### ${\bf RobotFramework\_Test suites}$

v. 0.1.0

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29.06.2022

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## Introduction

RobotFramework\_Testsuites
!!! add introduction - if wanted !!

# Description

The RobotFramework AIO test suites management: TO BE CONTINUED

### CConfig.py

#### 3.1 Class: dotdict

RobotFramework\_Testsuites.Config.CConfig

#### 3.2 Class: CConfig

RobotFramework\_Testsuites.Config.CConfig

Defines the properties of configuration Holds the identified config files. Level1 is highest priority, Level4 is lowest priority.

(remaining content needs to be fixed and restored)

#### 3.2.1 Method: loadCfg

#### 3.2.2 Method: updateCfg

staticmethod updateParams: This method updates preprocessor, global or local params base on ROBFW local config or any json config file according to purpose of specific testsuite.

Args: sUpdateCfgFile: str

Returns: None

#### 3.2.3 Method: verifyRbfwVersion

Validate the current robotframework version with maximum and minimum version (if provided in the configuration file). In case the current version is not between min and max version, then the execution of testsuite is terminated with "unknown" state Method: bValidateMinVersion ------

 $Validate\ current\ version\ with\ required\ minimun\ version.\ Method:\ bValidateMaxVersion\ -----$ 

 $Validate\ current\ version\ with\ required\ maximun\ version.\ Method:\ bValidateSubVersion\ -----$ 

Validate the format of provided sub version and parse it into sub tuple for version comparision. Method: tuple Version ------

Return a tuple which contains the (major, minor, patch) version.

(remaining content needs to be fixed and restored)

#### 3.2.4 Method: versioncontrol\_error

Wrapper version control error log: Log error message of version control due to reason and set to unknown state. reason can only be "conflict\_min", "conflict\_max" and "wrong\_minmax".

## COnFailureHandle.py

### 4.1 Class: COnFailureHandle

RobotFramework\_Testsuites.Keywords.COnFailureHandle

4.1.1 Method: is\_noney

4.1.2 Method: register\_keyword\_run\_on\_failure

TBD

## CSetup.py

### 5.1 Class: CSetupKeywords

RobotFramework\_Testsuites.Keywords.CSetup

Definition setup keywords Method: testsuite\_setup -----

5.1.1 Method: testsuite\_teardown

5.1.2 Method: testcase\_setup

5.1.3 Method: testcase\_teardown

5.1.4 Method: update\_config

5.2 Class: CGeneralKeywords

RobotFramework\_Testsuites.Keywords.CSetup

Definition setup keywords Method: get\_config ------

oConfigParams: is the dictionary consist of some configuration params which are return to user from get\_config\_params keyword Method: load\_json ------

## CStruct.py

### 6.1 Class: CStruct

RobotFramework\_Testsuites.Utils.CStruct

Constructor  $\_init\_\_$  creates the given attributes dynamically at runtime.

Args:

Attributes to be created with the initial value

Returns:

Accessible attributes

# Event.py

7.1 Class: Event

RobotFramework\_Testsuites.Utils/Events.Event

### 7.1.1 Method: trigger

## ScopeEvent.py

8.1 Class: ScopeEvent

RobotFramework\_Testsuites.Utils/Events.ScopeEvent

8.1.1 Method: trigger

8.2 Class: ScopeStart

RobotFramework\_Testsuites.Utils/Events.ScopeEvent

8.3 Class: ScopeEnd

RobotFramework\_Testsuites.Utils/Events.ScopeEvent

# $\_$ init $\_$ .py

- 9.1 Function: on
- 9.2 Function: dispatch
- 9.3 Function: register\_event

# LibListener.py

### 10.1 Class: LibListener

RobotFramework\_Testsuites.Utils.LibListener

Define some hook methods

## $\_$ init $\_$ .py

#### 11.1 Class: RobotFramework\_Testsuites

RobotFramework\_Testsuites.\_\_init\_\_

RobotFramework\_Testsuites is the Bosch testing library for Robot Framework. RobotFramework\_Testsuites control peripheral devices, tools and target under testing. Method: run\_keyword\_\_\_\_\_

11.1.1 Method: get\_keyword\_tags

11.1.2 Method: get\_keyword\_documentation

11.1.3 Method: failure\_occurred

11.2 Class: CTestsuitesCfg

RobotFramework\_Testsuites.\_\_init\_\_

# version.py

### 12.1 Function: robfwaio\_version

Return testsuitemanagement version as Robot framework AIO version

# Appendix

#### About this package:

Table 13.1: Package setup

Setup parameter	Value
Name	RobotFramework_Testsuites
Version	0.1.0
Date	29.06.2022
Description	Functionality to manage RobotFramework testsuites
Package URL	robotframework-testsuitesmanagement
Author	Mai Dinh Nam Son
Email	son.maidinhnam@vn.bosch.com
Language	Programming Language :: Python :: 3
License	License :: OSI Approved :: Apache Software License
OS	Operating System :: OS Independent
Python required	>=3.0
Development status	Development Status :: 4 - Beta
Intended audience	Intended Audience :: Developers
Topic	Topic :: Software Development

# History

0.1.0	06/2022
Initial version	on

 $RobotFramework\_Test suites.pdf$ 

Created at 30.06.2022 - 15:04:09 by GenPackageDoc v. 0.20.0