Realtime and Multimedia

Time Sensitive-Linux

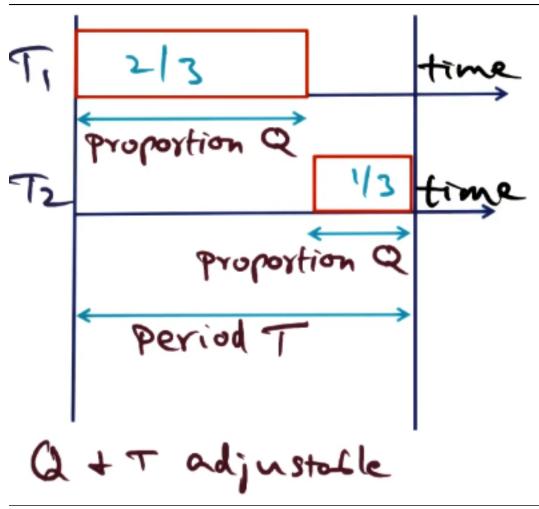
- * Time Sensitive-Linux Introduction
 - Traditional operating systems catered to databases and scientific applications which are throughput oriented
 - Modern workloads support A/V and video games, which have more strict latency requirements and real time guarantees ${\cal A}$
 - How do you provide guarantees for real time applications in the presence of background throughput-oriented applications such as databases?
 - How do you bound the performance loss of throughput-oriented applications in the presence of latency-sensitive applications?
- * Sources of Latency
 - Time sensitive applications require quickly responding to an event + Playing a video game
 - Three sources of latency for time-sensitive events
 - 1. Timer latency: Inaccuracy of timing mechanism; delta between timer event and timer interrupt due to the granularity of the timing mechanism (10ms in Linux)
 - 2. Preemption latency: Interrupt could occur when kernel is in the middle of doing something and cannot be preempted (handler disabled)
 - Latency = Activation of event Happening of event
 - + Latency = Ta Th
- * Timers Available

Choice of Timer	Pro	Con
Periodic	Periodicity	Event recognition latency
$\begin{array}{c} ext{One-shot} \\ ext{Soft} \end{array}$	Timely Reduced overhead	Overhead Polling overhead, latency
Firm	Combines all	, ,

- * Firm Timer Design
 - Goal: accurate timing with low overhead
 - Combine one-shot and soft timers
 - Overshoot: Knob between hard and soft timers
 - + Time between timer expiring and interrupt being triggered
 - + If a syscall occurs during this period, we dispatch the expired timers and reprogram the one-shot timers
 - + Advantage: The point at which the timer is programmed to interrupt will not actually cause an interrupt
 - Firm timer provides accuracy without additional overhead
- * Firm Timer Implementation
 - Task: Schedulable entity (T1, T2, T3)
 - Timer-q data structure: Queue of tasks sorted by expiry time
 - APIC timer hardware
 - + APIC: Advanced Programmable Interrupt Controller
 - + Reprogramming a one-shot timer only takes a few cycles
 - + Sets a value in a register and decrements it each cycle
 - + Allows for the implementation of very fine-grained timers
 - When the APIC timer expires, the interrupt handles traverses timer-q

data structure and look for tasks whose timers have expired

- + Callback handler associated with each event are called
- + Tasks are removed from the timer-q
- + If the task is periodic, the handler will re-enqueue the task
- Soft timers: Eliminates need for fielding one-shot interrupts
- If there's a long time between one-shot events and many periodic events occurring in between, we can process an upcoming one-shot event at the preceding periodic event
 - + Processing an event early is fine, just don't want to be late
 - + Periodic events are much more efficient in the kernel (0(1))
 - + One-shot events are O(logN) where N is is the number of timers
- Reduces the timer latency of event handling
- * Reducing Kernel Preemption Latency
 - Approaches
 - + Explicit insertion of preemption points in kernel (look for events and take action)
 - + Allow preemption anytime the kernel is not manipulating shared data structures (prevents race conditions)
 - Lock-Breaking Preemptive Kernel
 - + Combines the above ideas to reduce spin lock holding time
 - + Replace long critical section with two shorter critical sections
 - + acq() -> rel() vs acq() -> rel() -> reacq() -> rel()
 - + Can preempt the kernel after the first release
- * Reducing Scheduling Latency
 - Proportional period scheduler
 - + Can reserve a portion of the time quantum for throughput-oriented tasks to guarantee that their requirements are still satisfied in a timely manner
 - T is a time window/quantum (exposed to an application)
 - + Task requests Q, a proprtion of T
 - + Both are adjustable using a feedback control mechanism
 - Scheduler attempts to satisfy multiple requests within a quantum
 - + If one task needs 2/3 T and another needs 1/3 T, both can be satisfied within a single quantum
 - Priority inversion
 - + High priority C1 task issues a blocking call to a low priority server
 - + Until the server finishes, high priority task cannot proceed
 - + While the low priority task is executing, another task C2 can become runnable which will preempt the lower priority (priority C1 > C2)
 - + This results in priority inversion for C1
 - Priority-based Scheduling
 - + Server assumes the priority of C1 while it is executing its task
 - + Therefore, no priority inversion occurs
 - How TS-Linux deals with time-sensitive tasks
 - 1. Firm timer design that increases the accuracy of the timer without additional overhead $\,$
 - 2. Using a preemptable kernel to reduce kernel latency
 - 3. Using priority based scheduling to avoid priority and inversion and guaranteeing a portion of the CPU for throughput-oriented tasks



