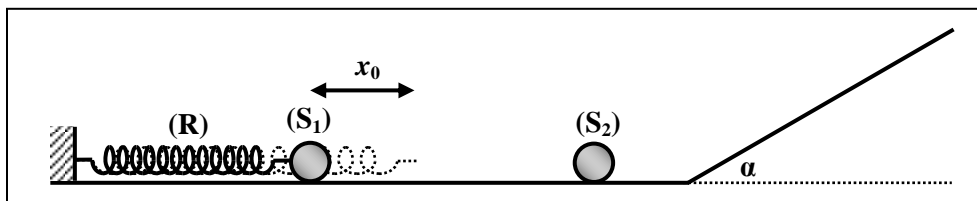


Shakib Irsan High School Physics Department Name:	PHYSICS EXTRA SHEET 4 LINEAR MOMENTUM	Academic Year: 2023-2024 Date: 11-12-2023 Class and Section: 12 LS & GS
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Exercise 1:

A solid (S_1), taken as a particle of mass $m_1 = 0.5\text{kg}$, is connected to the free end of a spring (R) of negligible mass and stiffness $k = 200\text{N/m}$. The other end of (R) is fixed to a support. (R) and (S_1) are placed on the horizontal part of a frictionless track. The inclined part of the track makes an angle $\alpha = 30^\circ$ with the horizontal. The horizontal plane containing the horizontal part of the track is taken as a gravitational potential energy reference. Take $g = 10\text{m/s}^2$.

(S_1) is shifted from its equilibrium position by $x_0 = 20\text{cm}$ and then released from rest at the instant $t_0 = 0\text{s}$.



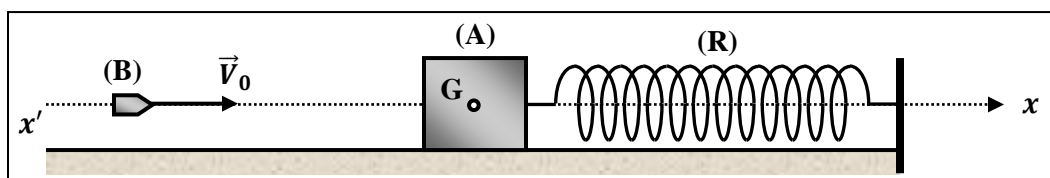
- 1- Determine the speed V_1 of (S_1) when it leaves the spring.
- 2- (S_1) enters in a perfectly elastic head-on collision with a stationary particle (S_2) of mass $m_2 = 1.5\text{kg}$.
 - 2.1- Determine, just after collision, the algebraic value V_1' and V_2' of the velocities of (S_1) and (S_2) respectively.
 - 2.2- After collision, (S_2) moves up the inclined rail. Determine the maximum distance covered by (S_2).
 - 2.3- (S_1) compresses the spring by a distance x_m where it stops. Determine x_m .

Exercise 2:

A bullet (B), of mass $m = 20\text{g}$, moving with a horizontal velocity $\vec{V}_0 = V_0\vec{i}$, enters in a head-on collision with a solid (A), of center of inertia G and mass $M = 5.6\text{kg}$, and rests on a smooth horizontal plane. (A) is connected to the free end of an un-stretched spring (R) of negligible mass and stiffness $k = 1000\text{N/m}$. The other end of (A) is fixed to a vertical support as shown in the document below.

Just after collision, (B) and (A) form one body (S) and acquire a velocity $\vec{V} = V\vec{i}$.

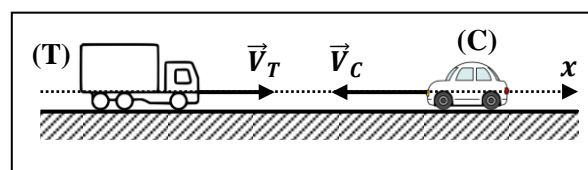
The horizontal plane passing G is taken as a gravitational potential energy reference.



