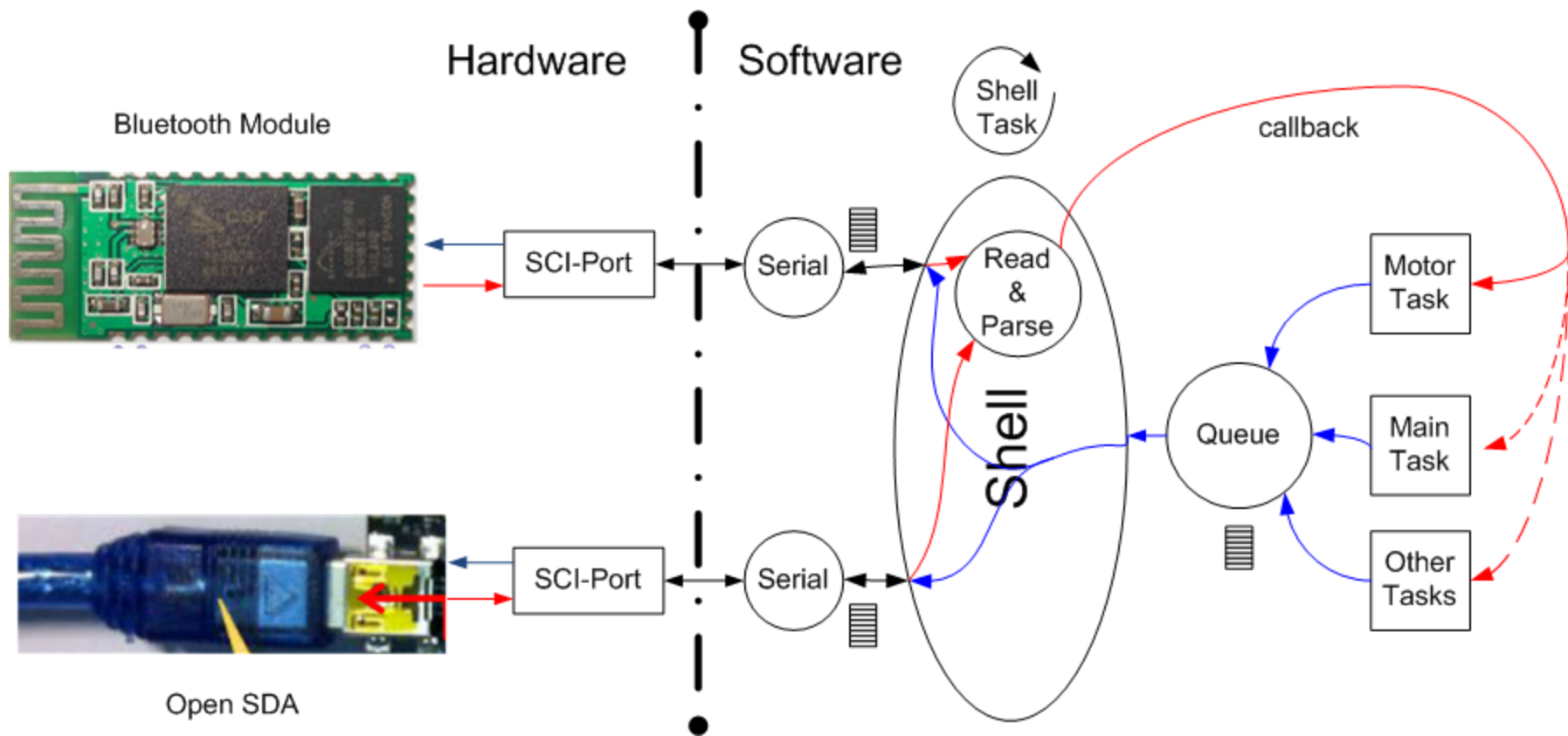


Shell, USB and UART, Memory and Queue

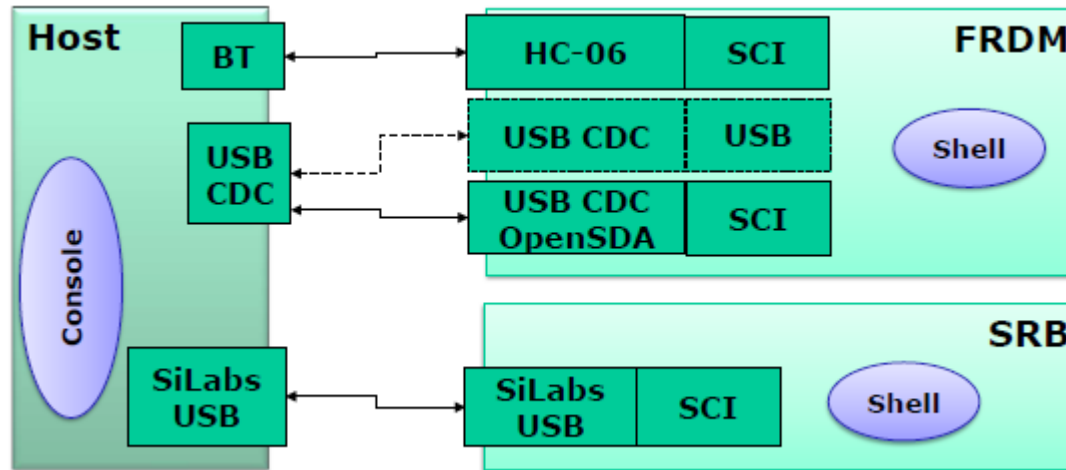
Andreas Walker,

Ruedi Herger,

Reto Müller



Ways to communicate



- Bluetooth to a SCI port of the MCU
- USB bridge to a SCI port of the MCU
- (USB directly to a USB port of the MCU)

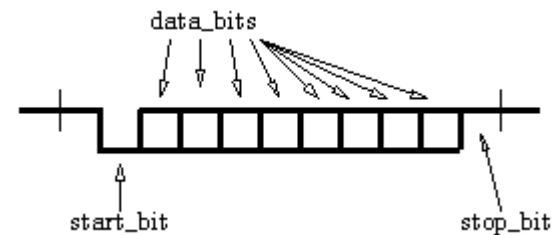
SCI Serial COM Interface (UART)

Wires:

- Rx, receive line
- Tx, send line
