# **Vaunix Technology Corporation Lab Brick® LMS Series of Signal Generators**

## API User Manual





#### NOTICE

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#### 1.0 OVERVIEW

The LabBrick Microwave Signal Generator Win32 SDK supports developers who want to control LabBrick LMS Series Signal Generators from Windows programs, or who want to control the synthesizers from LabVIEW¹ or other National Instruments programming environments. The SDK includes a dll which provides a Win32 API to find, initialize, and control the synthesizers, along with header files and an example Win32 C program which demonstrates the use of the API. The standard version of the DLL uses Microsoft's C++ style DLL linkage, which includes standard Microsoft style function name decoration. Other versions are available with traditional ANSI-C style DLL linkage, which is used with LabWindows², and versions for use with Microsoft's Visual Basic language. If you need a DLL with one of the other Microsoft support naming conventions, or a similar library for use with the Linux family ofoperating systems please contact Vaunix technical support.

<sup>&</sup>lt;sup>1</sup> LabVIEW is a trademark of National Instruments

<sup>&</sup>lt;sup>2</sup> LabWindows is a trademark of National Instruments

## 2.0 USING THE SDK

The SDK consists of a dll, named VNX\_fmsynth.dll, along with this documentation, a C style header file, a library file for linking to the dll, and a VC 6 example program. Unzip the SDK into a convenient place on your hard disk, and then copy the dll and library file into the directory of the executable program you are creating. Add the header file (VNX\_fmsynth.h) to your project, and include it with the other header files in your program. Make sure that the linker directives include the path of the library file.

#### 3.0 PROGRAMMING

#### 3.1 Overall Strategy and API Achitecture

The API provides functions for identifying how many and what type of LabBrick LMS signal generators are connected to the system, initializing signal generators so that you can send them commands and read their state, functions to control the operation of the signal generators, and finally a function to close the software connection to the signal generator when you no longer need to communicate with it.

The API can be operated in a test mode, where the functions will simulate normal operation but will not actually communicate with the hardware devices. This feature is provided as a convenience to software developers who may not have a LabBrick signal generator with them, but still want to be able to work on an applications program that uses the LabBrick. Of course it is important to make sure that the API is in its normal mode in order to access the actual hardware!

Be sure to call fnLMS\_SetTestMode(FALSE), unless of course you want the API to operate in its test mode. In test mode there will be 2 devices, an LMS-103 and an LMS-123. The first step is to identify the synthesizers connected to the system. Call the function fnLMS\_GetNumDevices() to get the number of synthesizers attached to the system. Note that USB devices can be attached and detached by users at any time. If you are writing a program which needs to handle the situation where devices are attached or detached while the program is operating, you should periodically call fnLMS\_GetNumDevices() to see if any new devices have been attached.<sup>3</sup>

Allocate an array big enough to hold the device ids for the number of devices present. While you should use the DEVID type declared in VNX\_fmsynth.h it's just an array of units at this point. You may want to allocate an array large enough to hold MAXDEVICES device ids, so that you do not have to handle the case where the number of attached devices increases.

Call fnLMS\_GetDevInfo(DEVID \*ActiveDevices), which will fill in the array with the device ids for each connected frequency synthesizer. The function returns an integer, which is the number of devices present on the machine.

<sup>&</sup>lt;sup>2</sup> Usually it is a good idea to call fnLMS\_GetNumDevices() at around 1 second intervals. While a short interval reduces the chances, it is still possible that the user will remove one device and replace it with another however, so to completely handle all the cases which can result from users hot plugging devices your application needs to check to see not only if the number of devices is different, but if the same number of devices are present, that they are not different devices.

The next step is to call fnLMS\_GetModelName(DEVID deviceID, char \*ModelName) with a null ModelName pointer to get the length of the model name, or just use a buffer that can hold MAX\_MODELNAME chars. You can use the model name to identify the type of synthesizer. Call fnLMS\_GetSerialNumber(DEVID deviceID) to get the serial number of the synthesizer. Based on that information, your program can determine which device to open.

Once you have identified the synthesizer you want to send commands to, call fnLMS\_InitDevice(DEVID deviceID) to actually open the device and get its various parameters like frequency setting, frequency sweep parameters, etc. After the fnLMS\_InitDevice function has completed you can use any of the get functions to read the settings of the synthesizer.

To change one of the settings of the synthesizer, use the corresponding set function. For example, to set the synthesizer frequency, call fnLMS\_SetFrequency(DEVID deviceID, int frequency). The first argument is the device id of the synthesizer, the second is the desired output frequency. Frequency is specified in 10 Hz increments, where:

frequency = Frequency (Hz) / 10

For example, to specify an output frequency of 5.5 GHz, frequency = 550000000.

