

## Homework 7 Solutions

3.1.27 (a) False: This subset never contains  $\vec{0}$  (since  $\vec{0}$  always is in  $C(A)$ ), so it can't be a subspace.

(b) True: If  $A$  is not the  $0$  matrix, then it has a non-zero column which is in  $C(A)$ . So if  $C(A) = \{\vec{0}\}$ , then  $A = 0$ .

(c) True: If columns of  $A$  are  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n$ , then  $C(A) = \text{span}(\vec{v}_1, \vec{v}_2, \dots, \vec{v}_n)$  and  $C(2A) = \text{span}(2\vec{v}_1, 2\vec{v}_2, \dots, 2\vec{v}_n)$

$\vec{v}_i$  is in  $C(2A)$  because  
 $\vec{v}_i = \frac{1}{2}(2\vec{v}_i)$  and  $C(2A)$  is  
closed under scalar multiplication.

in  $C(A)$  because  $C(A)$  is  
closed under scalar  
multiplication.

(d) False: For example, consider  $A = 2 \times 2$  identity.

Then  $C(A) = C(I) = \text{span}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \mathbb{R}^2$  ← not the same  
 $C(A - I) = C(0) = \text{span}\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \end{bmatrix}\right) = \{\vec{0}\}$  ←

3.1.28 column space should not be all of  $\mathbb{R}^3$ , so it should be  
only the plane spanned by  $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ . We can take these two  
vectors as the 1st two columns, then take the 3rd to be a  
linear combination of the 1st two:  $A = \begin{bmatrix} 1 & 1 & 2 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$  is one  
example.

For column space to be a line, all columns should be multiples of one  
of them, for example  $B = \begin{bmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \\ 1 & 2 & 3 \end{bmatrix}$ .

3.2.12  $\begin{bmatrix} 1 & -3 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \end{bmatrix}$

↑  
A

Free variables  $y, z$ :

$x = 3y + z$   
 $y, z$  free

$N(A): \vec{x} = \begin{bmatrix} 3y+z \\ y \\ z \end{bmatrix} = y \begin{bmatrix} 3 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

↖ ↗  
 The two special solutions, a basis for the plane  $x - 3y - z = 0$ .

3.2.20 Let's say we want  $N(A) = \text{span} \left( \begin{bmatrix} -2 \\ 1 \end{bmatrix} \right)$ , for example,

so  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \rightsquigarrow \begin{matrix} -2a + b = 0 \\ -2c + d = 0 \end{matrix} \rightsquigarrow \begin{matrix} b = 2a \\ d = 2c \end{matrix}$

We also need the columns to be multiples of  $\begin{bmatrix} -2 \\ 1 \end{bmatrix}$ :  $\begin{bmatrix} a \\ c \end{bmatrix} = x \begin{bmatrix} -2 \\ 1 \end{bmatrix}$   
 and  $\begin{bmatrix} b \\ d \end{bmatrix} = y \begin{bmatrix} -2 \\ 1 \end{bmatrix}$ .

Choose  $a = 2$ : Then  $b = 2(2) = 4$  and  $a = -2x \rightarrow x = -1$   
 $b = -2y \rightarrow y = -2$

so  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 2 & 4 \\ -1 & -2 \end{bmatrix} \leftarrow C(A) = \text{span} \left( \begin{bmatrix} 2 \\ -1 \end{bmatrix}, \begin{bmatrix} 4 \\ -2 \end{bmatrix} \right)$   
 $= \text{span} \left( \begin{bmatrix} 2 \\ -1 \end{bmatrix} \right) = \text{span} \left( \begin{bmatrix} -2 \\ 1 \end{bmatrix} \right) = N(A)$

3.2.31 (a)  $\begin{bmatrix} 4 & 4 & 4 & 4 \\ 4 & 4 & 4 & 4 \\ 4 & 4 & 4 & 4 \end{bmatrix} \xrightarrow[\text{Row 3} - \text{Row 1}]{\text{Row 2} - \text{Row 1}} \begin{bmatrix} 4 & 4 & 4 & 4 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\frac{1}{4} \text{Row 1}} \underbrace{\begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}}_R$

