# Reduction Techniques and other Combinatorial Tools in $\tau$ -tilting Theory

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#### Abstract

### 1 Introduction

### 1.1 Setting

We closely follow the notation of [ASS06]. An algebra A will always refer to a finite dimensional algebra over a field k, which need not be algebraically closed. All algebras encountered in this thesis will be, unless otherwise stated, on the form  $k\Gamma/I$  for some finite quiver  $\Gamma$  and admissible ideal I. The number n is, unless otherwise stated, reserved for the number of indecomposable projective summands of A. By mod A we denote the category of finite dimensional left A-modules (in contrast to [ASS06], who employ right modules). We denote by D the duality on modules, and by Tr the transpose. The Auslander-Reiten translate DTr is denoted  $\tau$ .

A module M is called basic if no two nonzero summands are equal, that is  $M \cong A \oplus X \oplus X$  implies X = 0. We denote by |M| the number of indecomposable summands of M.

#### 1.2 Approximations

TODO: add note on approximations

## 2 Tau-tilting theory

 $\tau$ -tilting theory was introduced in [AIR13] as a possible generalization of tilting theory, which has had tremendous impact on the field of representation theory of finite dimensional algebras as a whole. Although first introduced in [AIR13], some of the main results of  $\tau$ -tilting theory stem from (cite smalø). We here recall some important definitions and results from  $\tau$ -tilting theory. Also, we note that there are other approaches to defining  $\tau$ -rigid pairs which are fruitful

in other contexts. To make these introductory sections both concise and self-contained, we will not dwell on these alternative approaches to the theory here. When we need different but equivalent definitions in later sections, references to the literature will be made.

We start by discussing  $\tau$ -rigid modules, which may be considered the building blocks of  $\tau$ -tilting theory.

**Definition 2.1.** A module M in mod A is called  $\tau$ -rigid if  $\operatorname{Hom}(M, \tau M) = 0$ .

First note that the Auslander-Reiten formula gives that  $\tau$ -rigid objects must be exceptional objects. Note that X, Y being  $\tau$ -rigid does not imply  $X \oplus Y$  being  $\tau$ -rigid. In fact, studying how indecomposable  $\tau$ -rigid modules together form larger  $\tau$ -rigid modules is part of  $\tau$ -tilting theory.

**Definition 2.2.** [AIR13, Definition 0.3] A pair (M, P) where M is basic  $\tau$ -rigid and P basic projective such that  $\operatorname{Hom}_A(P, M) = 0$  is called a  $\tau$ -rigid pair.

Along with this definition follows many conventions. For a  $\tau$ -tilting module T=(M,P), P will be denote the projective part of T and M the module part. T is called support  $\tau$ -tilting if |M|+|P|=n, and almost complete support  $\tau$ -tilting if |M|+|P|=n-1. A support  $\tau$ -tilting pair with no non-zero projective part may also be denoted a  $\tau$ -tilting module.

For  $T_1, T_2$  both  $\tau$ -rigid pairs, we consider  $T_1$  a summand of  $T_2$  is both the module part and the projective part of  $T_1$  is a summand of the module part and the projective part of  $T_2$  respectively.

**Example 2.1.** Since  $\tau P = 0$  for any projective module P, any projective module is  $\tau$ -rigid. As a consequence,  $A = \bigoplus_{i=1}^{n} P(i)$  is a  $\tau$ -tilting module.

**Example 2.2.** For an hereditary algebra A, partial tillting modules coincide with  $\tau$ -rigid modules. For M partial tilting,  $0 = Ext_A^1(M, M) \cong \operatorname{Hom}_A(M, \tau M)$ , where the first equality follows from the definition of tilting-modules and the second equality follows from the Auslander-Reiten formula in the hereditary case.

#### 2.1 Torsion classes induced by support $\tau$ -modules

Given a support  $\tau$ -tilting pair (M, P), we may consider the modules generated by M, Fac M. As in classical tilting theory, this is a torsion class, and we have the following very important result.

**Theorem 2.1.** [AIR13, Theorem 2.7][AS81] There is a bijection between the set of functorially finite torsion pairs, denoted f-tors A and support  $\tau$ -tilting modules, denoted s $\tau$ -tiltA, given by sending a support  $\tau$ -tilting pair (M, P) to (Fac  $M, M^{\perp}$ ).

We order the objects in f-tors A by inclusion on the torsion classes. Thus  $(X_1, Y_1) > (X_2, Y_2)$  if  $X_2 \subseteq X_1$ . This induces an ordering on  $s\tau A$ . We denote by Q(f-tors A) the Hasse-quiver of the above defined ordering on f-tors A.

#### 2.2 Mutation

An essential property of support  $\tau$ -tilting modules is that one can *mutate* at each summand. More precisely, one has the following.

**Theorem 2.2.** For a almost complete support  $\tau$ -tilting pair (M, P), there exists exactly two distinct support  $\tau$ -tilting pairs  $(M_0, P_0)$  and  $(M_1, P_1)$ .