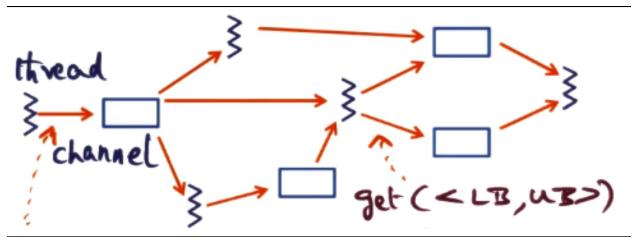
Proportional Period Scheduler

- * Time Sensitive-Linux Conclusion
 - TS-Linux is able to provide quality of service guarantees for realtime applications running on commodity operating systems
 - Admission control using proportional period scheduling ensures that throughput-oriented tasks receive adequate time to execute

Persistent Temporal Streams

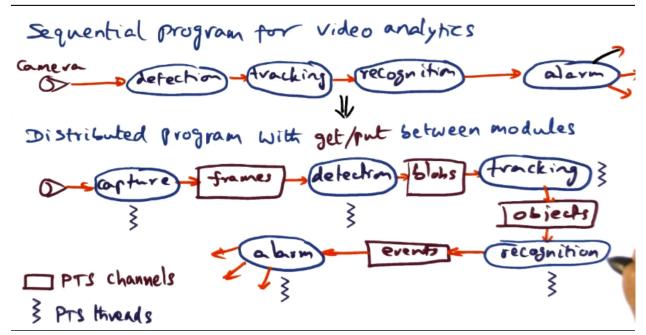
- * Persistent Temporal Streams Introduction
 - $\mbox{-}$ Focus on middleware between commodity operating systems and realtime, distributed multimedia applications
- * Programming Paradigms
 - Parallel programs: Pthreads
 - Distributed programs: Sockets (NFS, RPC)
- * Novel Multimedia Apps
 - Novel distributed applications tend to be sensor-based
 - + Cameras, radars, microphones, temperature sensors, etc.
 - + Access sensor data through the Internet
 - + Want to do live stream analysis of sensor data
 - + Sense -> Prioritize -> Process -> Activate actuators

- These computations are intensive and real-time
 - + Want to reduce latency as much as possible
- * Example Large Scale Situational Awareness
 - Monitoring activities in an airport, anything anomalous causes an alert
 - + London has over 400,000 cameras to monitor
 - Need to prune the data to deal with this many sensors
 - + Can't rely on humans to monitor thousands of cameras
 - + Avoid false positives and false negatives
 - + Programming infrastructure must facilitate domain expert
 - Pain points
 - 1. Right level of abstraction to promote ease of use
 - 2. Propagate temporal causality
 - 3. Correlate live data with historical data to draw inferences
- * Programming Model for Situational Awareness
 - Sequential program for video analysis
 - + Camera -> Detection -> Tracking -> Recognition -> Alarm
 - Objective in situational aware applications: Process streams of data for high level inference (not watching a video)
 - How does this scale to thousands of cameras?
 - + PTS is an example of a distributed programming system catering to the needs of situational awareness applications
- * PTS Programming Model
 - Similar to Unix socket API
 - Distributed application with threads and channels
 - + Channel holds time-sequenced data objects, allows many-to-many connections
 - $\hspace{0.1cm}+\hspace{0.1cm}$ Thread is generating time-sequenced data objects and inserting into the channel
 - + Can be multiple producers inserting into a channel and multiple consumers receiving from a channel
 - + Channel shows temporal evolution of what is being produced by a particular thread (one frame from a camera)
 - put(item, <timestamp>)
 - get(<lowerbound, upperbound>)
 - + Can specify time in an abstract way (oldest, newest) in addition to explicit lower/upper bounds
 - Channel ch1 = lookup("VideoChannel");
 - while(true) {
 - + response r = ch1.get(<LB, UB>);
 - + // process data
 - + // produce output
 - + ch2.put(item, <ts>); }
 - $\mbox{-}$ PTS model allows for the ability to associate timestamp with data items produced by a computation
 - + Allows for temporal causality
 - + Every stream is temporally indexed, so a computation can correlate incoming streams and recognize which data items are temporally related to one another



