

# Zero Forcing

## 1 Zero Forcing

### 1.1 Hermitian Matrix

If the Hermitian transpose of a matrix is itself, this matrix is called the Hermitian matrix, i.e,

$$A^H = A \quad (1)$$

Also, the inverse of a Hermitian matrix is Hermitian, i.e,

$$\begin{aligned} I &= AA^{-1} \\ I &= I^H = (AA^{-1})^H = (A^{-1})^H A^H = (A^{-1})^H A \\ I &= (A^{-1})^H A \\ A^{-1} &= (A^{-1})^H AA^{-1} \\ A^{-1} &= (A^{-1})^H \end{aligned} \quad (2)$$

### 1.2 The Implementation of the Channel Matrix

We implement the Hermitian matrix knowledge into the channel matrix  $H$ :  $H^H H$  or  $HH^H$  is a Hermitian matrix, i.e,

$$\begin{aligned} (H^H H)^H &= H^H (H^H)^H = H^H H \\ (HH^H)^H &= (H^H)^H H^H = HH^H \end{aligned} \quad (3)$$

Here, we need to know that  $(AB)^H = B^H A^H$ . Also,

$$\begin{aligned} ((H^H H)^{-1})^H &= (H^H H)^{-1} \\ ((HH^H)^{-1})^H &= (HH^H)^{-1} \end{aligned} \quad (4)$$

### 1.3 Least Square

#### 1.3.1 Mean

The zero forcing estimation is

$$\hat{x} = (H^H H)^{-1} H^H y \quad (5)$$

### 1.3.2 Variance

The error of zero forcing is

$$\begin{aligned}
e &= \hat{x} - x \\
&= (H^H H)^{-1} H^H y - x \\
&= (H^H H)^{-1} H^H (Hx + n) - x \\
&= (H^H H)^{-1} H^H Hx - x + (H^H H)^{-1} H^H n \\
&= H^{-1} Hx - x + (H^H H)^{-1} H^H n \\
&= (H^H H)^{-1} H^H n
\end{aligned} \tag{6}$$

Therefore, the covariance is

$$\begin{aligned}
\text{cov}(\hat{x}) &= E(ee^H) \\
&= E[(H^H H)^{-1} H^H n ((H^H H)^{-1} H^H n)^H] \\
&= E[(H^H H)^{-1} H^H n n^H H (H^H H)^{-1}] \\
&= (H^H H)^{-1} H^H E[nn^H] H (H^H H)^{-1} \\
&= (H^H H)^{-1} H^H \sigma^2 H (H^H H)^{-1} \\
&= \sigma^2 (H^H H)^{-1} H^H H (H^H H)^{-1} \\
&= \sigma^2 (H^H H)^{-1} [H^H H (H^H H)^{-1}] \\
&= \sigma^2 (H^H H)^{-1} I \\
&= \sigma^2 (H^H H)^{-1}
\end{aligned} \tag{7}$$

The variance is the diagonal, i.e.,

$$\text{var}(\hat{x}) = \text{diag}(\sigma^2 (H^H H)^{-1}) \tag{8}$$

## 1.4 Using the Estimated Channel Matrix

If we use the estimated channel matrix  $\hat{H}$ , the error is

$$\begin{aligned}
e &= \hat{x} - x = (\hat{H}^H \hat{H})^{-1} \hat{H}^H y - x \\
&= (\hat{H}^H \hat{H})^{-1} \hat{H}^H (Hx + n) - x \\
&= (\hat{H}^H \hat{H})^{-1} \hat{H}^H Hx - x + (\hat{H}^H \hat{H})^{-1} \hat{H}^H n \\
&= (\hat{H}^H \hat{H})^{-1} \hat{H}^H (\hat{H} + H - \hat{H})x - x + (\hat{H}^H \hat{H})^{-1} \hat{H}^H n \\
&= (\hat{H}^H \hat{H})^{-1} \hat{H}^H \hat{H}x - x + (\hat{H}^H \hat{H})^{-1} \hat{H}^H (H - \hat{H})x + (\hat{H}^H \hat{H})^{-1} \hat{H}^H n \\
&= (\hat{H}^H \hat{H})^{-1} \hat{H}^H (H - \hat{H})x + (\hat{H}^H \hat{H})^{-1} \hat{H}^H n
\end{aligned} \tag{9}$$

For simplification, we assume  $W = (\hat{H}^H \hat{H})^{-1} \hat{H}^H$  and  $\Delta H = \hat{H} - H$ . Therefore, (9) can be written as

$$e = -W \Delta H x + W n \tag{10}$$

Therefore, assuming the noise  $n \sim \mathcal{CN}(0, \sigma^2)$ , we can write the covariance as

$$\begin{aligned}
\text{cov}(\hat{x}) &= E(ee^H) \\
&= E[W\Delta Hx(W\Delta Hx)^H] + E(Wnn^H W^H) \\
&= E(W\Delta Hxx^H\Delta H^H W^H) + E(Wnn^H W^H) \\
&= \sigma_x^2 E(\Delta H\Delta H^H)WW^H + \sigma^2 WW^H
\end{aligned} \tag{11}$$

