

Motivating Transfer Functions

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Process Dynamics and Control

Laplace-transformed output in original variables are hard to find

Ex. Find the Laplace-transformed output $Y(s)$ of the ODE

$$\mathcal{L}\left[\frac{dy}{dt} = x - y\right]$$

$$X(s) = \mathcal{L}[x(t)]$$

$$Y(s) = \mathcal{L}[y(t)]$$

where x is the input and y is the output.

$$sY(s) - y(0) = X(s) - Y(s)$$

$$sY(s) + Y(s) = X(s) - y(0)$$

$$Y(s) = \frac{X(s) - y(0)}{s+1} \leftarrow \text{often nonzero}$$

$X(s)$ not separable
- cannot write in $\frac{Y(s)}{X(s)}$

Deviation variables have vanishing initial condition at steady-state in \mathcal{L} space

Ex. Find the Laplace-transformed output deviation $\underline{Y}'(s)$ of the ODE

$$\checkmark \frac{dy}{dt} = x - y$$

eg.

$$y'' = \frac{dy}{dx}$$

$$+2^\circ\text{F} = 72^\circ\text{F} - 70^\circ\text{F}$$

deviation variable phys nominal steady state value

$$y' = y - \bar{y}$$

where x is the input and y is the output, by defining deviation variable of

- ✓ Derive governing ODE
- Identify variables
 - Input variable (cause) x
 - Output variable (effect) y
- Derive steady-state expression $\frac{d}{dt} = 0$
- Derive ODE in deviation variables
- Get transfer function in \mathcal{L} space

$$\checkmark 0 = \bar{x} - \bar{y}$$

$$\frac{dy}{dt} - 0 = (x - \bar{x}) - y + \bar{y}$$

$$\frac{dy}{dt} = (x - \bar{x}) - (y - \bar{y})$$

$$\frac{dy}{dt} = x' - y'$$

$$\boxed{\frac{dy'}{dt} = x' - y'}$$

ODE in deviation space

$$\frac{dy'}{dt} = \frac{d}{dt} (y - \bar{y}) = \frac{dy}{dt}$$

⚠

$$\frac{dy}{dt} = x - y \quad \leftarrow \text{Ⓢ}$$

$$\frac{dy'}{dt} = x' - y'$$

Deviation variables have vanishing initial condition at steady-state in \mathcal{L} space

Ex. Find the Laplace-transformed output deviation $Y'(s)$ of the ODE

$$\frac{dy}{dt} = x - y$$

where x is the input and y is the output, by defining deviation variable of $y' = y - \bar{y}$.

$$* y'(0) = y(0) - \bar{y}$$

normally, init would
be at nominal steady
state: $y(0) = \bar{y}$

$$\Rightarrow y'(0) = 0$$

no deviation

$$\mathcal{L} \left[\frac{dy'}{dt} = x' - y' \right]$$

$$sY'(s) - \cancel{y'(0)}^0 = X'(s) - Y'(s)$$

$$sY'(s) + Y'(s) = X'(s)$$

$$Y'(s) = \frac{X'(s)}{s+1}$$

no $y'(0)$

$X'(s)$ can be sep.

$$s+1 = \frac{X'(s)}{Y'(s)}$$

$$\frac{Y'(s)}{X'(s)} = \frac{1}{s+1}$$

← scales between
input & output

Transfer function maps input-output relationship in the \mathcal{L} space

- **Transfer function** - characterizes dynamic relationship of input and output variables in the Laplace space

transfer func
e.g., original
deviation
(s)

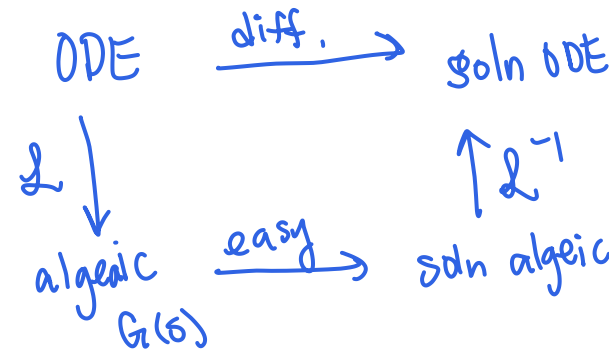
$$\downarrow$$

$$\boxed{G(s) = \frac{\mathcal{L}[\text{output}]}{\mathcal{L}[\text{input}]}} \cong \frac{Y(s)}{X(s)} \cong \frac{Y'(s)}{X'(s)}$$

