

No Labels? No problem! Unsupervised Domain Adaptation for Real World Person Re-Identification

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Definition

Person Re-Identification is an image retrieval task, where the object in the images are people.



Motivation

Regardless of the scenario or camera, the goal of person Re-ID is **Matching person images from different non-overlapping cameras views**. However, the addition of a new camera view normally has a direct impact in the algorithm performance, and this is a roadblock for diverse real-world applications.



Objectives

In this work, we aim to create person Re-ID framework capable of learning robust representations from non-annotated data. To achieve that, we set 3 auxiliary goals:

1. Implement a baseline domain adaptation method to start from;
2. Identify the flaws in our baseline domain adaptation method and propose techniques to undermine them;
3. Improve our proposed methods and compare them with the state-of-the-art algorithms.

Contributions

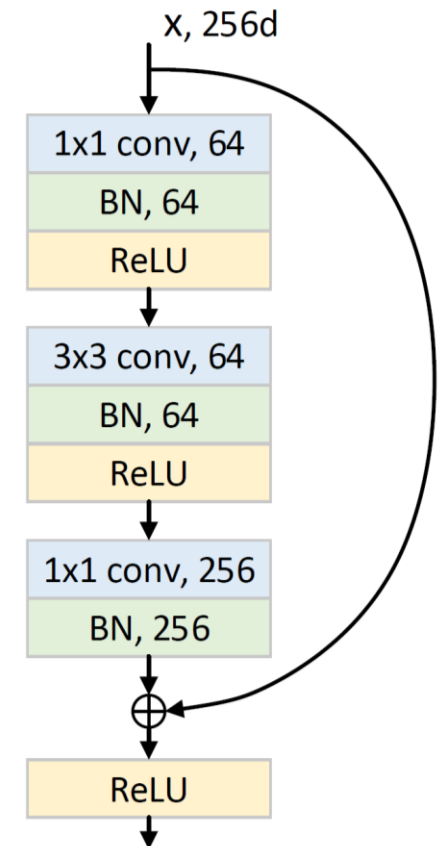
While working towards our goals, we proposed some techniques that generated the following publications:

- Pereira, T. and de Campos, T. Domain Adaptation for Person Re-identification on New Unlabeled Data (**best student paper award winner** at VISAPP 2020) [1]
- Pereira, T. and de Campos, T. Domain adaptation for person re-identification on new unlabeled data using AlignedReID++ (currently under review at IJPRAI) [2]
- Pereira, T. and de Campos, T. Learn by Guessing: Multi-Step Pseudo-Label Refinement for Person Re-Identification [3]

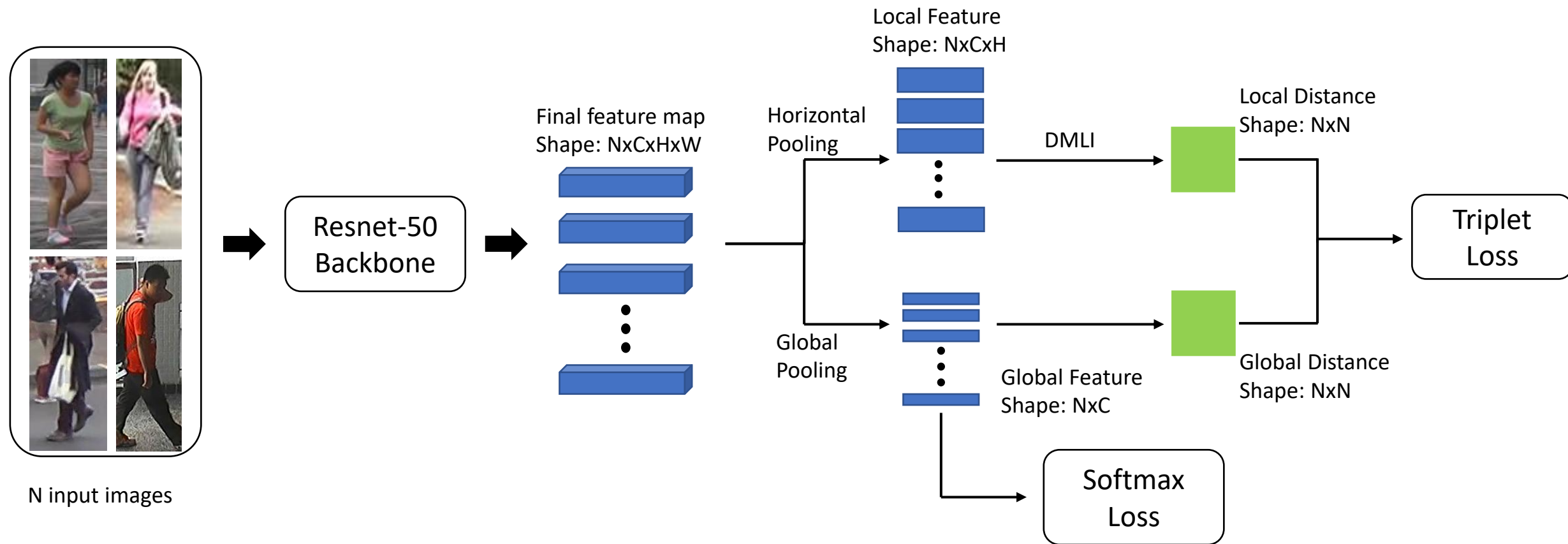
Model Architectures – Resnet 50 [4]

For the person Re-ID challenge, we need a feature extractor that can encode person information while disregarding camera variations and background noise. Therefore, architectures designed for image classification, like Resnet-50, are an excellent starting point.

We believe that Resnet-50 is the best choice, because the residual blocks are capable of efficiently propagating information of multiple semantic levels.

