

Stochastic Block Model Prior with Ordering Constraints for Gaussian Graphical Models

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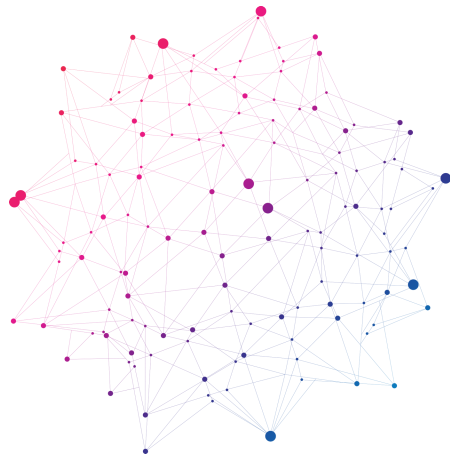
Bayesian Statistics
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THE MODEL

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$$\mathbf{y}_1, \dots, \mathbf{y}_n \mid \mathbf{K} \stackrel{\text{iid}}{\sim} \mathcal{N}_p(\mathbf{0}, \mathbf{K}^{-1})$$

$$\mathbf{K} \mid G \sim \text{G-Wishart}(b, D)$$

$$P((i, j) \in E \mid \mathbf{z}, Q) = Q_{z_i z_j}, \text{ independent}$$

$$Q_{rs} \mid \mathbf{z} \stackrel{\text{ind}}{\sim} \text{Beta}(\alpha, \beta), 1 \leq r \leq s \leq M$$

$$\rho \sim f_\rho(\rho)$$

Notation for the partition: ρ vector of cardinalities, \mathbf{z} vector of groups memberships.

The prior for the **partition** $f_\rho(\rho)$ is (5) from Martínez and Mena 2014.

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The prior for the **graph** given the vector of group memberships is

$$P(G \mid \mathbf{z}) = \prod_{u=1}^M \prod_{v=u}^M \frac{B(\alpha + S_{uv}, \beta + S_{uv}^*)}{B(\alpha, \beta)}$$

where

- S_{uv} is the sum of the edges between group u and v .
- S_{uv}^* is the sum of the “non-edges”, namely $S_{uv}^* = T_{uv} - S_{uv}$ and T_{uv} is the total number of possible edges.

THE SAMPLING STRATEGY

BLOCK GIBBS SAMPLER

Conditional distributions for our model:

| | |
|---------------------|--|
| Graph and Precision | $P(\mathbf{K}, G \mid \mathbf{Y}, \mathbf{z}) \propto P(\mathbf{Y} \mid \mathbf{K})P(\mathbf{K} \mid G)P(G \mid \mathbf{z})$ |
|---------------------|--|

| | |
|------------------|---|
| Random Partition | $P(\mathbf{z} \mid \mathbf{Y}, \mathbf{K}, G) \propto P(\mathbf{Y} \mid \mathbf{K})P(\mathbf{K} \mid G)P(G \mid \mathbf{z})P(\mathbf{z}) \propto P(G \mid \mathbf{z})P(\mathbf{z})$ |
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We implement a Block Gibbs-Sampler strategy:

1. **Sampling Graph and Precision Matrix**

G and \mathbf{K} - given \mathbf{z} - are sampled using a modified version of a Birth-and-Death chain (Mohammadi and Wit 2015), changing one link at a time.

2. **Sampling the Random Partition**

Conditionally on G , we can sample \mathbf{z} through an adaptive split and merge sampler.

BIRTH AND DEATH ALGORITHM FOR UPDATING THE GRAPH

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| | Target distribution | B/D rates |
|--------|--|--|
| Before | $P(G, \mathbf{K} \mid \mathbf{Y}) \propto \mathcal{L}(\mathbf{Y} \mid \mathbf{K})\mathcal{L}(\mathbf{K} \mid G)P(G)$ | $\frac{P(G')}{P(G)}$ |
| After | $P(G, \mathbf{K} \mid \mathbf{Y}, \mathbf{z}) \propto \mathcal{L}(\mathbf{Y} \mid \mathbf{K})\mathcal{L}(\mathbf{K} \mid G)P(G \mid \mathbf{z})$ | $\frac{P(G' \mid \mathbf{z})}{P(G \mid \mathbf{z})}$ |

where $G' = G^{\pm e}$ and e is an edge.

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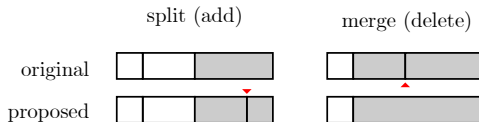
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where $G' = G^{\pm e}$ and e is an edge.

$$\text{Birth rate} \propto \frac{P(G^{+e} \mid \mathbf{z})}{P(G \mid \mathbf{z})} = \frac{S_{uv} + \alpha}{S_{uv}^* + \beta} \quad \text{Death rate} \propto \frac{P(G^{-e} \mid \mathbf{z})}{P(G \mid \mathbf{z})} = \frac{S_{uv}^* + \beta}{S_{uv} + \alpha}$$

GENERAL STEPS FOR UPDATING THE PARTITION

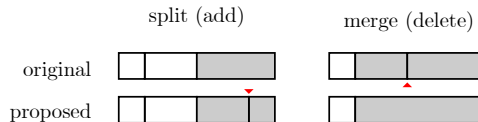
We perform an adaptive **split and merge**.



