# "Non-linear" Linear Regression

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# Recall: Feature Engineering X1 X2 X3 X4 X1 X2 X3 X4 when do we do this and why?

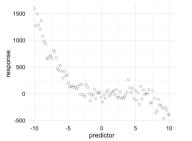
#### **Basis Function**

A family of functions/transformations that can be applied to a variable  $X: f(X_1), f(X_2), f(X_3), \dots$ 

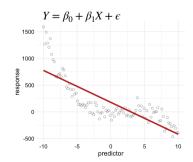
$$Y = \beta_0 + \beta_1 f(X_1) + \beta_2 f(X_2) + \beta_3 f(X_3) + \dots + \beta_k f(X_k) + \epsilon$$

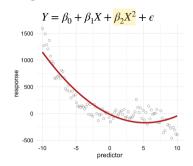
#### The Assumption of Linearity

in reality the relationships between predictors and the response are almost never exactly (first order) linear...

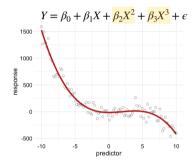


# Polynomial Regression Models

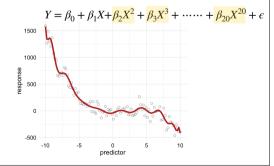




## Polynomial Regression Models



# Polynomial Regression Models



in general, polynomial models are of the form

$$Y = \beta_0 + \beta_1 X + \beta_2 X^2 + \beta_3 X^3 + \dots + \beta_n X^n + \epsilon$$

where d is called the **degree** of the polynomial

- non-linear relationship between predictors and response captured by polynomial terms but model remains linear in the parameters
- example: model can be written as

$$Y = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \beta_3 X_3 + \epsilon$$
 where  $X_1 = X$ ,  $X_2 = X^2$ ,  $X_3 = X^3$ 

• we can use LS for estimation

#### Polynomial Regression Models: Choosing d



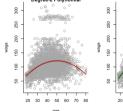


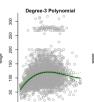


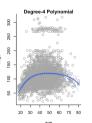
■ present data ■ future data

#### Polynomial Regression Models

Example: Wage (ISLR2)







95% confidence interval for the mean prediction at x:  $\hat{f}(x) \pm 2 \times \text{SE}[\hat{f}(x)]$  where  $\text{SE}[\hat{f}(x)]$  is the standard error of the mean prediction at x

Example: Wage (ISLR2)

#### ANOVA

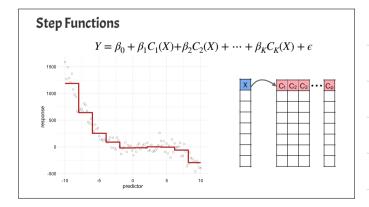
sequential comparisons based on the F-test  $\,$ 

For each step:

 $H_0={\rm the\; decrease\; in\; RSS\; is\; not\; significant}$ 

If hypothesis is rejected we move on to next comparison

#### **Step Functions**



Step Functions 
$$Y = \beta_0 + \beta_0$$

$$Y = \beta_0 + \beta_1 C_1(X) + \beta_2 C_2(X) + \dots + \beta_K C_K(X) + \epsilon$$

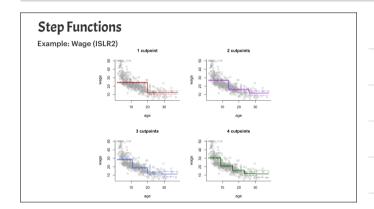
$$C_0(X) = I(X \le c_1)$$

$$C_1(X) = I(c_1 < X < c_2)$$

$$\vdots$$

$$C_{K-1}(X) = I(c_K < X)$$

$$C_K(X) = I(c_K < X)$$
where  $I(\cdot)$  is an indicator function



**Regression Splines** 

#### **Regression Splines**

The basis of regression splines is piecewise polynomial regression

Standard polynomial regression

$$Y = \beta_0 + \beta_1 X + \beta_2 X^2 + \beta_3 X^3 + \dots + \beta_n X^n + \epsilon$$