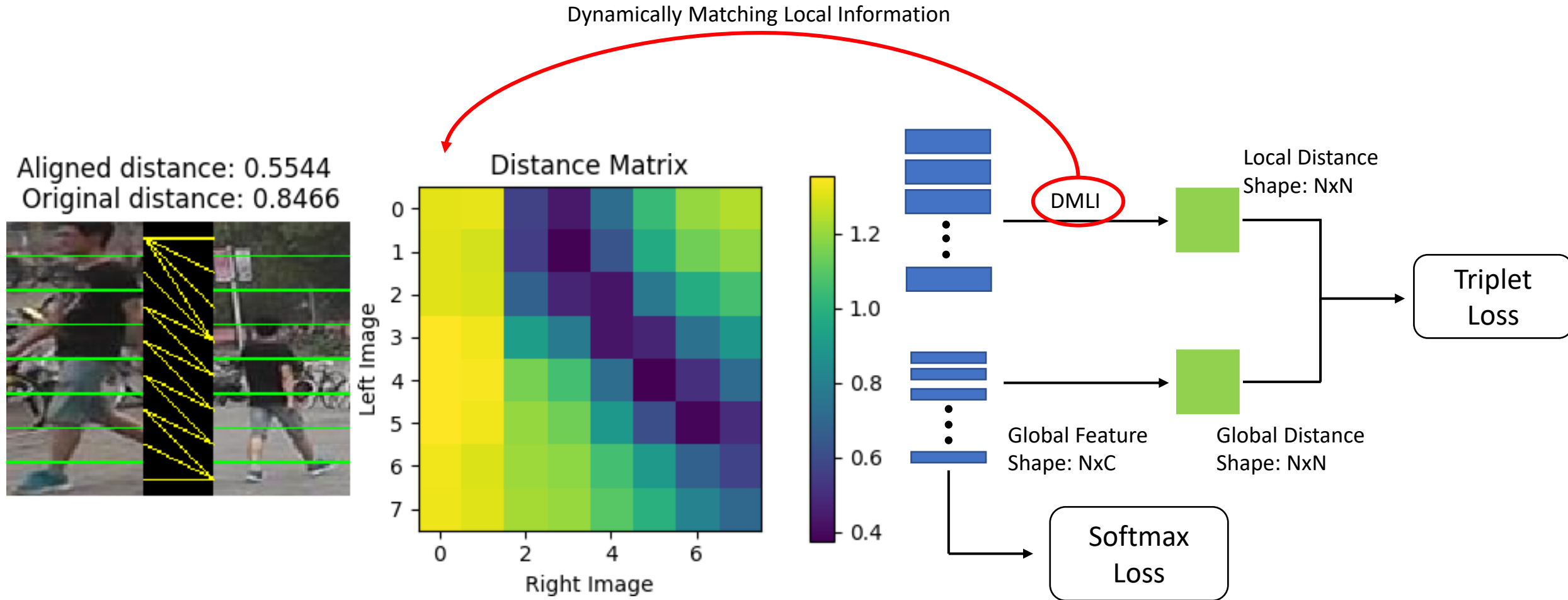


Model Architectures – Aligned ReID++ [5]



[5] Luo, H. et al. : AlignedReID++: Dynamically matching local information for person re-identification. Pattern Recognition, 2019.

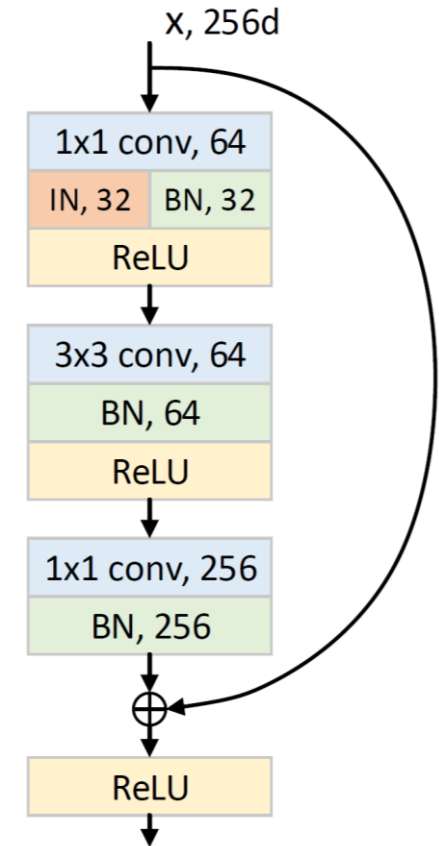
Model Architectures – Aligned ReID++



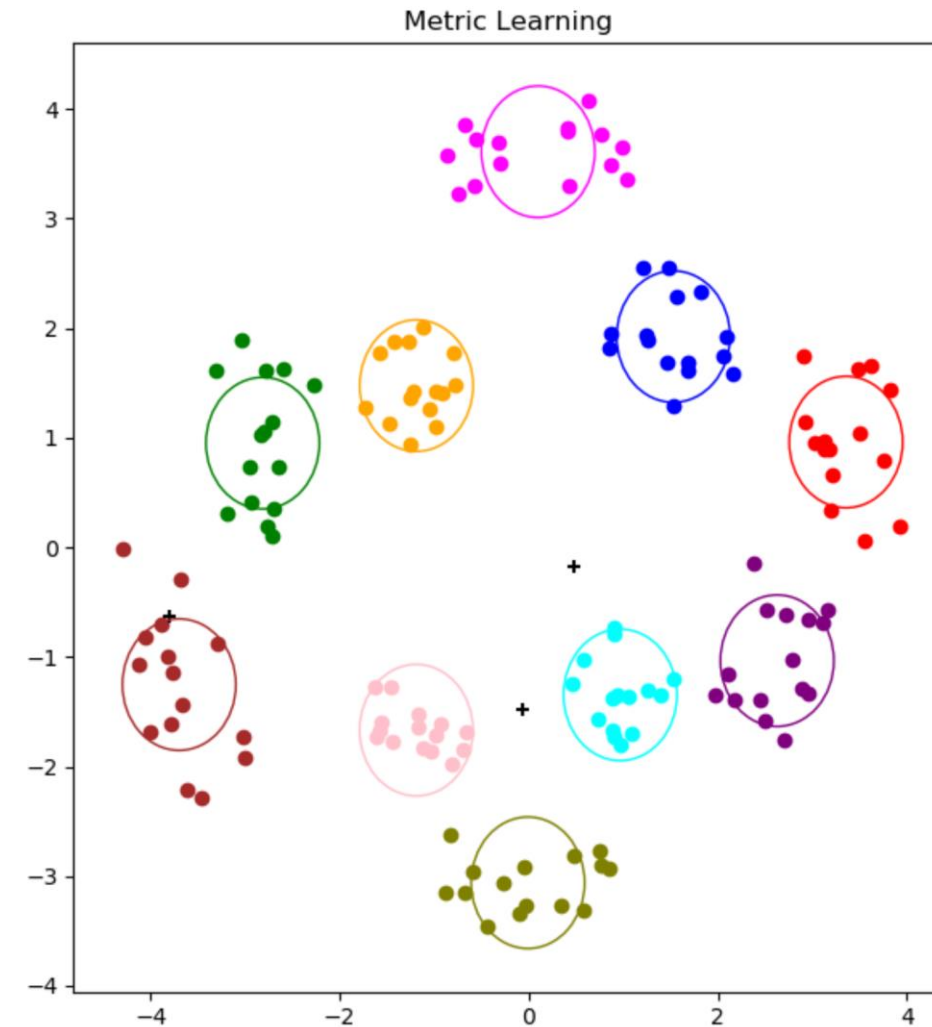
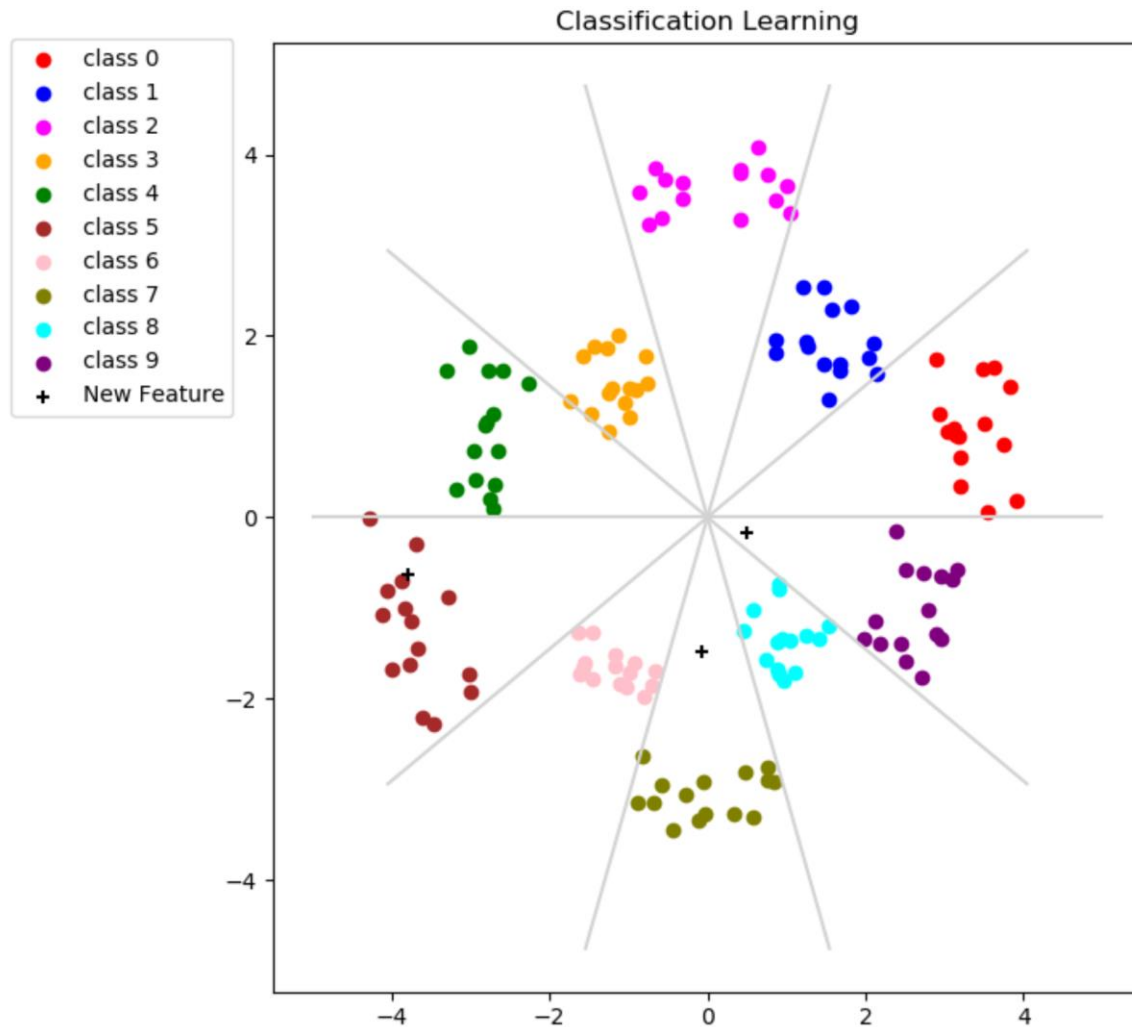
Model Architectures – IBN Net-50 a [6]