- 1- Show that the expression of the algebraic velocity of (S) just after collision is $V = \frac{mV_0}{m+M}$.
- 2- Determine, by applying the principle of conservation of mechanical energy, the value of V knowing that the spring undergoes a maximum compression of $x_m = 15\text{cm}$.
- 3- Deduce the value of V_0 .
- 4-
 - 4.1- Show that the collision between (B) and (A) is not elastic.
 - 4.2- In what form does the kinetic energy lost appear?

Exercise 3:

A truck (T), of mass $m_T = 3000\text{kg}$, moves with a speed of 54km/h on a horizontal and rectilinear road. A car (C), of mass $m_C = 1200\text{kg}$, moves with a speed of 72km/h in the opposite direction. (T) and (C) enter in a head-on collision. (C) rebounds with a speed of 36km/h .



- 1- Determine the speed of the truck after collision.
- 2- Is the collision elastic? Deduce the energy lost during collision.
- 3- The collision lasts for 10ms . Calculate the average force exerted by the truck on the car.

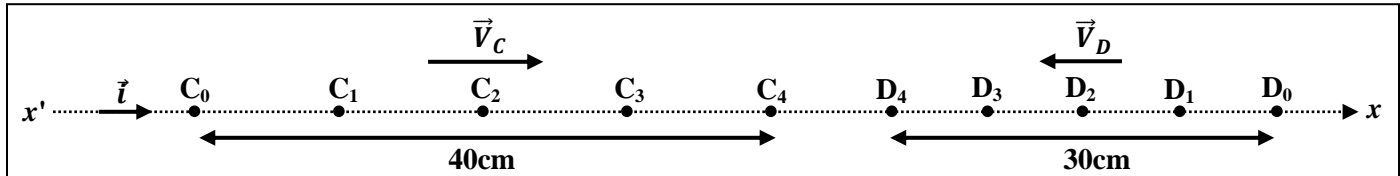
Exercise 4:

Consider a horizontal air table and two pucks (C) and (D) of respective masses $m_C = 100\text{g}$ and $m_D = 300\text{g}$.

Puck (C), moving with a velocity \vec{V}_C , enters in a head-on collision with puck (D) moving in the opposite direction with a velocity \vec{V}_D .

The positions of the center of mass of each puck are registered at successive instants separated by a constant time interval $\tau = 50\text{ms}$.

The document below represents, on the axis $x'x$, the dot-prints of the positions of the centers of masses of the two pucks before collision.



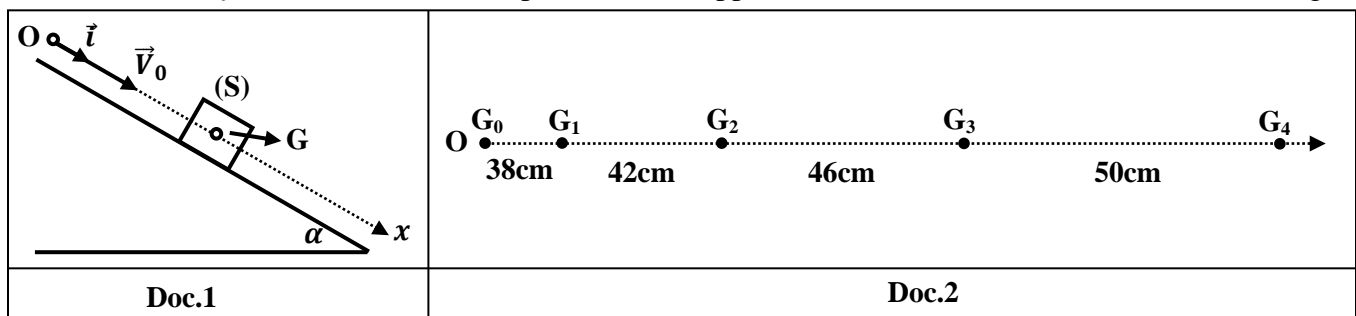
- 1- Show, referring to the above document, that the motion of the two pucks is uniform rectilinear.
- 2- Calculate, before collision, the magnitudes V_C and V_D of the velocities of (C) and (D) respectively.
- 3- After collision, (C) rebounds with a velocity $\vec{V}'_C = -3.25\vec{i} \text{ (m/s)}$. Determine the velocity \vec{V}'_D of (D) after collision.
- 4- Specify the nature of collision between (C) and (D).

