

Q.1

a. $f(x) = \text{Heaviside}(x_{i_1} \cdot x_{i_2} \cdot \dots \cdot x_{i_k} - 1)$
 $f(x)$ is positive only when all x_i 's are 1 else $f(x)$ is negative

b. $f(x) = \text{Heaviside}(x_{i_1} + x_{i_2} + \dots + x_{i_k} - \frac{k}{2})$

if sum of feature is .

$> \text{half of } k \rightarrow f(x) = 1$

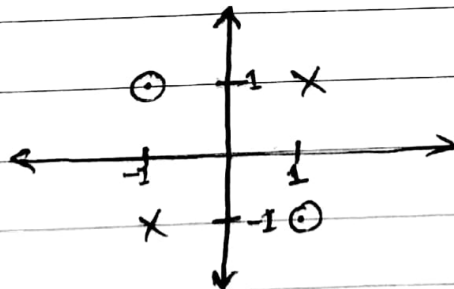
$\leq \text{half of } k \rightarrow f(x) = -1$

$= \text{half of } k \rightarrow f(x) = 0.5$

\rightarrow we can bias
it towards
negative

Q.2

a

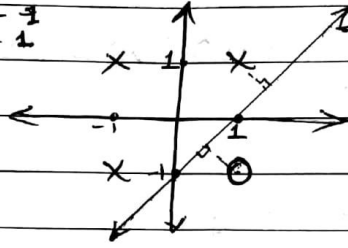


Since the 4 points lie in 4 different decision quadrants, a single perceptron cannot be used for linear classification.

Q-2

b.

(i) $\begin{matrix} x=1 \\ y=0 \end{matrix}$



hyperplane passes through $(0,1)$
slope = 1

$$y = mx + c$$

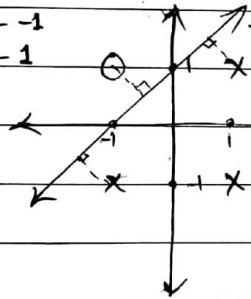
$$\therefore y+1 = mx$$

$$\therefore x - y - 1 = 0$$

$$(c = -1) \\ (m = 1)$$

here $w_1 = 1, w_2 = -1, b = -1$

(ii) $\begin{matrix} x=1 \\ y=0 \end{matrix}$



separating hyperplane passing through $(0,1)$

slope = 1

$$y = mx + c$$

$$\therefore y = mx + 1$$

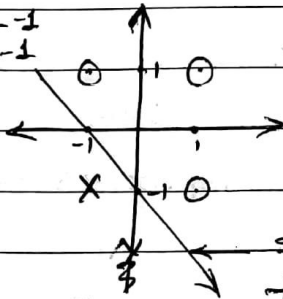
$$(c = 1)$$

$$\therefore x - y + 1 = 0$$

$$(m = 1)$$

$$\therefore w_1 = 1, w_2 = -1, b = 1$$

(iii) $\begin{matrix} x=1 \\ y=0 \end{matrix}$



separating hyperplane passing through $(0,1)$

slope = -1

$$y = mx + c$$

$$\therefore y = -x - 1$$

$$\therefore x + y + 1 = 0$$

$$\therefore w_1 = 1, w_2 = 1, b = 1$$

Q.2

c

$$X_1 (X \text{ OR } X_2)$$

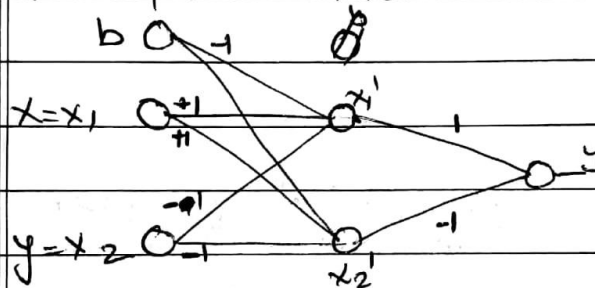
$$= (X_1 \text{ AND } (\text{NOT } X_2)) \text{ OR } ((\text{NOT } X_1) \text{ AND } X_2)$$

$$= X_1 - y - 1 + X_1 - y + 1$$

$$= X - y$$

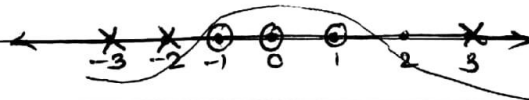
$$\text{Equation of line} \Rightarrow X = y$$

Perceptron Network:



Q.3

a.