The standard Resnet-50 and the AlignedReID++ have some flaws that we can undermine using the IBN Net 50-a.

- The standard Resnet-50 lacks generalization capacity for problems with multiple datasets;
- Aligned ReID++ increased the computational cost for training and evaluating. Furthermore, their DMLI algorithm was too heavy to generate pseudo-labels.

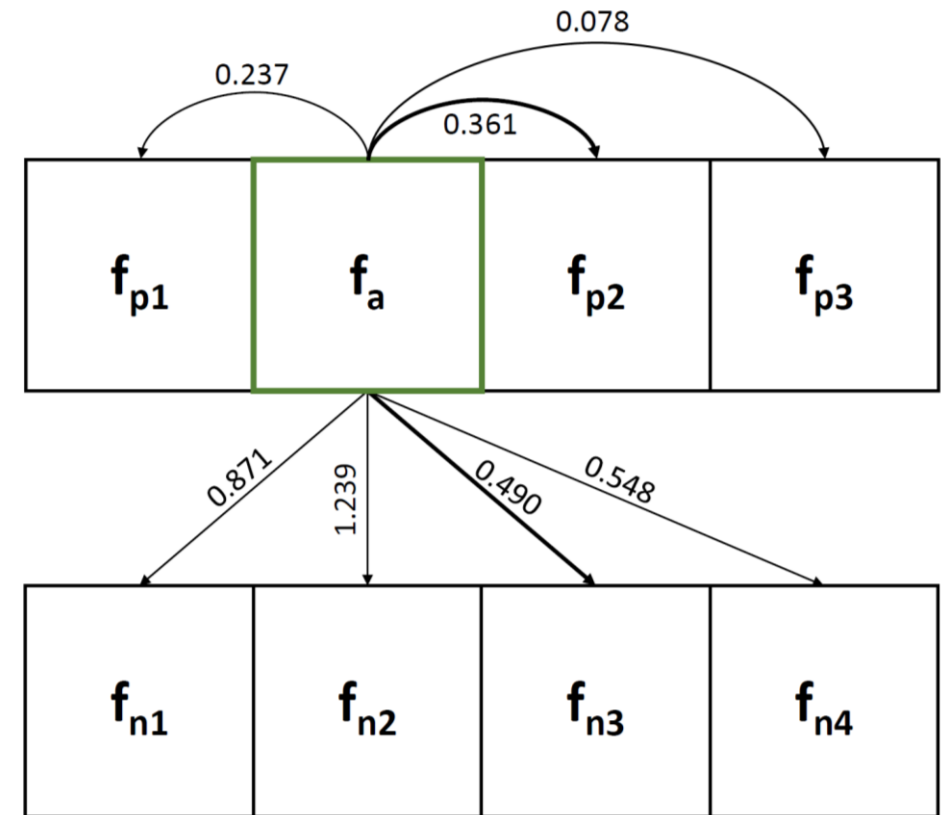


Metric Learning vs. Classification Learning



Triplet Loss & Batch hard

- The Triplet Loss is responsible for producing output vectors that belong to a Euclidean feature space;
- It is better than the contrastive loss, once it can push pairs from different people away while pulling feature pairs from same people together;
- **Challenge:** How to choose the best triplets? Based on Hermans et al. [7] work batch hard is the best approach.



Viper Dataset [8]

	Viper
Release Year	2007
Samples	1264
Identities	632
Cameras	2
Avg Number of Cameras Passed per Identity	2
Scene	outdoor



[8] Gray, D. et al.: Evaluating appearance models for recognition, reacquisition, and tracking. In In IEEE International Workshop on Performance Evaluation for Tracking and Surveillance, 2007.

CUHK03 Dataset [9]

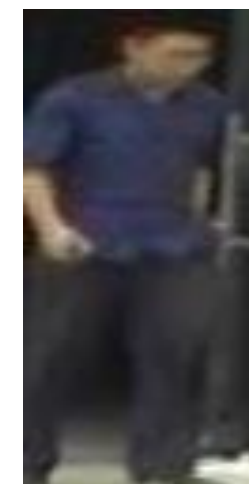
	CUHK03
Release Year	2014
Samples	28192
Identities	1467
Cameras	2
Avg Number of Cameras Passed per Identity	2
Scene	indoor



[9] Li, W. et al.: DeepReID: Deep Filter Pairing Neural Network for Person Re-identification. CVPR, 2014.

Market1501 Dataset [10]