(b)  $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 3 & 4 & 5 \\ 3 & 4 & 5 & 6 \end{bmatrix} \xrightarrow[\text{Row 3} - 3\text{Row 1}]{\text{Row 2} - 2\text{Row 1}} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -1 & -2 & -3 \\ 0 & -2 & -4 & -6 \end{bmatrix} \xrightarrow{\text{Row 3} - 2\text{Row 2}} \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & -1 & -2 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$   
 Then:  $-\text{Row 2} \rightarrow \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$   
 $\xrightarrow{\text{Row 1} - 2\text{Row 2}} \begin{bmatrix} 1 & 0 & -1 & -2 \\ 0 & 1 & 2 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \leftarrow R$

$$(c) \begin{bmatrix} -1 & 1 & -1 & 1 \\ -1 & 1 & -1 & 1 \\ -1 & 1 & -1 & 1 \end{bmatrix} \xrightarrow[\text{Row 3 - Row 1}]{\text{Row 2 - Row 1}} \begin{bmatrix} -1 & 1 & -1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{-\text{Row 1}} \underbrace{\begin{bmatrix} 1 & -1 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}}_R$$

3,2,32 Node 1:  $y_3 = y_1 + y_4$  Node 2:  $y_1 = y_2 + y_5$

Node 3:  $y_2 = y_3 + y_6$  Node 4:  $y_4 + y_5 + y_6 = 0$

$$\begin{cases} -y_1 + y_3 - y_4 = 0 \\ y_1 - y_2 - y_5 = 0 \\ y_2 - y_3 - y_6 = 0 \\ y_4 + y_5 + y_6 = 0 \end{cases} \rightarrow \begin{bmatrix} -1 & 0 & 1 & -1 & 0 & 0 \\ 1 & -1 & 0 & 0 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \\ y_6 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

$A^T$   $\vec{y}$

Row 2 + Row 1  
Then: -Row 1

$$\begin{bmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & -1 & -1 & 0 \\ 0 & 1 & -1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix} \xrightarrow[\text{Then: -Row 2}]{\text{Row 3 + Row 2}} \begin{bmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 1 & 1 & 0 \\ 0 & 0 & 0 & -1 & -1 & -1 \\ 0 & 0 & 0 & 1 & 1 & 1 \end{bmatrix} \xrightarrow[\text{Then: -Row 3}]{\text{Row 4 + Row 3}}$$

$$\begin{bmatrix} 1 & 0 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow[\text{Row 2 - Row 3}]{\text{Row 1 - Row 3}} \begin{bmatrix} 1 & 0 & -1 & 0 & -1 & -1 \\ 0 & 1 & -1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \leftarrow \text{This is R.}$$

$N(A^T):$

$$\begin{aligned} y_1 - y_3 - y_5 - y_6 &= 0 \\ y_2 - y_3 - y_6 &= 0 \\ y_4 + y_5 + y_6 &= 0 \end{aligned} \rightarrow \vec{y} = \begin{bmatrix} y_3 + y_5 + y_6 \\ y_3 + y_6 \\ y_3 \\ -y_5 - y_6 \\ y_5 \\ y_6 \end{bmatrix}$$

$y_3, y_5, y_6$  free

$$= y_3 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} + y_5 \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \\ 1 \\ 0 \end{bmatrix} + y_6 \begin{bmatrix} 1 \\ 0 \\ 0 \\ -1 \\ 0 \\ 1 \end{bmatrix}$$

3 special solutions

3.3.4  $\left[ \begin{array}{ccc|c} 1 & 3 & 1 & 2 \\ 2 & 6 & 4 & 8 \\ 0 & 0 & 2 & 4 \end{array} \right] \xrightarrow{\text{Row 1} - 2\text{Row 2}} \left[ \begin{array}{ccc|c} 1 & 3 & 1 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 2 & 4 \end{array} \right] \xrightarrow{\text{Row 3} - \text{Row 2}} \left[ \begin{array}{ccc|c} 1 & 3 & 1 & 2 \\ 0 & 0 & 2 & 4 \\ 0 & 0 & 0 & 0 \end{array} \right]$   
 Then:  $\frac{1}{2}\text{Row 2}$

$\left[ \begin{array}{ccc|c} 1 & 3 & 1 & 2 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{\text{Row 1} - \text{Row 2}} \left[ \begin{array}{ccc|c} 1 & 3 & 0 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \begin{cases} x_0 + 3y = 0 \\ z + 2t = 0 \\ y, t \text{ free} \end{cases}$