Piecewise polynomial regression:

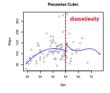
$$Y = \begin{cases} \beta_{01} + \beta_{11}X + \beta_{21}X^2 + \beta_{31}X^3 + \dots + \beta_{d1}X^d + \epsilon & \text{if } X < c \\ \beta_{02} + \beta_{12}X + \beta_{22}X^2 + \beta_{32}X^3 + \dots + \beta_{d2}X^d + \epsilon & \text{if } X \ge c \end{cases}$$

- The c is called a knot
- When there is no knot we have standard polynomial regression.
- When we include only the intercepts terms, we have step function regression.
- If we have K knots we are fitting K+1 polynomial models

# Regression Splines Example: Wage (ISLR2)

Piecewise cubic polynomial with a single knot placed a age = 50:

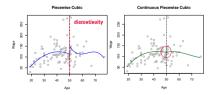
$$\text{wage} = \begin{cases} f_1(\text{age}) = \beta_{01} + \beta_{11}X + \beta_{21}X^2 + \beta_{31}X^3 & \text{if age} < 50 \\ f_2(\text{age}) = \beta_{02} + \beta_{12}X + \beta_{22}X^2 + \beta_{32}X^3 & \text{if age} \ge 50 \end{cases}$$



# Regression Splines Example: Wage (ISLR2)

Piecewise cubic polynomial with a single knot placed a age = 50. Constraints:

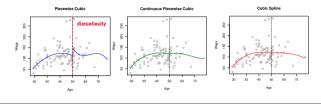
1.  $f_1(\text{age} = 50) = f_2(\text{age} = 50)$ 

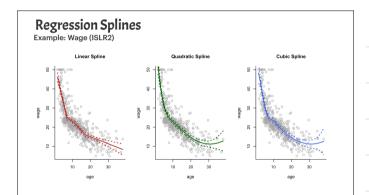


# Regression Splines Example: Wage (ISLR2)

Piecewise cubic polynomial with a single knot placed a age = 50. Constraints:

- 1.  $f_1(\text{age} = 50) = f_2(\text{age} = 50)$
- **2.**  $f'_1(\text{age} = 50) = f'_2(\text{age} = 50)$
- 3.  $f_1''(\text{age} = 50) = f_2''(\text{age} = 50)$





#### **Regression Splines**

Constraints and Degrees of Freedom

- In the previous example, we started with a cubic piecewise polynomial with 8 unconstrained parameters, so we started with 8 degrees of freedom (df)
- We initially imposed one constraint, which restricted one parameter, so we lost a degree of freedom 8 - 1 = 7
- With the further two constraints:  $8-3=5\,\mathrm{df}$
- ullet In general, a cubic spline with K knots has 4+K degrees of freedom. In R we can we can specify either the number of knots or just the degrees of freedom.

A degree-d regression spline is a piecewise degree-d polynomial with continuity in derivatives up to degree d-1 at each knot

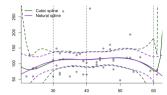
#### **Natural Splines**

- Regression splines have high variance at the outer range of the predictor (the tails)
- The confidence intervals at the tails can be wiggly (especially for small samples)

Natural splines are extensions of regression splines which remedy these problems

#### Two additional constraints at each boundary region:

- 1. The spline function is constrained to be close to linear when  $X<\,$  smallest knot
- 2. The spline function is constrained to be close to linear when X > largest knot



#### **How Many Knots?**

- Provided there is evidence from the data we can do it empirically:
- ▶ Place knots where it is clearly obvious there is a distributional shift in direction
- ▶ Place more knots on regions where we see more variability
- ▶ Place fewer knots in places which look more stable
- Alternatively, we can place knots in a uniform fashion (25th, 50th, 75th percentiles)