Exercise 5:

A solid (S), of center of inertia G and mass $m = 1.25\text{kg}$, is launched at the instant $t_0 = 0\text{s}$ with an initial velocity vector $\vec{V}_0 = V_0\vec{i}$ from the top O of a rough inclined plane that makes an angle $\alpha = 30^\circ$ with the horizontal. Thus, G moves along an axis $x'Ox$ parallel to the inclined plane as shown in document 1.

Document 2 represents the registrations of G during a constant time interval $\tau = 100\text{ms}$.

The force of friction \vec{f} between the inclined plane and (S) opposes its motion and assumed constant of magnitude f .



- 1- Complete the table below:

Dot	G_0	G_1	G_2	G_3	G_4
Instant: $t \text{ [ms]}$	0	τ	2τ	3τ	4τ
Position: $x = \overline{OG} \text{ [cm]}$	0		80		176
Speed: $V \text{ [m/s]}$	V_0		4.4		5.2
Linear momentum: $P \text{ [kgm/s]}$	P_0		5.5		6.5

- 2- Trace the graph that represents the variation of P as function of time t .

Scale: horizontal axis: 1div $\rightarrow 100\text{ms}$; Vertical axis: 1div $\rightarrow 1\text{kgm/s}$.

- 3- Find the equation of the obtained graph.

- 4- Deduce the values of P_0 and V_0 .

- 5-

5.1- Name and represent the external forces acting on (S).

5.2- Show that the sum of external forces acting on (S) is $\sum \vec{F}_{ext} = (mg \sin \alpha - f)\vec{i}$.

5.3- Deduce the value of f .

Exercise 1:

Part	Answer key	Mark
1	<p>The non-conservative force (friction) is neglected; then, the mechanical energy is conserved. $M.E_i = M.E_f \Rightarrow K.E_i + G.P.E_i + E.P.E_i = K.E_f + G.P.E_f + E.P.E_f$.</p> $0 + 0 + \frac{1}{2} kx_0^2 = \frac{1}{2} m_1 V_1^2 + 0 + 0 \Rightarrow V_1 = \sqrt{\frac{k}{m_1}} x_0 = \sqrt{\frac{200}{0.5}} \times 0.2 = 4m/s.$	
2.1	<p>During collision, the system [(S₁); (S₂)] is isolated. $\sum \vec{F}_{ext} = \frac{d\vec{P}}{dt} = \vec{0} \Rightarrow \vec{P} = constant.$</p> <p>The linear momentum is conserved: $\vec{P}_i = \vec{P}_f \Rightarrow m_1 \vec{V}_1 + m_2 \vec{V}_2 = m_1 \vec{V}_1' + m_2 \vec{V}_2'$. The collision is head on; then, the above expression can be written in its algebraic form. $m_1 V_1 + m_2 V_2 = m_1 V_1' + m_2 V_2'$ with $V_2 = 0$. $m_1(V_1 - V_1') = m_2 V_2' \dots (1).$</p> <p>The collision is elastic; then, the kinetic energy is conserved: $K.E_i = K.E_f$. $\frac{1}{2} m_1 V_1^2 + \frac{1}{2} m_2 V_2^2 = \frac{1}{2} m_1 V_1'^2 + \frac{1}{2} m_2 V_2'^2 \Rightarrow m_1 (V_1^2 - V_1'^2) = m_2 V_2'^2.$ $m_1(V_1 + V_1')(V_1 - V_1') = m_2 V_2'^2 \dots (2).$</p> <p>Divide (2) by (1): $V_1 + V_1' = V_2' \dots (3).$ Replace (3) in (1): $m_1(V_1 - V_1') = m_2(V_1 + V_1') \Rightarrow V_1' = \frac{m_1 - m_2}{m_1 + m_2} V_1.$ $V_1' = \frac{0.5 - 1.5}{0.5 + 1.5} \times 4 = -2m/s$ (the minus sign indicates that (S₁) rebounds back). Using equation (3): $V_2' = V_1 + V_1' = 4 - 2 = 2m/s.$</p>	
2.2	<p>The non-conservative force (friction) is neglected; then, the mechanical energy is conserved. $M.E_i = M.E_f \Rightarrow K.E_i + G.P.E_i = K.E_f + G.P.E_f$.</p> $\frac{1}{2} m_2 V_2'^2 + 0 = 0 + m_2 g d \sin \alpha \Rightarrow d = \frac{V_2'^2}{2g \sin \alpha} = \frac{4}{2 \times 10 \times 0.5} = 0.4m = 40cm.$	
2.3	<p>The non-conservative force (friction) is neglected; then, the mechanical energy is conserved. $M.E_i = M.E_f \Rightarrow K.E_i + G.P.E_i + E.P.E_i = K.E_f + G.P.E_f + E.P.E_f$.</p> $\frac{1}{2} m_1 V_1'^2 + 0 + 0 = 0 + 0 + \frac{1}{2} kx_m^2 \Rightarrow x_m = \sqrt{\frac{m_1}{k}} V_1' = \sqrt{\frac{0.5}{200}} \times 2 = 0.1m.$	