$\vec{x} = \begin{bmatrix} 1/2 - 3y \\ y \\ 1/2 - 2t \\ t \end{bmatrix} = \underbrace{\begin{bmatrix} 1/2 \\ 0 \\ 1/2 \\ 0 \end{bmatrix}}_{\vec{x}_p} + y \underbrace{\begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}}_{\vec{x}_n} + t \underbrace{\begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \end{bmatrix}}_{\vec{x}_n}$   
 Special null space solutions

3.3.7  $A = \begin{bmatrix} 1 & 3 & 1 \\ 3 & 8 & 2 \\ 2 & 4 & 0 \end{bmatrix} \begin{array}{l} \text{Row 2} - 3\text{Row 1} \\ \text{Row 3} - 2\text{Row 1} \end{array} \rightarrow \left[ \begin{array}{ccc|c} 1 & 3 & 1 & b_1 \\ 0 & -1 & -1 & b_2 - 3b_1 \\ 0 & -2 & -2 & b_3 - 2b_1 \end{array} \right] \xrightarrow{\begin{array}{l} \text{Row 3} \\ -2\text{Row 2} \end{array}}$

$\left[ \begin{array}{ccc|c} 1 & 3 & 1 & b_1 \\ 0 & -1 & -1 & b_2 - 3b_1 \\ 0 & 0 & 0 & (b_3 - 2b_1) - 2(b_2 - 3b_1) \end{array} \right]$

Need  $4b_1 - 2b_2 + b_3 = 0$  for  $\begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$  to be in  $C(A)$ .

Some combination of rows gives 0:  $4\text{Row 1} - 2\text{Row 2} + \text{Row 3} = 0$

3.3.13 (a) Not true unless  $\vec{b} = \vec{0}$ . For example, could  $2\vec{x}_p + 3\vec{x}_n$  be a solution to  $A\vec{x} = \vec{b}$ ? Then  $A(2\vec{x}_p + 3\vec{x}_n) = \vec{b}$ ,  
 so  $\vec{b} = A(2\vec{x}_p + 3\vec{x}_n) = 2\underbrace{A\vec{x}_p}_{\vec{b}} + 3\underbrace{A\vec{x}_n}_{\vec{0}} = 2\vec{b} \rightsquigarrow$   
 $2\vec{b} - \vec{b} = \vec{0} \rightsquigarrow \vec{b} = \vec{0}$ . Doesn't work unless  $\vec{b} = \vec{0}$ .

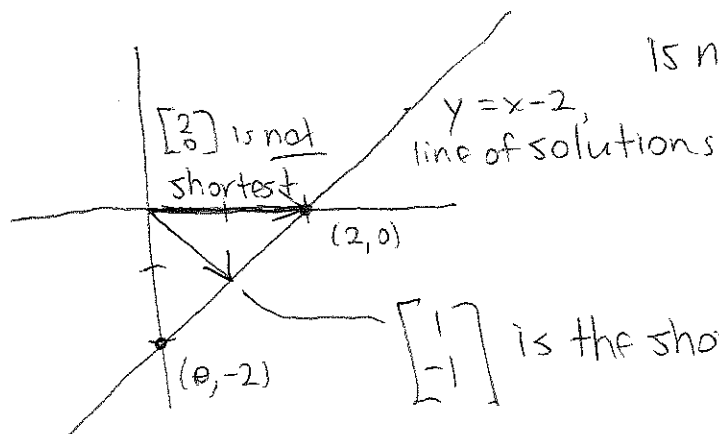
(b) Not true if  $N(A)$  is bigger than  $\{\vec{0}\}$ , because then if  $\vec{x}_p$  works as a particular solution, so does  $\vec{x}_p + \vec{x}_n$  any non-zero vector in  $N(A)$ .

(c) consider  $\begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \rightsquigarrow \begin{cases} x = 2 + y \\ y \text{ free} \end{cases}$

$$\rightarrow \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2+y \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix} + y \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

or,  $y = x - 2$

This  $\vec{x}_p$  has free variable  $y=0$ , but it is n/t the shortest solution



$\begin{bmatrix} 1 \\ -1 \end{bmatrix}$  is the shortest solution ( $\|\begin{bmatrix} 1 \\ -1 \end{bmatrix}\| = \sqrt{2}$ )

(d) The null space always has at least one vector,  $\vec{0}$ .