- Additionally: flow control lines (not at the FRDM)

Protocol properties:

- Asynchron, serial (no clock)
- Fixed baudrate



Processor expert component: AsynchroSerial

-> Used by the Shell and Bluetooth component

USB

Wires:

- 2 power supply lines
- 2 data lines (differential signal, noise resistant)

Device types:

- Host, device, OTG (On-The-Go)

Device classes:

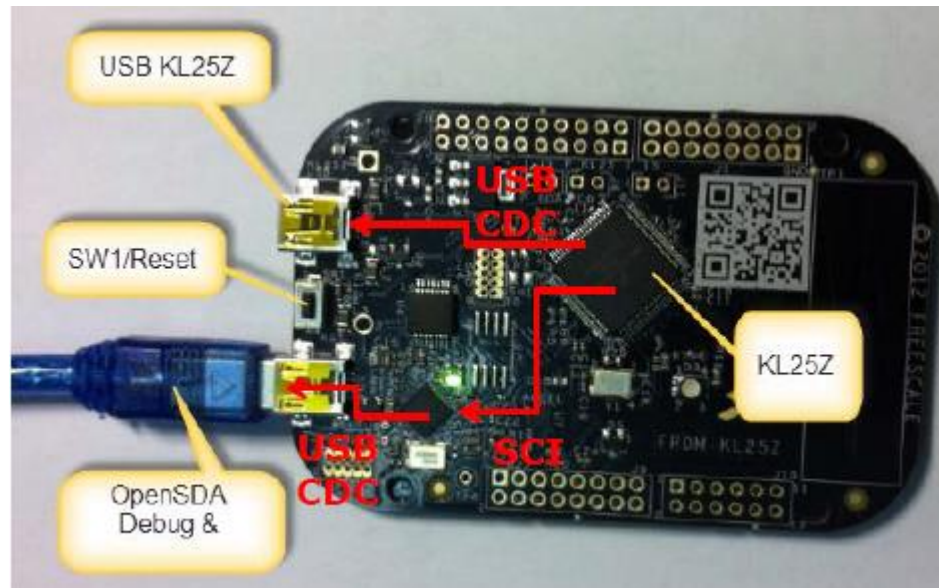
- CDC (Communication Device Class), HID, MSD, ...

