

# An educationnal HBRIDGE board

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## **Abstract**

This document describes an educationnal HBRIDGE board whose prime goal is to learn more about alelectronics.

## **1 Introduction**

### **1.1 Purpose**

I wanted a small project to learn more about electronics basics. Since I regularly need to drive a DC motors, I chose to work on a home made HBRIDGE board described in this document. Note that the circuit uses off the shelf parts and can be more complicated than needed and not efficient. A real application should use packaged HBRIDGE circuits.

## **2 Features**

The board features:

- safe H signalling interface avoid conflicting states
  - PWM,
  - FORWARD,
  - BRAKE.
- controlling software
  - coding done by XXX
- power stage driving up to XXX motors.

### 3 HBRIDGE theory of operation

An HBRIDGE is a circuit allowing to drive DC motors in both direction. The name comes from the circuit routing which looks like the 'H' alphabet letter.

### 4 Safe H signalling interface

Since I have a software background it is easier for me to think in terms of C programming control structures. I thus expressed the H state machine in a C code which I translated into logical statement. I used this statement set to design the H state circuit using electronic gates.

---

```
if (BRAKE == 0)
{
    if (FWD == 1)
    {
        Q01 = 0;
        Q10 = 0;
        Q11 = 1;

        Q00 = PWM;
    }
    else /* REVERSE */
    {
        Q00 = 0;
        Q01 = 1;
        Q11 = 0;

        Q10 = PWM;
    }
}
else /* (BRAKE == 1) */
{
    Q00 = 1;
    Q01 = 1;
    Q10 = 1;
    Q11 = 1;
}
```

---

The set of logical statments reduces to:

---

Q00 = (FWD & PWM)		BRAKE;
Q01 = (!FWD)		BRAKE;
Q10 = ((!FWD) & PWM)		BRAKE;
Q11 = FWD		BRAKE;

---

### 5 Bill of materials

TODO

## 6 Status

- PWM / FORWARD / BRAKE signaling interface: PROTOTYPED
- control software: TODO
- power stage: TODO
- documentation: STARTED

## 7 Conclusion

TODO

## 8 Further readings

### 8.1 HBRIDGE projects

- <http://embedded-lab.com/blog/?p=1159>
- <http://www.mcmanis.com/chuck/robotics/tutorial/h-bridge>
- [http://www.modularcircuits.com/h-bridge\\_secrets1.htm](http://www.modularcircuits.com/h-bridge_secrets1.htm)
- [http://www.solarbotics.net/library/circuits/driver\\_4varHbridge.html](http://www.solarbotics.net/library/circuits/driver_4varHbridge.html)
- [http://www.solarbotics.net/library/circuits/driver\\_buf\\_h.html](http://www.solarbotics.net/library/circuits/driver_buf_h.html)
- <http://www.robotroom.com/HBridge.html>
- <http://www.robotroom.com/BipolarHBridge.html>

### 8.2 Controlling software

- <http://www.seattlerobotics.org/encoder/200001/simplemotor.htm>