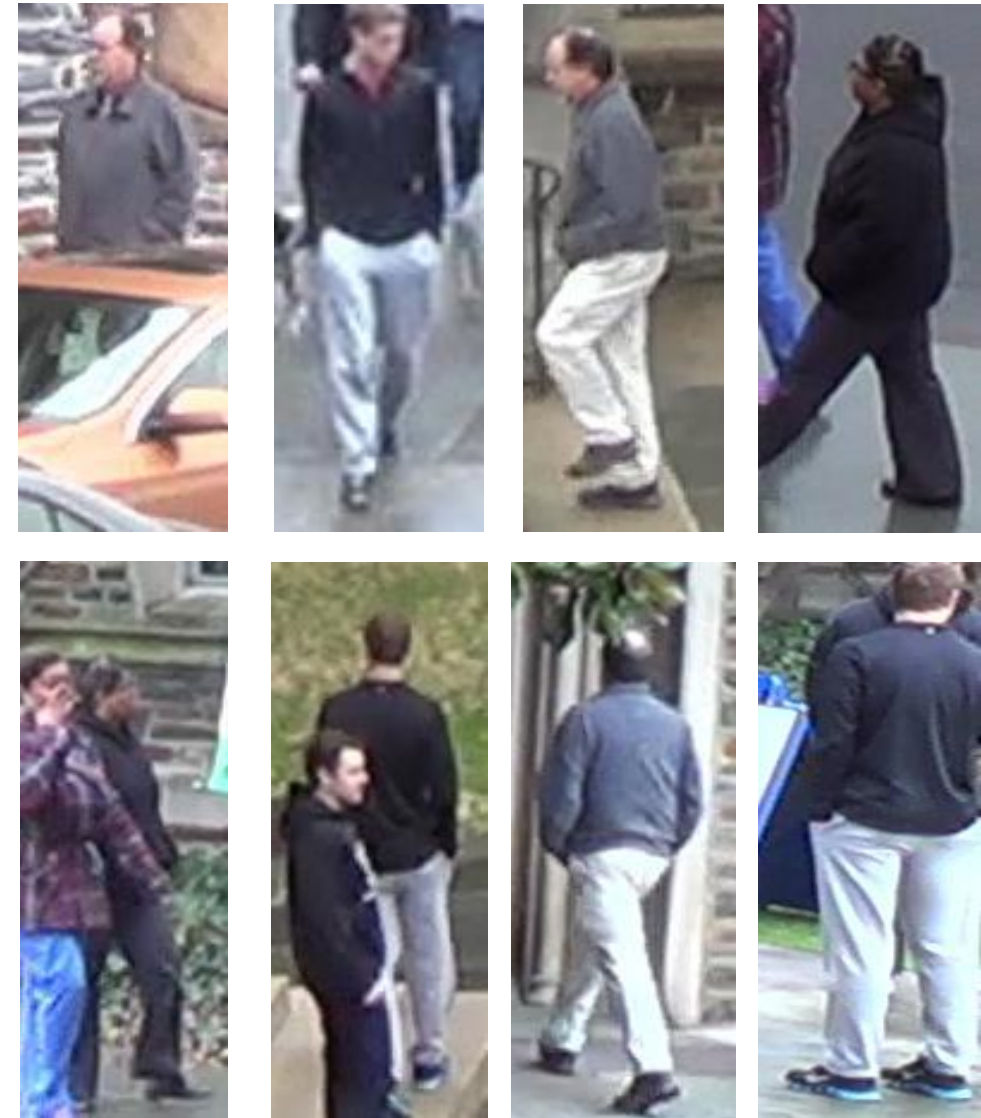
Market1501	
Release Year	2015
Samples	32668
Identities	1501
Cameras	6
Avg Number of Cameras Passed per Identity	4.42
Scene	outdoor



[10] Zheng, et al.: Scalable Person Re-identification: A Benchmark. ICCV, 2015.

DukeMTMC Dataset [11]

DukeMTMC	
Release Year	2016
Samples	36411
Identities	1812
Cameras	8
Avg Number of Cameras Passed per Identity	2.67
Scene	outdoor



[11] Zheng, Z. et al.: Unlabeled Samples Generated by GAN Improve the Person Re-identification Baseline in vitro. ICCV, 2017.

Overview

	Viper	CUHK03	Market1501	DukeMTMC
Release Year	2007	2014	2015	2016
Samples	1264	28192	32668	36411
Identities	632	1467	1501	1812
Cameras	2	2	6	8
Avg Number of Cameras Passed per Identity	2	2	4.42	2.67
Scene	outdoor	indoor	outdoor	outdoor

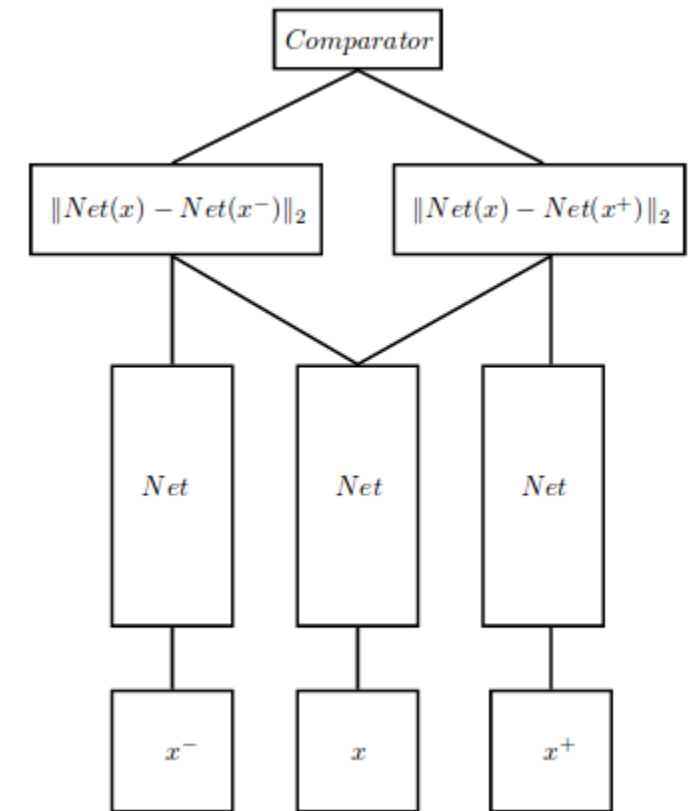
Training Strategy

Our general training strategy had the following configurations:

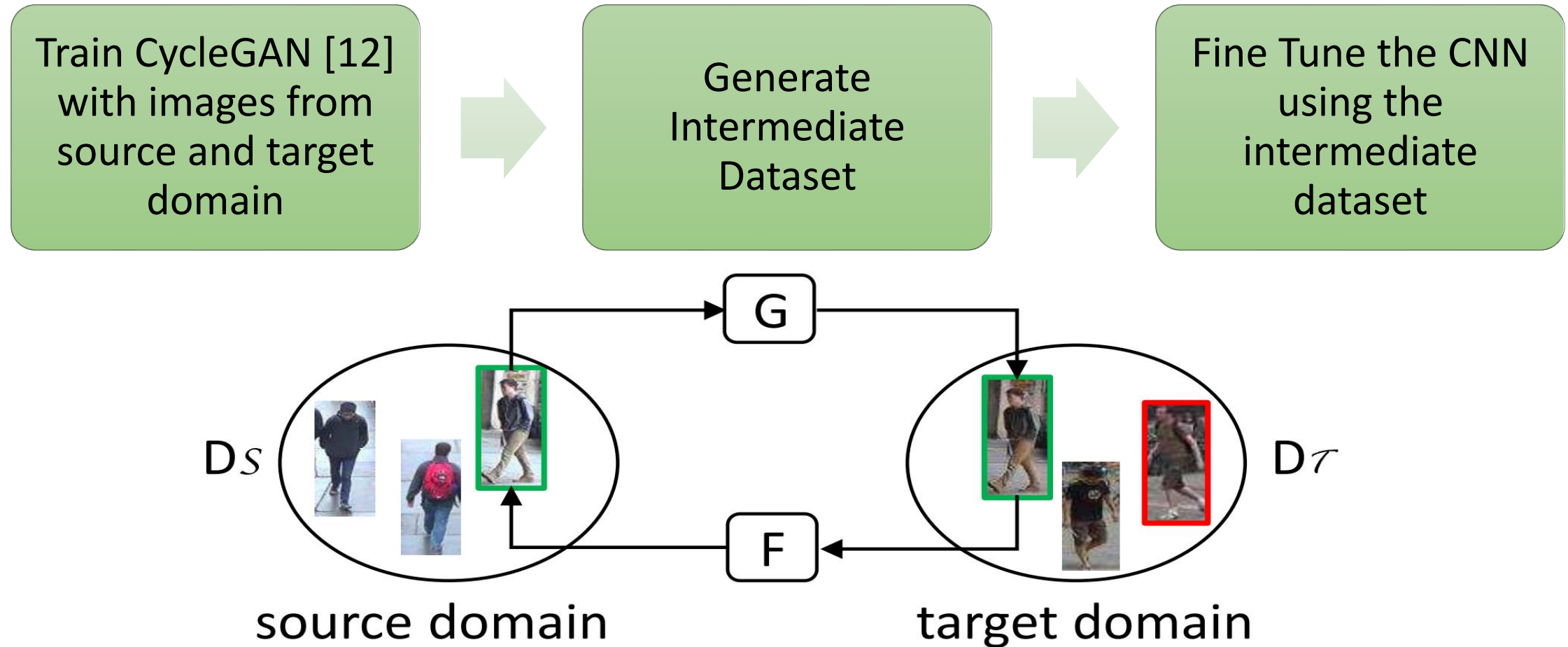
- ResNet-50 or AlignedReID++
- Triplet loss with batch hard
- Adam optimizer
- Batch scheduler