The  $WW^H$  in (11) can be simplified as,

$$\begin{aligned}
WW^H &= (\hat{H}^H \hat{H})^{-1} \hat{H}^H ((\hat{H}^H \hat{H})^{-1} \hat{H}^H)^H \\
&= (\hat{H}^H \hat{H})^{-1} \hat{H}^H \hat{H} (\hat{H}^H \hat{H})^{-1} \\
&= (\hat{H}^H \hat{H})^{-1}
\end{aligned} \tag{12}$$

Therefore, (11) can be written as

$$\text{cov}(\hat{x}) = \sigma_x^2 W E(\Delta H\Delta H^H) W^H + \sigma^2 (\hat{H}^H \hat{H})^{-1} \tag{13}$$

Herefore, the variance is

$$\begin{aligned}
\text{var}(\hat{x}) &= \text{diag}(\sigma_x^2 W E(\Delta H\Delta H^H) W^H + \sigma^2 (\hat{H}^H \hat{H})^{-1}) \\
&= \text{diag}(\sigma_x^2 W E(\Delta H\Delta H^H) W^H) + \text{diag}(\sigma^2 (\hat{H}^H \hat{H})^{-1}) \\
&= \sigma_x^2 \text{diag}(W E(\Delta H\Delta H^H) W^H) + \sigma^2 \text{diag}((\hat{H}^H \hat{H})^{-1})
\end{aligned} \tag{14}$$

Here,  $E(\Delta H\Delta H^H)$  is a diagonal matrix because each value in  $\Delta H$  is independent, i.e.,

$$E(\Delta H\Delta H^H) = D_e = \text{diag}\left(\sum_{j=0}^{N_t} \Sigma_{\hat{H}}[:, j]\right), \tag{15}$$

where  $D_e \in \mathbb{R}^{N_r \times N_r}$  and  $\Sigma_{\hat{H}} \in \mathbb{R}^{N_r \times N_t}$ .  $\sum_{j=0}^{N_t} \Sigma_{\hat{H}}[:, j]$  means we sum all columns of  $\Sigma_{\hat{H}}$  together to build a column vector.

## 1.5 Variance

The variance can be expressed in an explicit form,

$$\text{var}(\hat{x}_i) = \underbrace{E(|[Wn]_i|^2)}_{\text{Noise Part}} + \underbrace{E(|[W\Delta Hx]_i|^2)}_{\text{Channel Estimation Error Part}} \tag{16}$$

where  $E(|[Wn]_i|^2)$  comes from the noise and  $E(|[W\Delta Hx]_i|^2)$  comes from the channel estimation error. After simplification, (16) can be written as

$$\begin{aligned}
\text{var}(\hat{x}_i) &= \underbrace{\sigma^2 \sum_{j=1}^{N_r} |W_{i,j}|^2}_{\text{Noise Part}} + \underbrace{\sigma_x^2 \sum_{k=1}^{N_t} \sum_{j=1}^{N_r} |W_{ij}|^2 \sigma_{e,jk}^2}_{\text{Channel Estimation Error Part}}
\end{aligned} \tag{17}$$

### 1.5.1 Noise Part

$$E(|[Wn]_i|^2) = \sigma^2 ||W_{i,:}||^2 = \sigma^2 \sum_{j=1}^{N_r} |W_{i,j}|^2 \tag{18}$$

where  $W_{i,:}$  means we take  $i$ th row from  $W$

### 1.5.2 Channel Estimation Error Part

$$\begin{aligned}
[W\Delta Hx]_i &= \sum_{j=1}^{N_r} W_{ij} \cdot \left( \sum_{k=1}^{N_t} \Delta H_{jk} x_k \right) \\
&= \sum_{j=1}^{N_r} \sum_{k=1}^{N_t} W_{ij} \Delta H_{jk} x_k \\
&= \sum_{k=1}^{N_t} \sum_{j=1}^{N_r} W_{ij} \Delta H_{jk} x_k \\
&= \sum_{k=1}^{N_t} x_k \left( \sum_{j=1}^{N_r} W_{ij} \Delta H_{jk} \right)
\end{aligned} \tag{19}$$

Here,  $x_k$  and  $\Delta H_{jk}$  are independent with zero means, i.e.,

$$\begin{aligned}
E[|[W\Delta Hx]_i|^2] &= \sum_{k=1}^{N_t} \sigma_x^2 E \left[ \left| \sum_{j=1}^{N_r} W_{ij} \Delta H_{jk} \right|^2 \right] \\
&= \sigma_x^2 \sum_{k=1}^{N_t} E \left[ \left| \sum_{j=1}^{N_r} W_{ij} \Delta H_{jk} \right|^2 \right] \\
&= \sigma_x^2 \sum_{k=1}^{N_t} \sum_{j=1}^{N_r} |W_{ij}|^2 \sigma_{e,jk}^2
\end{aligned} \tag{20}$$

where  $\sigma_{e,jk}$  is  $(j, k)$  entry of the estimated channel variance matrix  $\Sigma_{\Delta H}$ .