EE430 Digital Signal Processing HW 1

- 1. A DT x[n] is obtained by sampling the $x_c(t) = 4\sin(20000\pi t + \frac{\pi}{13})$ at sampling rate of $3 \ kHz$.
 - (a) The same DT signal can be constructed by sampling the set of signals in a form

$$x_c(t) = 4\sin((20000 + 3000k)\pi t + \frac{\pi}{13})$$
, $k = [-6, \infty)$

or equivalently,

$$x_c(t) = 4\sin((2000 + 3000k)\pi t + \frac{\pi}{13})$$
, $k = [0, \infty)$

(b) Let $\Omega_0 = 2000$ for our signal, the sampled signal can be expressed as;

$$x[n] = 4\sin(\Omega_0 nT_s + \pi/3)$$

it should be equal to the signal sampled at $\widetilde{T}_s \triangleq T_s + \Delta T$

$$x[n] = 4\sin(\Omega_0 n \widetilde{T}_s + \pi/3) = 4\sin(\Omega_0 n (T_s + \Delta T) + \pi/3)$$

To satisfy the equation $\Omega_0 n \Delta T$ should be equal to $k2\pi$ and knowing that

$$\Omega_0 = 2\pi f_0$$

$$\Delta t = \frac{k}{f_0} = kT_0$$

$$\widetilde{T}_s = T_s + \Delta T$$

using the equations above, the new set sampling frequencies that give the same x[n] can be found as follows;

$$f'_s = \frac{f_s f_0}{f_0 + k f_s} \quad , \quad k = 0, 1, 2...$$

for our case $f_0 = 1000$ and $f_s = 3000$, from there other sampling frequencies that yield x[n] from $x_c(t)$ can be calculated.

2. For any DT sinusoidal $cos(w_0n + \phi)$ or complex exponential $e^{w_0n+\phi}$ to be periodic with N, it has to satisfy the following,

$$w_0 n = k2\pi$$

or equivalently,

$$N = \frac{2\pi}{w_0} k \quad , \quad k, N \in \mathcal{Z}$$

For the given functions,



- $\sin(1.74\pi n + 3.1)$, periodic with $N_1 = \frac{2\pi}{1.74\pi}k = 100$ with k = 87
- $\sin(1.74\pi n + 31\pi)$, periodic with $N_2 = \frac{2\pi}{1.74\pi}k = 100$ with k = 87
- $\cos(15.74\pi n + \frac{3\pi}{8})$, periodic with $N_3 = \frac{2\pi}{15.74\pi}k = 100$ with k = 787
- $\cos(\sqrt{\pi}n)$, not periodic since there is no integer k that makes $N_4 = \frac{2\pi}{\sqrt{\pi}}k$ an integer
- $\cos(\pi\sqrt{\pi}n)$, not periodic since there is no integer k that makes $N_5 = \frac{2\pi}{\pi\sqrt{\pi}}k$ an integer
- $\cos(\pi\sqrt{2}n)$, not periodic since there is no integer k that makes $N_6 = \frac{2\pi}{\pi\sqrt{2}}k$ an integer
- 3. For any linear system, the output can be calculated as,

$$y[n] = x[n] * h[n] \triangleq \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

Response to a shifted response, can be calculated as follows,

$$h_k[n] = (u - k)u[n - k] = \delta[n - k] * h[n]$$

$$\delta[n - k] * h[n] \triangleq \sum_{a = -\infty}^{\infty} \delta[a - k]h[n - a] = h[n - a]$$

$$h[n - a]|_{a = k} \equiv h[n - k] = h_k[n] = (n - k)u[n - k]$$

From there, the impulse response h[n] can be found as,

$$h[n] = nu[n]$$

Thus, y[n] for any input can be found as follows,

$$y[n] = x[n] * h[n] \triangleq \sum_{k=-\infty}^{\infty} x[k](n-k)u[n-k]$$

$$y[n] = \sum_{k=-\infty}^{n} x[k](n-k)$$



To check time-invariance, let us find y[n-m] and the output $y_1[n]$ for an input $x_1[n] \triangleq x[n-m]$

$$y[n-m] = \sum_{k=-\infty}^{\infty} x[k]h[n-m-k]$$

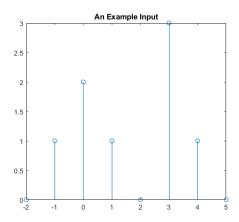
$$y_1[n] = x[n-m] * h[n] \triangleq \sum_{k=-\infty}^{\infty} x[k-m]h[n-k]$$

