CHEM E 330 Transport Processes I

-★- TRANSPORT PHENOMENA

Rate Laws for Diffusive Transport

| Description | Equations |
|--|--------------------------------------|
| General form | flux = -(coefficient)(driving force) |
| Fourier's law Heat conduction | $q=-krac{dT}{dy}$ |
| Fick's law Species diffusion | $J_A^* = -D_{AB}rac{dc_a}{dy}$ |
| Newton's law of viscosity Momentum transfer | $	au_{yx} = -\mu rac{dv_x}{dy}$ |

| Rate laws as concentration gradients

| Description | Equations |
|---------------------------|--|
| Fourier's law | $q_y = -lpha rac{dc_H}{dy}$ |
| Fick's law | $J_A^* = -D_{AB} rac{dc_a}{dy}$ |
| Newton's law of viscosity | $	au_{yx} = - u rac{dc_{p_x}}{dy}$ |
| Kinematic viscosity | $ u = \frac{\mu}{\rho} $ |
| Thermal diffusivity | $lpha = rac{k}{ ho \hat{c_P}}$ |
| Diffusivity of A in B | D_{AB} |
| Prandtl number | $	ext{Pr} = rac{ u}{lpha} = rac{\hat{C}_p \mu}{k}$ |
| Schmidt number | $\mathrm{Sc} = rac{ u}{D_{AB}} = rac{\mu}{ ho D_{AB}}$ |

| Heat transfer

| Description | Equations |
|-------------|----------------------|
| Heat flow | $\dot{Q}=rac{Q}{t}$ |
| Heat flux | $q=rac{\dot{Q}}{A}$ |

| Mass transfer

| Description E | -4 |
|----------------------------|-------------------------------|
| Mass (species) transport I | $N_A = x_A(\sum N_i) + J_A^*$ |

| Description | Equations |
|--|---|
| Diffusion of A through a stagnant layer of B | $N_A = -rac{cD_{AB}}{1-x_A}rac{dx_A}{dy} \ N_A = -rac{cD_{AB}}{L}\ln(1-x_A^s)$ |
| Equimolar counter diffusion | $N_A = -c D_{AB} rac{dx_A}{dy}$ |
| Reaction at catalytic surface ${ m A}=2{ m B} \implies N_B=2N_A$ | $N_A = -x_A N_A - c D_{AB} rac{dx_A}{dy}$ |

| Momentum transfer

| Description | Equations |
|--|--|
| Interpretation of $	au_{yx}$ | 1. viscous shear stress exerted on a y -plane in the $+x$ -direction by the fluid of lesser y on that of greater y 2. flux of x -momentum across a y -plane in the $+y$ -direction |
| Shear strain rate | $\dot{\gamma}=rac{dv_x}{dy}$ |
| Hooke's law ★ Hookean solid | $	au_{yx} = -Grac{dx}{dy} = -G\gamma$ |
| Newton's law of viscosity ★ Newtonian fluid | $	au_{yx} = -\mu rac{dv_x}{dy} = -\mu \dot{\gamma}$ |
| General Newton's law of viscosity | $	au_{yx} = -\eta(\dot{\gamma})\dot{\gamma}$ |
| Viscosity function of power law fluid | $\eta=m\dot{\gamma}^{n-1}$ |
| Newton's law of viscosity ★ Power law fluid | $	au_{yx} = -m\dot{\gamma}^n$ |
| Carreau equation ★ Slurry | $rac{\eta-\eta_{\infty}}{\eta_o-\eta_{\infty}}=[1+(\lambda\dot{\gamma})^2]^{(n-1)/2}$ |

Transport Coefficients of Fluids

| Ideal gas: Simple kinetic theory

| Description | Equations |
|--|--|
| Average velocity | $ar{u} = \sqrt{rac{8k_BT}{\pi m}}$ |
| Mean free path | $\lambda = rac{1}{\sqrt{2}\pi d^2 n}$ |
| Number density | $n=rac{N}{V}$ |
| Molecular flux in the y-direction | $z=rac{1}{4}nar{u}$ |
| Average distance of molecules from ref plane when they initiate their jump | $ar{a}=rac{2}{3}\lambda$ |
| Viscosity of ideal gas | $\mu=rac{1}{3} hoar{u}\lambda=rac{2}{3\pi^{3/2}}rac{\sqrt{mk_BT}}{d^2}$ |
| Thermal conductivity of ideal gas | $k=rac{1}{3} ho\hat{c_v}ar{u}\lambda=rac{2\hat{c_v}}{3\pi^{3/2}}rac{\sqrt{mk_BT}}{d^2}$ |

| Description | Equations |
|--|--|
| Diffusivity of ideal gas A in B | $D_{AB} = rac{1}{3}ar{u}_{AB}\lambda_{AB} = rac{2}{\pi^{3/2}}rac{\sqrt{k_B T^3/m_{AB}}}{d_{AB}^2P}$ |
| Mean mass for diffusivity | $m_{AB}=rac{2m_Am_B}{m_A+m_B}$ |
| Mean distance for diffusivity | $d_{AB}=rac{1}{2}(d_A+d_B)$ |
| Prandtl number of monoatomic ideal gas | $\mathrm{Pr}_{\mathrm{mono}} = 1$ |
| Schmidt number of general ideal gas | Sc = 1 |

