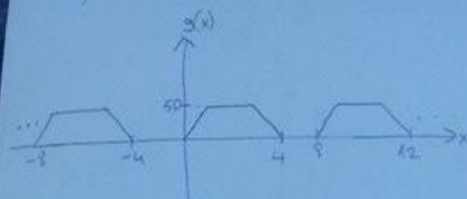


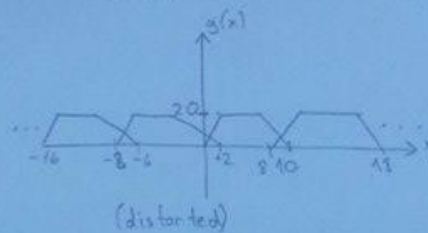
# EE430 HOMEWORK 4

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1)  $A=50$



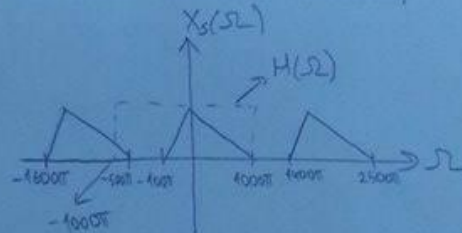
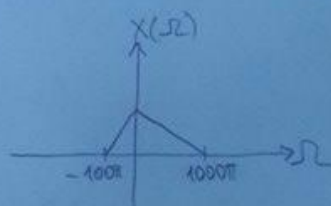
$A=20$



In above figures we can see that the rightmost edge of the signal closest to origin is at  $x = \frac{200}{A}$  and the leftmost edge of the signal shifted to its right is at  $x=8$ . For no overlap  $8 > \frac{200}{A}$ . More generally;

$$|A| > 25$$

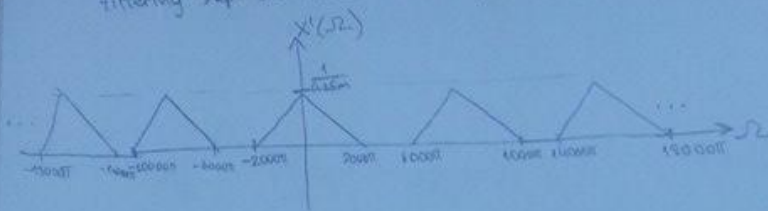
- 2) Minimum sampling frequency is two times the highest frequency component in the spectrum. In this case it must be  $2000\pi$  rad/s or 1 kHz. Since the spectrum is not symmetric there can be a misunderstanding that it is  $1000\pi$  rad/s (550 Hz). Think the below situation;



We have an  $X(\omega)$  signal that obeys the situation of the question and it is sampled with 750 Hz which is between 550 Hz and 1 kHz values. There is no aliasing after the sampling. But in order to recover the signal we must pass it through a lowpass filter at the last step. If we assume the filter  $H(\omega)$  has a real impulse response, its spectrum must be symmetric. By that way it also passes a small portion of shifted signal which causes distortion. Hence minimum sampling frequency must be 1 kHz not 550 Hz.

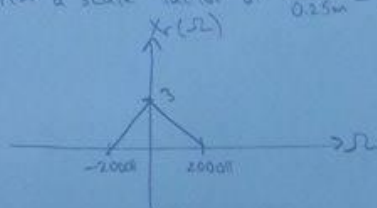
1

3)  $0.25 \text{ ms}$  corresponds to  $4 \text{ kHz}$  or  $8000\pi \text{ rad/s}$ . Thus before the lowpass filtering step, we have below signal.



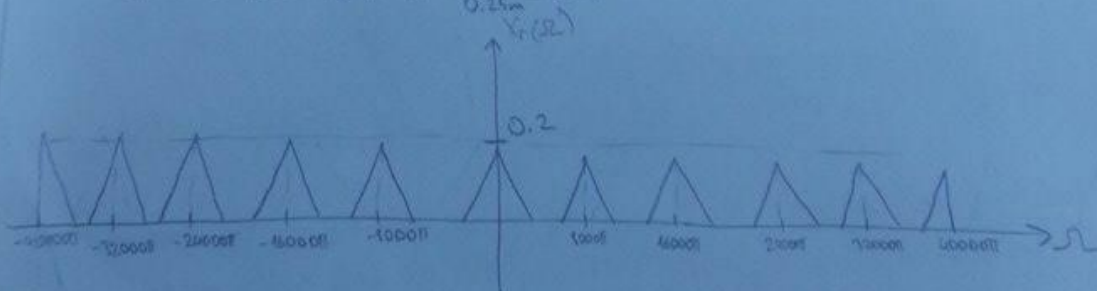
a)  $0.75 \text{ ms} \Rightarrow 1.33 \text{ kHz}$  or  $2660\pi \text{ rad/s}$