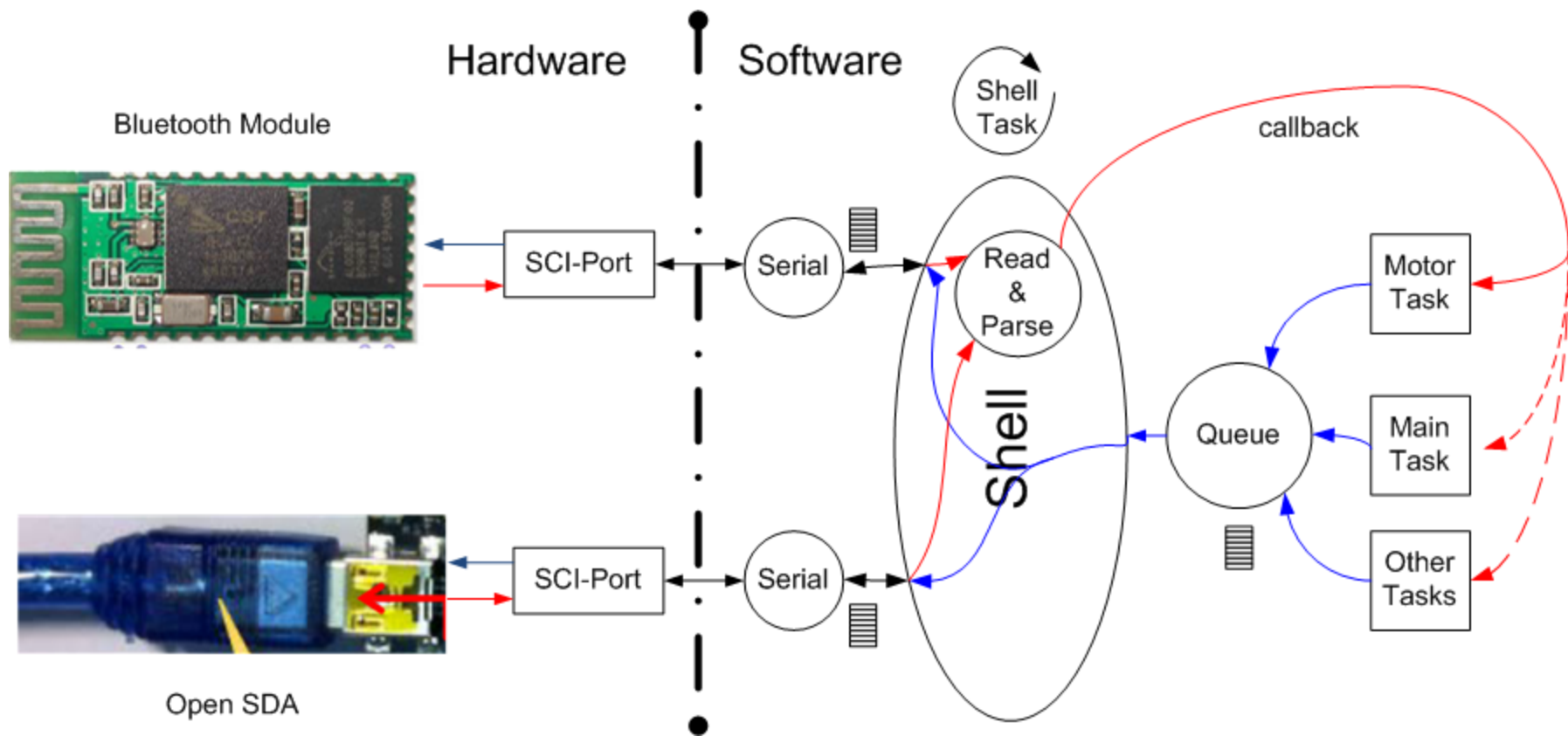
Protocol properties

- Not bound to a fixed baudrate
- Asynchron, serial, and asymmetrical (host requests to send data)

OpenSDA and USB CDC

- K20 adapts USB CDC protocol to the KL25Z SCI (UART) protocol
- Virtual COM port at the PC (USB CDC)
 - Handable like a UART protocol