Algorithm 1 Batch Scheduler

```
1:  $\gamma = 2 \times \tau$ 
2: for  $i = 0$  to  $epochs$  do
3:    $loss = train(i, \gamma)$ 
4:   if  $loss < (0.8 \times m)$  then
5:      $\gamma = \gamma \times 2$ 
6:   end if
7: end for
```



Domain Adaptation – Cycle GAN Step



[12] Isola, P. et al.: Image-To-Image Translation With Conditional Adversarial Networks. CVPR, 2017.

Domain Adaptation – Pseudo-Labels Step

Extract Features
from target
domain images



Group these
features using
k-means [13]



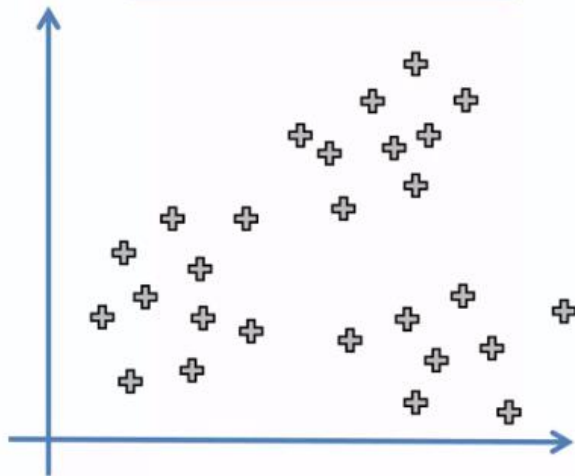
Generate a
pseudo labelled
dataset with
the grouped
features



Fine Tune the
CNN using the
pseudo labelled
dataset

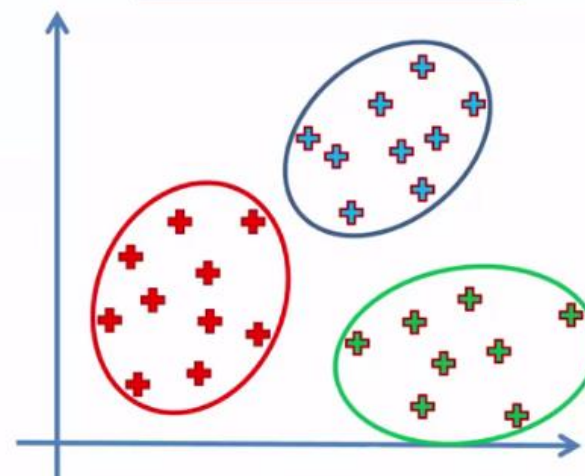


Before K-Means



K-Means

After K-Means



[13] Hartigan, J. A. and Wong, M. A. A K-means clustering algorithm. In: Journal of the Royal Statistical Society 1979.

Results - Baseline

		Accuracy (CMC scores)			
Source Domain	Target Domain	Method	Rank – 1	Rank - 5	Rank - 10
Market 1501	Viper	Direct Transfer	12.5%	25.0%	33.1%
		CycleGAN	9.8%	26.9%	36.4%
		Ours	13.9%	29.0%	40.7%
	CUHK 03	Direct Transfer	19.9%	49.4%	63.2%
		CycleGAN	34.8%	66.7%	79.1%
		Ours	38.2%	69.7%	81.6%
CUHK 03	Viper	Direct Transfer	10.1%	22.5%	29.0%
		CycleGAN	11.6%	25.5%	34.7%
		Ours	13.6%	33.9%	46.0%
	Market 1501	Direct Transfer	26.8%	45.9%	55.1%
		CycleGAN	35.8%	56.5%	65.7%
		Ours	37.3%	60.4%	70.4%
Viper	CUHK 03	Direct Transfer	5.9%	18.1%	29.0%
		CycleGAN	31.9%	64.4%	77.5%
		Ours	36.1%	69.2%	81.3%
	Market 1501	Direct Transfer	5.7%	15.5%	22.2%
		CycleGAN	6.7%	17.0%	23.7%
		Ours	8.6%	20.5%	28.4%

Results – AlignedReID++

		Accuracy (CMC scores)			
Source Domain	Target Domain	Method	Rank – 1	Rank – 5	Rank - 10
Market 1501	Viper	Direct Transfer	22.9%	41.8%	50.0%
		CycleGAN	21.4%	40.2%	50.3%
		Ours	23.7%	41.5%	50.8%
	CUHK 03	Direct Transfer	22.5%	45.0%	47.2%
		CycleGAN	37.0%	69.1%	80.9%
		Ours	42.9%	72.5%	81.2%
CUHK 03	Viper	Direct Transfer	20.6%	38.0%	47.2%
		CycleGAN	21.8%	43.2%	52.2%
		Ours	22.5%	43.2%	54.1%
	Market 1501	Direct Transfer	38.7%	55.1%	62.6%
		CycleGAN	42.7%	59.7%	67.3%
		Ours	46.8%	65.9%	73.6%
Viper	CUHK 03	Direct Transfer	9.9%	27.9%	40.1%
		CycleGAN	17.1%	41.6%	55.8%
		Ours	20.4%	43.9%	58.5%
	Market 1501	Direct Transfer	15.9%	28.2%	35.4%
		CycleGAN	23.1%	37.9%	45.8%
		Ours	28.4%	46.4%	55.2%

Multi-Step Pseudo-Label Refinement

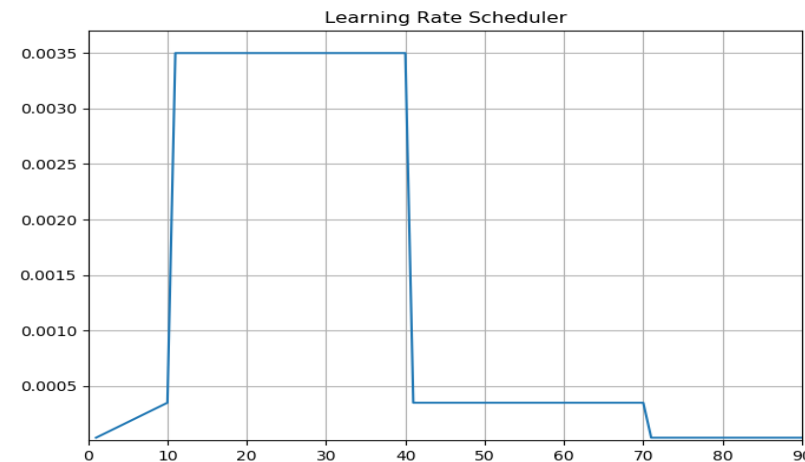
We identified some problems the previous method that we aim to solve using our Multi-Step Pseudo-Label Refinement method.