Letting $\widetilde{k} \triangleq k - m, k = m + \widetilde{k}$

$$y_1[n] = \sum_{\widetilde{k} = -\infty}^{\infty} x[\widetilde{k}]h[n - m - \widetilde{k}]$$

It can be easily seen that $y[n-m] = y_1[n]$. Thus, the system is **Time-Invariant**.

4. The system basically up-samples the system, by adding the average of two consecutive samples between these samples. An example Input/Output pair for the system can be seen at *Figure 1*.



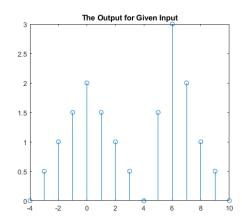


Figure 1: An Example Input/Output Pair

• For linearity, let us check the output y[n] for the input $x[n] = ax_1[n] + bx_2[n]$

$$y[n] = \begin{cases} \frac{x[n]}{2} & if \ n \ is \ even \\ \frac{x[\frac{n-1}{2}] + x[\frac{n+1}{2}]}{2} & if \ n \ is \ odd \end{cases}$$

$$y[n] = \begin{cases} a\frac{x_1[n]}{2} + b\frac{x_2[n]}{2} & n \text{ is even} \\ a\frac{x_1[\frac{n-1}{2}] + x_1[\frac{n+1}{2}]}{2} + b\frac{x_2[\frac{n-1}{2}] + x_2[\frac{n+1}{2}]}{2} & \text{if } n \text{ is odd} \end{cases}$$

Let us also find $y_1[n]$ and $y_2[n]$ for $x_1[n]$ and $x_2[n]$ respectively,

$$y_{1}[n] = \begin{cases} \frac{x_{1}[n]}{2} & n \text{ is even} \\ \frac{x_{1}[\frac{n-1}{2}] + x_{1}[\frac{n+1}{2}]}{2} & \text{if } n \text{ is odd} \end{cases}$$

$$y_{2}[n] = \begin{cases} \frac{x_{2}[n]}{2} & n \text{ is even} \\ \frac{x_{2}[\frac{n-1}{2}] + x_{2}[\frac{n+1}{2}]}{2} & \text{if } n \text{ is odd} \end{cases}$$

It can be clearly seen that $y[n] = ay_1[n] + y_2[n]$ for $x[n] = ax_1[n] + bx_2[n]$. Thus, the system is **Linear**.

• For time invariance, let us check y[n-m] and $y_1[n]$ for the $x_1[n] = x[n-m]$

$$y[n-m] = \begin{cases} \frac{x[n-m]}{2} & if \ (n-m) \ is \ even \\ \frac{x[\frac{n-m-1}{2}] + x[\frac{n-m+1}{2}]}{2} & if \ (n-m) \ is \ odd \end{cases}$$

$$y_1[n] = \begin{cases} \frac{x_1[n]}{2} & if \quad n \text{ is even} \\ \frac{x_1[\frac{n-1}{2}] + x_1[\frac{n+1}{2}]}{2} & if \quad n \text{ is odd} \end{cases}$$

$$y_{1}[n] = \begin{cases} \frac{x[n-m]}{2} & if \quad n \text{ is even} \\ \frac{x[\frac{n-m-1}{2}] + x[\frac{n-m+1}{2}]}{2} & if \quad n \text{ is odd} \end{cases}$$

Due to condition difference $y[n-m] \neq y[n]$. For different m, the result changes. Thus, the system is **not Time-Invariant**.