Proportional Period Scheduler

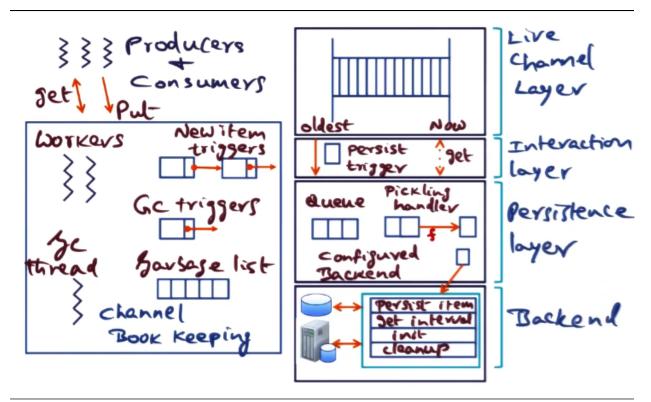
- * Bundling Streams
 - Might need data from multiple data streams simultaneously
 - Can create a "stream group" which is a bundle of different streams
 - + Video, audio, text, gesture
 - + One is the anchor stream, the other are dependents
 - groupget: Get corresponding time-stamped items from all the streams in the group $% \left(1\right) =\left(1\right) +\left(1\right)$
 - + Gets temporally related items from all streams in a group at once
- * Power of Simplicity
 - Interpose channels between modules to get/put data
 - Convert from sequential program to distributed using the channel abstraction and get/put primitives



PTS Program Workflow

^{*} PTS Design Principles

- PTS provides simple abstractions and interfaces
 - + Channel and get/put
- Do the heavy lifting (systems) under the covers
- PTS channels
 - + Can be anywhere (similar to Unix sockets)
 - + Can be accessed from anywhere (similar to Unix sockets)
 - + Network-wide unique (similar to Unix sockets)
 - + Time is a first class entity: Time is manipulated by the application in the way it specifies items to the runtime system and queries the runtime system using time as the index into the channel
 - + Persistet streams under application control: Data is continuously being produced, can't hold it all in memory. Stored to archival storage
 - + Seamlessly handle live and historical data
- PTS is simple to use, but provides the necessary handles to make the life of a domain expert developing a situation awareness application
- * Persistent Channel Architecture
 - How does PTS support this simple get/put programming model?
 - Everything is either a producer or a consumer
 - Threads
 - + Workers: Produce new data
 - + Garbage collection: Delete data from garbage list
 - Triggers
 - + New item triggers occur every time a producer in a worker thread creates a new piece of data
 - + Garbage collection triggers: Might specify channel to only keep last 30 seconds of data, throw everything else away. Move data into garbage list (no longer relevant to application)
 - + Persist triggers indicate that an item has become old and should be moved from memory to archive
 - Implementation of channel is a three-layer architecture
 - + Top: Live channel layer; reacts to new item triggers coming from worker threads
 - + Middle: Interaction layer; Go between the live channel and persistence layer
 - + Bottom: Persistence layer; receives persistence triggers and moves items from the channel according to the pickling handler. Persisted items must go to some non-volatile storage device
 - Pickling handler: Developer specifies a function to be used every time some of the items are persisted (might condense in some way)
 - Backend layer determines how to keep data in non-volatile storage
 - + Application choice as to which backend layer it wants to use
 - + Backend layers: MySQL, Unix filesystem, IBM GPFS



PTS Persistent Channel Architecture

- * PTS Conclusion
 - $\mbox{\sc Map}$ reduce is to big data applications as PTS is to live stream analysis applications
 - Unique features
 - 1. Time-based distributed data structures for streams
 - 2. Automatic data management
 - 3. Transparent stream persistence