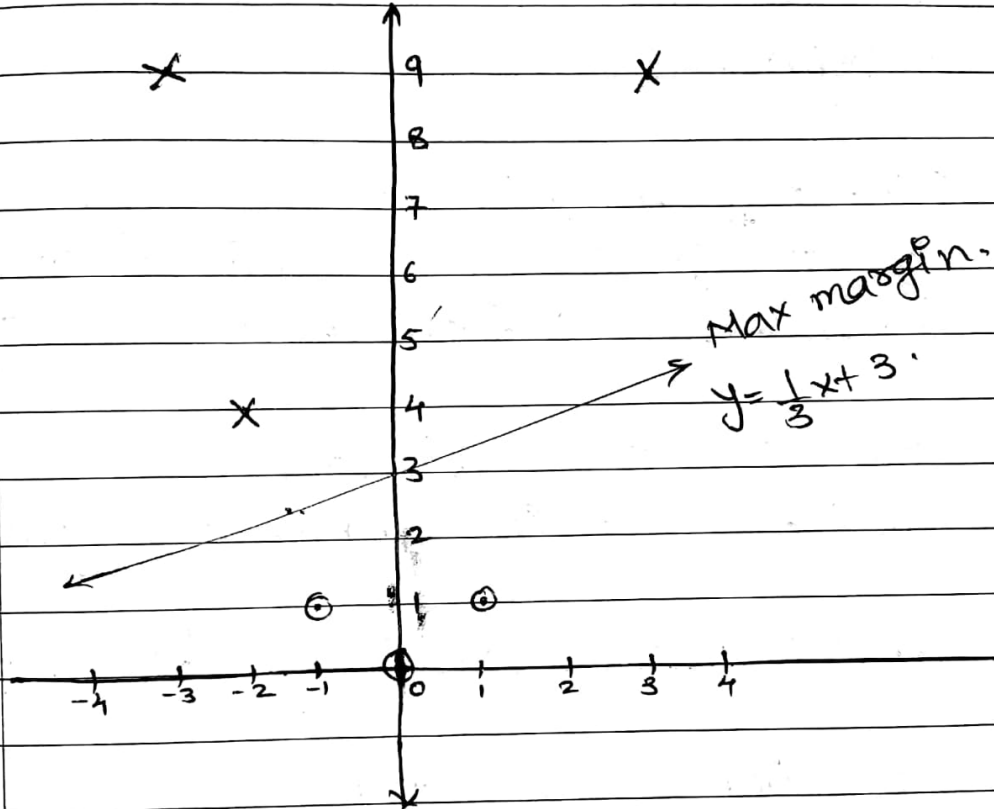


Since features is 1 dimensional scalar & distribution of class variables is as seen above, a linear separator cannot exist.

Q-3

$$b. \phi(x_-) = \{(0,0), (1,1), (-1,1)\}$$

$$\phi(x_+) = \{(-3,9), (3,9), (-2,4)\}$$



Perfect linear separator exists for $\phi(x)$ as seen above.

Q-3

$$k(\phi(x_1), \phi(x_2)) = \langle \phi(x_1), \phi(x_2) \rangle$$

c.

$$= \langle \{x_1, x_1^2\}, \{x_2, x_2^2\} \rangle$$

$$= x_1 * x_2 + x_1^2 * x_2^2$$

Q.3

d. As seen in graph of Q.3b, points $(-1, 1)$ and $(-2, 4)$ are closest to any linear separator. Therefore they will be used for finding maximum margin separator.

The max separator should be a perpendicular bisector ^{to line} joining $(-1, 1)$ and $(-2, 4)$ and should be equidistant from the two points.