| Real gas: Chapman-Enskog equations

\star Moderate pressure

| Description | Equations |
|--|--|
| Lenard-Jones potential | $arphi(r) = 4arepsilon \left[\left(rac{\sigma}{r} ight)^{12} - \left(rac{\sigma}{r} ight)^{6} ight]$ |
| Attractive force | $F_{ m attr} = rac{24arepsilon}{r} \left[\left(rac{\sigma}{r} ight)^6 - 2\left(rac{\sigma}{r} ight)^{12} ight]$ |
| Viscosity of real gas (analytic) | $\mu = rac{5}{16\pi} rac{\sqrt{\pi m k_B T}}{\sigma^2 \Omega_\mu}$ |
| Thermal conductivity of real gas (analytic) | $k=rac{25}{32\pi}rac{\sqrt{\pi mk_BT}}{\sigma^2\Omega_k}\hat{c_v}=rac{5}{2}\hat{c_v}\mu$ |
| Viscosity of real gas | $\mu\left(rac{	ext{g}}{	ext{cm}\cdot	ext{s}} ight)=2.6692	imes10^{-5}rac{\sqrt{\mathcal{M}T}}{\sigma^2\Omega_{\mu}}$ |
| Thermal conductivity of monoatomic real gas | $k_{ m mono}\left(rac{ m cal}{ m cm\cdot s\cdot K} ight)=1.989	imes 10^{-4}rac{\sqrt{T/\mathcal{M}}}{\sigma^2\Omega_k}$ |
| Thermal conductivity of polyatomic real gas Euken factor | $k_{ m poly}\left(rac{ m cal}{ m cm\cdot s\cdot K} ight) = \left[\hat{c_p} + rac{5}{4}rac{R}{\mathcal{M}} ight]\mu$ |
| Diffusivity of real gas | |
| $T[=]	ext{K} \ P[=]	ext{atm} \ \sigma_{AB}[=] 	ext{ Å}$ | $D_{AB}\left(rac{\mathrm{cm}^2}{\mathrm{s}} ight) = 2.63	imes 10^{-3} rac{\sqrt{T^3/\mathcal{M}_{AB}}}{P\sigma_{AB}^2\Omega_D}$ |
| Mean molar mass for diffusivity | $\mathcal{M}_{AB} = rac{2\mathcal{M}_A\mathcal{M}_B}{\mathcal{M}_A + \mathcal{M}_B}$ |
| Mean distance for diffusivity | $\omega_{AB}=rac{1}{2}(\omega_A+\omega_B)$ |
| Viscosity at different temperatures | $\mu(T_2)=\mu(T_1)\sqrt{rac{T_2}{T_1}}rac{\Omega_{\mu_1}}{\Omega_{\mu_2}}$ |
| Diffusivity at different temperatures | $D_{AB}(T_2) = D_{AB}(T_1) \left(rac{T_2}{T_1} ight)^{3/2} rac{\Omega_{D_1}}{\Omega_{D_2}}$ |
| ${\cal T}$ and ${\cal P}$ dependence of transport coefficients of gases at moderate pressure | $egin{aligned} \mu \propto \sqrt{T} \ k_{	ext{mono}} & \propto \sqrt{T} \ k_{	ext{poly}} & = f(T, \hat{c_p}(T)) \ D_{AB} & \propto T^{3/2} P^{-1} \ D_{AB} & = D_{BA} \end{aligned}$ |

| Wilke equation Viscosity of gas mixture | $\mu_{	ext{mix}} = \sum_{i=1}^N rac{x_i \mu_i}{\sum_{j=1}^N x_j \Phi_{ij}}$ |
|--|--|
| Wilke equation Thermal conductivity of gas mixture | $k_{	ext{mix}} = \sum_{i=1}^N rac{x_i k_i}{\sum_{j=1}^N x_j \Phi_{ij}}$ |
| Wilke equation parameter | $\Phi_{ij} = rac{1}{\sqrt{8}} \left[1 + rac{\mathcal{M}_i}{\mathcal{M}_j} ight]^{-1/2} \left[1 + \left[rac{\mu i}{\mu j} ight]^{1/2} + \left[rac{\mathcal{M}_i}{\mathcal{M}_j} ight]^{-1/4} ight]^2$ |
| Blanc's equation Diffusivity of gas mixture | $D_{i,	ext{mix}} = \left[\sum_{j eq 1}^N rac{x_j}{D_{ij}} ight]^{-1}$ |

| Liquids

| Description | Equations |
|---|---|
| Eyring model Viscosity of liquid | $\mu = rac{N_A h}{	ilde{V}} \exp \left[0.408 rac{\Delta U_{ m vap}}{RT} ight]$ |
| Bridgeman equation Thermal conductivity of liquid | $k=2.8\left(rac{N_A}{	ilde{V}}^{2/3}k_Bv_s ight)$ |
| Einstein equation | $D_{AB}pproxrac{k_BT}{f}$ |
| Hydrodynamic friction factor | $f = egin{cases} 6\pi \mu_B R_A & 	ext{no slip} \ 4\pi \mu_B R_A & 	ext{free slip} \end{cases}$ |
| Stoke-Einstein Equation Diffusivity of dilute liquid A | $D_{AB}=rac{k_BT}{4\pi\mu_BR_A}$ |
| Wilke-Chang correlation Diffusivity of dilute liquid A $	ilde{V}[=]	ext{cm}^3/	ext{mol} \ \mu_B[=]	ext{cP} \ T[=]	ext{K}$ | $D_{AB}\left(rac{\mathrm{cm}^2}{\mathrm{s}} ight) = 7.4	imes 10^{-8} rac{(\psi_B \mathcal{M}_B)^{1/2} T}{\mu 	ilde{V}_A^{0.6}}$ |
| Vigne's equation Diffusivity of liquid mixture | $D_{AB} = (D^0_{AB})^{x_B} (D^0_{BA})^{x_A}$ |
| ${\cal T}$ dependence of transport coefficients of liquids (no ${\cal P}$ dependence) | $\mu = A e^{B/T} \ D_{AB} \mu_B \propto T \ D_{AB} eq D_{BA}$ |

Shell Balance (Bottom-Up)

| Boundary conditions and shell volume

| Description | Equations |
|--------------------------|--------------------------------------|
| Rectilinear shell volume | $\Delta V = LW\Delta y$ |
| Cylindrical shell volume | $\Delta V = 2\pi r L \Delta r$ |
| Spherical shell volume | $\Delta V = 4\pi r^2 \Delta r$ |
| Newton's law of cooling | $q = h(T_{ m solid} - T_{ m fluid})$ |

| Description | Equations |
|--|---|
| Relationship between N_A and c_A at boundary | $N_A = k_m (c_{A,\mathrm{solid}} - c_{A,\mathrm{fluid}})$ |
| Reynolds number | $\mathrm{Re} = rac{L_{\mathrm{char}} v_{\mathrm{char}} ho}{\mu}$ |
| No slip condition | $v_1=v_2$ |
| Free slip condition | $-\mu_1 \left(rac{dv_x}{dy} ight)_1 = 0$ |
| Continuity of stress | $	au_{y,1} = 	au_{y,2} \ -\mu_1 \left(rac{dv_x}{dy} ight)_1 = -\mu_2 \left(rac{dv_x}{dy} ight)_2$ |

| Shell balance method

- 1. Sketch the system with coordinate system
- 2. Sketch the shell that is thin in the direction of transport (change)
- 3. Write shell volume ΔV
- 4. Write shell balance OIGA of transported quantity
 - out -in = generation accumulation
- 5. Take limit as shell thickness approach 0
 - · Differential equation of flux distribution
- 6. Separate variable and integrate
 - Flux distribution, c_1
- 7. Substitute rate law
- 8. Separate variable and integrate
 - Profile, c_1, c_2
- 9. Evaluate c_1, c_2 using boundary conditions

| Axial transport in rectilinear systems

- · Rectilinear coordinates
- No generation
- · No driving force
- · Steady state

| Description | Equations |
|--|-------------------------------|
| Differential equation of flux distribution | $rac{dq}{dy}=0$ |
| Temperature profile (linear) | $T(y) = T_1 - \frac{q}{k}y$ |
| Flux distribution (inverse) | $q(y) = \frac{k(T_1 - T)}{y}$ |
| Flux across the whole layer | $q=rac{k(T_1-T_2)}{H}$ |
| | |

