## **EE 430 Section 2 HW1 Solutions**

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- 1.  $x[n] = x_c(nT) = 4\sin\left(20000\pi nT + \frac{\pi}{13}\right), \ T = \frac{1}{fs} = \frac{1}{3000} s$  $x[n] = 4\sin\left(\frac{20000\pi n}{3000} + \frac{\pi}{13}\right) = 4\sin\left(\frac{20\pi n}{3} + \frac{\pi}{13}\right) = 4\sin\left(\frac{2\pi n}{3} + \frac{\pi}{13}\right)$ 
  - a. The frequencies of the continuous-time signals that yield x[n] with the same sampling frequency will be obtained as follows;

Let the signals be defined as  $4\sin\left(f2\pi nT + \frac{\pi}{13}\right)$  then

$$f = 1000, 4000, 7000, ...$$

b. Similarly for the this frequency the following sampling frequencies yield the same signal

$$T = \frac{1}{30000}, \frac{4}{30000}, \frac{7}{30000}, \dots$$

2. Remember for periodicity x[n] = x[n+N] then

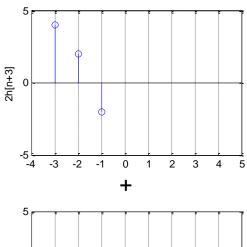
 $sin(1.74\pi n + 3.1)$ ,  $sin(1.74\pi (n + N) + 3.1\pi)$  and  $cos\left(15.74\pi (n + N) + \frac{3\pi}{8}\right)$  are periodic with fundamental period 100.

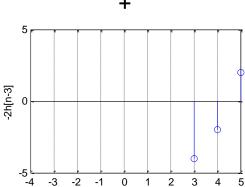
 $\cos(\sqrt{\pi}n)$ ,  $\cos(\pi\sqrt{\pi}n)$  and  $\cos(\pi\sqrt{2}n)$  are not periodic.

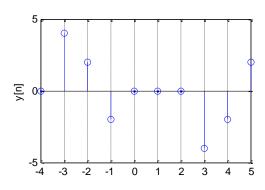
- 3. The highest frequency for a discrete time sinusoidal signal is  $\pi$ .
- 4. This is an interpolation operation. It is a linear operation. It is not time-invariant.
- 5. The first system is causal and stable.

The second system is both causal and stable system.

6. Note that x[n] can be written as  $x[n]=2\delta[n+3]-2\delta[n-3]$  so y[n]=h[n]\*x[n]=2h[n+3]-2h[n-3]



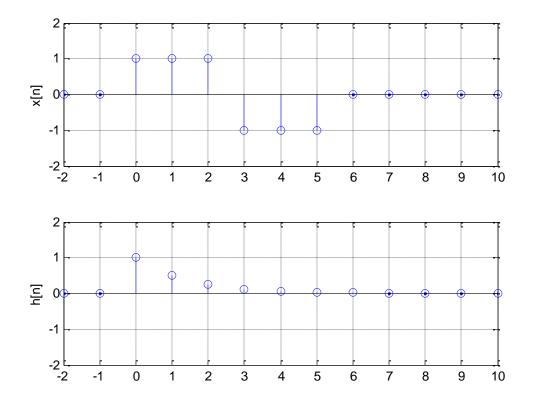


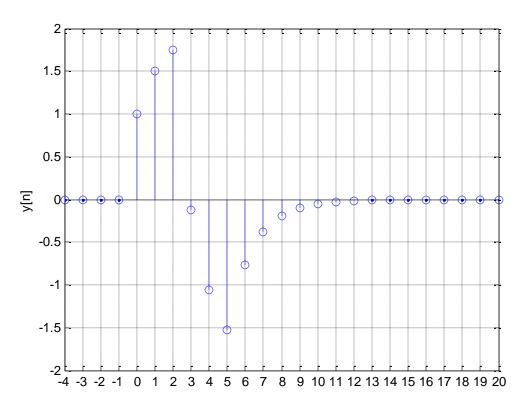


Or using the definition of convolution  $y[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$  the same result will be obtained

- 7. Hint: Let x'[n] = x[-n], h'[n] = h[-n] and find y'[n] = x'[n] \* h'[n]
- 8. Using MATLAB

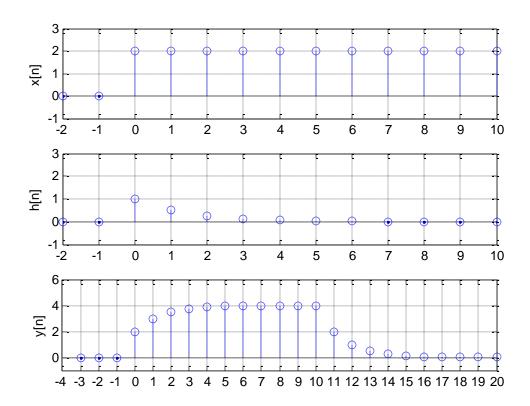
```
n = -2:10;
u = @(k)(n>=k);
x = u(0)-2*u(3)+u(6);
h = (1/2).^n.*u(0);
subplot(2,1,1); stem(n,x); set(gca,'XLim',[-2 10],'YLim', [-2 2],'XTick',n);
ylabel('x[n]');grid
subplot(2,1,2); stem(n,h); set(gca,'XLim',[-2 10],'YLim', [-2 2],'XTick',n);
ylabel('h[n]');grid
figure;
stem(-4:20,conv(x,h));set(gca,'XLim',[-4 20],'YLim', [-2 2],'XTick',-4:20);
ylabel('y[n]');grid
```





9. The code and graph is given below and the result of the convolution is as expected

```
n = -2:10;
u = (n>=0);
x = 2*u;
h = (1/2).^n.*u;
subplot(3,1,1); stem(n,x); set(gca,'XLim',[-2 10],'YLim', [-1 3],'XTick',n);
ylabel('x[n]');grid
subplot(3,1,2); stem(n,h); set(gca,'XLim',[-2 10],'YLim', [-1 3],'XTick',n);
ylabel('h[n]');grid
subplot(3,1,3);stem(-4:20,conv(x,h));set(gca,'XLim',[-4 20],'YLim', [-1 6],'XTick',-4:20); ylabel('y[n]');grid
```



10.

a. Multiplication of two polynomials means convolution of their coefficients. So multiplication of the following polynomials

$$a(x) = 2x^3 + 3x^2 + 1$$
  

$$b(x) = x^5 + 2x^4 + x^3 + 2x^2 + 3x + 5$$

Is obtained as follows

2 7 8 8 14 20 17 3 5

b.

c.  $y = [1 \ 1 \ 2 \ 3 \ 4 \ -1 \ 5];$ x = [1 2 3 4 5];[h r] = deconv(y,x)h =1 -1 1 r = 0 0 0 0 0 0 d. h= 1 0 -1 r =

0 0 0 1 2 3 10

In the first case there is no remainder so conv(h[n],x[n]) gives y[n] correctly but in the second case there is a remainder so to find y[n] correctly r should be added to convolution output that is conv(h[n],x[n])+r. This result is because deconv command of MATLAB use long division (polynomial division).