- The model lack of generalization;
- The noisy and low-quality pseudo-labels;
- The high influence of camera characteristics in the pseudo-labels generation;
- The high computational cost to train GANs and generate the intermediate dataset.

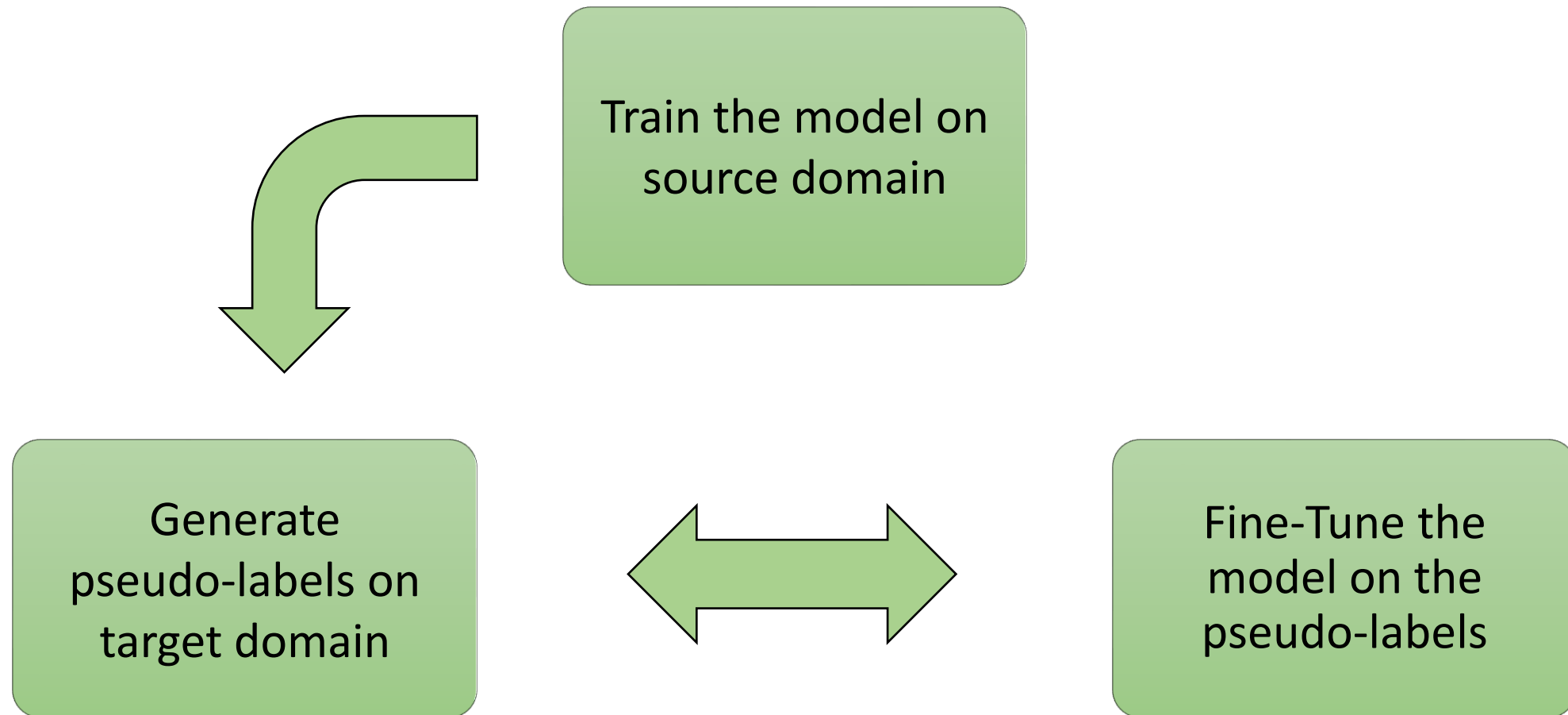
Step 1 – Architecture + Training Strategy

Our general training strategy had the following configurations:

- IBN Net-50 a
- Adam optimizer
- A three-factor loss function given by $\mathcal{L} = \mathcal{L}_{triplet} + \mathcal{L}_{ID} + 0.005 * \mathcal{L}_{center}$ where:
 - $\mathcal{L}_{triplet}$ is the triplet Loss responsible for the metric learning,
 - \mathcal{L}_{ID} is a label smooth cross entropy loss for person ID classification
 - \mathcal{L}_{center} is a center loss to guarantee cluster compactness
- A learning rate scheduler for the 90 training epochs defined by:

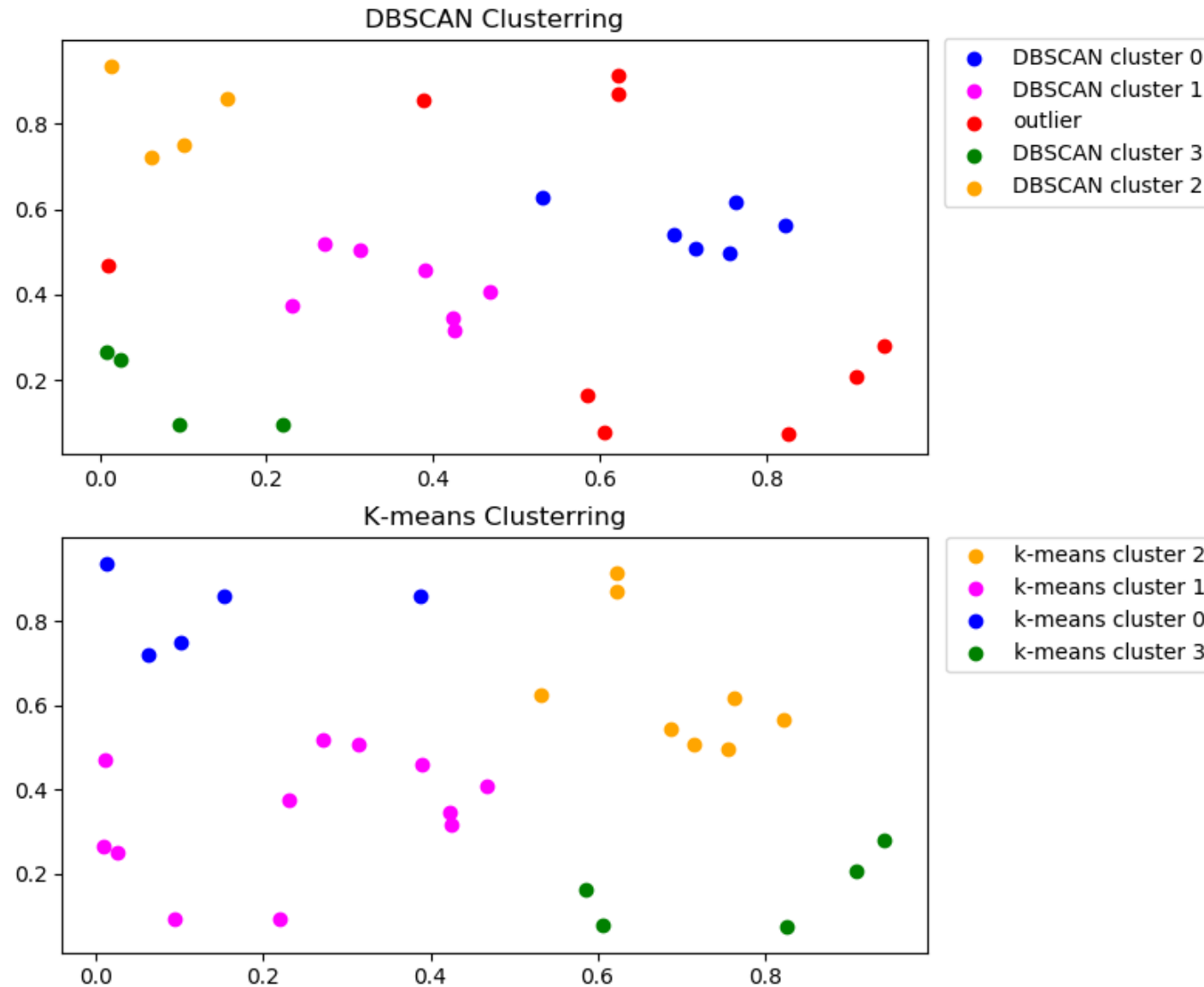


Step 2 – Progressive Learning [14]