- **Deviation variable** - deviation from a nominal steady-state
 - Have vanishing initial condition at steady-state in \mathcal{L} space

$$\begin{aligned}
 y' &= y(t) - \bar{y} \\
 y(0) &= \bar{y} \\
 y' &= \bar{y} - \bar{y} = 0
 \end{aligned}$$

$$\underline{G(s)} = \frac{Y'(s)}{X'(s)} = \frac{1}{s+1}$$



Laplace transform of multivariable ODE show linearity of transfer function

Ex. Find the Laplace-transformed output deviation $Z'(s)$ of the ODE

$$\frac{dz}{dt} = x - y - z \quad \text{original ODE}$$

where x and y are the inputs and z is the output.

1. steady-state $\frac{d}{dt} = 0$;
bars for in & outputs

$$0 = \bar{x} - \bar{y} - \bar{z} \quad \text{steady-state ODE}$$

$$\frac{dz}{dt} = (x - \bar{x}) - (y - \bar{y}) - (z - \bar{z})$$

$$\frac{dz}{dt} = x' - y' - z'$$

$$\frac{dz'}{dt} = \frac{d}{dt}(z(t) - \bar{z}) = \frac{dz}{dt}$$

2. get dev ODE

$$\mathcal{L} \left[\boxed{\frac{dz'}{dt} = x' - y' - z'} \right] \quad \text{deviation ODE}$$

3. get $Z'(s)$

$$s Z'(s) - \cancel{z'(0)}^0 = X' - Y' - Z'$$

$$Z'(s) = \frac{X' - Y'}{s+1} = \frac{X'}{s+1} - \frac{Y'}{s+1}$$

$$\bullet \quad z'(0) = 0$$

\Downarrow hold $y(t)$ const.
 $\Rightarrow \text{dev.} = 0, Y'(s) = 0$

$$Z'(s) = \frac{X'}{s+1}$$

$$\frac{Z'(s)}{X(s)} = \frac{1}{s+1}$$

Transfer function can predict step change



Ex. Determine the response $y(t)$ to a step change in x of magnitude M at $t = 0$ using the transfer function

$$G(s) = \frac{1}{s+1} = \frac{Y'(s)}{X'(s)}$$

- Rearrange for $Y'(s)$

$$Y'(s) = G(s) X'(s) = \frac{1}{s+1} \frac{M}{s}$$

- Determine $X'(s)$ from $x'(t)$

$$x'(t) = M \Rightarrow \mathcal{L}[x'(t)] = X'(s) = \frac{M}{s}$$

- Get deviation in time space

$$\mathcal{L}^{-1}[Y'(s)] = y'(t) = \mathcal{L}^{-1}\left[\frac{M}{(s+1)s}\right] \quad \begin{matrix} b_1=1 \\ b_2=0 \end{matrix}$$

- Get response in time space

$$= M \frac{1}{1-0} (e^0 - e^{-t})$$

$$= M(1 - e^{-t})$$

$$\mathcal{L}^{-1}\left[\frac{1}{(s+b_1)(s+b_2)}\right] = \frac{1}{b_1 - b_2} (e^{-b_2 t} - e^{-b_1 t})$$

$$y'(t) = y(t) - \bar{y}$$

$$y(t) = y'(t) + \bar{y} = \boxed{M(1 - e^{-t}) + \bar{y}}$$

Obtaining transfer function from ODE

(cause)
output

(cause)
input

Seborg Ex. 4.1a Find the transfer function model between liquid level h and inlet flow rate q_i in deviation variables with governing ODE of *const. A, R_v*

