



neighborhood inclusion





(i) concordance if
$$c_1(u) > c_1(v)$$
 and $c_2(u) > c_2(v)$
(iii) tie if $c_1(u) = c_1(v)$ and $c_2(u) = c_2(v)$
(iv) right tie if $c_1(u) \neq c_1(v)$ and $c_2(u) = c_2(v)$

(v) left tie if $c_1(u) = c_1(v)$ and $c_2(u) \neq c_2(v)$





(some of) the technical background

node u is dominated by node v if N(u) ⊆ N[v] neighborhood inclusion

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\Longrightarrow u is always less central than v: c(u) \le c(v)
                                                           (Schoch and Brandes, 2016)
      index c preserves neighborhood-inclusion
five different configurations of pairs (u,v) \in V
         concordance if c_1(u) > c_1(v) and c_2(u) > c_2(v)
    (ii) discordance if c_1(u) > c_1(v) and c_2(u) < c_2(v)
     (iii) tie if c_1(u) = c_1(v) and c_2(u) = c_2(v)
                                                                 high correlation means
low rank dissimilarity
     (iv) right tie if c_1(u) \neq c_1(v) and c_2(u) = c_2(v)
     (v) left tie if c_1(u) = c_1(v) and c_2(u) \neq c_2(v)
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the fraction of discordant pairs as a measure of dissimilarity among indices

rank dissimilarity experiments