# LAWRENCE H. KIM

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# **OBJECTIVE**

I am a HRI researcher looking at how to design ubiquitous robotics for intuitive and natural integration into our everyday lives and to better complement humans through the use of mechatronics, robotics and haptics.

# **EDUCATION**

Solidworks/Floworks.

Stanford University	2016 - now
PhD Candidate, Mechanical Engineering	
Advisor: Sean Follmer	
Stanford University	2013 - 2015
Master of Science, Mechanical Engineering Advisor: Allison M. Okamura	
University of Illinois at Urbana-Champaign	2010 - 2013
Bachelor of Science, Mechanical Engineering, Highest Honors	2010 - 2013
RESEARCH	
Research Assistant, SHAPE Lab, Stanford University Advised by Prof. Sean Follmer	2015 - now
<ul> <li>Developed a new Swarm User Interface named Zooids with other colleagues.</li> <li>Designed human perception studies to better understand how people perceive abstract motion and haptic display from a swarm of robots.</li> </ul>	
<ul> <li>Created algorithm to autonomously build complex structure using robots.</li> <li>Designed and evaluated human tactile perception of mobile shape changing device.</li> </ul>	
Haptics Engineer, Building 8, Pro Unlimited @ Facebook Inc.	2017 Fall
Advised by Dr. Ali Israr & Dr. Frances Lau	
<ul> <li>Developed prototypes of novel haptic device to communicate speech through touch.</li> <li>Evaluated perceptibility and perception of various haptic stimuli (submission in progress).</li> </ul>	
Research Assistant, CHARM Lab, Stanford University Advised by Prof. Allison M. Okamura	2013 - 2014
<ul> <li>Set up the Raven surgical robot and studied effect of master-slave tool misalignments.</li> <li>Designed studies to test the trilateral shared control using Omni Phantom and Chai3d.</li> </ul>	
<b>Undergraduate Researcher</b> , Bretl Research Group, University of Illinois at Urbana Advised by Prof. Tim W. Bretl	2012 - 2013
• Designed flight control algorithm and developed novel attachement mechanism for drones.	
Research Intern, Urban Energy System Center, Korea Institute of Science and Technology Advised by Dr. Dae-Young Lee	Summer 2012
• Improved efficiency of hybrid desiccant cooling system.	G
Research Intern, Refrigeration and Cryogenics Lab, Kookmin University Advised by Prof. Byung Ha Kang	Summer 2011
• Built experiment apparatus and performed experiments for a desiccant cooling system.	2000 2010
Student Researcher, Filtration Group, Inc. Advised by Phil Winters	2008 - 2010
• Improved and verified design of room air cleaner and gas turbine air filter through	

#### AWARDS & HONORS

CHI Best Paper Honorable Mention (SwarmHaptics) MDPI Robotics Travel Award Stanford Bio-X Travel Award	2019 2019 2019
Fast Company: Innovation by Design: Honorable Mention	2017
UIST Best Paper Award ( <b>Zooids</b> )	2016
Samsung Scholarship, \$50,000/year for 5 years	2016 - now
Dean's List for Academic Excellence	2010 - 2013
National Merit Scholarship	2010 - 2013
Guy RIchard Collins Scholarship	2012
Advanced Placement Scholar with Honor	2009

# **PUBLICATIONS**

#### **JOURNAL**

- 2. VPS Tactile Display: Tactile Information Transfer of Vibration, Pressure, and Shear LH Kim, P Castillo, S Follmer & A Israr. IMWUT'19 Volume 3 June. [Acceptance rate = %]
- 1. UbiSwarm: Ubiquitous Robotic Interfaces and Investigation of Abstract Motion as a Display LH Kim, & S Follmer. IMWUT'17 Volume 1 September. [Acceptance rate = 9%]

