System Identification Project Part 1: Fitting an unknown function

Team: Project Fit 17

Moroșanu Ștefania Raluca

Cuc Ana Alexia

Capac Teodora

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Problem Statement

- Having a nonlinear static function f, using a polynomial approximator, what would the model for this function be?
- What is the most optimal degree for which the approximated output is as close as possible to the true output?

Approximator structure and finding the parameters

Approximator structure:

- > Two independent variables as input
- ➤ The polynomial expansion up to a configurable maximum degree
- Matrix of regressors(φ)

Finding the parameters:

- ➤ The regressor matrix is formed for each degree
- Including all possible combinations for each degree
- Combining the terms to form each polynomial regressor term
- \triangleright Finding the vector of parameters(θ) using left division

theta =
$$PHI \setminus Y$$
;

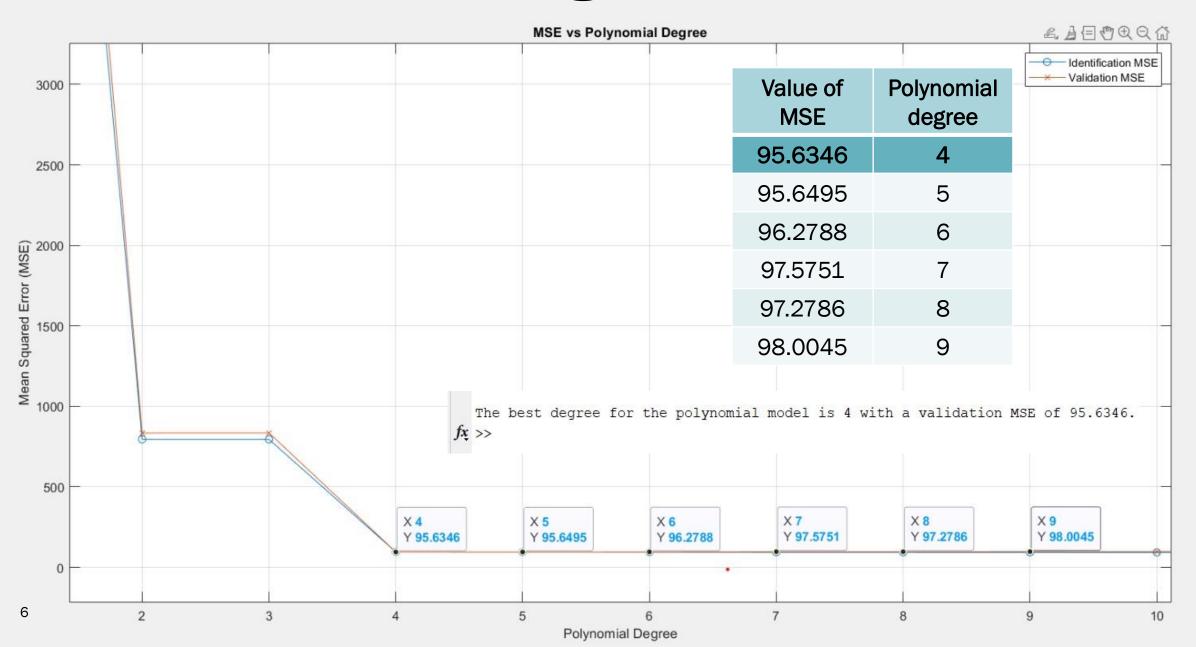
Key features

Constructing the regressor matrix

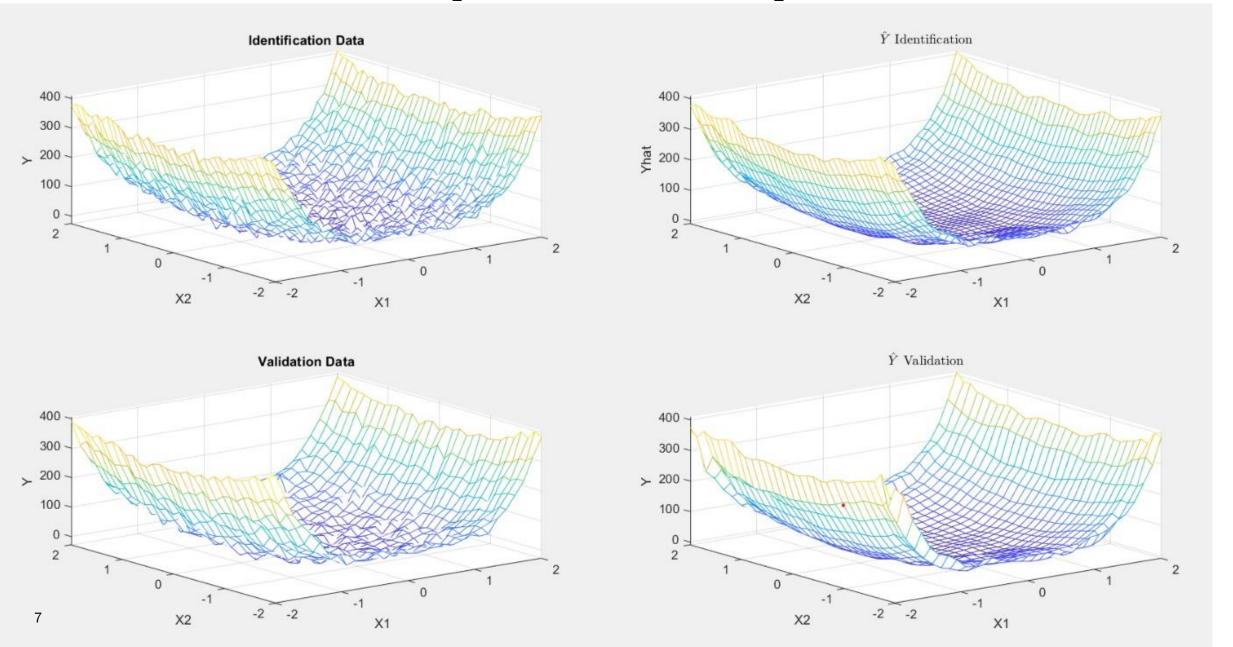
- \triangleright Initially, φ is a column of ones.
- ➤ For each polynomial degree, all possible combinations of powers are included
- > Exponents of X1 and X2 are computed so that they always sum up to the current degree.

