

Lost In Space Algorithm Research

Bryant.

A dark blue diagonal gradient bar that starts from the bottom left and extends towards the top right, covering the lower half of the slide.

Why do we need
to solve for the
Lost in Space
problem?



- To determine our camera orientation by star identification.



- A common strategy is to use a triangulation method, which has been done way better than my solution. Why?

Dalabie, Durt, and Vander steen's Algorithm (2011).

Tjorven Delabie, Thomas Durt, and Jeroen Vandersteen. "Highly Robust Lost-in-Space Algorithm Based on the Shortest Distance Transform", Journal of Guidance, Control, and Dynamics, Vol. 36, No. 2 (2013), pp. 476-484.

- Not triangle, but it has been the only algorithm that any of us have looked at. (Shortest Distance Transform Technique.)
- Images comparable to the camera image are generated from the Hipparcos database.
- Two brightest stars method and centroid method to match images.
- Handles false, missing, and distorted stars.
- But how distribute points on sphere

Liebe's Algorithm (1993).

C. C. Liebe, "Star trackers for attitude determination," IEEE Aerospace and Electronic Systems Magazine, vol. 10, no. 6, pp. 10–16, 1995.

- Guide triangles formed by guide stars.
- 1000 stars were selected from Smithsonian Astrophysical Observatory.
- 185,000 star triangles.
- 94.6% Recognition rate.
- Identification time: ~10 s.

Mortari's Algorithm (2004).

D. Mortari, M. A. Samaan, C. Bruccoleri,
and J. L. Junkins, "The pyramid star
identification technique," Navigation, vol.
51, no. 3, pp. 171–184, 2004.

- Pyramidal algorithm:
match four stars by ordering
angular distance between stars.
- Really good at false star
identification.
- Highly efficient and fast.
- No analysis of errors for
measurements.

Cole and Crassidis' Algorithm (2006).

C. L. Cole and J. L. Crassidis, "Fast star-pattern recognition using planar triangles," *Journal of Guidance, Control, and Dynamics*, vol. 29, no. 1, pp. 64–71, 2006.

- Triangulation of stars (+area and polar moment.)
- Number of similar solutions are rapidly reduced.
- Large memory required to hold triangle data.
- Affected by star positional noise in the image.

Yang's Algorithm (2007).

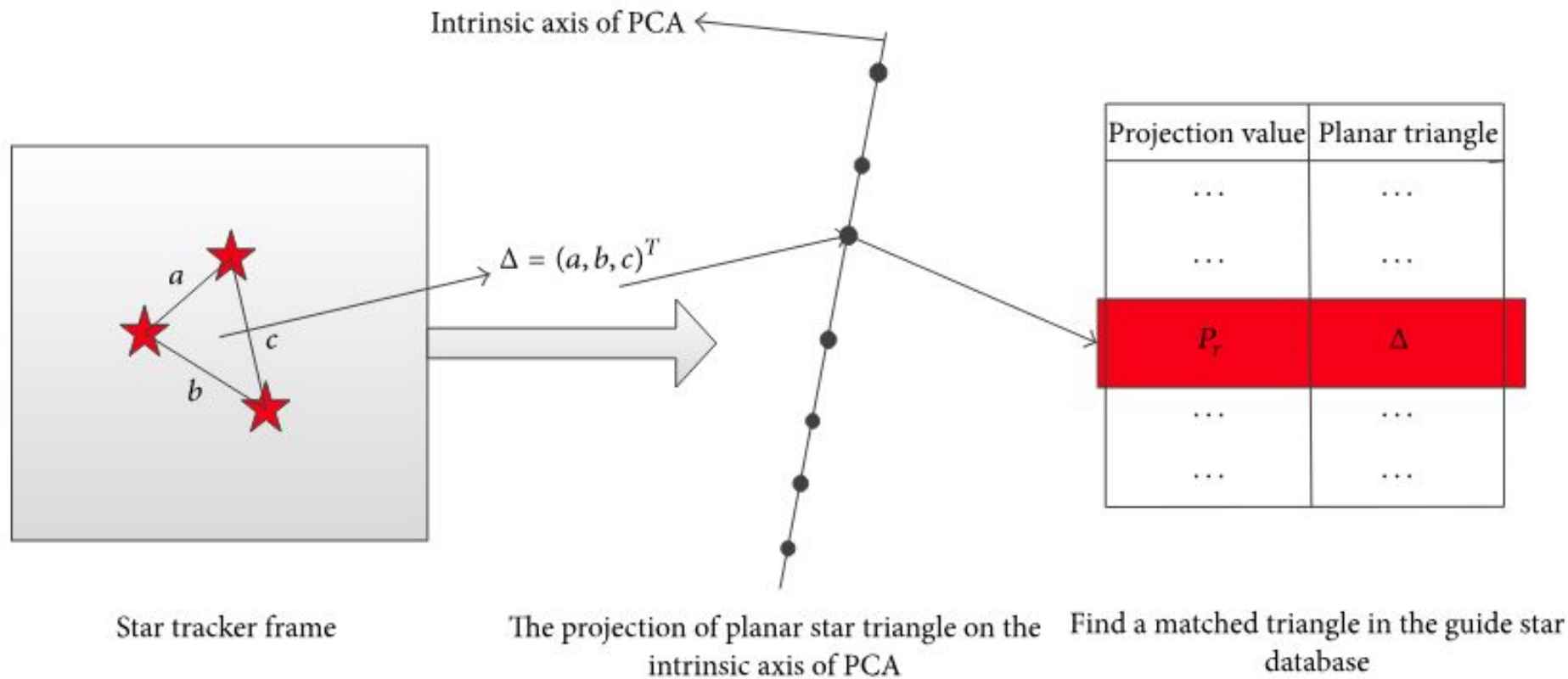
J. Yang, G.-J. Zhang, and J. Jiang, "Fast star identification algorithm using P vector,"
Acta Aeronautica et Astronautica Sinica,
vol. 28, no. 4, pp. 897–900, 2007.

- Storing parameters for each triangle.
- Star identification very vulnerable to magnitude noise b/c of brightest stars.
- Will not work if FOV cannot form a triangle from the catalog.

Zhou and Ye's Algorithm (2015).

Fuqiang Zhou and Tao Ye, "Lost-in-Space
Star Identification Using Planar Triangle
Principal Component Analysis Algorithm,"
Mathematical Problems in Engineering,
vol. 2015, Article ID 982420, 11 pages, 2015.

- A star pattern is computed using the 3 sides of the triangle projected on a projection line.
- K-Vector range speeds up catalog indexing.
- More robust than planar triangle and P-vector algorithms.
- No real sky images were tested.



Brown and Stubis's Algorithm (2017).

J. Brown and Stubis, K., "TETRA: Star Identification with Hash Tables", 2017..

- Solves Lost in Space with hash table. (as suggested by Prof. Pister.)
- Combines Mortari's Pyramidal algorithm with Samaan's ND Star ID algorithm with modifications.
- Hash tables used to efficiently perform cross-referencing step and lookup.