

Improving Mixing Time in Gibbs Sampling

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MLD Journal Club

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From Fields to Trees

Hamze, de Freitas 2004

Covariance Structure of the Gibbs Sampler ...

Liu, Wong, Kong 1994

Markov Chain Strategies in Scientific Computing

Jun Liu, 2001

The Problem

Given: Graphical Model with known Parameters.

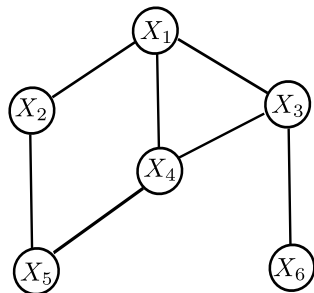
Goal: Estimate $\mathbb{E}[h(X)]$

E.g.: $\mathbb{1}_A(x)$, $\sum_i X_i$

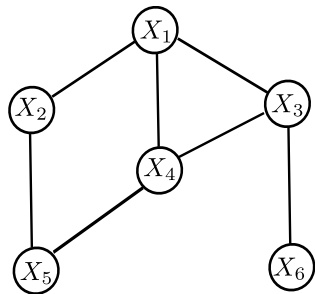
Generate Samples: $X^{(1)}, X^{(2)}, \dots, X^{(N)}$

Empirical Estimator

$$\mu_0 = \frac{1}{N} \sum_{i=1}^N h(X^{(i)})$$



Gibbs Sampling



Current Sample: $X^{(t)}$

$$X_1^{(t+1)} \mid X_{2,3,4,5,6}^{(t)}$$

$$X_2^{(t+1)} \mid X_1^{(t+1)}, X_{3,4,5,6}^{(t)}$$

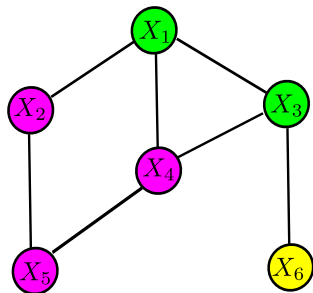
...

$$X_6^{(t+1)} \mid X_{1,2,3,4,5}^{(t+1)}$$

Next Sample: $X^{(t+1)}$

$X^{(1)} \rightarrow X^{(2)} \rightarrow \dots$ is a Markov Chain with eqib^m distribution P .

Blocked Gibbs Sampling



Current Sample: $X^{(t)}$

$$X_{1,3}^{(t+1)} \mid X_{2,4,5,6}^{(t)}$$

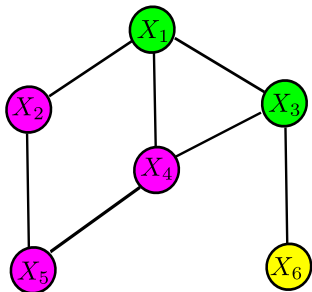
$$X_{2,4,5}^{(t+1)} \mid X_{1,3}^{(t+1)}, X_6^{(t)}$$

$$X_6^{(t+1)} \mid X_{1,2,3,4,5}^{(t+1)}$$

Next Sample: $X^{(t+1)}$

$X^{(1)} \rightarrow X^{(2)} \rightarrow \dots$ is a Markov Chain with eqlb^m distribution P .

Blocked Gibbs Sampling

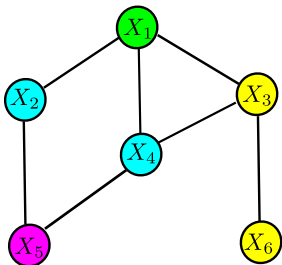
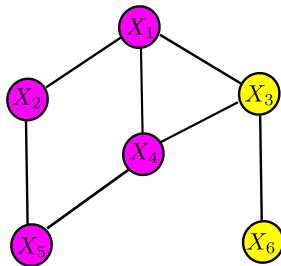
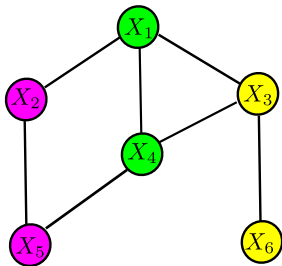


Why Blocked Gibbs ?

Sampling from conditional distribution is difficult.

BUT, Chain mixes faster
 \Rightarrow better samples.

How to Block (Partition) the Variables?