5. Let us check stability and causality for the following systems;

$$y[n] = 2^{\delta[n+1]} + x[n-3]$$

The system is **not casual** since the impulse response $h[n] \neq 0$ as n < 0;

$$h[n] = 2^{\delta[n+1]} + \delta[n-3]$$



For BIBO stability, let us assume $|x[n]| < \beta_x < \infty$ and check |y[n]|;

$$|y[n]| = |2^{\delta[n+1]} + x[n-3]| = |c+x[n]| = \beta_y < \infty$$

where c and β_y are finite constants, thus, the system is **Stable**.

$$y[n] = \begin{cases} y[-\delta[n-1]] + x[n-3] & if \quad n > 0 \\ 2^n x[n-3] & if \quad n \le 0 \end{cases}$$

The system is **Casual** since the impulse response h[n] = 0 as n < 0;

$$h[n] = \begin{cases} h[-\delta[n-1]] + \delta[n-3] & if \quad n > 0 \\ 2^n \delta[n-3] & if \quad n \le 0 \end{cases}$$

For BIBO stability, let us assume $|x[n]| < \beta_x < \infty$ and check |y[n]|;

$$|y[n]| = \begin{cases} |y[-\delta[n-1]] + x[n-3]| & if \quad n > 0\\ |2^n x[n-3]| & if \quad n \le 0 \end{cases}$$

Let us assume $|y[n]| < \beta_z < \infty$. Checking the two conditions, the assumption holds, thus, it can be seen that the system is **Stable**.

6.

$$y[n] = x[n] * x[n] = \sum_{k=-\infty}^{\infty} x[k]x[n-k]$$

If the first non-zero element of x[n] is x[-6] = -3 and the last non-zero element of x[n] is equal to x[24] = -4, the first and last non-zero elements of y[n] will be y[-12] from (-6 = 6 + n) and y[48] from (24 = -24 + n). These values can be calculated from the formula above as,

$$y[-12] = x[-6]x[-6] = 9$$

$$y[48] = x[24]x[24] = 16$$

7. Let us calculate y[n] as $n \to \infty$, given that x[n] = u[n] and $h[n] = 3(\frac{1}{2})^n u[n] + 2(\frac{1}{3})^{n-1} u[n]$

$$y[n] = x[n] * h[n] = \sum_{k=-\infty}^{\infty} x[k]h[n-k]$$

$$y[n] = \sum_{k=-\infty}^{\infty} u[k] \left(3\left(\frac{1}{2}\right)^{(n-k)} u[n-k] + 2\left(\frac{1}{3}\right)^{n-k-1} u[n-k]\right)$$



$$y[n] = \sum_{k=0}^{n} 3\left(\frac{1}{2}\right)^{(n-k)} + 6\left(\frac{1}{3}\right)^{(n-k)}$$

with simple change of variables, let $m \triangleq n - k$

$$= \sum_{m=n}^{0} 3(\frac{1}{2})^{m} + 6(\frac{1}{3})^{m}$$

or as $n \to \inf$

$$y[n] = \sum_{m=0}^{\infty} 3(\frac{1}{2})^m + 6(\frac{1}{3})^m$$

$$\left| \lim_{n \to \infty} y[n] = 3 \frac{1}{1 - 1/2} - 6 \frac{1}{1 - 1/3} = -3 \right|$$

8. Let us analyse the system $y[n] - \frac{1}{2}y[n-1] = x[n] - x[n-1] + x[n-2]$ Assume homogeneous system $y[n] - \frac{1}{2}y[n-1] = 0$ and solve it for finding homogeneous solution $y_h[n]$.

$$y[n]-rac{1}{2}y[n-1]=0$$
 , with $y_h[n]=Ar^n$
$$Ar^n-rac{A}{2}r^{n-1}=0$$

$$Ar^{n-1}(r-rac{1}{2})=0$$

$$\boxed{r=1/2}$$

Thus, the homogeneous solution will be in the form of $A(\frac{1}{2})^n$, Let us now find the impulse response of the system $y_1[n] - \frac{1}{2}y_1[n-1] = x[n]$, the homogeneous solution will also satisfy this system and the impulse response will be also in form of $y_h[n]$

$$h_1[n] - \frac{1}{2}h_1[n-1] = \delta[n]$$

We also know that $h_1[n]$ will be in the for $Ar^nu[n]$ since the system is casual. To find A, let us calculate $h_1[n]$ at n=0.

