

# Introduction to Descriptive Complexity Theory

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# Descriptive complexity theory

- a branch of **computational complexity theory** and **finite model theory**
- characterizes *complexity classes* by the type of *logic* needed to express the languages in them.

Main results by Fagin, Immerman, Vardi, and others.

## Definition 9.5

Let  $\mathcal{K}$  be a complexity class,  $\mathcal{L}$  a logic, and  $\mathcal{C}$  a class of finite structures.  $\mathcal{L}$  captures  $\mathcal{K}$  on  $\mathcal{C}$  if

- $\left( \mathfrak{A} \stackrel{?}{\models} \varphi \right) \in \mathcal{K}$ , with  $\varphi$  sentence in  $\mathcal{L}$ ,  $\mathfrak{A} \in \mathcal{C}$ ,
- for any  $\mathcal{P} \subseteq \mathcal{C}$  s.t.  $\left( \mathfrak{A} \stackrel{?}{\in} \mathcal{P} \right) \in \mathcal{K}$ , exists  $\varphi_{\mathcal{P}}$  sentence in  $\mathcal{L}$  s.t.

$$\mathfrak{A} \models \varphi_{\mathcal{P}} \iff \mathfrak{A} \in \mathcal{P}$$

Why?

- machine-independent characterization of complexity classes;
- proving separation of complexity classes (es.  $\mathbf{P} \stackrel{?}{=} \mathbf{NP}$ ).

$\mathcal{L}_1$  captures  $\mathcal{K}_1$ ,  $\mathcal{L}_2$  captures  $\mathcal{K}_2$ ,  $\mathcal{L}_1 = \mathcal{L}_2 \iff \mathcal{K}_1 = \mathcal{K}_2$ .

### Definition 7.3

Existential SO logic, or  $\exists\text{SO}$ , is defined as the restriction of SO that consists of the formulae of the form  $\exists X_1 \dots \exists X_n \varphi$ , with  $\varphi \in \text{FO}$ .

Analogous definition for universal SO logic, or  $\forall\text{SO}$ .

A more intuitive notation could be  $\exists^{\text{SO}}\text{FO}$  and  $\forall^{\text{SO}}\text{FO}$ .

### Theorem 9.6 (Fagin)

$\exists\text{SO}$  captures **NP**.

### Corollary 9.7

$\forall\text{SO}$  captures **coNP**.

*Steps of the proof.*

- ①  $\varphi \in \exists\text{SO} \implies \left( \mathfrak{A} \stackrel{?}{\models} \varphi \right) \in \mathbf{NP}$
- ② for any  $\mathcal{P}$  s.t.  $\left( \mathfrak{A} \stackrel{?}{\in} \mathcal{P} \right) \in \mathbf{NP}$ , exists  $\varphi_{\mathcal{P}} \in \exists\text{SO}$  s.t.

$$\mathfrak{A} \models \varphi_{\mathcal{P}} \iff \mathfrak{A} \in \mathcal{P}$$

*Proof.*

- ① Let  $\varphi_{\mathcal{P}} = \exists S_1 \dots \exists S_n \psi$ , with  $\psi \in \text{FO}$ . Given  $\mathfrak{A}$ , an NTM can guess non deterministically  $S_1, \dots, S_n$ , then decides if  $\mathfrak{A} \models \psi(S_1, \dots, S_n)$  in polynomial time in  $||\mathfrak{A}||$  plus the size of  $S_1, \dots, S_n$ .

- ② Let  $\mathcal{P}$  be a property of  $\sigma$ -structures that can be tested by a polynomial NTM  $M = (Q, \Sigma, \Delta, \delta, q_0, Q_a, Q_r)$  that has a one-way infinite tape and runs in  $n^k$ .

Let  $\sigma' = \sigma \cup \{\leq^2\} \cup \{(T_a)^{2k} \mid a \in \Delta\} \cup \{(H_q)^{2k} \mid q \in Q\}$ .

Intended meaning:

- $\leq$  is a linear order on the universe.
- $\leq_k$  is the lexicographic linear order on  $k$ -tuples (defined on  $\leq$ ).
- Positions on the tape ( $\vec{p}$ ) and time ( $\vec{t}$ ) by  $k$ -tuples of the elements of the universe.
- $\{T_a\}$  are *tape* predicates:  $T_a(\vec{p}, \vec{t})$  indicates that position  $\vec{p}$  at time  $\vec{t}$  contains  $a$ .
- $\{H_q\}$  are *head* predicates:  $H_q(\vec{p}, \vec{t})$  indicates that at time  $\vec{t}$ , the machine is in state  $q$ , and its head is in position  $\vec{p}$ .