Exercise 2:

Part	Answer key	Mark
1	<p>During collision, the system (S) = [(A); (B)] is isolated. $\sum \vec{F}_{ext} = \frac{d\vec{P}_S}{dt} = \vec{0} \Rightarrow \vec{P}_S = constant.$</p> <p>Law of conservation of linear momentum: $\vec{P}_{bc} = \vec{P}_{ac} \Rightarrow m\vec{V}_0 + \vec{0} = (m + M)\vec{V}.$ $mV_0 = (m + M)V \Rightarrow V = \frac{mV_0}{m + M}.$</p>	
2	<p>The non-conservative force (friction) is neglected; then, the mechanical energy is conserved. $M.E_i = M.E_f \Rightarrow K.E_i + G.P.E_i + E.P.E_i = K.E_f + G.P.E_f + E.P.E_f$.</p> $\frac{1}{2} (m + M)V^2 + 0 + 0 = 0 + 0 + \frac{1}{2} kx_m^2 \Rightarrow V = \sqrt{\frac{k}{m + M}} x_m = \sqrt{\frac{1000}{5.6 + 0.02}} \times 0.15 = 2m/s.$	
3	$V_0 = \frac{m + M}{m} V = \frac{0.02 + 5.6}{0.02} \times 2 = 562m/s.$	
4.1	$K.E_{bc} = \frac{1}{2} mV_0^2 = \frac{1}{2} (0.02)(562)^2 = 3,158.44J.$ $K.E_{ac} = \frac{1}{2} (m + M)V^2 = \frac{1}{2} (5.62)(2)^2 = 11.24J.$ <p>$K.E_b \neq K.E_a \Rightarrow$ The kinetic energy of the system (S) is not conserved.</p>	
4.2	Heat or thermal energy	