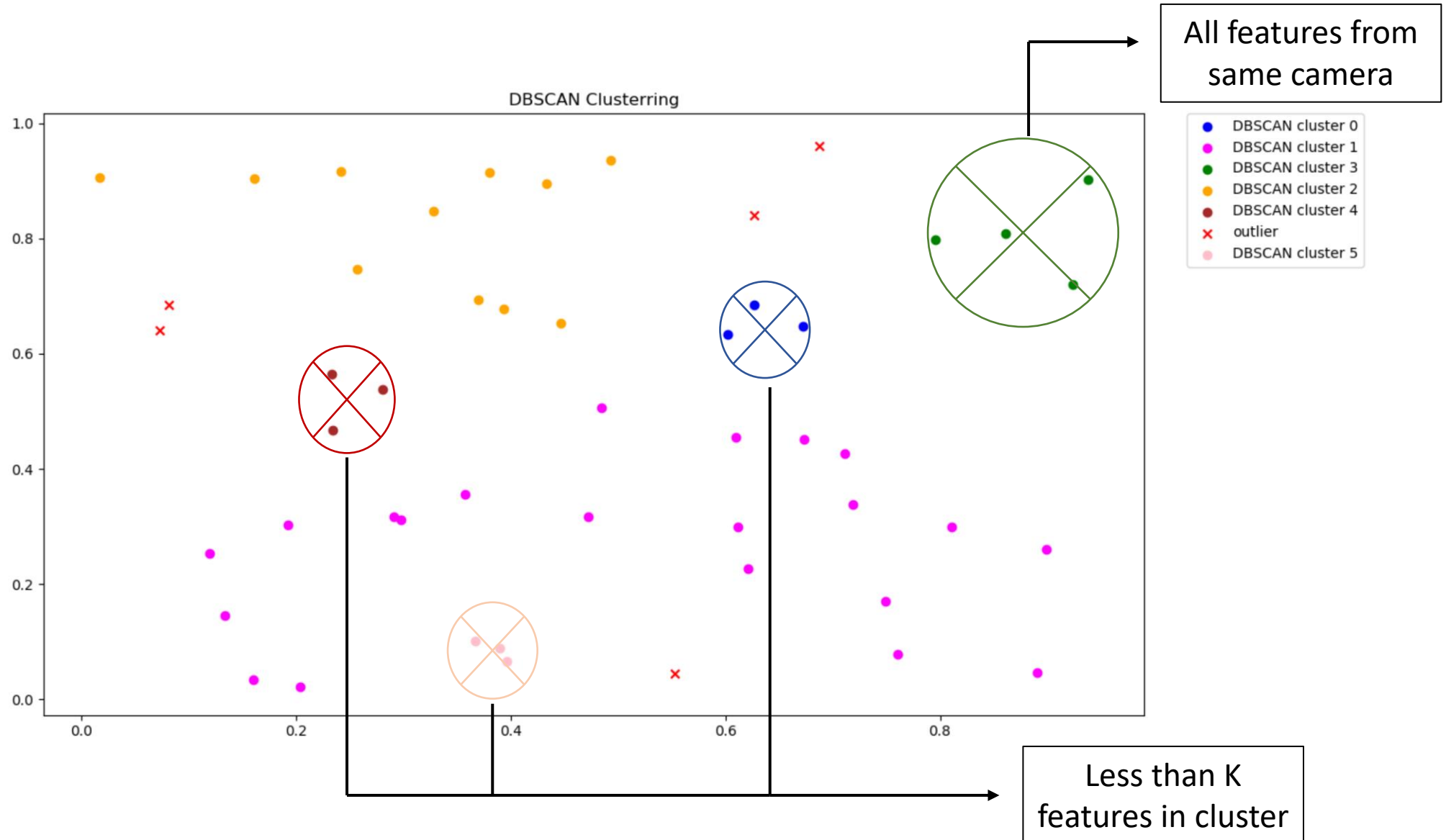


[14] Fan, H. et al.: Unsupervised Person Re-identification: Clustering and Fine-tuning. TOMM, 2018.

Step 3 – Clustering Technique



Step 4 – Cluster Selection



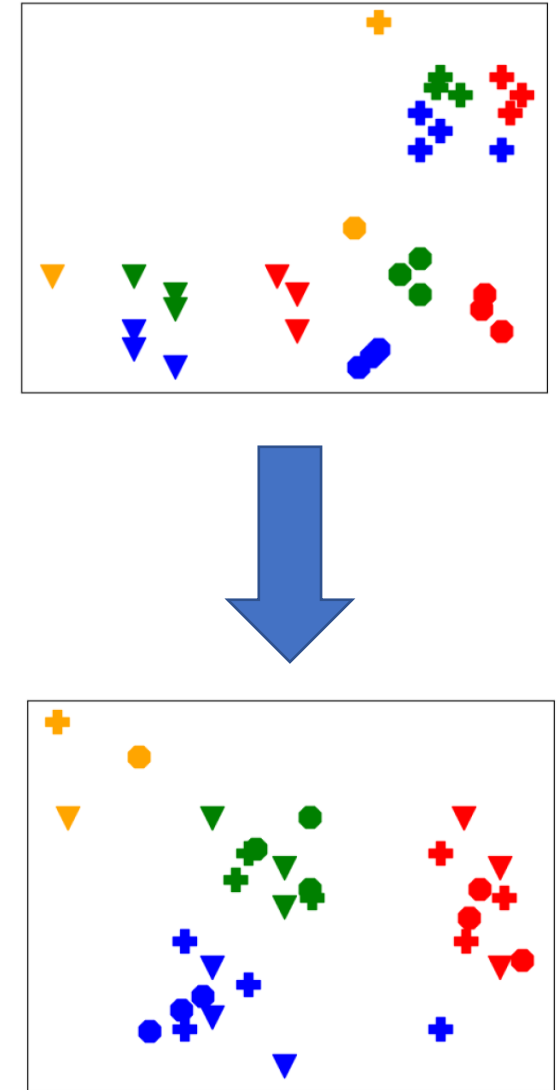
Step 5 – Camera-Guided Feature Normalisation

The high variance present in person Re-ID is mainly caused by different camera views, as each camera has its own characteristics.