In the above theorem,  $(M_0, P_0)$  and  $(M_1, P_1)$  are said to be mutations of each other, and we may write  $M_1 = \mu_X(M_0)$  where X is the indecomposable summand of  $M_0$  that we must replace to get  $M_1$ ; formally, we require  $M_0 = X \oplus M$  or  $P_0 = X \oplus P$ . In this case, we *mutate* at X.

It turns out that mutation of support  $\tau$ -tilting module is compatible with the ordering induced by the set of functorially finite torsion classes.

**Proposition 2.1.** [AIR13, Definition-Proposition 2.28] Let  $T_1$  and  $T_2$  be support  $\tau$ -tilting modules which are mutations of each other. Then either  $T_1 < T_2$  or  $T_2 < T_1$ . In the first case, we consider  $T_2$  a right-mutation of  $T_1$  and in the second case we consider  $T_2$  a left-mutation of  $T_1$ . Note that if  $T_2$  is a left-mutation of  $T_1$ ,  $T_1$  is a right-mutation of  $T_2$  and vice versa.

We may then define a quiver containing the information of mutation.

**Definition 2.3.** The support  $\tau$ -tilting quiver  $Q(s\tau$ -tiltA) has a vertex for each support  $\tau$ -tilting module and an arrow  $T_1 \to T_2$  if  $T_2$  is a left mutation of  $T_1$ .

**Proposition 2.2.**  $Q(s\tau\text{-tilt}A)$  is isomorphic to Q(f-torsA).

*Proof.* We have an isomorphism between the vertex sets of the two quivers. It is enough to prove that there is an arrow  $(T_1, P_1) \to (T_2, P_2)$  if and only if there is an arrow (Fac  $T_1, T_1^{\perp}$ )  $\to$  (Fac  $T_2, T_2^{\perp}$ ).

If there is an arrow (Fac  $T_1, T_1^{\perp}$ )  $\rightarrow$  (Fac  $T_2, T_2^{\perp}$ ), we have Fac  $T_2 \subset$  Fac  $T_1$  and no functorially finite torsion class  $T \neq T_1, T_2$  such that Fac  $T_2 \subset T \subset$  Fac  $T_1$ . By [AIR13, Theorem 2.33], this implies that  $(T_2, P_2)$  is a left mutation of  $(T_1, P_1)$  and thus there is an arrow  $(T_1, P_1) \rightarrow (T_2, P_2)$  in  $Q(s\tau\text{-tilt}A)$ .

By [AIR13, Theorem 2.33], a symmetrical argument proves the other direction.  $\hfill\Box$ 

**Example 2.3.** As Fac A = mod A, the support  $\tau$ -tilting module (A, 0) is the largest element in Q(f-tors A), and any mutation  $\mu_X(A)$  must be a left-mutation.

One may also consider the graph-theoretical properties of  $Q(s\tau\text{-tilt}A)$  by forgetting the orientation of the edges. From the properties of mutation, it follows at once that the mutation graph is (n-1)-regular. It may be finite or infinite. In the finite case the graph is connected [AIR13, Corollary 3.10].

#### 2.3 g-vectors

For an indecomposable module M, let  $P_1 \to P_2 \to M \to 0$  be a minimal projective presentation of M, where  $P_1 \cong \bigoplus_{i=1}^n P(i)^{v_i}$  and  $P_2 \cong \bigoplus_{i=1}^n P(i)^{u_i}$ .

We may consider  $(v_1, v_2, ..., v_n)$  and  $(u_1, u_2, ..., u_n)$  to be vectors describing the building blocks of  $P_1$  and  $P_2$  respectively. Then we define  $g^M$  to be v - u.

**Definition 2.4.** For a  $\tau$ -rigid pair (M, P), its g-vector is defined as  $g^M - g^P$ .

Further, we follow [ST20] and define G-matrices as follows.

**Definition 2.5.** [ST20, Definition 2.4] For a support  $\tau$ -tilting pair  $(M, P) = (M_1 \oplus \cdots \oplus M_i, P_1 \oplus \cdots \oplus P_j)$ , we define its G-matrix  $G_{(M,P)}$  to be the  $n \times n$  matrix  $(g^{M_1}, g^{M_2}, \ldots, g^{M_i}, -g^{P_1}, \ldots, -g^{P_j})$ , where we consider the g-vectors to be column vectors.

An important property of g-vectors is that they uniquely identify  $\tau$ -rigid pairs[AIR13, Theorem 5.5]. This immediately gives a combinatorial proof that the set of indecomposable  $\tau$ -rigid objects must be countable (a fact known more generally for the set of exceptional objects up to isomorphism), as there are only countably many integer vectors of dimension n.

Further, G-matrices of support  $\tau$ -tilting pairs are invertible. This follows immediately from [AIR13, Theorem 5.1].

## 3 Tau-exceptional sequences

Tau-exceptional sequences were introduced in [BM20] as a generalization of exceptional sequences to any finite dimensional algebra.

### References

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