Let  $\varphi_{\mathcal{P}} = \exists L \exists T_{a_1} \dots \exists T_{a_n} \exists H_{q_0} \dots H_{q_{m-1}} \psi$  sentence over  $\sigma'$ , with  $\psi \in \text{FO}$ .  $\psi$  the conjunction of the sentences expressing the following properties:

- $L$  is a linear order ( $\leq$ );
- in every configuration of  $M$ , each cell of the tape contains exactly one element of  $\Delta$ ;
- at any time the machine is in exactly one state;
- eventually,  $M$  enters a state  $q \in Q_a$ ;
- $\{T_a\}$  and  $\{H_q\}$  relations respect the transition of  $M$ :

$$\forall a \in \Delta: \forall q \in Q: \bigvee_{(q', b, m) \in \delta(q, a)} \alpha(q, a, q', b, m),$$

where  $m \in \{l, -, r\}$ , and  $\alpha(q, a, q', b, m)$  is the sentence describing the transition in which upon reading  $a$  in state  $q$ , the machine writes  $b$ , makes the move  $m$ , and enters state  $q'$ .

- At the beginning of the computation, the input tape contains  $\text{enc}(\mathfrak{A})$ . Suppose  $\iota(\vec{p})$  and  $\xi(\vec{p})$  are formulas such that:
  - $\mathfrak{A} \models \iota(\vec{p})$  iff the  $\vec{p}$ th position of  $\text{enc}(\mathfrak{A})$  is 1;

- $\mathfrak{A} \models \xi(\vec{p})$  iff  $\vec{p}$  exceeds the length of  $enc(\mathfrak{A})$ .

$$\forall \vec{p} \forall \vec{t} \left( \neg \exists \vec{u} (\vec{u} \leq_k \vec{t}) \rightarrow \begin{matrix} (\iota(\vec{p}) \leftrightarrow T_1(\vec{t}, \vec{p})) \\ \wedge (\xi(\vec{p}) \leftrightarrow T_{\#}(\vec{t}, \vec{p})) \end{matrix} \right)$$





Solving  $\exists\text{SO} \stackrel{?}{=} \forall\text{SO} \implies$  interesting results:

- $\exists\text{SO} \neq \forall\text{SO} \implies \mathbf{NP} \neq \mathbf{coNP} \implies \mathbf{P} \neq \mathbf{NP}$
- $\exists\text{SO} = \forall\text{SO} \implies \mathbf{NP} = \mathbf{coNP} \implies \Sigma_n\mathbf{P} = \Pi_n\mathbf{P} = \Delta_n\mathbf{P} = \mathbf{NP}$

The polynomial hierarchy collapses to the first level!

(see Papadimitriou 1994, Theorem 17.9)

How to prove  $\exists\text{SO} \neq \forall\text{SO}$ ? Find a property  $\mathcal{P}$  expressible in  $\exists\text{SO}$  but not in  $\forall\text{SO}$  (or vice versa).

Some related results:

- on some infinite structures (e.g.,  $\langle \mathbb{N}, +, \cdot \rangle$ ) is known that  $\exists\text{SO} \neq \forall\text{SO}$ ;
- $\exists\text{MSO} \neq \forall\text{MSO}$ .

### Definition 7.3

Existential monadic SO logic, or  $\exists\text{MSO}$ , and universal monadic SO logic, or  $\forall\text{MSO}$ , are defined as the restrictions of  $\exists\text{SO}$  and  $\forall\text{SO}$  respectively where all second-order quantifiers have arity 1.

### Proposition 7.14 (Fagin, Stockmeyer, and M. Vardi 1995)

Graph connectivity is expressible in  $\forall\text{MSO}$ , but is not expressible in  $\exists\text{MSO}$ .

Hence,  $\exists\text{MSO} \neq \forall\text{MSO}$ .

Fagin's theorem can be extended to

- other fragments of **second order logic**
- and other computational classes in the **polynomial hierarchy**.

Which classes?  $\Sigma_k^1, \Pi_k^1 \subseteq \text{SO}$  and  $\Sigma_k^P, \Pi_k^P \subseteq \text{PH}$ .

# $\Sigma_k^1$ and $\Pi_k^1$ , fragments of SO

## Remark

$$\exists\text{SO} = \{(\exists \dots \exists)(\varphi) \mid \varphi \in \text{FO}\}, \quad \forall\text{SO} = \{(\forall \dots \forall)(\varphi) \mid \varphi \in \text{FO}\}.$$

## Definition (Väänänen 2020, Section 4)

$\Sigma_k^1$  and  $\Pi_k^1$  are defined as the restrictions of SO that consist of the formulae of the forms

$$\underbrace{(\exists \dots \exists)(\forall \dots \forall)(\exists \dots \exists) \dots}_k (\varphi) \quad \text{and} \quad \underbrace{(\forall \dots \forall)(\exists \dots \exists)(\forall \dots \forall) \dots}_k (\varphi)$$

respectively, with  $\varphi \in \text{FO}$ . Also,  $\Delta_k^1 = \Sigma_k^1 \cup \Pi_k^1$ .