$$h_1[0] = \frac{1}{2}h[-1] + \delta[0] = 1 = A(\frac{1}{2})^0 = A$$

Thus, we have found the impulse response of the system $y_1[n] - \frac{1}{2}y_1[n-1] = x[n]$ as

$$h_1[n] = \left(\frac{1}{2}\right)^n u[n]$$



(a) Due to lineartity of the system, the impulse response of the system $y[n] - \frac{1}{2}y[n-1] = x[n] - x[n-1] + x[n-2]$ will be superposition of the impulse response $h_1[n]$;

$$h[n] = h_1[n] - h_1[n-1] + h_1[n-2]$$

$$h[n] = \frac{1}{2}^n u[n] - \frac{1}{2}^{n-1} u[n-1] + \frac{1}{2}^{n-2} u[n-2]$$

$$h[n] = \frac{1}{2}^n (u[n] - 2u[n-1] + 4u[n-2])$$

$$h[n] = \frac{1}{2} (\delta[n] - \delta[n-1] + 3u[n-2])$$

(b) Frequency response $H(e^{jw})$ can be found as;

$$\begin{split} H(e^{jw}) &= \sum_{n=\infty}^{\infty} h[n] e^{-jwn} \\ H(e^{jw}) &= \sum_{n=\infty}^{\infty} \left(\frac{1}{2}\right)^n e^{-jwn} \delta[n] - \sum_{n=\infty}^{\infty} \left(\frac{1}{2}\right)^n e^{-jwn} \delta[n-1] + 3 \sum_{n=\infty}^{\infty} \left(\frac{1}{2}\right)^n e^{-jwn} u[n-2] \\ H(e^{jw}) &= 1 - \frac{1}{2} e^{jw} + 3 \sum_{n=2}^{\infty} \left(\frac{e^{-jw}}{2}\right)^n \\ H(e^{jw}) &= -2 - 2 e^{-jw} + \frac{6}{2 - e^{-jw}} \ if \ |\frac{e^{-jw}}{2}| < 1 \\ H(e^{jw}) &= -2 - 2 e^{-jw} + \frac{6}{2 - e^{-jw}} \ if \ \pi < w < \pi \end{split}$$

(c) To use freqz command, we have to compete the Z-transform of the system,

$$Y(z) - \frac{1}{2}Y(z)z^{-1} = X(z) - X(z)z^{-1} + X(z)z^{-2}$$
$$H(z) \triangleq \frac{Y(z)}{X(z)} = \frac{1 - z^{-1} + z^{-2}}{1 - \frac{1}{2}z^{-1}}$$

The result can be seen at Figure 2.



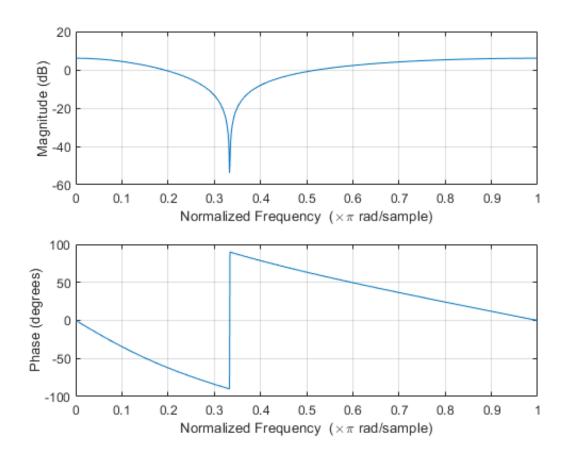


Figure 2: Magnitude and Phase of Frequency Response

$$\begin{array}{c|c} a = [1 & -1 & 1]; \\ b = [1 & -1/2]; \\ freqz(a,b,1024) \end{array}$$