## CONFERENCE

- 6. SwarmHaptics: Haptic Display with Swarm Robots LH Kim & S Follmer. CHI'19. [Acceptance rate = 24%] Best Paper Honorable Mention
- 5. Robotic Assembly of Haptic Proxy Objects for Tangible Interaction and Virtual Reality Y Zhao, LH Kim, Y Wang, M Le Goc & S Follmer. ISS'17. [Acceptance rate = 27%]
- 4. **Zooids: Building Blocks for Swarm User Interfaces.** M Le Goc, <u>LH Kim</u>, A Parsaei, JD Fekete, P Dragicevic, & S Follmer. *UIST'16*. [Acceptance rate = 21%] **Best Paper Award**
- 3. Haptic Edge Display for Mobile Tactile Interaction. S Jang, <u>LH Kim</u>, K Tanner, H Ishii, & S Follmer. *CHI'16*. [Acceptance rate = 23%]
- 2. Design and Evaluation of a Trilateral Shared-Control Architecture for Teleoperated Training Robots. K Shamaei, LH Kim, & AM Okamura. EMBC'15.
- 1. Effects of Master-Slave Tool Misalignment in a Teleoperated Surgical Robot. LH Kim, C Bargar, Y Che, & AM Okamura. ICRA'15. [Acceptance rate = 41%]

## WORKSHOP

1. **Interaction with Ubiquitous Robots and Autonomous IoT** <u>LH Kim</u>, & S Follmer. Workshop on New Directions for the IoT: Automate, Share, Build, and Care *CHI'19* 

## POSTERS & DEMOS

# Human Perception of Swarm Robot Motion.

Griffin Dietz, Jane L E., Peter Washington, <u>Lawrence H. Kim</u>, & Sean Follmer.

CHI Extended Abstracts May. 2017

### Zooids: Building Blocks for Swarm User Interfaces

Adobe Creative Lab Retreat at Stanford

UIST Demo

Oct. 2016

Center for Au	tomotive Research at Stanford (CARS) Annual Meeting potics Symposium	Dec. 2015 Oct. 2015
TEACHING		
	sual Thinking ant for Instructors John Edmark and Patrick Fenton	Autumn 2015
ENGR 105:	Introduction to Feedback Control  ant for Prof. Abbas Emami-Naeini	Spring 2015
	Introduction to Feedback Control ant for Prof. Allison M. Okamura and Inst. Adam Leeper	Winter 2015
MEDIA		
	varmHaptics: Haptic Display with Swarm Robots.	2019
_	ny Design, This Swarm Of Little Robots Is A Totally New Kind Of Interface.	2017
• ,	ooids - Swarm User Interface  kaday.com/2017/02/17/zooids-swarm-user-interface/	2017
NowThis Fu	ture, Check Out These Hive Mind Robots, >12M views facebook.com/NowThisFuture/videos/1310676325640211/	2016
	ker, Swarm of Tiny Robots, >4M views facebook.com/circuitbreaker/videos/1640944836198339/	2016
Adafruit, 'Zo	poids' are Open-Source, Open-Hardware 'Bots for 'Swarm User Interfaces' padafruit.com/2016/11/07/	2016
Makery, Zoo	ids: who are these cute robots?  makery.info/en/2016/11/28/zooids-mais-qui-sont-ces-robots-mignons/	2016
TechCrunch	, Swarms of tiny, cute robots will one day bring you your phone, like this crunch.com/2016/10/20/	2016
PROFESSION.	AL SERVICES	
Proceedings of World Haptic	Software and Technology Symposium (UIST) n Interactive, Mobile, Wearable and Ubiquitous Technologies (IMWUT) Symposium (WHC) mputational Design and Engineering	2019 2019 2019 2018
SKILLS		
Design Program Fabrication	Technical Pro/Engineering, Solidworks, Floworks, Adobe Photoshop, Illustrator C++, C, MATLAB, IATEX, Chai3D, MotionGenesis, Mambo, JAVA 3D printing, Laser cutting, PCB etching Languages	
Native	Languages English, Korean	

Haptic Edge Display for Mobile Tactile Interaction