Shell Standard I/O

- I/O structure with callbacks
 - Stdin: read char (Commands)
 - Stdout: write char (Answers)
 - Stderr: write char (Error)

Shell Parser

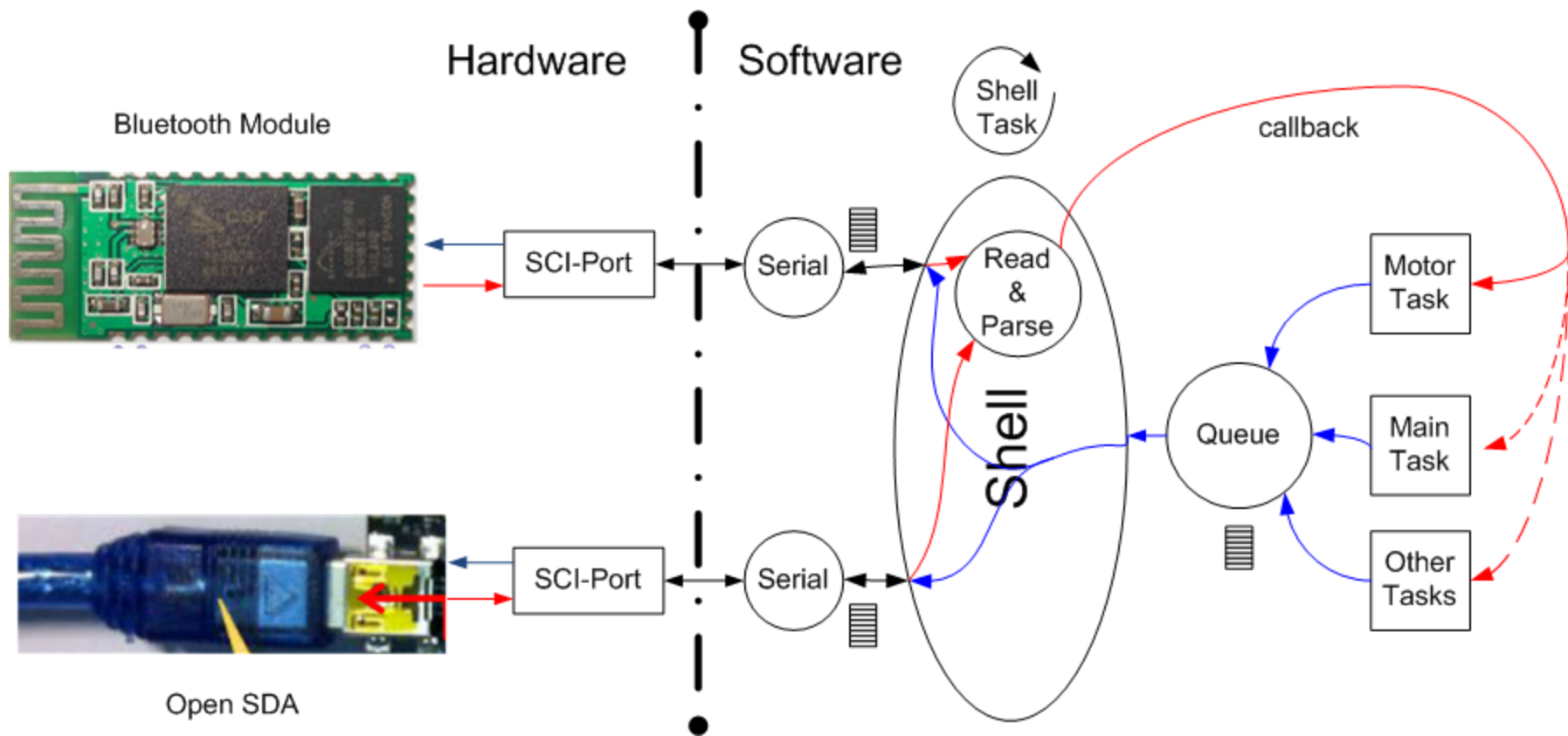
```
void APP_Run(void) {  
    for(;;) {  
        ...  
        SHELL_Parse();  
    }  
}
```