(d) Since we have $H(e^{jw})$, we can find y[n] from

$$Y(e^{jw}) = X(e^{jw})H(e^{jw})$$

instead of convolution, for that we need to find $X(e^{jw})$ first. Given that $x[n]=\cos(\frac{\pi}{3}n)+\sin(\frac{\pi}{2}n+\frac{\pi}{4})$

$$x[n] = \cos(\frac{\pi}{3}n) + \sin(\frac{\pi}{2}n)\cos(\frac{\pi}{4}) + \cos(\frac{\pi}{2}n)\sin(\frac{\pi}{4}))$$
$$x[n] = \cos(\frac{\pi}{3}n) + \sin(\frac{\pi}{2}n)\frac{1}{\sqrt{2}} + \cos(\frac{\pi}{2}n)\frac{1}{\sqrt{2}})$$



$$\begin{split} X(e^{jw}) &= \pi \left[\delta[w - \frac{\pi}{3}] + \delta[w + \frac{\pi}{3}] \right] - \frac{j\pi}{\sqrt{2}} \left[\delta[w - \frac{\pi}{2}] - \delta[w + \frac{\pi}{2}] \right] \\ &+ \frac{\pi}{\sqrt{2}} \left[\delta[w - \frac{\pi}{2}] + \delta[w + \frac{\pi}{2}] \right] \\ X(e^{jw}) &= \pi \left[\delta[w - \frac{\pi}{3}] + \delta[w + \frac{\pi}{3}] \right] + \frac{\pi}{\sqrt{2}} (1 - j) \left[\delta[w - \frac{\pi}{2}] \right] \\ &+ \frac{\pi}{\sqrt{2}} (1 + j) \left[\delta[w + \frac{\pi}{2}] \right] \\ Y(e^{jw}) &= X(e^{jw}) H(e^{jw}) \\ Y(e^{jw}) &= \pi \left[-2 - 2e^{-j\pi/3} + \frac{6}{2 - e^{-j\pi/3}} \right] \delta[w - \frac{\pi}{3}] \\ &+ \pi \left[-2 - 2e^{-j\pi/3} + \frac{6}{2 - e^{-j\pi/3}} \right] \delta[w + \frac{\pi}{3}] \\ &+ \frac{\pi}{\sqrt{2}} (1 - j) \left[-2 - 2e^{-j\pi/2} + \frac{6}{2 - e^{-j\pi/2}} \right] \delta[w - \frac{\pi}{2}] \\ &+ \frac{\pi}{\sqrt{2}} (1 + j) \left[-2 - 2e^{j\pi/2} + \frac{6}{2 - e^{j\pi/2}} \right] \delta[w + \frac{\pi}{2}] \end{split}$$

by some computation, the term above becomes

$$Y(e^{jw}) = \frac{\pi}{\sqrt{2}} \left[\frac{6}{5} + j\frac{2}{5} \right] \delta[w - \frac{\pi}{2}] + \frac{\pi}{\sqrt{2}} \left[\frac{6}{5} - j\frac{2}{5} \right] \delta[w + \frac{\pi}{2}]$$

the y[n] can be found to be as

$$y[n] = \frac{\pi}{\sqrt{2}} \left[\frac{6}{5} + j\frac{2}{5} \right] \frac{1}{2\pi} e^{j\frac{\pi}{2}n} + \frac{\pi}{\sqrt{2}} \left[\frac{6}{5} - j\frac{2}{5} \right] \frac{1}{2\pi} e^{-j\frac{\pi}{2}n}$$

by also some computation, the term above becomes

$$y[n] = \frac{1}{\sqrt{2}} \left[\frac{3}{5} + j\frac{1}{5} \right] e^{j\frac{\pi}{2}n} + \frac{1}{\sqrt{2}} \left[\frac{3}{5} - j\frac{1}{5} \right] e^{-j\frac{\pi}{2}n}$$

(e) Let us analyse $H(e^{jw})$ found,

$$H(e^{jw}) = -2 - 2e^{-jw} + \frac{6}{2 - e^{-jw}}$$



$$H^*(e^{j(2\pi-w)}) = \left(-2 - 2e^{-j(2\pi-w)} + \frac{6}{2 - e^{-j(2\pi-w)}}\right)^*$$

$$H^*(e^{j(2\pi-w)}) = \left(-2 - 2e^{-j2\pi}e^{jw}\right) + \frac{6}{2 - e^{-j2\pi}e^{jw}}\right)^*$$

$$H^*(e^{j(2\pi-w)}) = \left(-2 - 2e^{jw}\right) + \frac{6}{2 - 2e^{jw}}\right)^*$$

$$H^*(e^{j(2\pi-w)}) = -2 - 2e^{-jw} + \frac{6}{2 - 2e^{-jw}}$$

which obliviously equal to the $H(e^{jw})$ as asked in the question.