To set the output power level, call fnLMS\_SetPowerLevel(DEVID deviceID, int powerlevel) with the output power level you want. The power level is encoded as the number of .25dB increments, with a resolution of .5dB. To set a power level of +5 dBm, for example, powerlevel would be 20. To set a power level of -20 dBm, powerlevel would be -80.

Note that the LabBrick signal generators have a maximum and minimum settable power level. You can query the limits with calls to fnLMS\_GetMaxPwr(DEVID deviceID) and fnLMS\_GetMinPwr(DEVID deviceID). Both functions use the same encoding of the powerlevel as the SetPowerLevel function.

When you are done with the device, call fnLMS CloseDevice(DEVID deviceID).

#### 3.2 Status Codes

All of the set functions return a status code indicating whether an error occurred. The get functions normally return an integer value, but in the event of an error they will return an error code. The error codes can be distinguished from normal data by their numeric value, since all error codes have their high bit set, and they are outside of the range of normal data.

Functions that return a floating point result use specific, negative numeric values to indicate if an error occurred

A separate function, fnLMS\_GetDeviceStatus(DEVID deviceID) provides access to a set of status bits describing the operating state of the synthesizer. This function can be used to check if a device is currently connected or open.

The values of the status codes are defined in the VNX fmsynth.h header file.

#### 3.3 Functions – Selecting the Device

#### VNX FSYNSTH API void fnLMS SetTestMode(bool testmode)

Set testmode to FALSE for normal operation. If testmode is TRUE the dll does not communicate with the actual hardware, but simulates the basic operation of the dll functions. It does not simulate the operation of frequency sweeps generated by the actual hardware, but it does simulate the behavior of the functions used to set the parameters for sweeps.

#### VNX FSYNSTH API int fnLMS GetNumDevices()

This function returns a count of the number of connected synthesizers.

#### VNX FSYNSTH API int fnLMS GetDevInfo(DEVID \*ActiveDevices)

This function fills in the ActiveDevices array with the device ids for the connected synthesizers. Note that the array must be large enough to hold a device id for the number of devices returned by fnLMS\_GetNumDevices. The function also returns the number of active devices, which can, under some circumstances, be less than the number of devices returned in the previous call to fnLMS\_GetNumDevices.

The device ids are used to identify each device, and are used in the rest of the functions to select the device. Note that while the device ids may be small integers, and may, in some circumstances appear to be numerically related to the devices present, they should only be used as opaque handles.

#### VNX FSYNSTH API int fnLMS GetModelName(DEVID deviceID, char \*ModelName)

This function is used to get the model name of the synthesizer. If the function is called with a null pointer, it returns just the length of the model name string. If the function is called with a non-null string pointer it copies the model name into the string and returns the length of the string. The string length will never be greater than the constant MAX\_MODELNAME which is defined in VNX\_fmsynth.h. This function can be used regardless of whether or not the synthesizer has been initialized with the fnLMS\_InitDevice function.

#### VNX FSYNSTH API int fnLMS GetSerialNumber(DEVID deviceID)

This function is used to get the serial number of the synthesizer. It can be called regardless of whether or not the synthesizer has been initialized with the fnLMS\_InitDevice function. If your system has multiple synthesizers, your software should use each device's serial number to keep track of each specific device. Do not rely upon the order in which the devices appear in the table of active devices. On a typical system the individual synthesizers will typically be found in the same order, but there is no guarantee that this will occur.

#### VNX FSYNSTH API int fnLMS GetDeviceStatus(DEVID deviceID)

This function can be used to obtain information about the status of a device, even before the device is initialized. (Note that information on the sweep activity of the device is not guaranteed to be available before the device is initialized.)

#### VNX FSYNSTH API int fnLMS InitDevice(DEVID deviceID)

This function is used to open the device interface to the synthesizer and initialize the dll's copy of the device's settings. If the fnLMS\_InitDevice function succeeds, then you can use the various fnLMS\_Get\* functions to read the synthesizer's settings. This function will fail, and return an error code if the synthesizer has already been opened by another program.

#### VNX FSYNSTH API int fnLMS CloseDevice(DEVID deviceID)

This function closes the device interface to the synthesizer. It should be called when your program is done using the synthesizer.

## 3.4 Functions – Setting parameters on the Signal Generator

#### VNX FSYNSTH API LVSTATUS fnLMS SetFrequency(DEVID deviceID, int frequency)

This function is used to set the output frequency of the synthesizer. Frequency is encoded as an integer number of 10 Hz steps:

frequency = Frequency (Hz) / 10

For example, to specify an output frequency of 6 GHz, frequency = 6000000. The value of frequency must be within the range of the attached synthesizer or an error will be returned.

## VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetPowerLevel(DEVID deviceID, int powerlevel);

This function is used to set the output power level of the programmable synthesizer. The power level is specified in .25dB units. The encoding is:

powerlevel = (max power level - desired output power) / .25dB

For example, if the maximum output power is +10 dBm and you want -7.5 dBm output power then you should set powerlevel to -70.