| Radial transport in cylindrical systems

- · Cylindrical coordinates
- No generation
- · No driving force

| Description | Equations |
|--|---|
| Differential equation of flux distribution | $rac{d(rq)}{dr}=0$ |
| Flux distribution (inverse) | $q(r) = rac{k(T_i - T_0)}{r \ln(rac{R_0}{R_i})}$ |
| Temperature profile (logarithmic) | $T(r) = T_i - rac{T_i - T_0}{\ln(rac{R_0}{R_i})} \ln\left(rac{r}{R_i} ight)$ |

| Radial transport in spherical systems

- Spherical coordinates
- No generation
- · No driving force
- · Steady state

| Description | Equations |
|--|--|
| Differential equation of flux distribution | $rac{d(r^2q)}{dr}=0$ |
| Flux distribution (inverse squared) | $q(r)=rac{k(T_i-T_0)}{r^2(rac{1}{R_i}-rac{1}{R_0})}$ |
| Temperature profile (inverse) | $T(r)=T_i-rac{T_i-T_0}{(rac{1}{R_i}-rac{1}{R_0})}\left(rac{1}{r}-rac{1}{R_i} ight)$ |

| Axial transport in rectilinear systems (with generation)

- Rectilinear coordinates
- · With generation
- · No driving force
- · Steady state

| Description | Equations |
|--|--|
| Differential equation of flux distribution | $rac{dq}{dy} = S$ |
| Flux distribution (linear) | $q(y) = Sy + \frac{k}{H}(T_2-T_1) - \frac{SH}{2}$ |
| Temperature profile (quadratic) | $T(y)=T_1-rac{S}{2k}y^2+\left[rac{SH}{2k}-rac{T_2-T_1}{H} ight]y$ |

| Flow down inclined plane (falling film)

- · Rectilinear coordinates
- Gravity driving force, but no pressure gradient
- Steady state

| Description | Equations |
|--|---|
| Differential equation of flux distribution | $rac{d	au_{yx}}{dy}= ho g\coseta$ |
| Flux distribution (linear) | $	au_{yx}(y) = - ho g\coseta(\delta-y)$ |

| Description | Equations |
|----------------------------------|---|
| Velocity profile (quadratic) | $v_x(y) = rac{g\coseta}{2 u}(2\delta y - y^2)$ |
| ★ No entry length effect | $L\gg\delta$ |
| ★ No edge effect | $W\gg\delta$ |
| ★ Incompressible Newtonian fluid | $\Delta \mu = 0, \Delta ho = 0$ |
| ★ No end effect, no ripple | $ m Re_{rippling} \lesssim 20$ |
| Reynolds number for falling film | $\mathrm{Re} = rac{4\delta \langle v_x angle ho}{\mu}$ |

| Flow descriptors

| Description | Equations |
|------------------------------------|--|
| Skin friction | $	au^0 = ho g \cos(eta) \delta$ |
| Free surface velocity | $v_x^{ m surf} = rac{g\coseta}{2 u}\delta^2$ |
| Volumetric flow rate | $Q=\int v_{\perp}~dA$ |
| Volumetric flow rate per unit area | $rac{Q}{W} = rac{g\cos(eta)\delta^3}{3 u}$ |
| Average velocity | $\langle v_x angle = rac{g\cos(eta)\delta^2}{3 u}$ |
| Mass flow rate | $\dot{m}= ho Q$ |
| Mass flow rate per unit width | $\Gamma = rac{ ho Q}{W} = rac{ ho g \cos(eta) \delta^3}{3 u}$ |
| Film thickness given Γ | $\delta = \sqrt[3]{rac{3 u\Gamma}{ ho g\coseta}}$ |

| Flow in round tube (Hagen-Poiseuille flow)

- · Cylindrical coordinates
- Pressure-gravity driving force
- Steady state
- No tube bents, constant cross section
- Negligible P dependence with r

| Description | Equations |
|--|--|
| Modified pressure | $\mathcal{P}=P+ ho g h$ |
| Pressure-gravity driving force | $-rac{dP}{dz}+ ho g\coseta=rac{{\cal P}_1-{\cal P}_2}{L}$ |
| Differential equation of flux distribution | $rac{d(r	au_{rz})}{dr} = \left(rac{{\cal P}_1-{\cal P}_2}{L} ight)r$ |
| Flux distribution (linear) | $	au_{rz}(r) = rac{1}{2} \left(rac{{\cal P}_1 - {\cal P}_2}{L} ight) r$ |
| Velocity profile (quadratic) | $v_z(r) = rac{R^2}{4\mu} \left(rac{{\cal P}_1 - {\cal P}_2}{L} ight) \left[1 - \left(rac{r}{R} ight)^2 ight]$ |
| ★ Incompressible Newtonian fluid | $\Delta \mu = 0, \Delta ho = 0$ |
| ★ Laminar flow | $\mathrm{Re_{laminar}} \leq 2100$ |

| Description | Equations |
|---|--|
| ★ Fully developed flow (no entry length effect) | $L_e \approxeq 0.035 D \mathrm{Re}$ |
| Reynolds number for pipe flow | $\mathrm{Re}_{\mathrm{pipe}} = rac{D\langle v_z angle ho}{\mu}$ |

| Flow descriptors

| Description | Equations |
|------------------|---|
| Skin friction | $	au_{rz}^0 = rac{1}{2} \left(rac{{\cal P}_1 - {\cal P}_2}{L} ight) R$ |
| Volumetric flow | $Q=rac{R^4\pi}{8\mu}\left(rac{{\cal P}_1-{\cal P}_2}{L} ight)$ |
| Average velocity | $\langle v_z angle = rac{R^2}{8\mu} \left(rac{{\cal P}_1 - {\cal P}_2}{L} ight)$ |
| Mass flow rate | $\dot{m}=rac{R^4\pi ho}{8\mu}\left(rac{{\cal P}_1-{\cal P}_2}{L} ight)$ |

| Laminar flow through porous media

| Description | Equations |
|---|--|
| Darcy's law - average velocity κ - bed permeability | $\langle v angle = rac{\kappa}{\mu L} ({\cal P}_1 - {\cal P}_2)$ |
| Darcy's law - volumetric flow rate A - empty bed cross section $arepsilon$ - porosity, void fraction | $Q=rac{\kappa Aarepsilon}{\mu L}({\cal P}_1-{\cal P}_2)$ |
| Blake-Kozeny model Bed permeability | $\kappa = rac{D_p^2}{150} \left(rac{arepsilon}{1-arepsilon} ight)^2$ |
| Effective packing particle diameter | $egin{aligned} D_p &= rac{6}{a_v} = rac{6V}{A} \ D_{p,	ext{spheres}} &= D \end{aligned}$ |
| Bed Reynolds number | $\mathrm{Re}_\mathrm{bed} = rac{D_p Q ho}{\mu A (1-arepsilon)}$ |
| ★ Laminar flow | $ m Re_{laminar} < 10$ |