## Examples

$$\text{FO} = \Sigma_0^1 = \Pi_0^1 = \Delta_0^1, \quad \exists\text{SO} = \Sigma_1^1, \quad \forall\text{SO} = \Pi_1^1.$$

## $\Sigma_k^P$ and $\Pi_k^P$ , computational classes in **PH**

### Definition 14.3 (Papadimitriou 1994)

A **Turing machine  $M^?$  with oracle** is a machine that includes a *query string*, and three special states:  $q_?$ , the *query state*, and  $q_{YES}$ ,  $q_{NO}$ , the *answer states*.

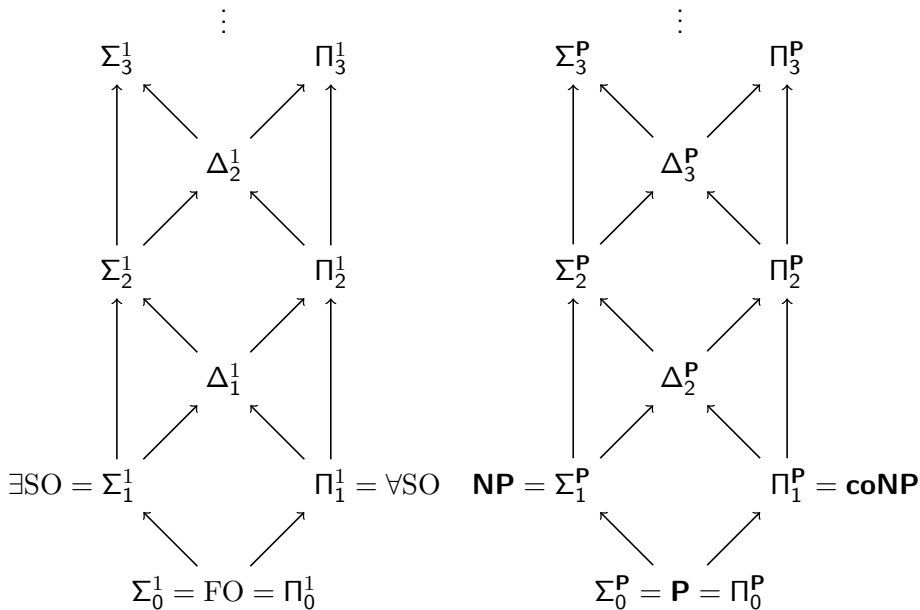
The computation of oracle machine  $M^?$  with oracle  $A \subseteq \Sigma^*$  proceeds ordinarily, except that the machine moves from the query state to one of the answer states depending on whether the current query string is in  $A$  or not.

$\mathcal{C}'$  the class of all languages decided by machines having the same resources bounds as in  $\mathcal{C}$ , using as oracle a language of  $\mathcal{C}'$ .

### Definition 17.2 (Papadimitriou 1994)

$$\Delta_0^P = \Sigma_0^P = \Pi_0^P = P.$$

$$\Delta_{k+1}^P = P^{\Sigma_k^P}, \Sigma_{k+1}^P = NP^{\Sigma_k^P}, \Pi_{k+1}^P = coNP^{\Sigma_k^P}. \quad \mathbf{PH} = \bigcup_{k \geq 0} \Sigma_k^P$$



## Corollary 9.9

For each  $k \geq 1$ ,

- $\Sigma_k^1$  captures  $\Sigma_k^P$ , and
- $\Pi_k^1$  captures  $\Pi_k^P$ .

In particular,  $\Sigma_0^1$  captures **PH**.

*Proof.*

The base case is Fagin's theorem. If we consider a problem in  $\Sigma_{k+1}^P = \mathbf{NP}^{\Sigma_k^P}$ , there is an  $\exists\text{SO}$  sentence  $\varphi$  with additional predicates expressing  $\Sigma_k^P$  properties. We know, by inductive hypothesis, that these properties are definable by  $\Sigma_k^1$ . Then pushing the second-order quantifier outwards, we convert  $\varphi$  into a  $\Sigma_{k+1}^1$  sentence.



## Example

$$\exists x (P(x) \wedge \neg \exists y (xRy)) \longrightarrow \exists x \forall y (P(x) \wedge \neg xRy)$$

Note that the corollary does **not** imply FO captures **P**!

### Theorem

There are logics that capture **P** over the class of **ordered** structures (M. Y. Vardi 1982, Immerman 1986), such as Horn- $\exists$ SO (Grädel 1991, Papadimitriou 1994).

### Conjecture (Gurevich 1988)

There is no logic that captures **P** over the class of **all** finite structures.

Finding a logic that captures **P** *may* solve  $\mathbf{P} \stackrel{?}{=} \mathbf{NP}$ .



$$\begin{array}{ccc}
 \exists\text{SO} = \forall\text{SO} & \iff & \mathbf{NP} = \mathbf{coNP} \\
 \Downarrow & & \Downarrow \\
 \text{SO} = \exists\text{SO} & \iff & \mathbf{PH} = \mathbf{NP}
 \end{array}$$

# References I

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