Let: Mid point = $(-\frac{3}{2}, \frac{5}{2})$

and slope of line joining two points = -3

\therefore slope of perpendicular bisector = $\frac{1}{3} = m'$

\therefore equation of separator:

$$(y - \frac{5}{2}) = m' (x + \frac{3}{2})$$

$$\therefore (y - \frac{5}{2}) = \frac{1}{3} (x + \frac{3}{2})$$

$$\therefore y = \frac{5}{2} + \frac{1}{3}x + \frac{1}{2}$$

$$\therefore y = \frac{1}{3}x + 3$$

$$\begin{aligned} \Rightarrow \text{The value of margin} &= \sqrt{(4-1)^2 + (-2+1)^2} \\ &= \sqrt{3^2 + (-1)^2} \\ &= \sqrt{10} \end{aligned}$$

Q.4 $n=d=10^{10}$

a) Perceptron:

Training time: $O(nd \cdot T)$

Since $T = \frac{1}{\gamma}$ and $\gamma = \arg \min (w, x_i)$

~~time = $O(nd)$~~

Test time = $O(d)$

or

b) Nearest Neighbour

Training Time: $O(1)$

(No preprocessing)

Testing Time: $O(nd)$

c) Kernel Perceptron with polynomial kernel of order 4.

Training Time: $O(ndT)$

Testing Time: $O(d)$

d) Kernel ^{perceptron} with gaussian kernel.

Training Time: $O(ndT)$

Testing Time: $O(d)$

e) Linear Support Vector Machine.

Training Time: $O(nd)$

Testing Time: $O(d)$

Decreasing order

(i) Training Time

$$a=c=d > e > b$$

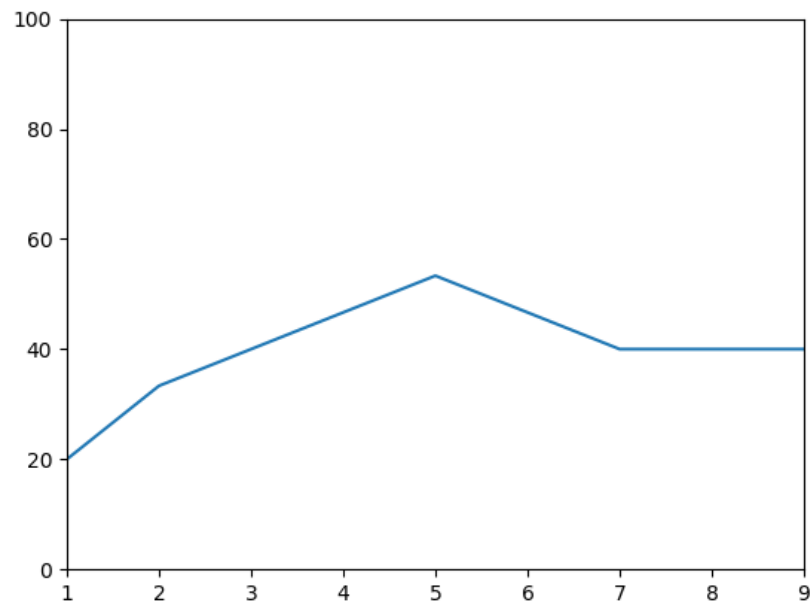
(ii) Testing Time

$$b > a=c=d=e$$

Q5)

KNN – Without Normalization

```
>>>
RESTART: C:/Tanmay/Assignments - Github folder/Semester 3/Data Analytics/Assign
ment 2/KNN.py
Error Percentage for k = 1 : 20.0
Error Percentage for k = 2 : 33.3333333333
Error Percentage for k = 3 : 40.0
Error Percentage for k = 4 : 46.6666666667
Error Percentage for k = 5 : 53.3333333333
Error Percentage for k = 6 : 46.6666666667
Error Percentage for k = 7 : 40.0
Error Percentage for k = 8 : 40.0
Error Percentage for k = 9 : 40.0
|
```