The  $2660\pi \text{ rad/s}$  only passes baseband signal so we obtain the original signal with a scale factor of  $\frac{T}{0.25\text{ms}} = 3$ .

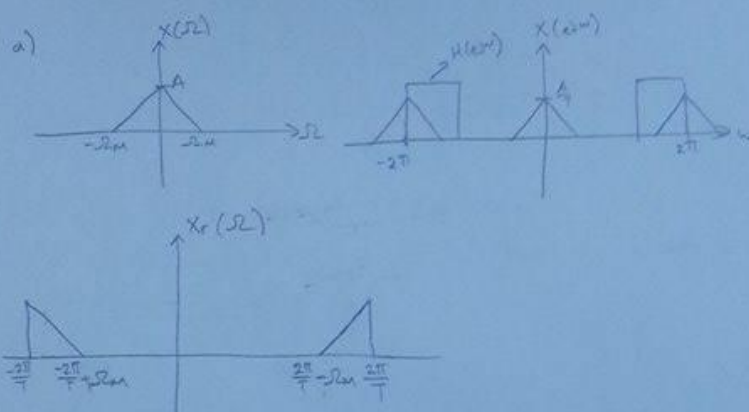
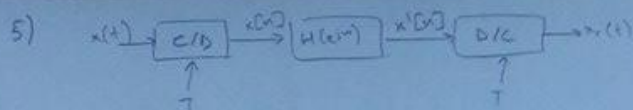


b)  $0.05 \text{ ms} \Rightarrow 20 \text{ kHz}$  or  $40000\pi \text{ rad/s}$ .

This filter passes baseband signal and high frequency terms until  $40000\pi \text{ rad/s}$  with a scale factor of  $\frac{T}{0.25\text{ms}} = 0.2$ .



We cannot recover the original signal in this case.



Equating  $\frac{2\pi}{T} = 10000\pi \Rightarrow T = 0.2 \text{ ms}$

Also  $\frac{2\pi}{T} - 2\pi = 9000\pi \Rightarrow \Omega_m = 1000\pi \text{ rad/s}$

Hence sampling period is  $T = 0.2 \text{ ms}$ . Our constraint is input signal must be bandlimited to  $1000\pi \text{ rad/s}$  or  $500 \text{ Hz}$ .

b)  $\frac{2\pi}{T} = 1000\pi \Rightarrow T = 2 \text{ ms}$        $\frac{2\pi}{T} - 2\pi = 900\pi \Rightarrow \Omega_m = 100\pi \text{ rad/s}$