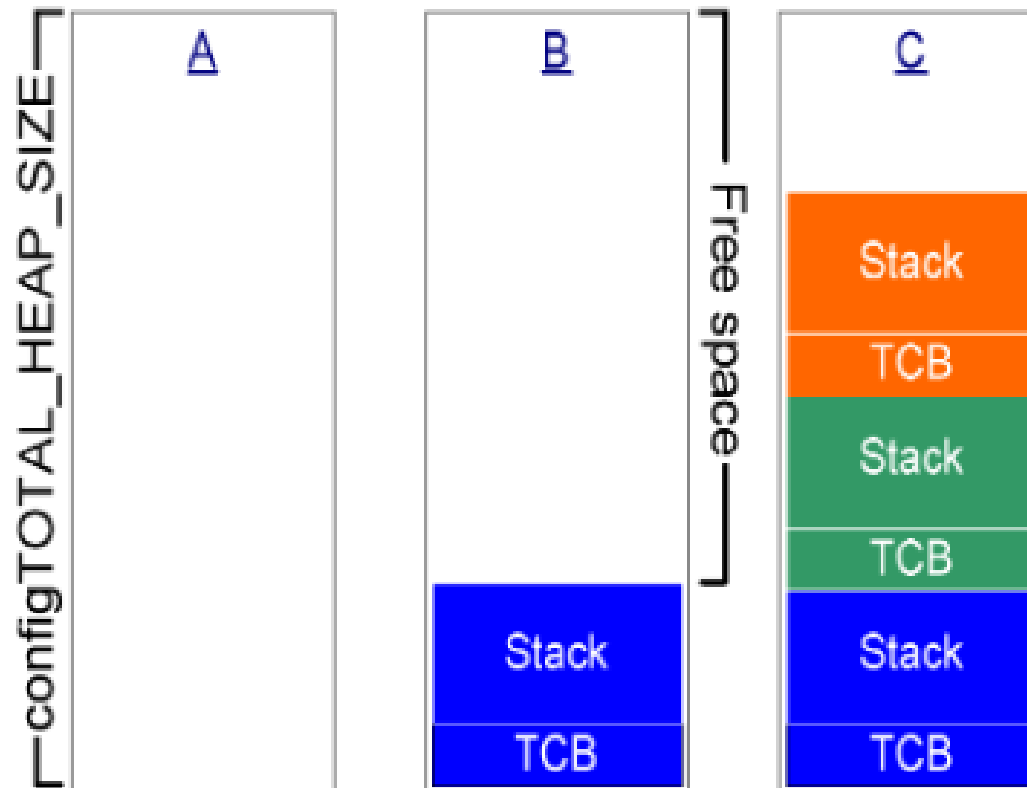
```
void SHELL_Parse(void) {  
    (void)CLS1_ReadAndParseWithCommandTable(  
        buf,  
        sizeof(buf),  
        CLS1_GetStdio(),  
        CmdParserTable)  
}
```

