Steady-State Gain K

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Steady-state gain quantifies how much output changes upon unit input change

Steady-state gain K - ratio of the output variable change to an sustained input variable change at new

steady state

$$K=rac{\overline{y}_2-\overline{y}_1}{\overline{u}_2-\overline{u}_1}$$
 out $rac{ar{y}_2}{ar{y}_2-ar{y}_1}$, we see Sees.

Steady state gain is a constant for linear processes.

output drange is normalized input change.

Steady-state gain can be evaluated from G(0)

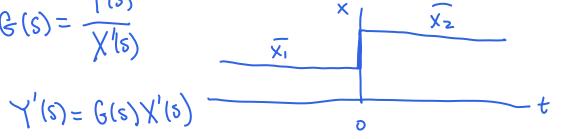
Ex. Prove that steady-state gain can be evaluated from G(s) by setting s=0 (if the gain exists).

• Final value theorem:
$$\lim_{t \to \infty} [y(t)] = \lim_{s \to 0} [sY(s)]$$

$$K = \frac{\overline{y}_z - \overline{y}_1}{\overline{x}_z - \overline{x}_1} = \lim_{s \to 0} \frac{y'}{s'} = \lim_{s \to 0} [s Y'(s)]$$

$$\frac{\Im}{\Im z} \qquad t \rightarrow \infty$$

$$G(s) = \frac{\chi(s)}{\chi(s)}$$



$$\chi'(4) = \chi_2 - \chi_1$$

$$\chi'(5) = \overline{\chi_2 - \chi}$$

Example: determining steady-state gain

Ex. Determine the steady state gain given transfer function of $G(s) = \dfrac{w_1}{\rho V s + w}$

$$K = G(0) = \frac{gV(0) + \omega}{gV(0) + \omega} = \frac{\omega_1}{\omega}$$