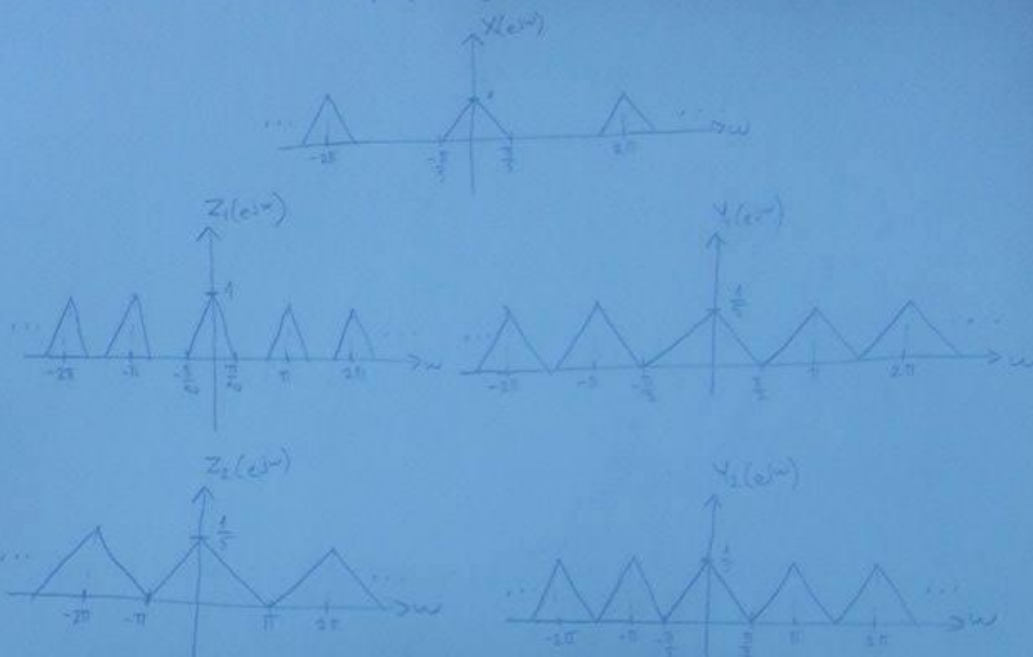
7) a)  $Z_1(e^{j\omega}) = X(e^{j\omega/2})$        $Y_1(e^{j\omega}) = \frac{1}{5} \sum_{k=0}^4 Z_1(e^{j(\frac{\omega}{5} - k\frac{2\pi}{5})}) = \frac{1}{5} \sum_{k=0}^4 X(e^{j(\frac{\omega}{5} - k\frac{2\pi}{5})})$

b)  $Z_2(e^{j\omega}) = \frac{1}{5} \sum_{k=0}^4 X(e^{j(\frac{\omega}{5} - k\frac{2\pi}{5})})$        $Y_2(e^{j\omega}) = Z_2(e^{j\omega/2}) = \frac{1}{5} \sum_{k=0}^4 X(e^{j(\frac{\omega}{5} - k\frac{2\pi}{5})})$

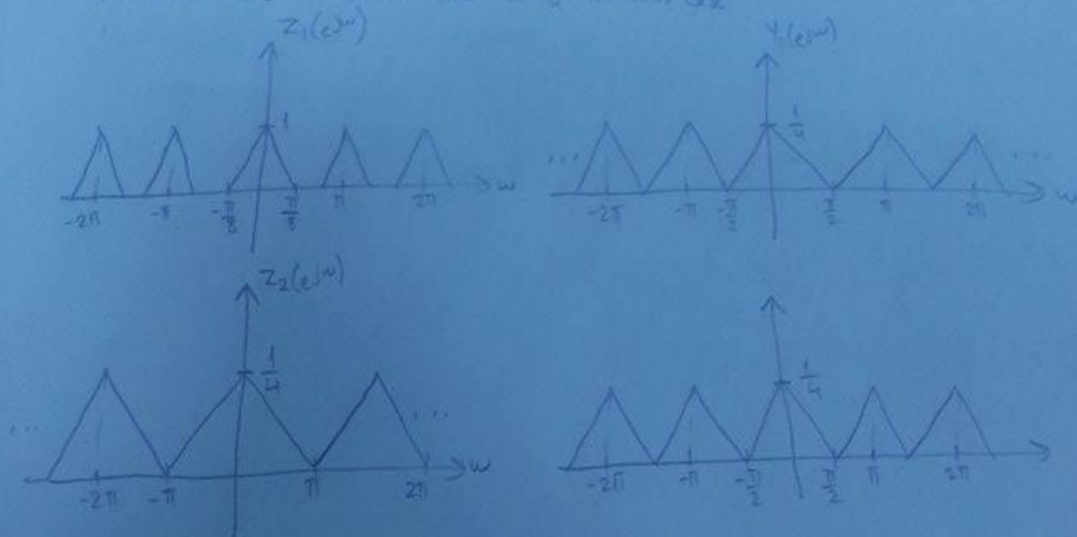
c) As can be seen in parts a and b  $Y_1(e^{j\omega})$  and  $Y_2(e^{j\omega})$  are same.  
Hence  $y_1[n]$  and  $y_2[n]$  are the same.

(3)

c) Assume we have a proper signal which means it is bandlimited to  $\frac{\pi}{5}$ .



d) Assume  $x[n]$  is bandlimited to  $\frac{\pi}{4}$  in this case



The answer does not change since there is no filtering order does not matter in this case.

(1)