- 9. (a) Since x[n] is a real sequence, magnitude of its frequency response must be even symmetric and phase plot of its frequency response must be odd symmetric.
 - (b) With given x[n], $x_c[n]$ and $x_s[n]$, the DTFTs can be found by convolution in the frequency domain,

$$x_{c}[n] = \cos(\frac{\pi}{5}n)x[n]$$

$$X_{c}(e^{jw}) = X(e^{jw}) * \mathcal{F}\{\cos(\frac{\pi}{5}n)\}$$

$$\mathcal{F}\{\cos(\frac{\pi}{5}n)\} = \pi \left[\delta[w - \frac{\pi}{5}] + \delta[w + \frac{\pi}{5}]\right]$$

$$X_{c}(e^{jw}) = \pi \left[X(e^{j(w+\pi/5)}) + X(e^{j(w-\pi/5)})\right]$$

$$x_{s}[n] = \sin(\frac{\pi}{5}n)x[n]$$

$$X_{s}(e^{jw}) = X(e^{jw}) * \mathcal{F}\{\sin(\frac{\pi}{5}n)\}$$

$$\mathcal{F}\{\sin(\frac{\pi}{5}n)\} = -j\pi \left[\delta[w - \frac{\pi}{5}] - \delta[w + \frac{\pi}{5}]\right]$$

$$X_{s}(e^{jw}) = -j\pi \left[X(e^{j(w+\pi/5)}) - X(e^{j(w-\pi/5)})\right]$$

(c)

10. It is known that, the DTFT of x[n] can be calculated as follows;

$$X(e^{jw}) = \sum_{-\infty}^{\infty} x[n]e^{-jwn}$$

$$X(e^{jw})|_{w=0} = \sum_{-\infty}^{\infty} x[n] = 6$$



(b)

$$X(e^{jw})|_{w=\pi} = \sum_{-\infty}^{\infty} x[n]e^{-j\pi n}$$

$$X(e^{jw})|_{w=\pi} = \sum_{-\infty}^{\infty} x[n](-1)^n = 2$$

(c) Since x[n] is symmetric about n=2, the signal has linear phase

$$X(e^{jw}) = A(w)e^{-j2w}$$

A(w) is a zero phase (real) function of w. Thus,

$$\underline{/X(e^{jw})} = -2w \ , \ -\pi \le w \le \pi$$

(d) Knowing that $\int_{\infty}^{\infty} X(e^{jw}e^{-jwn})dw = 2\pi x[n]$, for n=0, equations becomes what we desired

$$\int_{-\infty}^{\infty} X(e^{jw})dw = 2\pi x[0] = 4$$

(e) Assume $x_1[n]$ whose DTFT is $X(e^{-jw})$.

$$X(e^{jw}) = \sum_{-\infty}^{\infty} x[n]e^{jwn} = \sum_{-\infty}^{\infty} x[-n]e^{-jwn} = \sum_{-\infty}^{\infty} x_1[n]e^{-jwn}$$

Thus, it can be seen that,

$$x_1[n] = x[-n]$$

x[-n] can be seen from Figure 3.

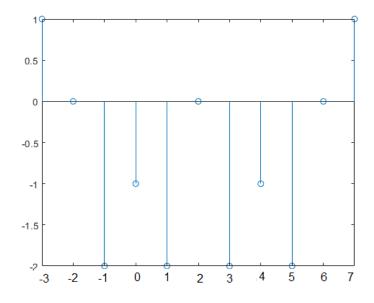


Figure 3: x[-n]



(f) Remembering $X(e^{jw}) = A(w)e^{-j2w}$, real part of $X(e^{jw})$ can be written as

$$X_R(e^{jw}) = A(w)\cos(2w)$$

$$X_R(e^{jw}) = \frac{1}{2}A(w)\left(e^{j2w} + e^{-j2w}\right)$$

$$x_R[n] = \mathcal{F}^{-1}\{X_R(e^{jw})\}$$

$$x_R[n] = \frac{1}{2}a[n+2] + \frac{1}{2}a[n-2]$$

$$x_R[n] = \frac{1}{2}x[n+4] + \frac{1}{2}x[n]$$

 $x_R[n]$ can be seen from Figure 4.