 Φ is constructed by concatenation of columns which correspond to each polynomial term

Tuning results



Representative plots



Conclusion

➤ Goal:

- to build a polynomial approximator by using a matrix of regressors
- to find the optimal degree for which the MSE has the lowest value
- to find the polynomial model which has the best performance

> How we achieved it:

- formed the regressor matrix and theta accordingly up to a maximum degree
- compared the values of MSEs for each degree and took the minimum one
- evaluated the representative plots until finding a maximum degree which fits performs accurately

Our team

Capac Teodora

-forming the matrix of regressors

Cuc Ana Alexia

-calculating the parameters of the approximator



Moroșanu Ștefania

-finding the optimal degree for the approximation according to the MSE

*data acquisition, plots, research and the presentation were a joined effort

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clear
clc
<pre>load('proj fit 17.mat');</pre>

Declaring the identification and validation data

Define maximum polynomial degree

```
m_max = 25;

MSE_id = zeros(1, m_max);

MSE val = zeros(1, m_max);
```

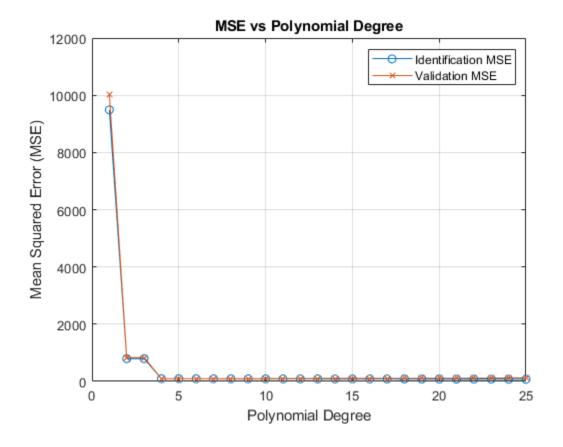
Finding the best polynomial model for our data

Find Best Polynomial Degree Based on Validation MSE

```
[best_MSE_val, best_degree] = min(MSE_val);
fprintf('The best degree for the polynomial model is %d with a validation
MSE of %.4f.\n', best_degree, best_MSE_val);
The best degree for the polynomial model is 4 with a validation MSE of
95.6346.
```

MSE vs. Polynomial Degree

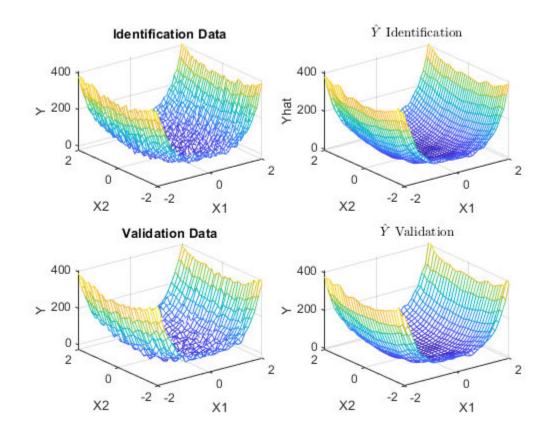
```
figure;
plot(1:m_max, MSE_id, '-o', 'DisplayName', 'Identification MSE');
hold on;
plot(1:m_max, MSE_val, '-x', 'DisplayName', 'Validation MSE');
xlabel('Polynomial Degree');
ylabel('Mean Squared Error (MSE)');
legend show;
title('MSE vs Polynomial Degree');
grid on;
```



Mesh Plots of Identification and Validation Data

```
figure;
subplot(2, 2, 1);
mesh(X1, X2, id.Y);
title('Identification Data');
xlabel('X1');
ylabel('X2');
zlabel('Y');
subplot(2, 2, 2);
mesh(X1, X2, reshape(yhat id, length(X2), length(X1)));
                                                             %Creates a 3D
mesh plot of the identification data s predicted values,
                                                             %reshaped to
match the dimensions of X1 and X2.
title('$\hat{Y}$ Identification', 'Interpreter', 'latex');
xlabel('X1');
ylabel('X2');
zlabel('Yhat');
subplot(2, 2, 3);
mesh(X1 val, X2 val, val.Y);
title('Validation Data');
xlabel('X1');
ylabel('X2');
```

```
zlabel('Y');
subplot(2, 2, 4);
mesh(X1_val, X2_val, reshape(yhat_val, length(X2_val), length(X1_val)));
title('$\hat{Y}$ Validation', 'Interpreter', 'latex');
xlabel('X1');
ylabel('X2');
zlabel('Y');
```



Construction of the Regressor Matrix

```
function phi = form_phi(X1, X2, degree) %form_phi constructs the feature
matrix phi for a polynomial model of a specified degree.
  [X1, X2] = meshgrid(X1, X2); %returns 2-D grid coordinates
based on the coordinates contained in vectors x and y
  phi = ones(prod(size(X1)), 1); %initializes phi with a column of
ones to account for the constant term in the polynomial.

for i = 1:degree
  for j = 0:i
        k = i - j;
        phi = [phi, (X1(:) .^ k) .* (X2(:) .^ j)]; % concatenates each
polynomial term to phi.
  end
```

end end

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