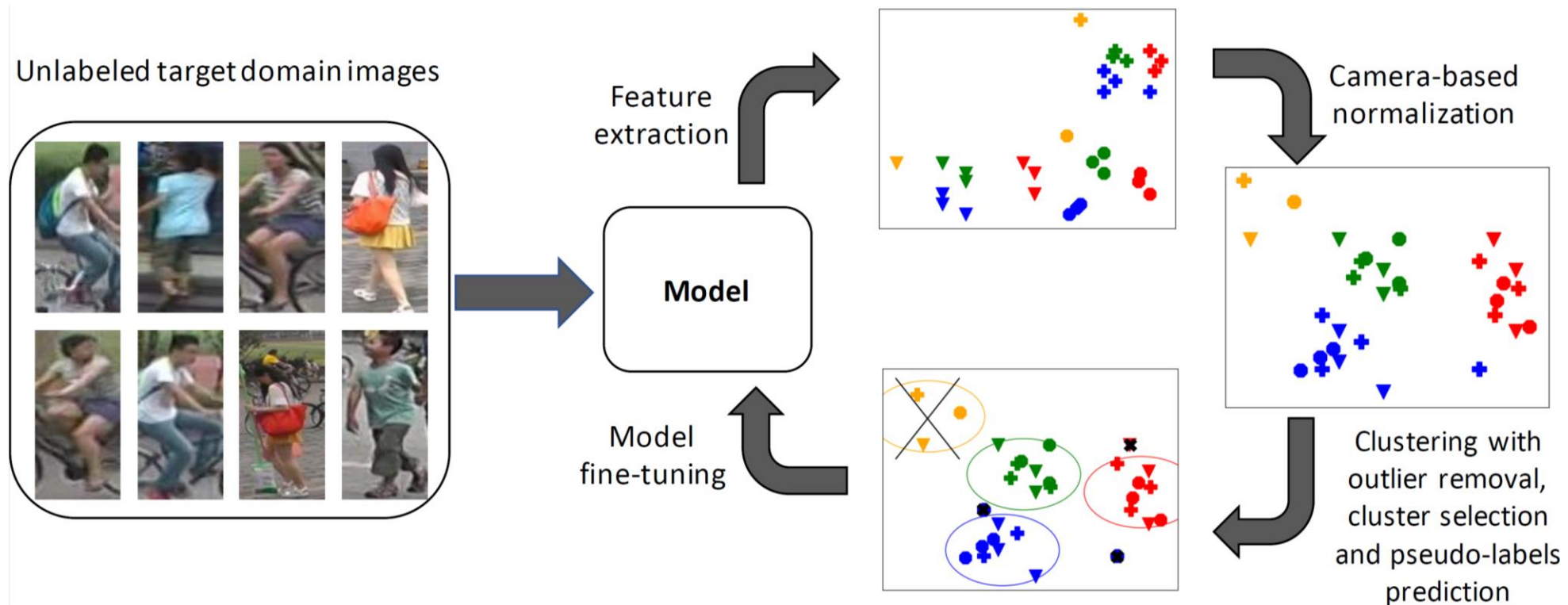
Therefore, the model tends to cluster images by cameras rather than clustering images from the same person in different views.

A camera guided normalization step is then necessary to reduce this variance and allow the clustering step to create better clusters. The normalisation is done by:

$$\bar{f}_{v_j} = \frac{f_{v_j} - \mu_{v_j}}{\sigma_{v_j}}$$



Step 6 – Unsupervised Domain Adaptation



Results

Methods	Market1501 -> DukeMTMC				DukeMTMC -> Market1501			
	Rank – 1	Rank – 5	Rank - 10	mAP	Rank – 1	Rank – 5	Rank - 10	mAP
SPGAN	46.9	62.6	68.5	26.4	58.1	76.0	82.7	26.9
UCDA-CCE	55.4	-	-	36.7	64.3	-	-	34.5
ARN	60.2	73.9	79.5	33.4	70.3	80.4	86.3	39.4
MAR	67.1	79.8	-	48.0	67.7	81.9	-	40.0
ECN	63.3	75.8	80.4	40.4	75.1	87.6	91.6	43.0
PDA-Net	63.2	77.0	82.5	45.1	75.2	86.3	90.2	47.6
EANet	67.7	-	-	48.0	78.0	-	-	51.6
CBN + ECN	68.0	80.0	83.9	44.9	81.7	91.9	94.7	52.0
Theory	68.4	80.1	83.5	49.0	75.8	89.5	93.2	53.7
CR-GAN	68.9	80.2	84.7	48.6	77.7	89.7	92.7	54.0
PCB-PAST	72.4	-	-	54.3	78.4	-	-	54.6
AD Cluster	72.6	82.5	85.5	54.1	86.7	94.4	96.5	68.3
SSG	76.0	85.8	89.3	60.3	86.2	94.6	96.5	68.7
DG-Net++	78.9	87.8	90.4	63.8	82.1	90.2	92.7	61.7
MMT	79.3	89.1	92.4	65.7	<u>90.9</u>	96.4	97.9	<u>76.5</u>
Ours	<u>82.7</u>	<u>90.5</u>	93.5	<u>69.3</u>	89.1	<u>95.8</u>	<u>97.2</u>	73.6
Ours + RR	84.8	90.8	<u>93.2</u>	81.2	92.0	95.3	96.6	88.1

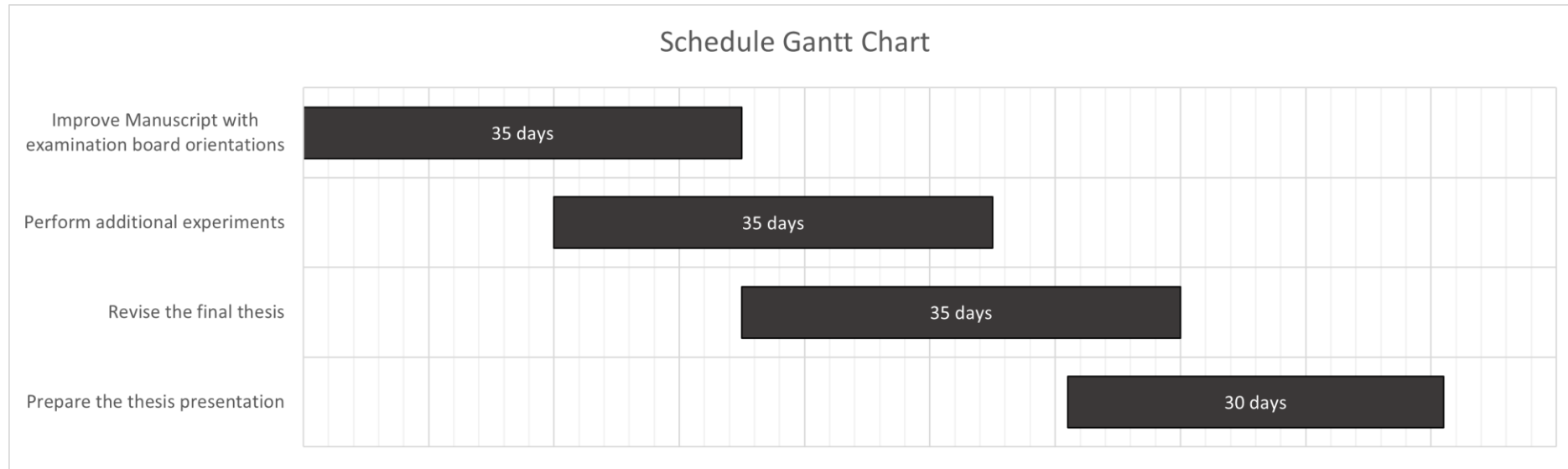
Final Observations

In this work we proposed two methods for unsupervised domain adaptation in person Re-ID:

- The GAN + pseudo-labels method, which created a baseline for us with the resnet-50 and proved its efficiency with the addition of the AlignedReID++
- The Multi-Step Pseudo-Labels Refinement that solved some flaws present in the previous method and achieved a state-of-the-art result

We believe that we achieved our main goal. However, there is still room for improvement in the manuscript.

Schedule



Thank You!