1. With probability α_{split} , usually 0.5, choose an **split move**, otherwise a **merge move**. Unless we are forced by extreme cases.
 - 1.1 Propose a new partition by splitting one group into two or merging two adjacent.
 - 1.2 Accept or reject using Metropolis Hastings. The target is: $f(\rho \mid G) \approx f_G(G \mid \rho)f_\rho(\rho)$

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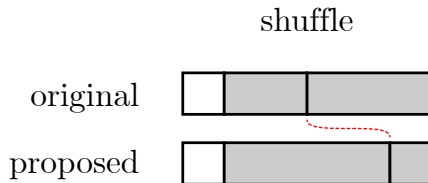


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$$\alpha_{\text{accept}} = \min \left\{ 1, \underbrace{\frac{f_G(G \mid \rho')}{f_G(G \mid \rho)}}_{\text{graph ratio}} \underbrace{\frac{f_\rho(\rho')}{f_\rho(\rho)}}_{\text{partition ratio}} \underbrace{\frac{Q(\rho', \rho)}{Q(\rho, \rho')}}_{\text{proposal ratio}} \right\}$$

SHUFFLE MOVE

2. To improve the mixing of the chain we also perform a **shuffle move**.
 - 2.1 Propose a new partition by moving some nodes from a group to an adjacent one.
 - 2.2 Accept or reject using Metropolis Hastings.



PROPOSAL RATIO

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$$\frac{Q(\rho', \rho)}{Q(\rho, \rho')} = \frac{P(\text{choose merge})}{P(\text{choose split})} \cdot \frac{P(\text{merge at node } i)}{P(\text{split at node } i)} = \frac{1 - \alpha_{\text{split}}}{\alpha_{\text{split}}} \cdot \frac{\frac{d_i^{(t)}}{d^\star + d_i^{(t)}}}{\frac{a_i^{(t)}}{a^\star}}$$

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The extreme cases “every node belonging to the same group” and “every node has its own group” are dealt with separately.

ADAPTIVE STEP

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- If a **split** move at node i has been accepted, then update:

$$\log(a_i^{(t+1)}) = \log(a_i^{(t)}) + \frac{h}{t/p}(\alpha_{\text{split}} - \alpha_{\text{target}}).$$

- If a **merge** move at node i has been accepted, then update:

$$\log(d_i^{(t+1)}) = \log(d_i^{(t)}) + \frac{h}{t/p}(\alpha_{\text{merge}} - \alpha_{\text{target}}).$$

Where $h > 0$ is the initial adaptation, t/p are the iterations (t) per number of nodes (p), α_{target} is the target MH acceptance rate and $\alpha_{\text{merge}} = 1 - \alpha_{\text{split}}$.

NEXT STEPS






NEXT STEPS

The first draft of the code is completed.

Next things to do:

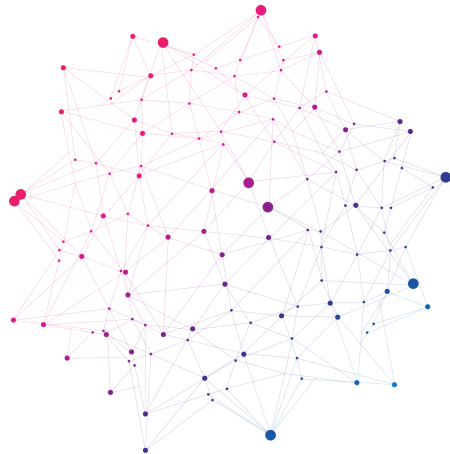
- Debugging the code.
- Run simulations.
- Perform posterior analysis.

MAIN REFERENCES

-  Benson, A. and N. Friel (2018). "Adaptive MCMC for Multiple Changepoint Analysis with Applications to Large Datasets". In: Electronic Journal of Statistics 12.2.
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Thank you!

Any questions?



PARTITION RATIO

As a prior, we use an EPPF induced by the **two-parameter Poisson-Dirichlet** process (Pitman-Yor process) from Martínez and Mena 2014.

Let M and p be the number of groups and nodes, respectively, and $n_j, j = 1, \dots, M$ the cardinalities of the groups, ϑ and σ are parameters.

$$P(\rho = \{n_1, \dots, n_M\}) = \begin{cases} \frac{p!}{M!} \frac{\prod_{i=1}^{M-1} (\vartheta + i\sigma)}{(\vartheta+1)_{(p-1)\uparrow}} \prod_{j=1}^M \frac{(1-\sigma)_{(n_j-1)\uparrow}}{n_{j\uparrow}}, & \rho \text{ admissible} \\ 0, & \rho \text{ not admissible.} \end{cases}$$

Hence, in the split case, after simplifying common factors, the **partition ratio** is:

$$\frac{f_\rho(\rho')}{f_\rho(\rho)} = \frac{1}{M} (\vartheta + M\sigma) \frac{(1-\sigma)_{(n'_s-1)\uparrow} (1-\sigma)_{(n'_s+1)\uparrow}}{(1-\sigma)_{(n_s-1)\uparrow}} \frac{n_s!}{n'_s! n'_{s+1}!}$$

GRAPH RATIO

Suppose a split move.

The **graph ratio**, after simplifying common factors, is:

$$\frac{f_G(G \mid \rho')}{f_G(G \mid \rho)} = \left(\frac{1}{B(\alpha, \beta)} \right)^{M+1} \times \frac{\prod_{l=1}^{S-1} f_B(C'_l, C'_S) f_B(C'_l, C'_{S+1}) \cdot \prod_{m=S+2}^{M+1} f_B(C'_S, C'_m) f_B(C'_{S+1}, C'_m) \cdot f_B(C'_S, C'_{S+1}) f_B(C'_S, C'_S) f_B(C'_{S+1}, C'_{S+1})}{\prod_{l=1}^{S-1} f_B(C_l, C_S) \prod_{m=S+1}^M f_B(C_S, C_m) \cdot f_B(C_S, C_S)}$$

where

$$f_B(C_u, C_v) = B(\alpha + S_{uv}, \beta + S_{uv}^*)$$