3.3.34 (a) One special solution means  $\underbrace{\# \text{columns}}_4 = \text{rank} + 1$

So rank of  $A = 3$ .

complete solution to  $A\vec{x} = \vec{0}$  is just all linear combinations of special solutions, so  $\vec{x} = x_3 \begin{bmatrix} 2 \\ 3 \\ 1 \\ 0 \end{bmatrix}$  the free variable.

(b) Free variable  $x_3$  means pivot columns are 1, 2, and 4.

$R = \begin{bmatrix} 1 & 0 & -2 & 0 \\ 0 & 1 & -3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$  To get  $\begin{cases} x_1 = 2x_3 \\ x_2 = 3x_3 \end{cases}$  in null space equations.

(c)  $R$  has no row of 0's, so no condition on  $b_1, b_2, b_3$  is necessary to guarantee  $A\vec{x} = \vec{b}$  has a solution.

# Graded Problem 1

$$\begin{bmatrix} -3 & -1 & 0 & 1 \\ -4 & -1 & 1 & 1 \\ -1 & 1 & 4 & -1 \end{bmatrix} \xrightarrow[\text{Row 1} \leftrightarrow \text{Row 3}]{-\text{Row 3, then}} \begin{bmatrix} 1 & -1 & -4 & 1 \\ -4 & -1 & 1 & 1 \\ -3 & -1 & 0 & 1 \end{bmatrix}$$

(6)

$$\begin{array}{l} \text{Row 2} + 4\text{Row 1} \\ \text{Row 3} + 3\text{Row 1} \end{array} \rightarrow \begin{bmatrix} 1 & -1 & -4 & 1 \\ 0 & -5 & -15 & 5 \\ 0 & -4 & -12 & 4 \end{bmatrix} \xrightarrow[\text{Then Row 3} - \text{Row 2}]{-\frac{1}{5}\text{Row 2}, -\frac{1}{4}\text{Row 3}} \begin{bmatrix} 1 & -1 & -4 & 1 \\ 0 & 1 & 3 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{\text{Row 1} + \text{Row 2}}$$

$$\begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 3 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

R

$$\begin{array}{l} x_1 - x_3 = 0 \\ x_2 + 3x_3 - x_4 = 0 \\ x_3, x_4 \text{ free} \end{array} \rightarrow \vec{x} = \begin{bmatrix} x_3 \\ -3x_3 + x_4 \\ x_3 \\ x_4 \end{bmatrix}$$

$$= x_3 \begin{bmatrix} 1 \\ -3 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

special solutions

# Graded Problem 2

$$A: \begin{bmatrix} 2 & -1 & -1 & | & b_1 \\ -1 & 2 & -1 & | & b_2 \\ -1 & -1 & 2 & | & b_3 \end{bmatrix} \xrightarrow[\text{Row 3} + \frac{1}{2}\text{Row 1}]{\text{Row 2} + \frac{1}{2}\text{Row 1}} \begin{bmatrix} 2 & -1 & -1 & | & b_1 \\ 0 & 3/2 & -3/2 & | & b_2 + \frac{1}{2}b_1 \\ 0 & -3/2 & 3/2 & | & b_3 + \frac{1}{2}b_1 \end{bmatrix}$$

$$\xrightarrow{\text{Row 3} + \text{Row 2}} \begin{bmatrix} 2 & -1 & -1 & | & b_1 \\ 0 & 3/2 & -3/2 & | & b_2 + \frac{1}{2}b_1 \\ 0 & 0 & 0 & | & b_1 + b_2 + b_3 \end{bmatrix} \xrightarrow[b_3 = -2]{b_1 = 1, b_2 = 1} \begin{bmatrix} 2 & -1 & -1 & | & 1 \\ 0 & 3/2 & -3/2 & | & 3/2 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

The condition  $b_1 + b_2 + b_3 = 0$  guarantees  $\vec{b}$  is in  $C(A)$

$\downarrow \frac{2}{3}\text{Row 2}$

$$\xrightarrow{\text{Row 1} + \text{Row 2}} \begin{bmatrix} 2 & -1 & -1 & | & 1 \\ 0 & 1 & -1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\xrightarrow{\frac{1}{2}\text{Row 1}} \begin{bmatrix} 1 & 0 & -1 & | & 1 \\ 0 & 1 & -1 & | & 1 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

$$\begin{array}{l} x_1 = x_3 + 1 \\ x_2 = x_3 + 1 \\ x_3 \text{ free} \end{array} \rightarrow \vec{x} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$