# LAWRENCE KIM

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### RESEARCH INTERESTS

Human-Computer Interaction, Human-Robot Interaction, Human-Centered Design, Robotics, Haptics

#### **EDUCATION**

Stanford University
PhD Candidate, Mechanical Engineering
Thesis: Designing In Situ Interaction with Ubiquitous Robots
Committee: Sean Follmer, Allison Okamura, James Landay, Wendy Ju, Martin Fischer

Stanford University
Master of Science, Mechanical Engineering
University of Illinois at Urbana-Champaign
Bachelor of Science, Mechanical Engineering, Highest Honors

### RESEARCH EXPERIENCE

## SHAPE Lab, Stanford University

2015 - now

Research Assistant Stanford, CA

Research with Prof. Sean Follmer on interaction with ubiquitous robots and haptic devices.

Designed and built novel hardware platforms such as swarm robot platform and haptic devices.

Conducted human subject testings to quantify human perception and elicit qualitative inputs from users.

## Facebook Building 8 thru Pro Unlimited

2017 Fall

 $Research\ Intern$ 

Menlo Park, CA

Research with Dr. Ali Israr & Dr. Frances Lau on communication through touch.

Developed, and ran studies with new haptic device to enable speech communication through the skin.

## CHARM Lab, Stanford University

2013 - 2014

Research Assistant

Stanford, CA

Research with Allison M. Okamura on surgical robotics and trilateral shared control.

Evaluated effects of tool misalignment and trilateral shared control for robot teleoperation.

## Bretl Research Group, University of Illinois at Urbana

2012 - 2013

 $Under graduate\ Researcher$ 

Urbana, IL

Research with Tim W. Bretl on use of drone in construction sites.

Designed and developed attachment mechanism for drones to perch on construction beams.

## KAIST, Urban Energy System Center

2012 Summer

Research Intern

Seoul, Korea

Research with Dae-Young Lee on hybrid desiccant cooling system.

## **AWARDS & HONORS**

CHI Best Paper Honorable Mention (Top 5%)	2020
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Fast Company: Innovation by Design: Honorable Mention	2017
UIST Best Paper Award (Top 1%)	2016
Samsung Scholarship, \$50,000/year for 5 years	2016 - now
Computing Reviews: Notable Books and Articles	2016

## **PUBLICATIONS**

Premiere conference venues in human-computer interaction (e.g., ACM CHI and UIST) are highly selective. Unlike in many fields, these venues publish archival papers and are comparable to or exceed many HCI journals in terms of visibility and impact.

See: https://dl.acm.org/citation.cfm?id=1743546.1743569

#### **JOURNAL**

## 3. Lawrence H Kim, Sean Follmer

"Generating Legible Swarm Motion"

ACM Transactions on Human-Robot Interaction (THRI) '20. [In Preparation]

2. Lawrence H Kim, Pablo Castillo, Sean Follmer, Ali Israr

"VPS Tactile Display: Tactile Information Transfer of Vibration, Pressure, and Shear" *Proceedings of the ACM on Interactive, Mobile, Wearable and Ubiquitous Technologies (IMWUT)*. 3(2), 51, June 2019. (Presented at UbiComp 2019)

1. Lawrence H Kim, Sean Follmer

"UbiSwarm: Ubiquitous Robotic Interfaces and Investigation of Abstract Motion as a Display" Proceedings of the ACM on Interactive, Mobile, Wearable and Ubiquitous Technologies (IMWUT). 1(3), 66, Sep. 2017. (Presented at UbiComp 2017) [Acceptance rate = 9%]

### CONFERENCE

## 7. Best Paper Honorable Mention (Top 5%)

Lawrence H Kim, Daniel Drew, Vernoika Domova, Sean Follmer

"User-defined Swarm Robot Control"

Proceedings of the 2020 CHI Conference on Human Factors in Computing Systems (CHI). [Accepted]

6. Best Paper Honorable Mention (Top 5%)

Lawrence H Kim, Sean Follmer

"SwarmHaptics: Haptic Display with Swarm Robots"

Proceedings of the 2019 CHI Conference on Human Factors in Computing Systems. p.688. [Acceptance rate = 24%]

5. Yiwei Zhao, Lawrence H Kim, Ye Wang, Mathieu Le Goc, Sean Follmer

"Robotic Assembly of Haptic Proxy Objects for Tangible Interaction and Virtual Reality" In Proceedings of the 2017 ACM International Conference on Interactive Surfaces and Spaces (ISS). pp. 82-91. [Acceptance rate = 27%]

4. Best Paper Award (Top 1%)

Mathieu Le Goc, **Lawrence H Kim**, ..., Jean-Daniel Fekete, Pierre Dragicevic, Sean Follmer "Zooids: Building Blocks for Swarm User Interfaces"

In Proceedings of the 29th Annual Symposium on User Interface Software and Technology (UIST). pp. 97-109. [Acceptance rate = 21%]

3. Sungjune Jang, Lawrence H Kim, Kesler Tanner, Hiroshi Ishii, Sean Follmer

"Haptic Edge Display for Mobile Tactile Interaction"

In Proceedings of the 2016 CHI Conference on Human Factors in Computing Systems. pp. 3706-3716. [Acceptance rate = 23%]

2. Kamran Shamaei, Lawrence H Kim, Allison M Okamura

"Design and Evaluation of a Trilateral Shared-Control Architecture for Teleoperated Training Robots"

In 2015 37th Annual International Conference of the IEEE Engineering in Medicine and Biology Society (EMBC). pp. 4887-4893.