| Fluid pressure, hydrostatic, manometer

| Description | Equations |
|-------------------------|---|
| Equation of hydrostatic | $P_1-P_2=\rho g(h_2-h_1)$ |
| Manometer equation | $P_1-P_2=(\rho_m-\rho)gH+\rho g(h_2-h_1)$ |
| Manometer equation | ${\cal P}_1-{\cal P}_2=(ho_m- ho)gH$ |

| Unsteady state transport

| Description | Equations |
|---|--|
| Unsteady state conduction in rectilinear system | $\left(rac{\partial T}{\partial t} ight)_y = lpha rac{\partial^2 T}{\partial y^2} + rac{S}{ ho \hat{c_p}}$ |
| Unsteady state diffusion in rectilinear system | $\left(rac{\partial c_A}{\partial t} ight)_y = D_{AB}rac{\partial^2 c_A}{\partial y^2} + R_A$ |
| Unsteady state Couette flow (1D rectilinear shear flow) | $\left(rac{\partial v_x}{\partial t} ight)_y = u \left(rac{\partial^2 v_x}{\partial y^2} ight)_t$ |
| Unsteady state flow in cylindrical system | $\left(rac{\partial v_z}{\partial t} ight)_r = u \left[rac{\partial^2 v_z}{\partial r^2} + rac{1}{r}rac{\partial v_z}{\partial r} ight] + rac{1}{ ho}\left[rac{{\cal P}_1 - {\cal P}_2}{L} ight]$ |

Rate Laws in 3D

| Description | Equations |
|---------------------------------|--|
| Fourier's law in 3D | $\overset{q}{\widetilde{\sim}} = -k abla T$ |
| Fick's law in 3D | $ \widetilde{\mathcal{L}}_{A}^{*} = -D_{AB} \nabla c_{A} $ |
| Newton's law of viscosity in 3D | $	au = -\mu(\mathop{\Delta}\limits_pprox + \mathop{\Delta}\limits_pprox^\dagger)$ |
| Viscous stress tensor | $egin{aligned} 	au &= egin{bmatrix} 	au_{xx} & 	au_{xy} & 	au_{xz} \ 	au_{yx} & 	au_{yy} & 	au_{yz} \ 	au_{zx} & 	au_{zy} & 	au_{zz} \end{bmatrix} \end{aligned}$ |
| Rate of strain tensor | $\Delta_{pprox} = egin{bmatrix} rac{\partial v_x}{\partial x} & rac{\partial v_x}{\partial y} & rac{\partial v_x}{\partial z} \ & & & & & & & & & & & & & & & & & & $ |

Conservation Laws in 3D

| Description | Equations |
|---|---|
| Conservation of thermal energy | $ abla \cdot \overset{q}{ec{g}} = S - ho \hat{c_p} rac{\partial T}{\partial t}$ |
| Conduction equation ★ No convection | $rac{\partial T}{\partial t} = lpha abla^2 T + rac{S}{ ho \hat{c_p}}$ |
| Molecular diffusion equation ★ No convection | $rac{\partial c_A}{\partial t} = D_{AB} abla^2 c_A + R_A$ |

#-★- FLUID MECHANICS

Navier-Stokes Equation

| Description | Equations |
|---|--|
| Continuity equation | $rac{\partial ho}{\partial t} + abla \cdot (ho ec{v}) = 0$ |
| Continuity equation of incompressible liquid \bigstar Constant ρ | $ abla \cdot ec{v} = 0$ |

| Description | Equations |
|---------------------------------------|--|
| Equation of motion $(v	ext{-form})$ | $ horac{D ec{v}}{D t} = - abla p + \mu abla^2 ec{v} + ho g$ |
| Equation of motion $(au	ext{-form})$ | $ ho rac{D v}{D t} = - abla p - abla \cdot rac{	au}{lpha} + ho g$ |
| Equation of motion (x -component) | $egin{aligned} ho \left[rac{\partial v_x}{\partial t} + ec{v} \cdot abla v_x ight] \ = & -rac{\partial p}{\partial x} - \left[rac{\partial 	au_{xx}}{\partial x} + rac{\partial 	au_{yx}}{\partial y} + rac{\partial 	au_{zx}}{\partial z} ight] + ho g_x \end{aligned}$ |

| Operators

| Description | Equations |
|---|--|
| Gradient operator $ abla$ | Operates on scalar to give a vector, whose magnitude is the maximum rate of change of the scalar with position, and whose direction points in the direction of that change |
| Divergence operator $(abla \cdot)$ | Operates on a vector to give a scalar |
| Divergence of a flux vector $(abla \cdot \widetilde{\underline{f}})$ | Rate of efflux (outflow) of the transported quantity per unit volume |
| Laplacian operator | $ abla^2 = abla \cdot abla$ |
| Substantial derivative operator | $rac{D}{Dt} = rac{\partial}{\partial t} + ec{v} \cdot abla$ |

| Generalization to convection

| Description | Equations |
|-------------------------------|--|
| | $rac{DT}{Dt} = lpha abla^2 T + rac{S}{ ho \hat{c_p}}$ |
| Convective diffusion equation | $rac{Dc_A}{Dt} = D_{AB} abla^2 c_A + R_A$ |

| Flow in conduit

| Description | Equations |
|---|---|
| Mach number | $\mathrm{Ma} = rac{v_{\mathrm{char}}}{v_{\mathrm{sound}}}$ |
| Conduit flow | $egin{aligned} \dot{m}_1 &= \dot{m}_2 \ ho_1 Q_1 &= ho_2 Q_2 \end{aligned}$ |
| Incompressible conduit flow $igstar$ Constant $ ho$ | $egin{aligned} Q_1 &= Q_2 \ A_1 \langle v angle_1 &= A_2 \langle v angle_2 \end{aligned}$ |

Apply N-S Equations (Top-Down)

| Flow between parallel plates

| Assumptions | Equations |
|-------------|-----------|
|-------------|-----------|

| Assumptions | Equations |
|---|--|
| Rectilinear coordinates | f(x,y,z) |
| Constant $ ho,\mu$ | $rac{\partial ho}{\partial t}=0, rac{\partial \mu}{\partial t}=0$ |
| Laminar flow | $ m Re < Re_{cr}$ |
| Steady state | $rac{\partial}{\partial t}=0$ |
| v_x component only | $v_y=v_z=0$ |
| No edge effect | $rac{\partial}{\partial z}=0$ |
| No end effect | $rac{\partial v_x}{\partial x}=0$ |
| No hydrostatic pressure diff between plates | $b \ll W, L \implies -rac{\partial p}{\partial y} + ho g_y = 0$ |
| December | Empations |