#### VNX FSYNSTH API LVSTATUS fnLMS SetStartFrequency(DEVID deviceID, int startfrequency)

This function sets the frequency at the beginning of a frequency sweep. The encoding of startfrequency is the same as the fnLMS\_SetFrequency function. Note that the start frequency should be less than the end frequency when you want the frequency to step upwards during the sweep. For a sweep where the frequency decreases, then the start frequency should be larger than the end frequency.

## VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetEndFrequency(DEVID deviceID, int endfrequency)

This function sets the frequency at the end of a frequency sweep. The encoding of endfrequency is the same as the fnLMS\_SetFrequency function.

## VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetSweepTime(DEVID deviceID, int sweeptime)

This function sets the time duration of the frequency sweep. The sweeptime variable is encoded as a number of milliseconds. The minimum sweep time is 1 millisecond.

#### VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetRFOn(DEVID deviceID, bool on)

This function turns the RF stages of the synthesizer on (on = TRUE) or off (on = FALSE).

#### VNX FSYNSTH API int fnLMS SetUseInternalRef(DEVID deviceID, bool internal);

This function configures the synthesizer to use the internal reference if internal = 1. If internal = 0, then the synthesizer is configured to use an external frequency reference.

#### VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetSweepDirection(DEVID deviceID, bool up)

This function is used to set the direction of the frequency sweep. To create a sweep with increasing frequency, set up = TRUE. Note that the sweep start frequency value must be less than the sweep end frequency value for a sweep with increasing frequency. For a sweep that decreases in frequency, the sweep start value must be greater than the sweep end value.

#### VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetSweepMode(DEVID deviceID, bool mode)

This function is used to select either a single frequency sweep, or a repeating series of sweeps. If mode = TRUE then the sweep will be repeated, if mode = FALSE the sweep will only happen once.

VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetSweepType(DEVID deviceID, bool swptype)
This function is used to select between a single directional frequency sweep, or a sweep which returns to its original frequency after each sweep. If swptype = TRUE then the sweep will be bidirectional, if swtype = FALSE the sweep will only go in one direction. For a bidirectional sweep a graph of frequency vs. time for a repeating sweep will appear like a triangle wave, for a non-bidirectional sweep, the graph of frequency vs. time will appear like a sawtooth wave.

#### VNX FSYNSTH API LVSTATUS fnLMS StartSweep(DEVID deviceID, bool go)

This function is used to start and stop the frequency sweeps. If go = TRUE the synthesizer will begin sweeping, FALSE stops the sweep. You must set the sweep parameters before calling this function to start the sweep.

VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetFastPulsedOutput(DEVID deviceID, float pulseontime, float pulsereptime, bool on)

This function is the preferred way to control the internal pulse modulation option. The pulseontime parameter is the length of the pulse on time in seconds. The pulsereptime parameter is the length of the repetition period in seconds. Both values can range from 100 nanoseconds (0.100e-6) to 1000 seconds (1.0e3). Set on = TRUE to start the pulsed output modulation.

- VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetPulseOnTime(DEVID deviceID, float pulseontime)
  This function is used to set the length of the RF pulse on time of the device's internal modulation for devices that support pulsed output modulation. The pulseontime parameter is the length of the pulse on time in seconds, with a 100 nanosecond minimum. This function is not recommended for general use. Instead use the fnLMS\_SetFastPulsedOutput function.
- VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SetPulseOffTime(DEVID deviceID, float pulseofftime)
  This function is used to set the length of the RF pulse off time of the device's internal modulation.
  The pulseofftime parameter is the length of the pulse off time in seconds, with a 100 nanosecond minimum. The repetition period of the pulse modulation is equal to pulseontime + pulseofftime.
  This function is not recommended for general use. Instead use the fnLMS\_SetFastPulsedOutput function.
- VNX\_FSYNSTH\_API LVSTATUS fnLMS\_EnableInternalPulseMod(DEVID deviceID, bool on) This function is used to turn on and off the internal output modulation. If on = TRUE the synthesizer will pulse its RF output on and off according to the values set for the pulse on time and pulse off time using either the fnLMS\_SetFastPulsedOutput function or the functions to set pulse on and off time directly . To stop the internal pulse modulation, set on = FALSE. Always disable internal pulse modulation before setting the pulse on and off time using the fnLMS\_SetPulseOnTime and fnLMS\_SetPulseOffTime functions.
- VNX\_FSYNSTH\_API fnLMS\_SetUseExternalPulseMod(DEVID deviceID, bool external); This function configures the synthesizer to use the external pulse modulation input signal if external = TRUE. If external = FALSE, then the synthesizer is configured to use the internal pulse modulation. Not all hardware configurations support an external pulse modulation input. Both the internal and external pulse modulation can operate at the same time, allowing more complex modulation patterns.
- VNX\_FSYNSTH\_API LVSTATUS fnLMS\_SaveSettings(DEVID deviceID)
  The LabBrick synthesizers can save their settings, and then resume operating with the saved settings when they are powered up. Set the desired parameters, then use this function to save the settings.