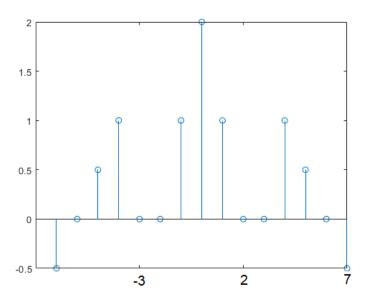


Figure 4: $x_R[n]$

- 11. (a) From the given informations
 - h[n] = 0 for n < 0, causality,
 - h[n] is real, FT is conjugate symmetric,
 - h[n+1 is even, real FT]

From above, , it can be understood that, h[n] is 3-length long, thus, it is finite-duration.

(b) Notice that, h[n] has three elements and symmetric, so, let us assume h[0] = h[2] = a and h[1] = b.

From extra informations



- $2a^2 + b^2 = 2$, Parseval's Theorem
- $\bullet \ 2a b = 0$

Solving the equations found above, $a = \frac{\pm 1}{\sqrt{3}}$ and $b = \frac{\pm 2}{\sqrt{3}}$.

$$h[0] = h[2] = \frac{\pm 1}{\sqrt{3}}$$
, $h[1] = \frac{\pm 2}{\sqrt{3}}$

12. It can be observed from the question that $X(e^{jw})$ is real and

$$Y(e^{jw}) = \begin{cases} -jX(e^{jw}) &, & 0 < w < \pi \\ +jX(e^{jw}) &, & -\pi < w < 0 \end{cases}$$

It is also given that w[n] = x[n] + jy[n], thus,

$$W(e^{jw}) = +jY(e^{jw})$$

$$W(e^{jw}) = \begin{cases} 2X(e^{jw}) &, 0 < w < \pi \\ 0 &, -\pi < w < 0 \end{cases}$$

 $W(e^{jw})$ can be seen from Figure 3.

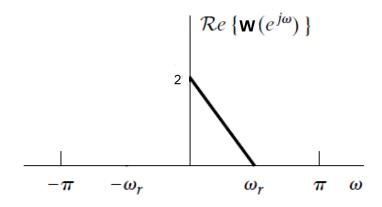


Figure 5: $W(e^{jw})$



13. [MATLAB]

```
(a)
   function y
                 = myconv (x,h)
 1
        i = 1;
 2
        for i = 1:10
 3
             y(i) = 0;
 4
             for k=1:numel(x)
                  if (i+1-k) <= 0
                      y(i)=y(i)+(x(k)*0);
                  else
                       if (i+1-k)>numel(h)
 9
                           y(i)=y(i)+(x(k)*0);
10
                       else
11
                           y(i)=y(i)+(x(k)*h(i+1-k));
12
                           k=k+1;
13
                       end
14
                  end
15
             end
16
             i=i+1;
17
        end
18
   end
19
```

(b) The result of 'conv' function can be seen at Figure 6.

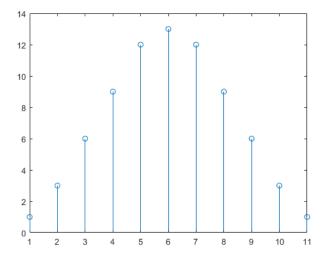


Figure 6: The result of 'conv' function



(c) Magnitude and phase response of the filter h[n] can be seen at Figure 7.

