

Topic

Sparse Matrix and the Jacobi Method

The Jacobi Method

$$\begin{aligned} a_{11}x_1 + a_{12}x_2 + \cdots a_{1n}x_n &= b_1 \\ a_{21}x_1 + a_{22}x_2 + \cdots a_{2n}x_n &= b_2 \\ &\vdots \\ a_{n1}x_1 + a_{n2}x_2 + \cdots a_{nn}x_n &= b_n \end{aligned}$$

$$Ax = b$$

The matrix A has no zeros on its diagonal: $a_{ii} \neq 0$.

If all off-diagonal elements are 0: $\mathbf{x} = A^{-1}\mathbf{b}$

If not:

$$\begin{aligned} x_1 &= \frac{1}{a_{11}}(b_1 - a_{12}x_2 - a_{13}x_3 - \cdots a_{1n}x_n) \\ x_2 &= \frac{1}{a_{22}}(b_2 - a_{21}x_1 - a_{23}x_3 - \cdots a_{2n}x_n) \\ &\vdots \\ x_n &= \frac{1}{a_{nn}}(b_n - a_{n1}x_1 - a_{n2}x_2 - \cdots a_{n,n-1}x_{n-1}) \end{aligned}$$

$$\overbrace{\begin{bmatrix} 0 & a_{12} & a_{13} & \cdots & a_{1n} \\ a_{21} & 0 & a_{23} & & \\ a_{31} & a_{32} & 0 & & \\ \vdots & & & \ddots & \\ a_{n1} & & & & 0 \end{bmatrix}}^R \overbrace{\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_n \end{bmatrix}}^{\mathbf{x}}$$

$$A = D + R \qquad \begin{aligned} \mathbf{x} &= D^{-1} \mathbf{b} + D^{-1} R \mathbf{x} \\ &= D^{-1} (\mathbf{b} + R \mathbf{x}) \end{aligned} \qquad \begin{array}{l} \text{(Remember for } R, \\ \text{all diagonal elements} \\ \text{are 0).} \end{array}$$

If A is “sparse”, i.e., most of $a_{ij} = 0$, for $i \neq j$ (i.e., R is mostly 0):

$$\mathbf{x} \cong D^{-1} \mathbf{b}$$

So you can start with $\mathbf{x}_{\text{guess}} = D^{-1} \mathbf{b}$, which is close to the solution...
then $D^{-1} R \mathbf{x}_{\text{guess}}$ is approximately the correction you need to get even
closer to the solution; then you can iterate:

$$\mathbf{x}^{(k+1)} \cong D^{-1} (\mathbf{b} + R \mathbf{x}^{(k)})$$

Making it concrete:

$$\mathbf{x}^{(k+1)} \cong D^{-1} (\mathbf{b} + R\mathbf{x}^{(k)})$$

$$x_1^{(k+1)} = \frac{1}{a_{11}} (b_1 - r_{12} x_2^{(k)} - r_{13} x_3^{(k)} - \cdots - r_{1n} x_n^{(k)})$$

$$\mathbf{r}_1 = \{r_{1j}\} \quad (\text{Remember: } r_{11} = 0.)$$

$$x^{(k+1)}_1 \cong 1/a_{11} (b_1 + \mathbf{r}_1 \cdot \mathbf{x}^{(k)})$$

In general:

$$x^{(k+1)}_i \cong 1/a_{ii} (b_i + \mathbf{r}_i \cdot \mathbf{x}^{(k)})$$

Now, numerical implementation...