| Description | Equations |
|-------------------------------|---|
| x-momentum equation | $rac{{\cal P}_0-{\cal P}_L}{L} + \mu rac{\partial^2 v_x}{\partial y^2} = 0$ |
| Velocity profile (quadratic) | $v_x(y) = rac{1}{2\mu} \left(rac{{\cal P}_0 - {\cal P}_L}{L} ight) (-y^2 + by)$ |
| Average velocity | $\langle v_x angle = rac{b^2}{12 \mu} \left(rac{{\cal P}_0 - {\cal P}_L}{L} ight)$ |
| Skin friction at bottom plate | $	au^0 = rac{b}{2} \left(rac{{\cal P}_0 - {\cal P}_L}{L} ight)$ |

| Couette flow between concentric rotating cylinders

| Equations |
|--|
| f(r,	heta,z) |
| $rac{\partial ho}{\partial t}=0, rac{\partial \mu}{\partial t}=0$ |
| $\mathrm{Re} < \mathrm{Re}_{\mathrm{cr}}$ |
| $rac{\partial}{\partial t}=0$ |
| $v_r=v_z=0$ |
| $rac{\partial}{\partial 	heta} = 0$ |
| $rac{\partial v_{m{	heta}}}{\partial z}=0$ |
| $g_z=-g, g_	heta=g_r=0$ |
| |

| Description | Equations |
|---------------------------------|---|
| r-momentum equation | $- horac{v_{	heta}^2}{r}=-rac{\partial p}{\partial r}$ |
| heta-momentum equation | $\murac{\partial}{\partial r}\left(rac{1}{r}rac{\partial}{\partial r}(rv_{	heta}) ight)=0$ |
| z-momentum equation | $-rac{\partial p}{\partial z}- ho g=0$ |
| Velocity profile (general form) | $v_{	heta}(r) = c_1 rac{r}{2} + rac{c_2}{r}$ |
| Velocity profile | $v_{	heta}(r) = rac{\Omega_0}{1-\kappa^2} \left[r - rac{(\kappa R)^2}{r} ight]$ |
| | |

| Description | Equations |
|---------------------------|---|
| Pressure profile | $P-P_{\kappa R} = rac{1}{2} ho\left(rac{\Omega_0\kappa R}{1-\kappa^2} ight)^2\left[\left(rac{r}{\kappa R} ight)^2-\left(rac{\kappa R}{r} ight)^2-4\ln\left(rac{r}{\kappa R} ight) ight]$ |
| Shear stress distribution | $	au_{r	heta} = -2\mu\kappa^2\left(rac{\Omega_0}{1-\kappa^2} ight)\left(rac{R}{r} ight)^2$ |
| Torque | $\mathcal{T}=4\pi\mu L\Omega_0R^2rac{\kappa^2}{1-\kappa^2}$ |
| Couette viscometer | $\mu = rac{\mathcal{T}}{4\pi L \Omega_0 R^2} rac{1-\kappa^2}{\kappa^2}$ |

| Stoke's law: Flow around a sphere

| Assumptions | Equations |
|---------------------------------------|--|
| Spherical coordinates | $f(r,	heta,\phi)$ |
| Constant $ ho,\mu$ | $rac{\partial ho}{\partial t}=0, rac{\partial \mu}{\partial t}=0$ |
| Laminar flow | $ m Re < Re_{cr}$ |
| Steady state | $rac{\partial}{\partial t}=0$ |
| Axial symmetry | $rac{\partial}{\partial \phi}=0$ |
| No spinning | $v_\phi=0$ |
| Vertical orientation | $g_r = -g\cos	heta, g_	heta = g\sin	heta, g_\phi = 0$ |
| $v_{	heta}$ component only | $v_r=v_z=0$ |
| | |
| Description | Equations |
| r velocity profile | $v_r = v_\infty \left[1 - rac{3}{2} \left(rac{R}{r} ight) + rac{1}{2} \left(rac{R}{r} ight)^2 ight]\cos	heta$ |
| heta velocity profile | $v_{	heta} = -v_{\infty} \left[1 - rac{3}{4} \left(rac{R}{r} ight) - rac{1}{4} \left(rac{R}{r} ight)^3 ight] \sin 	heta$ |
| Pressure profile | $p=p_0- ho gz-rac{3}{2}rac{\mu v_\infty}{R}\left(rac{R}{r} ight)^2\cos	heta$ |
| Viscous drag | $4\pi\mu v_{\infty}R$ |
| Pressure force (buoyancy + form frag) | $rac{4}{3}\pi R^3 ho g + 2\pi R\mu v_\infty$ |
| Stoke's law | $v_{\infty}=rac{2R^{2}(ho_{s}- ho)g}{9\mu}$ |
| Falling ball viscometer | $\mu=rac{2R^2(ho_s- ho)g}{9v_\infty}$ |

| Centrifuge viscometer

| • | Equations |
|-------------------|---|
| Terminal velocity | $v_{\infty}=rac{2R^2(ho_s- ho)\omega^2r}{9\mu}$ |

Turbulence

| Transition to turbulence

| Geometry | Reynolds Number | Critical Reynolds Number |
|---|--|-----------------------------|
| Circular tube flow | $\mathrm{Re} = rac{D\langle v angle ho}{\mu}$ | $\mathrm{Re_c} pprox 2100$ |
| Falling film | $\mathrm{Re} = rac{4\delta \langle v angle ho}{\mu}$ | $\mathrm{Re_c} pprox 1500$ |
| Flow between parallel plates | $\mathrm{Re} = rac{2b\langle v angle ho}{\mu}$ | $\mathrm{Re_c}\approx1780$ |
| Tangential flow in an annulus (Couette flow between rotating cylinders) | $\mathrm{Re} = rac{\Omega_0 R^2 \langle v angle ho}{\mu}$ | $\mathrm{Re_c} pprox 50000$ |

| Laminar vs. turbulent

| Property | Laminar Flow $({ m Re} < 2100)$ | Turbulent Flow $(\mathrm{Re} \in [10^4, 10^5])$ |
|----------------------|---|--|
| Velocity profile | $rac{v_z}{v_{z,	ext{max}}} = 1 - \left(rac{r}{R} ight)^2$ | $rac{v_z}{v_{z,	ext{max}}}pprox \left(1-rac{r}{R} ight)^{1/7}$ |
| Average velocity | $\langle v_z angle = rac{1}{2} v_{z,	ext{max}}$ | $\langle v_z anglepprox rac{4}{5}ar{v}_{z,	ext{max}}$ |
| Volumetric flow rate | $Q=rac{\pi R^4}{8\mu}\left(rac{{\cal P}_0-{\cal P}_1}{L} ight)$ | $Q \propto \left(rac{{\cal P}_0 - {\cal P}_1}{L} ight)^{4/7}$ |
| Entry length | $L_e=0.035D{ m Re}$ | $L_e pprox 40D$ |
| Derivation | From theory | From experiment |

| Description | Equations |
|------------------------------------|--|
| Velocity decomposition | $v_z=ar{v}_z+v_z'$ |
| Velocity profile in turbulent flow | $egin{aligned} ar{v}_z &= ar{v}_{z,	ext{max}} \left(1 - rac{r}{R} ight)^{1/n} \ n &= egin{cases} 6 & 	ext{Re} \in [2 	imes 10^3, 10^4] \ 7 & 	ext{Re} \in [10^4, 10^5] \ 8 & 	ext{Re} \in [10^5, 10^6] \end{cases} \end{aligned}$ |

| Time-smoothed N-S equation

| Description | Equations |
|---|---|
| Time-smoothed continuity equation | $egin{aligned} abla \cdot ar{v} &= 0 \ abla \cdot ar{v}' &= 0 \end{aligned}$ |
| Time-smoothed equation of motion ($	au$ -form) | $ horac{Dar{ar{v}}}{Dt} = - ablaar{p} - abla \cdot ar{ar{	au}}^{	ext{total}} + ho g$ |

