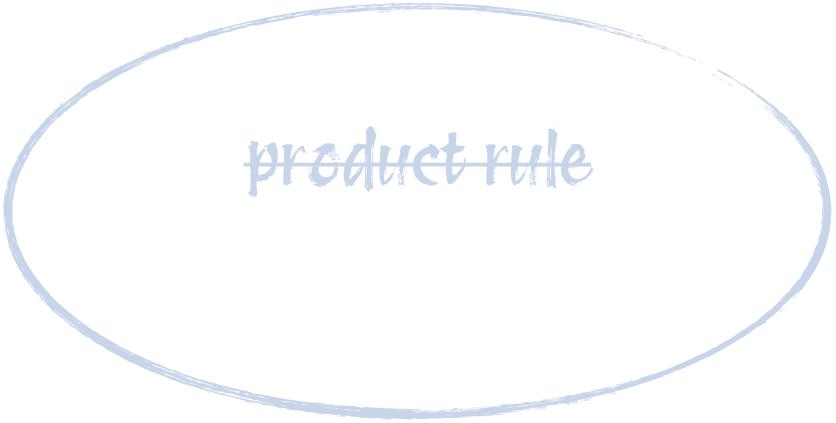
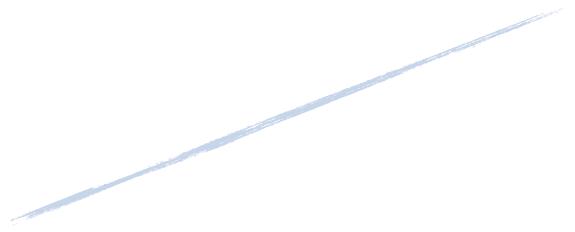


rules of differentiation

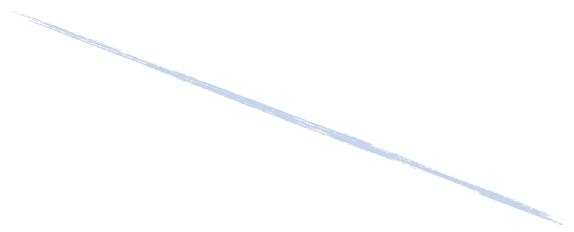








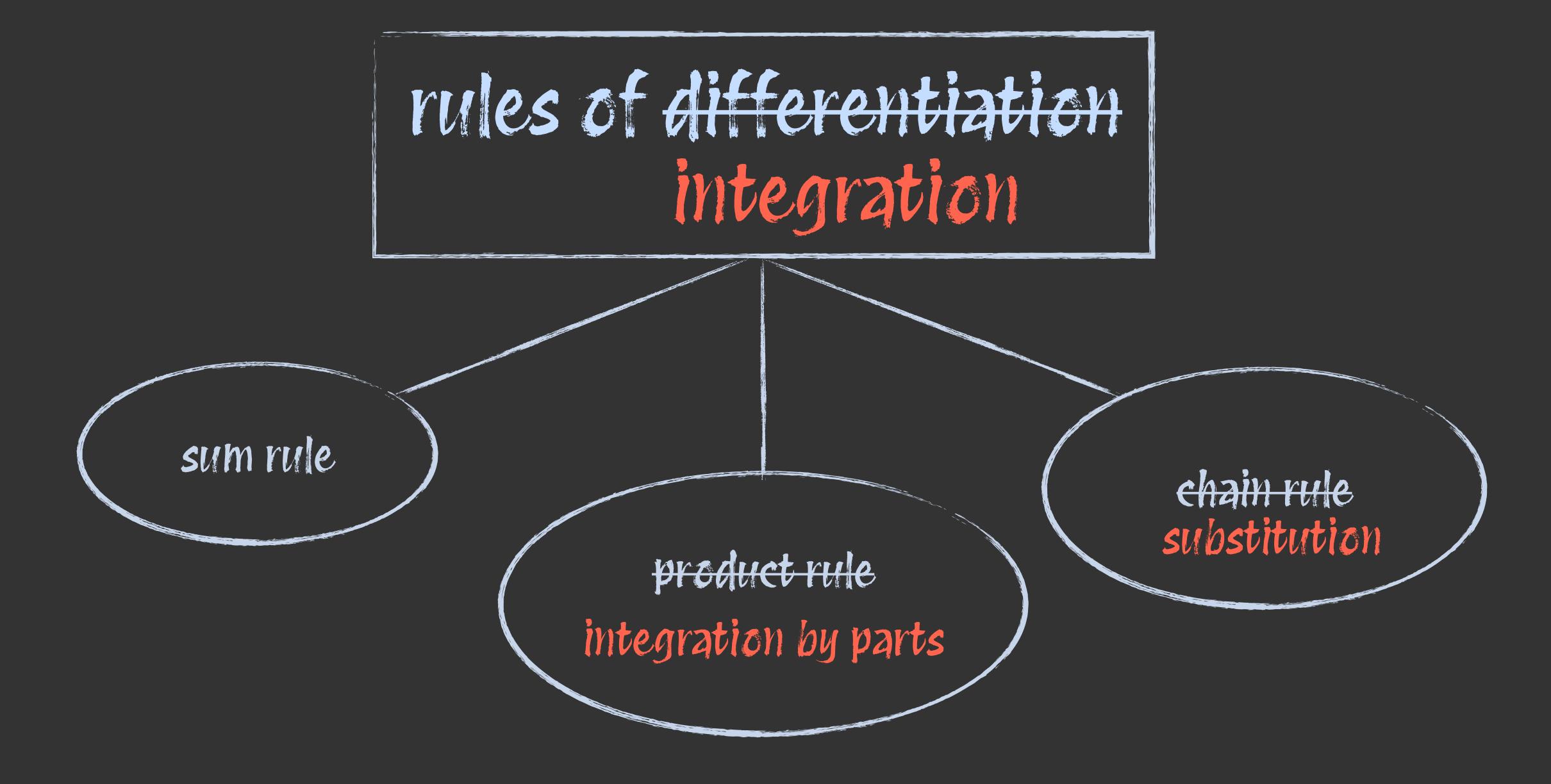




integration

substitution

integration by parts



Remember the machine we built for differentiation? We can use their reverse application for integration...

the sum rule