$$A \frac{dh}{dt} = q_i - \frac{1}{R_v} h \checkmark$$

original

- Derive steady-state expression

$$\frac{d}{dt} = 0$$

$$0 = \bar{q}_i - \frac{1}{R_v} \bar{h}$$

S.S

- Derive ODE in deviation variables

$$A \frac{dh}{dt} = (q_i - \bar{q}_i) - \frac{1}{R_v} (h - \bar{h})$$

$$\frac{dh'}{dt} = \frac{d}{dt} (h(t) - \bar{h}) = \frac{dh}{dt}$$

$$A \frac{dh'}{dt} = q_i' - \frac{1}{R_v} h'$$

deviation

Obtaining transfer function from ODE

Seborg Ex. 4.1a Find the transfer function model between liquid level h and inlet flow rate q_i in deviation variables with governing ODE of

$$A \frac{dh}{dt} = q_i - \frac{1}{R_v} h$$

- Know ODE in deviation variables

$$\mathcal{L} \left[A \frac{dh'}{dt} = q_i' - \frac{1}{R_v} h' \right]$$

- Get transfer function in \mathcal{L} space
 - Initial condition

$$\begin{aligned} h'(0) &= h(0) - \bar{h} \\ \downarrow h(0) &= \bar{h} \\ &= 0 \end{aligned}$$

$$A[sH'(s) - \overset{0}{h'(0)}] = Q_i'(s) - \frac{1}{R_v} H'(s)$$

$$AsH'(s) + \frac{1}{R_v} H'(s) = Q_i'(s)$$

$$H'(s) = \frac{Q_i'(s)}{As + \frac{1}{R_v}} \cdot \frac{R_v}{R_v} = \frac{Q_i'(s) R_v}{AR_v s + 1}$$

$$G(s) = \frac{\text{out}}{\text{in}} = \frac{H'(s)}{Q_i'(s)} = \boxed{\frac{R_v}{AR_v s + 1}} = \frac{K}{\tau s + 1} \quad \left\{ \begin{array}{l} K \equiv R_v \\ \tau = AR_v \end{array} \right.$$

Use transfer function to predict step change

Seborg Ex. 4.1b Determine the response $h(t)$ to a step change in q_i of magnitude M at $t = 0$ using the transfer function

$$G(s) = \frac{\overset{\text{out}}{H'(s)}}{\overset{\text{input}}{Q'_i(s)}} = \frac{R_v}{AR_v s + 1}$$

- Rearrange for $\overset{\text{out}}{H'(s)}$ $H'(s) = \overset{\checkmark}{G(s)} \overset{\checkmark}{Q'_i(s)} = \frac{R_v}{AR_v s + 1} \cdot \frac{M}{s}$

- Determine $Q'_i(s)$ from $q'_i(t)$ $q'_i(t) = M \Rightarrow Q'_i(s) = \frac{M}{s}$

- Get deviation response in time space $h'(t) = \mathcal{L}^{-1}[H'(s)] = \mathcal{L}^{-1}\left[\frac{R_v M}{(AR_v s + 1)s}\right] = \mathcal{L}^{-1}\left[\frac{R_v M / AR_v}{(s + \frac{1}{AR_v})s}\right]$

- Get response in time space

$$\mathcal{L}^{-1} \frac{1}{(s+b_1)(s+b_2)}$$

$$= \frac{1}{b_1 - b_2} (e^{-b_2 t} - e^{-b_1 t})$$

$$b_1 = \frac{1}{AR_v}$$

$$b_2 = 0$$

$$= \frac{R_v M}{AR_v} \frac{1}{\frac{1}{AR_v} - 0} (e^0 - e^{-t/AR_v})$$

$$= \frac{M}{AR_v} (1 - e^{-t/AR_v})$$

$$= MR_v (1 - e^{-t/AR_v})$$

$$h(t) = h'(t) + \bar{h} = \boxed{MR_v (1 - e^{-t/AR_v}) - \bar{h}}$$