$\begin{array}{ll} \text{Description} & \text{Equations} \\ & \rho \left[\frac{\partial \bar{v}_x}{\partial t} + \bar{z} \cdot \nabla \bar{v}_x \right] \\ & = -\frac{\partial \bar{p}}{\partial x} - \left[\frac{\partial \bar{\tau}_{txx}^{total}}{\partial x} + \frac{\partial \bar{\tau}_{yx}^{total}}{\partial y} + \frac{\partial \bar{\tau}_{zx}^{total}}{\partial z} \right] + \rho g_x \\ & \text{Total shear stress (viscous + turbulent)} & \bar{\tau}_{yx}^{total} = \bar{\tau}_{yx}^{(v)} + \bar{\tau}_{yx}^{(t)} \\ & = \bar{\tau}_{yx} + \rho v_y^{\prime} v_x^{\prime} \end{array}$

| Shear stress distribution

| Description | Equations |
|--|--|
| Shear stress distribution in round tube | $	au_{r	heta} = rac{1}{2} \left[rac{{\cal P}_0 - {\cal P}_1}{L} ight] r$ |
| Shear stress distribution in general conduit | $	au_{r	heta} = \left[rac{{\cal P}_0 - {\cal P}_1}{L} ight] R_H$ |
| Hydraulic radius | $R_H = rac{	ext{cross sectional area}}{	ext{wetted perimeter}}$ |
| Characteristic length | $l_{ m char}=4R_H$ |
| Characteristic velocity | $v_{ m char} = \langle v_z angle$ |

| Universal velocity profile

| Layer | Normalized velocity | Normalized length range |
|------------------|-----------------------------------|-------------------------|
| Laminar sublayer | $v^+=y^+$ | $y^+\in(0,5)$ |
| Buffer layer | $v^+ = 5 \ln(y^+ + 0.205) - 3.27$ | $y^+ \in (5,30)$ |
| Turbulent core | $v^+ = 2.5 \ln(y^+) + 5.5$ | $y^+ \in (30,\infty)$ |

| Description | Equations |
|-------------------------|---|
| Characteristic length | $y_* = rac{\mu}{v_* ho}$ |
| Characteristic velocity | $v_* = \sqrt{rac{	au^0}{ ho}}$ |
| Normalized length | $y^+=rac{y}{y_*}$ |
| Normalized velocity | $v^+=rac{v}{v_*}$ |
| Eddie viscosity | $\mu^{(t)} = -rac{ar{	au}_{yz}^{	ext{total}}}{\left(rac{dv_z}{dy} ight)} - \mu = -rac{\left[rac{\mathcal{P}0-\mathcal{P}1}{L} ight]rac{r}{2}}{\left(rac{dv_z}{dy} ight)} - \mu$ |

Dynamic Similarity and Dimensional Analysis

| Flow around a sphere outside of Stoke's law

| Description | Equations |
|-----------------------------|------------------------|
| ★ Non-Stoke's law condition | $\mathrm{Re} \geq 0.1$ |

| Description | Equations |
|--|---|
| Nondimensionalized continuity equation | $reve{ abla}\cdot reve{v}=0$ |
| x-component of momentum equation | $rac{Dreve{v}_x}{Dreve{t}} = -rac{\partialreve{p}}{\partialreve{x}} + rac{1}{\mathrm{Re}}reve{ abla}^2reve{v}_x + rac{1}{\mathrm{Fr}}reve{g}_x$ |
| Drag coefficient Friction factor | $c_D = f = rac{F_D}{rac{1}{2} ho v_\infty^2 A_{ m approach}}$ |
| Drag coefficient in Stoke's law region | $c_D = rac{24}{	ext{Re}}$ |
| Drag coefficient in non-Stoke's law region | $c_D = \left(\sqrt{rac{24}{\mathrm{Re}}} + 0.5407 ight)^2$ |

| Dimensionless groups

| Description | Equations |
|------------------|--|
| Reynolds number | $	ext{Re} = rac{l_0 v_0 ho}{\mu} = rac{	ext{inertial forces}}{	ext{viscous forces}}$ |
| Froude number | $\mathrm{Fr} = rac{v_0^2}{g l_0} = rac{\mathrm{inertial\ forces}}{\mathrm{gravitational\ forces}}$ |
| Capillary number | $	ext{Ca} = rac{\mu v_0}{\sigma} = rac{	ext{viscous forces}}{	ext{surface tension forces}}$ |
| Weber number | $	ext{Fr} = rac{l_0 ho v_0^2}{\sigma} = rac{	ext{inertial forces}}{	ext{surface tension forces}}$ |
| Euler's number | $\mathrm{Eu} = rac{(\Delta p) D^4}{ ho Q^2}$ |

| Dimensional analysis

- Buckingham π theorem A function $f(X_1, X_2, \ldots, X_k)$ with dimensional variables X_i can be rewritten in a function $\Phi(\Pi_1, \Pi_2, \ldots, \Pi_{k-n})$ with dimensionless variables Π_j by enforcing dimensional consistency using n fundamental dimensions.
 - Define fundamental dimensions
 - Choose stand-in variables for fundamental dimensions
 - Rewrite other variables in terms of stand-in variables to get dimensionless groups