Lawrence H Kim, Cliff Bargar, Yuhang Che, Allison M Okamura
 "Effects of Master-Slave Tool Misalignment in a Teleoperated Surgical Robot"
 In 2015 IEEE International Conference on Robotics and Automation (ICRA). pp. 5364-5370. [Acceptance rate = 41%]

## WORKSHOP

1. Lawrence H Kim, Sean Follmer

"Interaction with Ubiquitous Robots and Autonomous IoT" Workshop on New Directions for the IoT: Automate, Share, Build, and Care, CHI'19

### POSTERS & DEMOS

"User-defined Swarm Robot Control" Bay Area Robotics Symposium (BARS)	2019
Griffin Dietz, Jane L E., Peter Washington, <b>Lawrence H Kim</b> , Sean Follmer. "Human Perception of Swarm Robot Motion"  Proceedings of the 2017 CHI Conference Extended Abstracts on Human Factors in Computing Systems	2017
"Zooids: Building Blocks for Swarm User Interfaces"  Adobe Creative Lab Retreat at Stanford  In Proceedings of the 29th Annual Symposium on User Interface Software and Technology  (UIST) Demo	2016 2016
"Haptic Edge Display for Mobile Tactile Interaction"  Center for Automotive Research at Stanford (CARS) Annual Meeting  Bay Area Robotics Symposium (BARS)	2015 2015

## **INVITED TALKS & DEMOS**

- 2. Interactive Tabletop Swarm Robots **Exploratorium**, After Dark Session: *Tactile*, San Francisco, CA January 2020
- 1. Interaction with Ubiquitous Robots and Autonomous Vehicles

  Hyundai Global Top Talent Forum, San Diego, CA, August 2019

### **TEACHING**

ME 101: Visual Thinking Course Assistant for Instructors John Edmark and Patrick Fenton	Autumn 2015
ENGR 105: Introduction to Feedback Control Course Assistant for Prof. Abbas Emami-Naeini	Spring 2015
ENGR 105: Introduction to Feedback Control Course Assistant for Prof. Allison M. Okamura and Inst. Adam Leeper	Winter 2015

### **MENTORING**

Yuqi Yao, Education Masters	2019 - now
Yiwei Zhao, ME Masters – now at Electronic Art (EA) Digital Platform	2016 - 2017
Ye Wang, ME/CS Coterm/undergraduate – now at Apple	2017
Ali Parsaei, ME Masters – now at Omron Automation	2015 - 2016

## PROFESSIONAL SERVICES

International Program Committee	Graphics Interface 2020
Reviewer	CHI 2020, DIS 2019, UIST 2019, WHC 2019, IMWUT 2018-2020, JCDE 2018
Outreach	Teacher, "Stories in Motion: Mechanical Automata and Rapid Prototyping", <b>Stanford's Splash Program</b> , Nov 2019
	Demo of haptic technology, Duncan Polytechnical High School's Health and Technology Pathways, May 2014
	Demo of haptic technology, Manteca High School's Health Science Pathway, April 2014

# SELECTED PRESS

Fast Company Design, This Swarm Of Little Robots Is A Totally New Kind Of Interface. www.fastcodesign.com/90136009	2017
<pre>Hackaday, Zooids - Swarm User Interface https://hackaday.com/2017/02/17/zooids-swarm-user-interface/</pre>	2017
NowThis Future, Check Out These Hive Mind Robots, >12M views https://www.facebook.com/NowThisFuture/videos/1310676325640211/	2016
Circuit Breaker, Swarm of Tiny Robots, >4M views https://www.facebook.com/circuitbreaker/videos/1640944836198339/	2016
${\bf Adafruit, 'Zooids' \ are \ Open-Source, \ Open-Hardware 'Bots \ for 'Swarm \ User \ Interfaces' \ https://blog.adafruit.com/2016/11/07/}$	2016
Makery, Zooids: who are these cute robots? http://www.makery.info/en/2016/11/28/zooids-mais-qui-sont-ces-robots-mignons/	2016
<b>TechCrunch</b> , Swarms of tiny, cute robots will one day bring you your phone, like this https://techcrunch.com/2016/10/20/	2016