

Stochastic Block Model Prior with Ordering Constraints for Gaussian Graphical Models

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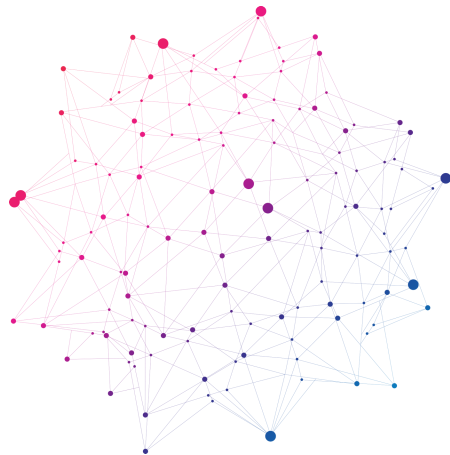
Bayesian Statistics
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BACKGROUND

GAUSSIAN GRAPHICAL MODELS

Models for the **conditional dependence structure** among variables, represented through an undirected graph $G = (V, E)$

$$\mathbf{y}_1, \dots, \mathbf{y}_n \mid \mathbf{K} \stackrel{\text{iid}}{\sim} \mathcal{N}_p(\mathbf{0}, \mathbf{K}^{-1})$$

Conditional independence described through a **map** between a **graph** and a family of multivariate **probability models**

$$Y_i \perp\!\!\!\perp Y_j \mid Y_{-(ij)} \iff (i, j) \notin E \iff k_{ij} = 0$$

Usual prior for \mathbf{K} conditionally to the graph is a G-Wishart

$$\mathbf{K} \mid G \sim \text{G-Wishart}(b, D)$$

G is a r.v. in the space of undirected graphs with p nodes.

If we assume a possible **grouping** of the variables, we need a prior $\pi(G)$ that induces a **block structure on its adjacency matrix**.

STOCHASTIC BLOCK MODELS FOR THE PRIOR ON G

Given a random network, SBM **infer a node partition** based on similarity of connectivity patterns. Let

- H be the fixed number of clusters
- $\mathbf{z} \in \mathbb{R}^p$ be the vector of group memberships, $z_i \in \{1, \dots, H\}$

Then the model of the graph conditionally on \mathbf{z} is the following

$$P((i, j) \in E \mid \mathbf{z}, Q) = Q_{z_i z_j}, \text{ independent}$$

$$Q_{rs} \stackrel{\text{ind}}{\sim} \text{Beta}(a, b), \quad 1 \leq r \leq s \leq H$$

$$\mathbf{z} \sim f_{\mathbf{z}}(\mathbf{z})$$

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Problems:

- How to **identify the number of clusters** H ?
- How to model **constraints on the ordering of the nodes** when generating the partition?

CHANGEPOINT MODELS

Let $\mathbf{y} = (y_1, \dots, y_n)$ be **ordered** observations, each depending on a parameter ϑ_i . Consider a process where the underlying generating mechanism changes at time τ_j , $j = 1, \dots, k + 1$, where τ_j, k are unknown. The likelihood can be modeled as

$$f(y_1, \dots, y_n \mid \vartheta_1, \vartheta_2, \dots, \vartheta_{k+1}, \mathbf{z}) = \prod_{j=1}^{k+1} \prod_{i=\tau_{j-1}+1}^{\tau_j} f(y_i \mid \vartheta_j), \quad k = \sum_{i=1}^{n-1} z_i$$

where τ_j are called **changepoints** and $z_i = 1$ if i is a changepoint, 0 otherwise. We are interested in **generating a random partition with ordering constraints**

$$\pi(\mathbf{z}, \boldsymbol{\vartheta} \mid \mathbf{y}) \propto f(\mathbf{y} \mid \boldsymbol{\vartheta}, \mathbf{z}) \pi(\boldsymbol{\vartheta} \mid \mathbf{z}) \pi(\mathbf{z})$$

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Martínez and Mena 2014 assign

$$P(\rho_p = \{C_1, \dots, C_M\}) = p'(n_1, \dots, n_k) = \begin{cases} \binom{n}{n_1, \dots, n_k} \frac{1}{k!} p(n_1, \dots, n_k), & \rho_p \text{ admissible} \\ 0, & \rho_p \text{ not admissible} \end{cases}$$

where $n_j = |C_j|$, $p(n_1, \dots, n_k)$ any Exchangeable Partition Probability Function (EPPF).

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The vector \mathbf{z} is derived by setting

$$z_i = m \iff i \in C_m, \quad i = 1, \dots, p, \quad m = 1, \dots, M.$$

PROJECT GOALS AND NEXT STEPS

GOAL OF THE PROJECT AND NEXT STEPS

Goal: propose a **new prior** that accounts for

- Ordering Constraint: taking advantage of the study of changepoint models
- Block Structure: using a stochastic block model prior

$$\mathbf{y}_1, \dots, \mathbf{y}_n \mid \mathbf{K} \stackrel{\text{iid}}{\sim} \mathcal{N}_p(\mathbf{0}, \mathbf{K}^{-1})$$

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Next steps:

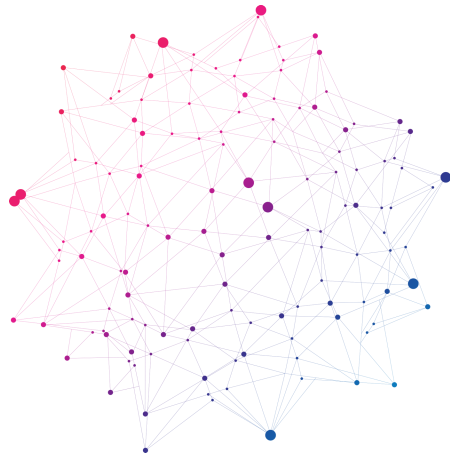
- understand the nonparametric prior on ordered partitions
- implement the sampling strategy

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Thank you!

Any questions?



STOCHASTIC BLOCK MODELS FOR THE PRIOR ON G

$$G_{ij} \mid \Theta, \mathbf{z} \stackrel{\text{iid}}{\sim} \text{Be}(\vartheta_{ij}), G \in \mathbb{R}^{p \times p}, \quad \vartheta_{ij} = \Theta_{z_i z_j}, \quad 1 \leq i < j \leq p$$

$$\Theta_{z_i z_j} \stackrel{\text{iid}}{\sim} \text{Beta}(\alpha, \beta)$$

$$\mathbf{z} \stackrel{\text{iid}}{\sim} \pi_{\mathbf{z}}(\mathbf{z}), \quad \mathbf{z} \in \mathbb{R}^p$$

Θ can be marginalized out via beta-binomial conjugacy.



CHOOSING THE NUMBER OF CLUSTERS H

H is usually chosen using data driven methods **before** estimating the model. However

- uncertainty quantification for H at this stage is ignored
- the model does not account for new clusters (**prediction**)

Among others, Legramanti et al. 2022 proposed the **Extended Stochastic Block Models (ESBM)**, which use priors for \mathbf{z} that naturally allow to adaptively modify the number of groups H , e.g.,

- Finite Dirichlet
- Infinite Dirichlet
- Finite mixtures with a random number of components

None of the ESBM models pose constraints on the ordering of the nodes when generating the partition, that may be of relevance in a real-life context (e.g., gene expression).