Code:

```
import csv
import numpy as np
import random
from sklearn import neighbors
import sys
import matplotlib.pyplot as plt

#Variable definition
CLASS1 = 59
CLASS2 = 71
CLASS3 = 48
totalrecords = 178
train_rows = (CLASS1-5)+(CLASS2-5)+(CLASS3-5)
train_cols = 13
```

```
global train_data, train_label, test_data, test_label, label, data
global knn, wrong_class, neighbors, error
```

```
def main():
    #readcsv data
    data = np.genfromtxt('wine.data.csv', delimiter=',')
    label = data[:, 0]
    data = data[:,1:]

    #train data
    global wrong_class, neighbors, error
    error=[0]*10
    splitdata(data, label)

    for i in range(1,10):
        train_model(i)

        #predict data label
        iter_no = 100
        wrong_class=0
        predict_label(i, iter_no)
        error_prob(i, 15, iter_no)
        plot_error()

def plot_error():
    plt.plot(error[:])
    plt.axis([1, 9, 0, 100])
    plt.show()

def error_prob(k, total_data, iter_no):
    global wrong_class, error
    error[k] = (wrong_class / (total_data*iter_no)) * 100.0
    print "Error Percentage for k =",k,":", error[k]

def predict_label(k, iter_no):
    global test_data, test_label
    global knn, wrong_class

    for i in range(iter_no):
        #result = KNN(k)
        result = knn.predict(test_data)

        for i in range(0, len(result)):
            if(result[i] != test_label[i]):
                wrong_class+=1.0

def train_model(k):
    global train_data, train_label
```


global knn

#Train Model

```
knn = neighbors.KNeighborsClassifier(n_neighbors = k, algorithm='kd_tree')  
knn.fit(train_data, train_label)
```

```
def splitdata(data, label):  
    global train_data, train_label, test_data, test_label  
    train_data = data  
    train_label = label  
  
    test_data = np.empty([15, train_cols])  
    test_label = np.empty([15, 1])  
  
    no1 = random.sample(range(0, 59-1), 5)  
    no2 = random.sample(range(59, 130-1), 5)  
    no3 = random.sample(range(130, totalrecords-1), 5)  
    no4 = no1 + no2 + no3  
    train_data = np.delete(train_data, (no4), axis=0)  
    train_label = np.delete(train_label, (no4), axis=0)  
  
    i=0  
    for no in no4:  
        test_data[i] = data[no]  
        test_label[i] = label[no]  
        i+=1
```

main()

```
def calc_EHdist(train_row, test_row):  
    dist=0.0  
    for i in range(0, len(train_row)):  
        dist += pow((train_row[i]-test_row[i]),2)  
    #print dist  
    return dist
```

```
def kneighbors(min_val, dist, row_index, k):
```

```
    largest=0.0  
    #print min_val  
    index=0  
    for i in range(0,k):  
        if min_val[i][0] > largest:  
            largest = min_val[i][0]  
            index = i  
    if min_val[index][0] > dist:
```

```

    min_val[index][0] = dist
    min_val[index][1] = row_index
return min_val

```

```

def KNN(k):
    #compute manhattan distance between test data and training data
    global test_data, train_data
    result = []
    #For each test record
    for test_row in test_data:
        #argmin of manhattan distance
        min_val=[]
        for i in range(0,k):
            if(i==0):
                min_val=[[sys.float_info.max,0]]
                continue

            min_val.append([sys.float_info.max, 0])

        row_index=0
        for train_row in train_data:
            dist = calc_EHdist(train_row, test_row)
            min_val = kneighbors(min_val, dist, row_index,k)
            row_index+=1

        #return max label
        a, b, c = 0,0,0

        for minv in min_val:
            label = train_label[minv[1]]
            if label == 1:
                a+=1
            elif label == 2:
                b+=1
            else:
                c+=1
        print a,b,c
        if (a>=b & a>=c):
            result.append(1)
        elif (b>a & b>=c):
            result.append(2)
        else:
            result.append(3)
    return result

```

Q.7)

Time spent = 12 hours

Acknowledgement: Discussed with Nitesh Gupta.