***Appends* to buffer!
Initialize!**

```
void SHELL_Init(void) {  
    buf[0] = '\\0'; /* init */  
}
```

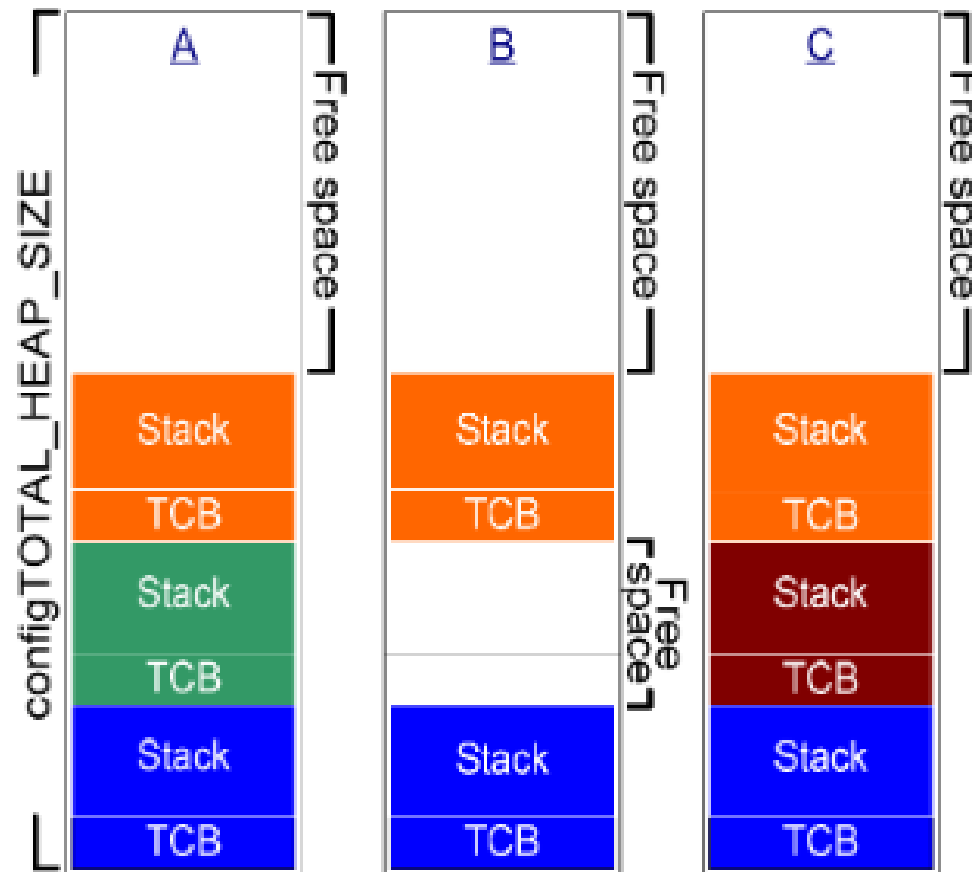


Memory Scheme 1



Source: freeRTOS.org

Memory Scheme 2



Source: freeRTOS.org

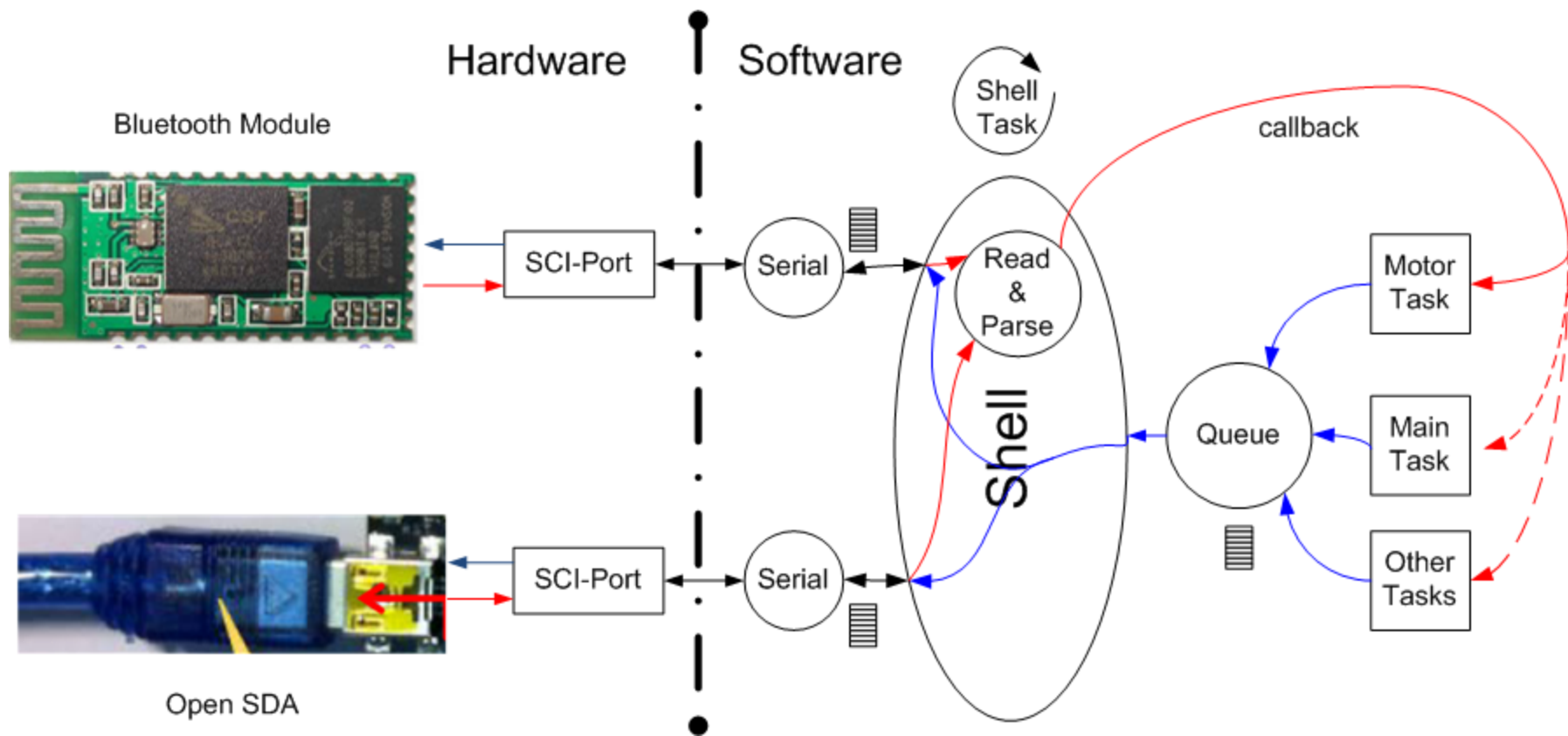
Malloc(), Free() Example

```
void *pvPortMalloc(size_t xWantedSize);
void vPortFree(void *pv);
size_t xPortGetFreeHeapSize(void);

void foo(void) {
    char_t *bufP;

    bufP = (char_t*)pvPortMalloc(sizeof("Hello"));
    if (bufP==NULL) {
        for(;;); /* ups! */
    }
    (void)strcpy(bufP, "Hello");
    /* do something with it */
    vPortFree(bufP);
}

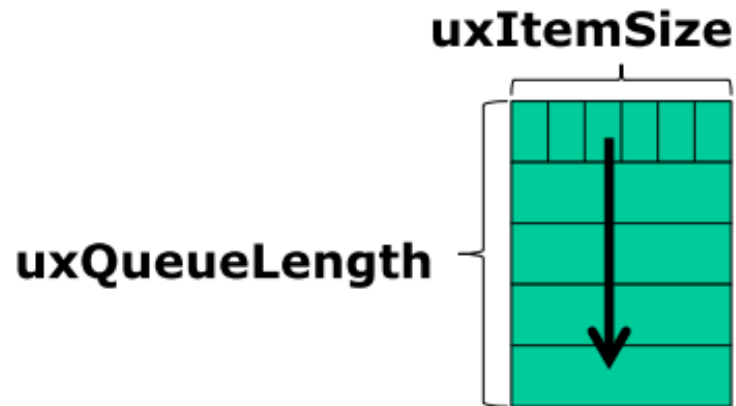
UTIL1_strcpy(buf, sizeof(buf), "Hello");
```



Queue Create & Delete

```
xQueueHandle xQueueCreate(  
    unsigned portBASE_TYPE uxQueueLength,  
    unsigned portBASE_TYPE uxItemSize  
);
```

```
void vQueueDelete(xQueueHandle xQueue);
```



Queue Send

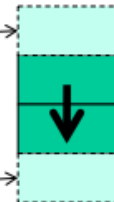
```
portBASE_TYPE xQueueSendToBack(  
    xQueueHandle xQueue,  
    const void *pvItemToQueue,  
    portTickType xTicksToWait  
);  
portBASE_TYPE xQueueSendToFront(  
    xQueueHandle xQueue,  
    const void *pvItemToQueue,  
    portTickType xTicksToWait  
);
```

Hint:
portMAX_DELAY

0: return immediately
>0: ticks to wait

SendToBack()

SendToFront()



Queue Receive & Peek

```
portBASE_TYPE xQueueReceive(  
    xQueueHandle xQueue,  
    void *pvBuffer,  
    portTickType xTicksToWait  
);  
portBASE_TYPE xQueuePeek(  
    xQueueHandle xQueue,  
    void *pvBuffer,  
    portTickType xTicksToWait  
);
```

0: return immediately
>0: ticks to wait