Outline

- 1 Digression
 - MCMC Theory
 - Rao-Blackwellisation
- 2 Primary Idea
 - Tree Partitions
- 3 Hamze & de Freitas, 2004
- 4 My 701 Course Project

$$X^{(1)} \rightarrow X^{(2)} \rightarrow \dots \rightarrow X^{(t)} \rightarrow X^{(t+1)} \rightarrow \dots$$

$\pi \leftarrow$ Equilibrium Distribution

$$L_0(\pi) = \{h : \Omega \rightarrow \mathbb{R} : \mathbb{E}_\pi h(X) = 0, \mathbb{V}_\pi h(X) < \infty\}$$

$$\langle h, g \rangle = \text{Covar}_\pi(h(X), g(X))$$

$(L_0(\pi), \langle \cdot, \cdot \rangle)$ is a Hilbert Space.

$$\|h\|^2 = \langle h, h \rangle = \text{Covar}_\pi(h(X), h(X)) = \mathbb{V}_\pi(h(X))$$

Forward Operator

Define $F : L_0(\pi) \rightarrow L_0(\pi)$, $[Fh](z) = \mathbb{E}[h(X^{(1)}) | X^{(0)} = z]$

Norm of operator: $\|F\| = \sup_{\|h\| \leq 1} \|Fh\|$.

$$\begin{aligned}\|Fh\|^2 &= \mathbb{V}_{X^{(0)} \sim \pi}(\mathbb{E}[h(X^{(1)}) | X^{(0)}]) \\ &\leq \mathbb{V}_{X^{(1)} \sim \pi}(h(X^{(1)})) = \|h\|^2\end{aligned}$$

Hence, $\|F\| \leq 1$.

If MC is reversible, F is self-adjoint $\implies \|F^n\| = \|F\|^n$.

Convergence of a MC

Rate of Convergence: $\|F\|$

$$\|F\| = \sup_{f,g} \text{Corr}(f(X^{(t+1)}), g(X^{(t)}))$$

Theorem: Let $X^{(0)} \sim P^{(0)}$. $P^{(n)}, \mathbb{E}^{(n)}$: n^{th} step evolution.

$$|\mathbb{E}^{(n)} h(X) - \mathbb{E}_{\pi} h(X)| \leq C \|F\|^n \|h\|.$$

Finite State space: $\|F\| \equiv 2^{\text{nd}}$ eigval of Transition Matrix.

$(X, Y) \sim P$. Samples:

$$\{(X^{(1)}, Y^{(1)}), (X^{(2)}, Y^{(2)}), \dots (X^{(N)}, Y^{(N)})\}$$

Goal: Estimate $\mathbb{E}_P[h(X)]$

Empirical Estimator $\mu_0 = \frac{1}{N} \sum_{i=1}^N h(X^{(i)})$

Rao-Blackwellised Estimator $\mu_{rb} = \frac{1}{N} \sum_{i=1}^N \mathbb{E} \left[h(X) | Y^{(i)} \right]$

$(X, Y) \sim P$. Samples:
 $\{(X^{(1)}, Y^{(1)}), (X^{(2)}, Y^{(2)}), \dots (X^{(N)}, Y^{(N)})\}$

Independent samples: RB Estimator is better.

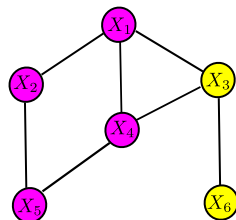
2-Stage Gibbs: RB Estimator is better (LKW 1994).

$$\mathbb{V}(\mu_0) - \mathbb{V}(\mu_{rb}) \leq \frac{\mathbb{V}(h(X))}{n^2} \left(n(1 - \|F\|) + 2(n-1)(\|F\| - \|F\|^2) \right. \\ \left. \dots + (\|F\|^{n-1} - \|F\|^n) \right)$$

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Primary Idea



Blocked Gibbs Sampler:

Correlated Partitions \implies

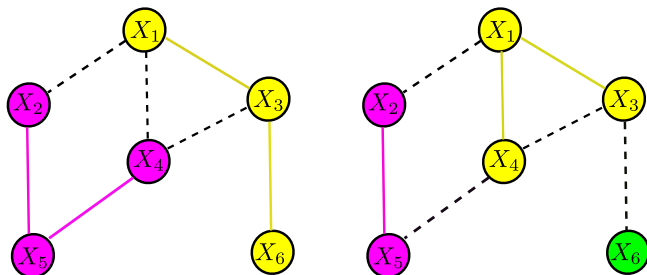
Successive Samples Correlated \implies
Large $\|F\|$

Blocked Gibbs : $\|F\|$ is determined by the partitions.

Partition the Graph so that $\|F\|$ is small !

Is this the best strategy ?

