Chapter H: Know what orthogonal vectors/subspaces are.

- Projections Know how to project vectors onto a subspace and how to compute projection matrices.
- Least squares approximations (application of projection)
- -Orthogonal matrices and orthonormal basis. Know how to turn any basis into orthonormal using Gram-Schmidt process.

Chapter 5: Determinants

- Know how to compute using row operations and cofactor expansion.
- Applications to volumes, and cross products.
- Chapter 6: Know how to find eigenvalues/eigenvectors. (Hint: on final, eigenvalues will never be more complicated than simple fractions.)
- Know how to diagonalize A lifthere is a bosis of eigenvectors), and use it to calculate AN.
- Note = Differential equations will not be on the final exam.

Chapter 7: Know how to compute singular value decomposition of a 2x2 matrix, and know the geometric interpretation of singular values (of=max of ||Ax||/||x||)

Key topics to know from earlier in the course: Motrix algebra: - Matrix multiplication - Inverses 3 Know how to use these - LU decomposition 3 to solve linear equations. Connections to geometry = Dot products, lengths, angles. Chapter 3 - Definitions of subspace, null space, column space, row space left null space. - Finding all solutions to linear equations. - Know what it means for vectors to be independent. - Know how to find bases for subspaces, especially for the four subspaces associated to a matrix.