## 3.5 Functions – Reading parameters from the Signal Generator

#### VNX FSYNSTH API int fnLMS GetFrequency(DEVID deviceID)

This function returns the current frequency setting of the selected device. When a sweep is active this value will change dynamically to reflect the current setting of the device. The return value is in 10 Hz units.

## VNX\_FSYNSTH\_API int fnLMS\_GetStartFrequency (DEVID deviceID)

This function returns the current frequency sweep starting value setting of the selected device. The return value is in 10 Hz units.

## VNX\_FSYNSTH\_API int fnLMS\_GetEndFrequency (DEVID deviceID)

This function returns the current frequency sweep end setting of the selected device. The return value is in 10 Hz units.

## VNX\_FSYNSTH\_API int fnLMS\_GetSweepTime(DEVID deviceID)

This function returns the current frequency sweep time in milliseconds. A one second sweep time, for example, would be returned as 1000.

## VNX\_FSYNSTH\_API float fnLMS\_GetPulseOnTime(DEVID deviceID)

This function returns the pulse on time, which is the length of time that RF output is enabled when internal pulse modulation is operating, in seconds.

#### VNX FSYNSTH API float fnLMS GetPulseOffTime(DEVID deviceID)

This function returns the pulse off time, which is the length of time that RF output is disabled when internal pulse modulation is operating, in seconds. The pulse repetition period is equal to the pulse on time added to the pulse off time.

#### VNX FSYNSTH API int fnLMS GetPulseMode(DEVID deviceID)

This function returns an integer value which is 1 when the synthesizer internal pulse modulation is active, or 0 when the internal pulse modulation is off.

#### VNX FSYNSTH API int fnLMS GetUseInternalPulseMod(DEVID deviceID)

This function returns an integer value which is 1 when the synthesizer is configured to use its internal pulse modulation, or 0 when the external pulse modulation input is selected to control the output.

#### VNX FSYNSTH API int fnLMS GetHasFastPulseMode(DEVID deviceID)

This function returns an integer value which is 1 when the synthesizer has the internal pulse modulation option, or 0 when the option is not installed.

#### VNX FSYNSTH API int fnLMS GetRF On(DEVID deviceID)

This function returns an integer value which is 1 when the synthesizer is "on", or 0 when the synthesizer has been set "off" by the fnLMS\_SetRFOn function.

#### VNX FSYNSTH API int fnLMS GetUseInternalRef(DEVID deviceID);

This function returns an integer value which is 1 when the synthesizer is configured to use its internal frequency reference. It returns a value of 0 when the synthesizer is configured to use an external frequency reference.

#### VNX FSYNSTH API int fnLMS GetPowerLevel(DEVID deviceID);

This function returns the difference between the MaxPwr and the current power level setting as an integer number of .25 dB units. As an example, if the MaxPwr is +10 dBm and the unit has a current output power level of +3 dBm, this will result in the value 28 being returned (+10-3)/.25=28, while an output power level of +3.5 dBm would result in the value 26 being returned. The output power resolution is .5 dB.

#### VNX FSYNSTH API int fnLMS GetMaxPwr(DEVID deviceID);

This function returns the maximum output power level that the synthesizer can provide, encoded in the same format as the fnLMS\_GetPowerLevel function. For a synthesizer with +10 dBm maximum output power level this function returns the integer value 40. This is a read only value.

#### VNX FSYNSTH API int fnLMS GetMinPwr(DEVID deviceID);

This function returns the minimum output power level that the synthesizer can provide, encoded in the same format as the fnLMS\_GetPowerLevel function. Typically this value is a negative number. For example, a device with -45 dBm minimum output power would return an integer value of -180. This is a read only value.

#### VNX FSYNSTH API int fnLMS GetMaxFreq (DEVID deviceID)

This function returns the maximum output frequency that the device can provide. The value is represented in 10 Hz units.

#### VNX FSYNSTH API int fnLMS GetMinFreq(DEVID deviceID)

This function returns the minimum output frequency that the device can provide. The value is represented in 10 Hz units.

## 4.0 PROGRAMMING SUPPORT

Lab Brick programming support is available from Vaunix Technology Corporation. Please contact our technical support group by email - LabBrickSupport@Vaunix.com.

Vaunix Technology also offers custom programming solutions. Send us your requirements to receive a fixed rate project quotation.

Thank you for using our Lab Brick products.