Tree Partitions



Lets focus on Tree Partitions.

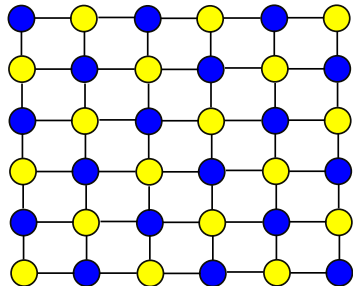
Computing conditional distribution on trees is easy.

Best Tree Partition ? Not easy.

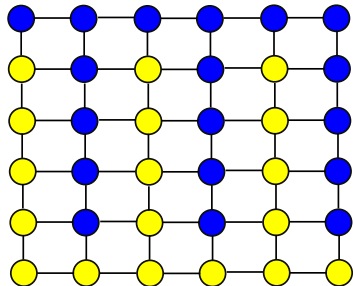
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Grid Graph

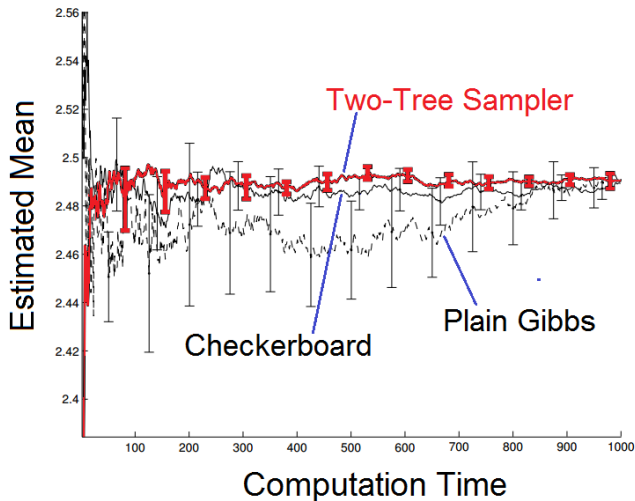


Checkerboard



Two-Trees

Results

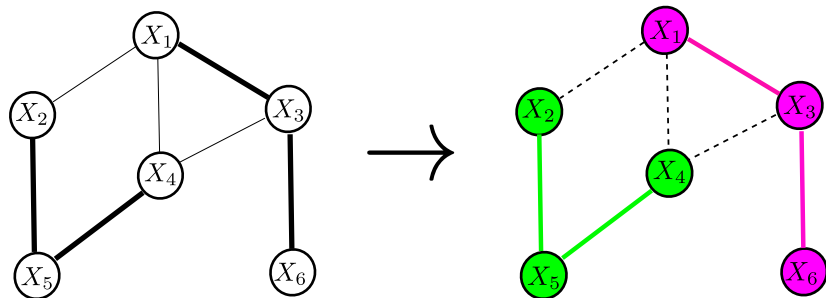


H/deF use a a Rao-Blackwellised Estimator.

Outline

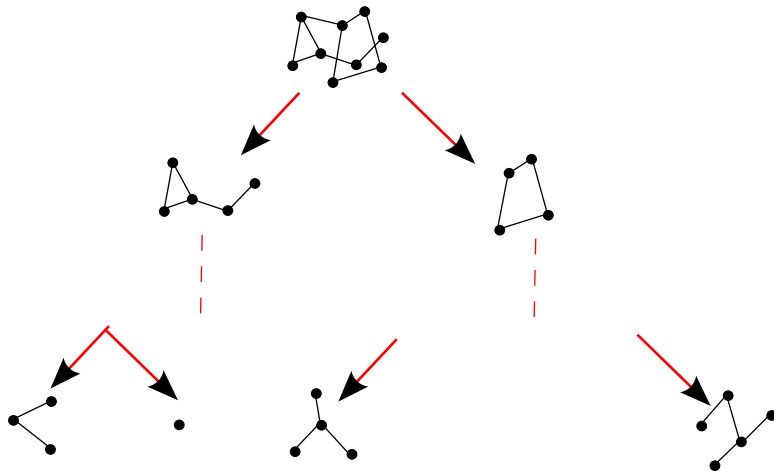
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Incorporate Correlations via Weights (thanks Geoff !)



Partitioning into K trees is NP-Hard ☹ (credit: Elara W)

Greedy Splitting & Recombination



Questions

- 1 What measure of Correlation for Weights ?
- 2 How to Greedy Split ? (Min-Cut, N-Min-Cut, Max-Cut)
How optimal is this ?
- 3 Guarantees about $\|F\|$?
- 4 On what kind of graphs can we expect to win ?