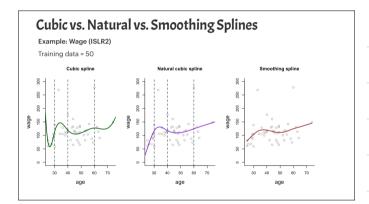
**Smoothing Splines** 

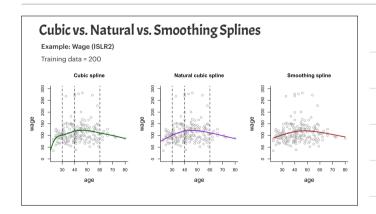
#### **Smoothing Splines**

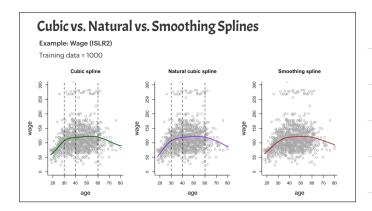
- Unlike regression splines and natural splines, there are no knots!
- The discrete problem of selecting a number of knots into a continuous penalization problem
- ullet We seek a function g among all possible functions (linear + non-linear) which minimizes

model fit + penalty term = 
$$\sum_{i=1}^{n} (y_i - g(x_i))^2 + \lambda \int (g''(t))^2 dt$$
not the usual RSS catches wiggles or

- The function g that minimizes the above quantity is called a smoothing spline
- $\lambda \ge 0$  is the tuning penalty parameter, also called roughness penalty
- when  $\lambda=0$  we get an extremely wiggly non-linear function g (completely useless)
- as  $\lambda$  increases, the function becomes smoother
- $\qquad \qquad \text{theoretically: when } \lambda \to \infty, \, g'' \, \text{is zero everywhere} \Longrightarrow g(X) = \beta_0 + \beta_2 X \, \text{ i.e. linear model}$
- the solution for any finite and non-zero  $\lambda$  is that the function g is a natural cubic spline but with knots placed on each individual sample point  $x_1, x_2, x_3, \ldots, x_n$







## Cubic vs. Natural vs. Smoothing Splines

Criterion	Polynomial Splines	Natural Splines	Smoothing Splines
Flexibility	High with more knots	Moderate	High, controlled by $\lambda$
<b>Boundary Behavior</b>	May behave erratically	Linear at boundaries	Smooth, but depends on $\lambda$
Noise Handling	Poor, sensitive to noise	Moderate	Excellent, balances fit and smoothness
Interpretability	Good for low degree	Good	Moderate, influenced by $\lambda$
Knot Selection	User-defined	User-defined	Not required
Computation	Fast	Fast	Slower for large data

Generalized Additive Models (GAMs)

#### **Generalized Additive Models (GAMs)**

GAMs provide a general framework for extending a standard linear model: allowing non-linear functions of each of the variables, while maintaining additivity

$$Y = \beta_0 + f_1(X_1) + f_2(X_2) + f_3(X_3) + \dots + f_p(X_p) + \epsilon$$

each linear component  $\beta_i X_i$  can be replaced by smooth non-linear function  $f_i(X_i)$ 

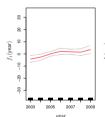
For example, a GAM may include

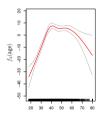
- non-linear polynomial method for continuous predictors
- step functions which are more appropriate for categorical predictors
- linear models if that seems more appropriate for some predictors

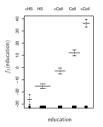
#### Generalized Additive Models (GAMs)

Example: Wage (ISLR2)

the first two functions are natural splines in year and age the third function is a step function, fit to the qualitative variable education







#### Generalized Additive Models (GAMs)

- + Very flexible in choosing non-linear models and generalizable to different types of responses.
- + Because of the additivity we can still interpret the contribution of each predictor while considering the other predictors fixed.
- + GAMs can outperform linear models in terms of prediction.
- + Built on the framework of GLMs, so can handle different response distributions
- Additivity is convenient but it is also one of the main limitations of GAMs (independent contributions of predictors)
- Spline fitting and penalization can be computationally intensive for large data.
- GAMs might miss non-linear interactions among predictors.

