

Laboration 1: PID-controls

Sensors and Sensing

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List of Figures

Octave code listings

1 Implementation of a PID controller

Describe PID here

1.1 Minimum jerk

Describe minimum jerk here, esp. the maximum-1 addition.

2 Position controller

Describe the implementation of the position controller

3 Velocity controller

Describe the implementation of the velocity controller