Bernoulli Analysis and Applications

| N-S equation for steady flow in stream tubes

| Assumptions | Equations |
|---|---|
| Constant density fluid | $\Delta ho=0$ |
| 1D flow in z direction | $v_r=v_	heta=0$ |
| Plug flow - uniform velocity across cross section | $\langle v angle = v = { m constant} \ v_z = v_z(z)$ |
| Inviscid flow | $\mupprox 0, \mathrm{Re}\geq 10000$ |
| No sharp bends | Straight stream lines |
| Description | Equations |

| Description | Equations |
|---------------------|---|
| Continuity equation | $egin{aligned} Q_1 &= Q_2 \ A_1 \langle v angle_1 &= A_2 \langle v angle_2 \end{aligned}$ |
| Equation of motion | $ ho v rac{dv}{dz} = -rac{dp}{dz} - ho g rac{dh}{dz}$ |

| Bernoulli equation

| Description | Equations |
|--|--|
| Bernoulli equation (energy form) | $p_1 + rac{1}{2} ho v_1^2 + ho g h_1 = p_2 + rac{1}{2} ho v_2^2 + ho g h_2$ |
| Bernoulli equation (head form) | $rac{v_1^2}{2g} + rac{p_1}{ ho g} + h_1 = rac{v_2^2}{2g} + rac{p_2}{ ho g} + h_2$ |
| Bernoulli head | $\mathcal{B} = rac{v^2}{2g} + rac{p}{ ho g} + h = 	ext{constant}$ |
| Drag coefficient | $c_D = rac{F_D}{rac{1}{2} ho v_\infty^2 A_{ m approach}}$ |
| Lift coefficient | $c_L = rac{F_L}{rac{1}{2} ho v_\infty^2 A_{ m planform}}$ |
| Pressure change in contracting conduit $\Delta p \equiv p_1 - p_2$ | $\Delta p = rac{8 ho Q^2}{\pi^2 D_1^4} \left[\left(rac{D_1}{D_2} ight)^4 - 1 ight] + ho g(h_2 - h_1)$ |
| Torricelli's law | $\langle v angle = \sqrt{2g\Delta h}$ |
| Pressure at stagnation point | $p = p_{ m static} + p_{ m dynamic} \ = p_{ m static} + rac{1}{2} ho v_{\infty}^2$ |

| Flow-metering devices

| Description | Equations |
|---|---|
| Manometer equation | $\Delta p = (ho_{ m m} - ho)gH$ |
| Local velocity Pitot tube | $v=\sqrt{rac{2\Delta p}{ ho}}$ |
| Volumetric flow rate Venturi meter $c_0 \in [0.96, 0.98]$ Orfice meter $c_0 \in [0.40, 0.80]$ Nozzle meter $c_0 \in [0.96, 0.98]$ | $Q = c_0 \pi D_0^2 \sqrt{rac{\Delta p}{8 ho [1-(rac{D0}{D})^4]}}$ |
| Rotameter | Calibrated specifically to the fluid with falling sphere |

| Full Bernoulli analysis

| Description | Equations |
|-------------------------------|---|
| Full Bernoulli equation | $rac{v_1^2}{2g} + rac{p_1}{ ho g} + h_1 = rac{v_2^2}{2g} + rac{p_2}{ ho g} + h_2 + H_{L12}$ |
| Head loss | $H_{L12} = H_{L12f} + H_{L12c}$ |
| Skin friction loss H_{L12f} | Viscous work done per unit weight by fluid on walls of conduit in moving from 1 to 2 |

| Description | Equations |
|---|--|
| Skin friction loss (general) | $H_{L12f}=rac{	au^0L}{ ho gR_H}$ |
| Skin friction loss for circular tube | $H_{L12f}=rac{4	au^0L}{ ho gD}$ |
| Fanning friction factor | $f=rac{	au^0}{rac{1}{2} ho\langle v angle^2}$ |
| Skin friction loss for circular tube | $H_{L12f}=rac{2\langle v angle^2 L}{gD}f=rac{32Q^2L}{\pi^2D^5g}f$ |
| Skin friction loss for non-circular tube | $H_{L12f}=rac{\langle v angle^2 L}{2gR_H}f=rac{Q^2 L}{2gA_c^2R_H}f$ |
| Reynolds number for noncircular pipes | $	ext{Re} = rac{4R_H \langle v angle ho}{\mu}$ |
| Configurational loss of one fitting in circular tube | $H_{Lc} = e_v rac{\langle v angle_{ m downstream}^2}{2g}$ |
| Configurational loss of all fittings in circular tube | $H_{L12c} = rac{\langle v angle_{	ext{down}}^2}{2g} (\sum_i e_{v,i}) = rac{8Q^2}{\pi^2 D^4 g} (\sum_i e_{v,i})$ |
| Total head loss for circular tube | $H_{L12} = egin{cases} rac{2 \langle v angle^2}{Dg} [(\sum_i L_i) f + rac{D}{4} (\sum_i e_{v,i})] \ rac{32 Q^2}{\pi^2 D^5 g} [(\sum_i L_i) f + rac{D}{4} (\sum_i e_{v,i})] \end{cases}$ |
| Kinetic head correction factor | $lpha = rac{\langle v^3 angle}{\langle v angle^3}$ |
| Brake horse power | $\mathrm{bhp} = rac{P}{\eta} = rac{H_p ho g Q}{\eta}$ |
| | |

| Fanning friction factor correlations

| Description | Equations | Conditions |
|---|--|--|
| Hydraulically smooth pipes (Blasius) | $f=\frac{0.0791}{\mathrm{Re}^1/4}$ | ${ m Re} \in [2100, 10^5]$ |
| Hydraulically smooth pipes (Koo) | $f = 0.0014 + rac{0.125}{\mathrm{Re}^{0.32}}$ | ${ m Re} \in [10^4, 10^7]$ |
| Pipes of general roughness (Haaland) | $rac{1}{\sqrt{f}} = -3.6 \log_{10} \left[rac{6.9}{	ext{Re}} + \left(rac{k/D}{3.7} ight)^{10/9} ight]$ | ${ m Re} \in [4	imes 10^4, 10^7] \ k/D < 0.05$ |
| Commercial standard piping (Drew) | $f = 0.0014 + rac{0.090}{\mathrm{Re}^{0.27}}$ | $\mathrm{Re} \in [10^4, 10^7] \ k/D pprox 0.00015$ |
| Full rough conduit | $rac{1}{\sqrt{f}} = 2.28 - 4.0 \log_{10}\left(rac{k}{D} ight)$ | $\mathrm{Re} > 10^4 \ k/D > 0.01$ |

| Kinetic head correction factor

| Re | n | α | |
|-------------------------|---|----------|--|
| $2	imes 10^3 \sim 10^4$ | 6 | 1.08 | |
| $10^4\sim 10^5$ | 7 | 1.06 | |
| $10^5\sim 10^7$ | 8 | 1.05 | |
| | | | |