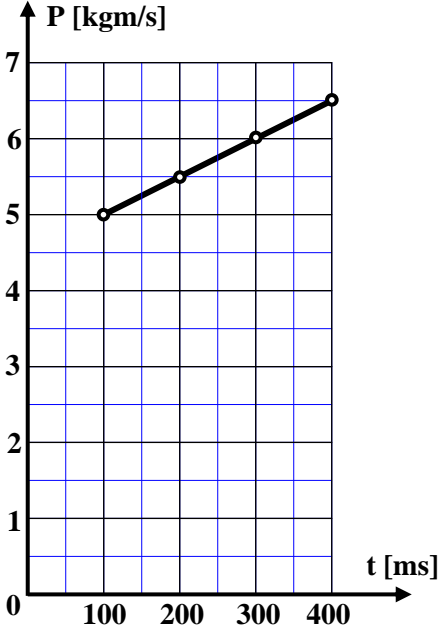
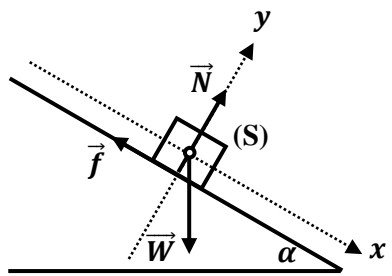
Exercise 3:

Part	Answer key	Mark
1	<p>Before collision, the velocity of (T) is $V_T = 54\text{km/h} = 15\text{m/s}$ and that of (C) is $V_C = -72\text{km/h} = -20\text{m/s}$ ($\text{km/h} \xrightarrow{\div 3.6} \text{m/s}$).</p> <p>After collision, the velocity of (T) is V'_T and that of (C) is $V'_C = 36\text{km/h} = 10\text{m/s}$.</p> <p>During collision, the system [(T); (C)] is isolated.</p> $\sum \vec{F}_{ext} = \frac{d\vec{P}_S}{dt} = \vec{0} \Rightarrow \vec{P}_S = \text{constant}.$ <p>Principle of conservation of linear momentum: $\vec{P}_b = \vec{P}_a$.</p> $m_T \vec{V}_T + m_C \vec{V}_C = m_T \vec{V}'_T + m_C \vec{V}'_C.$ <p>The collision is head-on and the velocities are collinear:</p> $m_T V_T + m_C V_C = m_T V'_T + m_C V'_C.$ $(3000)(15) + (1200)(-20) = (3000)V'_T + (1200)(10) \Rightarrow V'_T = 3\text{m/s}.$	
2	$K.E_b = \frac{1}{2} m_T V_T^2 + \frac{1}{2} m_C V_C^2 = \frac{1}{2} (3000)(15)^2 + \frac{1}{2} (1200)(20)^2 = 577,500\text{J}.$ $K.E_a = \frac{1}{2} m_T V_T'^2 + \frac{1}{2} m_C V_C'^2 = \frac{1}{2} (3000)(3)^2 + \frac{1}{2} (1200)(10)^2 = 73,500\text{J}.$ <p>$K.E_b \neq K.E_a \Rightarrow$ The kinetic energy of the system [(T); (C)] is not conserved; then, collision is not elastic.</p> $\text{Energy lost} = \Delta K.E = 577,500\text{J} - 73,500\text{J} = 504,000\text{J}.$	
3	$\vec{F}_{T/C} = \frac{\Delta \vec{P}_C}{\Delta t} = \frac{\vec{P}'_C - \vec{P}_C}{\Delta t} = \frac{m_C \vec{V}'_C - m_C \vec{V}_C}{\Delta t} = \frac{m_C (\vec{V}'_C - \vec{V}_C)}{\Delta t} = \frac{(1200)(10\vec{i} + 20\vec{i})}{0.01} = 3,600,000\vec{i} \text{ [N]}.$	

Exercise 4:

Part	Answer key	Mark
1	The dots are collinear and the distance separating two consecutive dots is constant.	
2	$V_C = \frac{C_0 C_4}{4\tau} = \frac{40 \times 10^{-2}}{4 \times 50 \times 10^{-3}} = 2\text{m/s}.$ $V_D = \frac{D_0 D_4}{4\tau} = \frac{30 \times 10^{-2}}{4 \times 50 \times 10^{-3}} = 1.5\text{m/s}.$	
3	<p>During collision, the system [(C); (D)] is isolated.</p> $\sum \vec{F}_{ext} = \frac{d\vec{P}_S}{dt} = \vec{0} \Rightarrow \vec{P}_S = \text{constant}.$ <p>Principle of conservation of linear momentum: $\vec{P}_{S(bc)} = \vec{P}_{S(ac)}$.</p> $m_C \vec{V}_C + m_D \vec{V}_D = m_C \vec{V}'_C + m_D \vec{V}'_D.$ $(0.1)(2\vec{i}) + (0.3)(-1.5\vec{i}) = (0.1)(-3.25\vec{i}) + 0.3\vec{V}'_D \Rightarrow \vec{V}'_D = -0.25\vec{i} \text{ (m/s)}.$	
4	$K.E_{S(bc)} = \frac{1}{2} m_C V_C^2 + \frac{1}{2} m_D V_D^2 = \frac{1}{2} (0.1)(2)^2 + \frac{1}{2} (0.3)(1.5)^2 = 0.5375\text{J}.$ $K.E_{S(ac)} = \frac{1}{2} m_C V_C'^2 + \frac{1}{2} m_D V_D'^2 = \frac{1}{2} (0.1)(3.25)^2 + \frac{1}{2} (0.3)(0.25)^2 = 0.5375\text{J}.$ <p>$K.E_{S(bc)} = K.E_{S(ac)} \Rightarrow$ The kinetic energy of the system [(C); (D)] is conserved.</p> <p>Therefore, the collision is elastic.</p>	

Exercise 5:

Part	Answer key	Mark
1	$x_1 = \overline{OG}_1 = 38cm.$ $x_3 = \overline{OG}_3 = 38cm + 42cm + 46cm = 126cm.$ $V_1 = \frac{x_2 - x_0}{2\tau} = \frac{(80-0) \times 10^{-2}}{2 \times 100 \times 10^{-3}} = 4m/s.$ $V_3 = \frac{x_4 - x_2}{2\tau} = \frac{(176-80) \times 10^{-2}}{2 \times 100 \times 10^{-3}} = 4.8m/s.$ $P_1 = mV_1 = 1.25 \times 4 = 5kgm/s.$ $P_3 = mV_3 = 1.25 \times 4.8 = 6kgm/s.$	
2		<p>3 The general equation of a straight line is: $P = kt + b.$ $k = \frac{\Delta P}{\Delta t} = \frac{6.5-5}{0.4-0.1} = 5kgm/s^2.$ $P = 5t + b.$ For $t = 100ms = 0.1s$; $P = 5kgm/s.$ $5 = 5 \times 0.1 + b \Rightarrow b = 4.5kgm/s.$ Therefore, $P = 5t + 4.5.$</p> <p>4 $P_0 = b = 4.5kgm/s.$ $V_0 = \frac{P_0}{m} = \frac{4.5}{1.25} = 3.6m/s.$</p>
5.1	<p>The external forces acting on (S): \vec{W}: Weight. \vec{N}: Normal reaction of a support. \vec{f}: Friction.</p>	
5.2	$\sum \vec{F}_{ext} = \vec{W} + \vec{N} + \vec{f} = \vec{W}_x + \vec{W}_y + \vec{N} + \vec{f} = mg \sin \alpha \vec{i} - f \vec{i} = (mg \sin \alpha - f) \vec{i}.$ $\vec{W}_y + \vec{N} = \vec{0}$ (no motion along the y-axis).	
5.2	$\vec{P} = P \vec{i} \Rightarrow \frac{d\vec{P}}{dt} = \frac{dP}{dt} \vec{i}.$ $\sum \vec{F}_{ext} = \frac{d\vec{P}}{dt} = \frac{dP}{dt} \vec{i} \Rightarrow (mg \sin \alpha - f) \vec{i} = \frac{dP}{dt} \vec{i}.$ $mg \sin \alpha - f = \frac{dP}{dt} \Rightarrow 1.25 \times 10 \times \sin 30^\circ - f = 5 \Rightarrow f = 1.25N.$	