

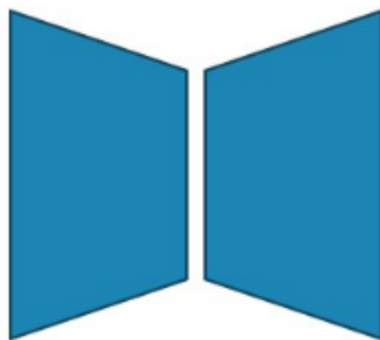
$\tau_0 : a_0, a_1, \dots, a_T$

$\tau_1 : a_0, a_1, \dots, a_T$

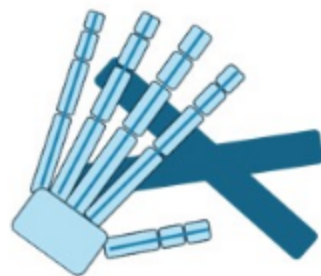
\vdots

$\tau_N : a_0, a_1, \dots, a_T$

data collection



skill embedding



efficient RL

on **simulation**

on **real**