| Flow through packed bed

| Description | Equations |
|---|--|
| Specific area of packing element | $a_v = rac{	ext{area of packing element}}{	ext{volume of packing element}}$ |
| Effective diameter of packing element (particle) | $D_p = rac{6}{a_v}$ |
| Darcy's law $\star \mathrm{Re}_\mathrm{bed} \lesssim 10$ | $\langle v angle = rac{\kappa}{\mu} \left[rac{{\cal P}_0 - {\cal P}_L}{L} ight]$ |
| Volumetric flow rate | $Q=\langle v angle arepsilon A=v_0 A$ |
| Superficial velocity | $v_0 = \langle v angle arepsilon$ |
| Bed Reynolds number | $egin{aligned} 	ext{Re}_{	ext{bed}} &= rac{D_p v_0 ho}{\mu} rac{1}{1 - arepsilon} \ &= rac{D_p \langle v angle ho}{\mu} rac{arepsilon}{1 - arepsilon} \ &= rac{D_p Q ho}{\mu A} rac{1}{1 - arepsilon} \end{aligned}$ |
| Tube Reynolds number | $\mathrm{Re_{tube}} = rac{2}{3}\mathrm{Re_{bed}}$ |
| Hydrolic radius | $R_H = rac{D_p arepsilon}{6(1-arepsilon)}$ |
| Friction factor of tube $ \bigstar \ \mathrm{Re}_{\mathrm{bed}} \leq 10 $ | $f_{ m tube} = rac{24(1-arepsilon)\mu}{D_p v_0 ho}$ |
| Friction factor of tube $ \bigstar \mathrm{Re}_{\mathrm{bed}} > 1000 $ | $f_{ m tube} = rac{7}{12}$ |
| Bed permeability | $\kappa = rac{D_p^2}{150} \left(rac{arepsilon}{1-arepsilon} ight)^2$ |
| Blake-Kozeny equation $\star \mathrm{Re}_{\mathrm{bed}} \leq 10$ | $\left[rac{{\cal P}_0-{\cal P}_L}{L} ight]=150rac{\mu v_0}{D_p^2}rac{(1-arepsilon)^2}{arepsilon^3}$ |
| Burke-Plummer equation $ \bigstar \ \mathrm{Re}_{\mathrm{bed}} > 1000 $ | $\left[rac{{\cal P}_0-{\cal P}_L}{L} ight] = rac{7}{4}rac{ ho v_0^2}{D_p}rac{1-arepsilon}{arepsilon^2}$ |
| Superficial mass flux | $G_0 = ho v_0 = rac{\dot{m}}{A}$ |
| $\begin{array}{l} \textbf{Ergun equation} \\ \bigstar \ \mathrm{Re_{bed}} \in [10, 1000] \end{array}$ | $egin{aligned} \left[rac{(\mathcal{P}_0-\mathcal{P}_L) ho}{G_0^2} ight]rac{D_p}{L}rac{arepsilon^3}{1-arepsilon} &= 150\left[rac{1-arepsilon}{rac{D_pG_0}{\mu}} ight] + rac{7}{4} \ \left[rac{(\mathcal{P}_0-\mathcal{P}_L) ho}{G_0^2} ight]rac{D_p}{L}rac{arepsilon^3}{1-arepsilon} &= 150rac{1}{	ext{Re}_{	ext{bed}}} + rac{7}{4} \end{aligned}$ |

| Cavitation and vortex motion

| Description | Equations |
|-------------------|--|
| Cavitation number | $\sigma = rac{p_A - p_C}{rac{1}{2} ho v_\infty^2}$ |

| Forced vortex flow in rotating cylinder

Description Equations

| Description | Equations |
|---|---|
| Velocity profile | $v_{	heta}=r\Omega$ |
| Pressure difference ★ 1 defined arbitrarily, 2 defined at center | $p_2-p_1=rac{1}{2} ho\Omega^2(r_2^2-r_1^2)+ ho g(z_1-z_2)$ |
| Height | $h=rac{\Omega^2}{2g}r^2$ |

| Free vortex flow during drainage

| Description | Equations |
|--|--|
| Pressure difference $igstar$ 1 defined arbitrarily, 2 defined at $r 	o \infty$ | $p_2 - p_1 = rac{1}{2} ho C^2 \left(rac{1}{r_1^2} - rac{1}{r_2^2} ight) + ho g(z_1 - z_2)$ |
| Depth | $h=rac{C^2}{2g}rac{1}{r^2}$ |

Microfluidics*

| Validity of continuum description

| Description | Equations |
|---|---|
| Mean free path | $\lambda = rac{1}{\sqrt{2}\pi d^2 n} \ \lambda(\mu\mathrm{m}) pprox 3.1 	imes 10^{-3} rac{T(\mathrm{K})}{\sigma^2(\mathring{\mathrm{A}}^2)p(\mathrm{atm})}$ |
| Knudsen number | $\mathrm{Kn}=rac{\lambda}{L_c}$ |
| Characteristics | Range |
| Molecular flow | $\mathrm{Kn} \in (10,\infty)$ |
| Transition flow | $\mathrm{Kn} \in (0.1, 10)$ |
| N-S equations hold, but no-slip condition fails | ${ m Kn} \in (0.001, 0.1)$ |
| | |

| Forces in microfluidic flows

- Viscous force dominate over inertial forces and gravity forces
 - · Driving force
 - Pressure
 - Capillary (surface tension) forces
 - Electro-kinetic forces
 - · Magnetic forces
 - Resisting forces: viscous force, dominated by wall effects

| Description | Equations |
|---------------------------------|--|
| Reynolds number ★ Creeping flow | $	ext{Re} = rac{	ext{inertial forces}}{	ext{viscous forces}} = rac{Lv ho}{\mu} 	o 0$ |

| Description | Equations |
|---------------------------------------|--|
| Froude number | ${ m Fr} = {{ m inertial~forces}\over { m gravity~forces}} = {v^2\over gL}$ |
| Viscous force dominates gravity force | $rac{	ext{Re}}{	ext{Fr}} = rac{	ext{gravity forces}}{	ext{viscous forces}} = rac{gL^2}{\mu v} ightarrow 0$ |

| Generalized Hagen-Poiseuille flow

| Description | Equations |
|---|---|
| Differential equation of generalized H-P flow | $0 = rac{\Delta p}{L} + \mu \left(rac{\partial^2 v_z}{\partial x^2} + rac{\partial^2 v_z}{\partial y^2} ight)$ |
| No-slip condition $F(x,y)$ is equation of conduit perimeter | $v_z(x,y)=0 for F(x,y)=0$ |
| Velocity profile | $v_z(x,y) = rac{\Delta p}{\mu L} F(x,y)$ |
| Volumetric flow rate | $Q = rac{\Delta p}{\mu L} \iint F(x,y) \ dy \ dx$ |

| Hydraulic resistance in micro-channels

| Description | Equations |
|----------------------|---|
| Flow equation | $\Delta p = \mathcal{R}_{	ext{hyd}} Q$ |
| Volumetric flow rate | $Q=rac{\Delta p}{\mathcal{R}_{	ext{hyd}}}$ |

| Capillary driving force and wicking phenomena

| Description | Equations |
|---------------------------|---|
| Pressure difference | 16 |
| Wicking velocity | $v=rac{r^2}{8\mu}rac{\Delta P}{x}=rac{r\sigma\cos	heta}{4\mu x}$ |
| Washburn equation | $x = \sqrt{rac{r\sigma\cos	heta}{2\mu}t} \propto \sqrt{t}$ |
| Wicking into porous media | $h=\sqrt{rac{r_e\sigma\cos	heta}{2\mu}t}\propto\sqrt{t}$ |