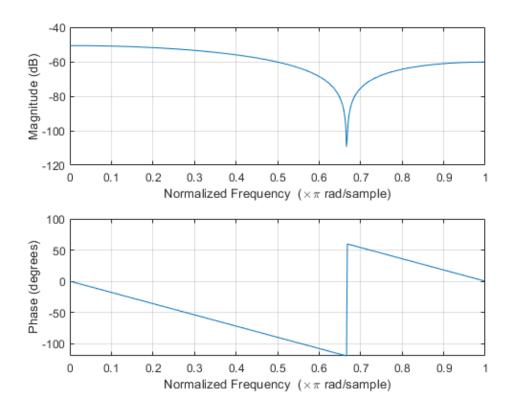


Figure 7: Magnitude and phase response of the filter h[n]

```
freqz(h,1024)
```



(d) The result for the $h_2[n] * x[n]$ can be seen at Figure 8.

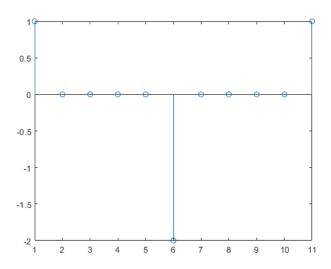


Figure 8: $h_2[n] * x[n]$

```
\begin{array}{c|cccc}
h2 = [1 & -2 & 1] \\
y3 = & conv(x, h2) \\
stem(y3)
\end{array}
```



(e) Magnitude and phase response of the filter $h_2[n]$ can be seen at Figure 9.

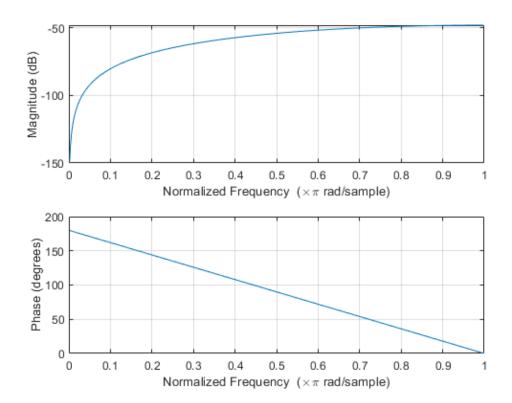


Figure 9: Magnitude and phase response of the filter $h_2[n]$

freqz(h2,1024)



(f) Magnitude and phase response of z[n] can be seen at Figure 11.

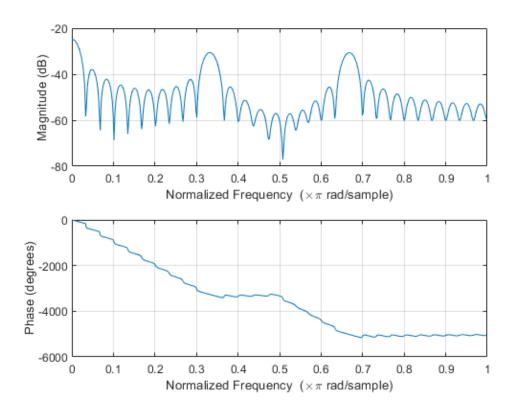


Figure 10: Magnitude and phase response of the $\boldsymbol{z}[n]$

```
i = 1;
1
  z(1)=0;
2
   while i < 60
3
        if i < 1
4
             z(i) = 0;
        else
6
             z(i)=1+\sin(pi/3*i)+\sin(2*pi/3*i)
       end
8
        i=i+1;
9
  end
10
11
  freqz(z,1024)
12
```



(g) Magnitude and phase response of y[n] = z[n] * h[n] can be seen at Figure 11.

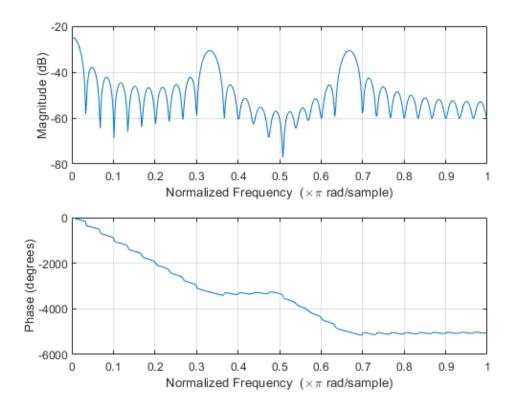


Figure 11: Magnitude and phase response of the y[n]

