# chapter 5 Performance Analysis

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# Regret Analysis

- A player chooses an action  $\theta^{(t)} \in K$  every t period, where K is a feasible set of actions.
- ullet The cost function  $f^{(t)}$  determines the cost  $f^{(t)}(\theta^{(t)})$  for action  $\theta^{(t)}$ .
- The player decides his action based on the strategy.

# Regret Analysis

- How does the player choose an action which minimizes a total cost  $\sum f^{(t)}(\theta^{(t)})$ ?
- Can the cost function be minimized even if it is not unknown?
- We introduce a regret about the strategy.

#### definition (Regret)

The difference between the total cost of an action based on a strategy A and the total cost of the optimal strategy  $\theta^*$  is defined as the regret Regret(A) of strategy A.

$$Regret(A) = \Sigma_{t=1}^T f^{(t)}(\theta^{(t)}) - \Sigma_{t=1}^T f^{(t)}(\theta^*)$$

# Regret Analysis

#### Regret analysis in online learning

- Let action be the parameter of the online learner  $\boldsymbol{\theta}^{(t)} \in \mathbb{R}^m$  given the training data  $(\boldsymbol{x}^{(t)}, y^{(t)})$ .
- Let the cost function be a loss function  $f^{(t)} = (\boldsymbol{x}^{(t)}, y^{(t)}, \boldsymbol{\theta})$ .
- In this case, the optimal strategy is the strategy that chooses the action that minimizes the cost function for all training data.

#### Follow the Leader

• At first, We consider strategy for choosing action that minimizes the total cost to date.

$$\pmb{\theta}^{(t)} = \operatorname*{arg\ min}_{\pmb{\theta} \in K} \Sigma_{i=1}^{t-1} f^{(t)}(\pmb{\theta})$$

This strategy is called Follow the Leader (FTL).

#### Follow the Leader

- However, there are cases where FTL doesn't work.
- Consider action  $\theta \in [-1,1]$  and cost function  $f^{(t)}(\theta) = (1/2)(-1)^t \theta$ .
- In this case, the action goes back and forth between -1 and 1 except for the first, as  $\theta^{(1)}=0, \theta^{(2)}=-1, \theta^{(2)}=1,....$
- The cost function is 1/2 except for the first, as  $f^{(1)}(\theta^{(1)})=0, f^{(2)}(\theta^{(2)})=1/2, f^{(3)}(\theta^{(3)})=1/2,....$

#### Follow the Leader

- On the other hand, The optimal strategy is  $\theta=0$  and the total cost of it is 0.
- Therefore, FTL regret in this case doesn't approach 0.
- We have to expand FTL.

Regularized Follow the Leader (RFTL)

$$\boldsymbol{\theta}^{(t)} = \operatorname*{arg\ min}_{\boldsymbol{\theta} \in K} \eta \Sigma_{i=1}^{t-1} f^{(t)}(\boldsymbol{\theta}) + R(\boldsymbol{\theta})$$

- Let  $R(\theta)$  be convex regularization function. Let  $\eta \geq 0$  be parameter that determines the degree of regularization.
- When choosing the first action, the cost function is not presented, so action is determined only by the regularization term.

$$\boldsymbol{\theta}^{(1)} = \operatorname*{arg\ min}_{\boldsymbol{\theta} \in K} R(\boldsymbol{\theta})$$

• We introduce lemma and definitions to derive RFTL regret.

#### lemma

For any vector  $\mathbf{u} \in K$ , the following holds.

$$\Sigma_{t=1}^T \boldsymbol{f}^{(t)T}(\boldsymbol{\theta}^{(t)} - \boldsymbol{u}) \leq \Sigma_{t=1}^T \boldsymbol{f}^{(t)T}(\boldsymbol{\theta}^{(t)} - \boldsymbol{\theta}^{t+1}) + \frac{1}{\eta} \left\{ R(\boldsymbol{u}) - R(\boldsymbol{\theta}^{(1)}) \right\} \tag{1}$$

#### Proof.

For simplicity, let us assume that  ${\pmb f}^{(0)}=\frac{1}{\eta}R({\pmb \theta})$  and the algorithm starts at t=0.

$$\Sigma_{t=0}^{T} \boldsymbol{f}^{(t)}(\boldsymbol{\theta}) = \Sigma_{t=1}^{T} \boldsymbol{f}^{(t)}(\boldsymbol{\theta}) + \frac{1}{\eta} R(\boldsymbol{\theta})$$

In this time, the lemma can be expressed as following.

$$\boldsymbol{\Sigma}_{t=0}^{T} \boldsymbol{f}^{(t)T}(\boldsymbol{\theta}^{(t)} - \boldsymbol{u}) \leq \boldsymbol{\Sigma}_{t=0}^{T} \boldsymbol{f}^{(t)T}(\boldsymbol{\theta}^{(t)} - \boldsymbol{\theta}^{(t+1)})$$

#### Proof.

At t=0, by definition,  $\pmb{\theta}^{(1)}=\mathop{\arg\min}_{\pmb{\theta}}R(\pmb{\theta})$  and  $\pmb{f}^{(0)}(\pmb{\theta}^{(1)})\leq \pmb{f}^{(0)}(\pmb{u})$  holds. therefore,

$$\boldsymbol{f}^{(0)}(\boldsymbol{\theta}^{(0)}) - \boldsymbol{f}^{(0)}(\boldsymbol{u}) \leq \boldsymbol{f}^{(0)}(\boldsymbol{\theta}^{(0)}) - \boldsymbol{f}^{(0)}(\boldsymbol{\theta}^{(1)})$$



#### Proof.

At t>0, assume that lemma holds for t=T. In this time,

$$\boldsymbol{\theta}^{(T+2)} = \arg\min_{\boldsymbol{\theta}} \Sigma_{t=0}^{T+1} \boldsymbol{f}^{(t)}(\boldsymbol{\theta})$$
 (2)

$$\boldsymbol{\theta}^{(T+1)} = \arg\min_{\boldsymbol{\theta}} \Sigma_{t=0}^{T} \boldsymbol{f}^{(t)}(\boldsymbol{\theta})$$
 (3)



#### Proof.

Using equation (2) and (3),

$$\begin{split} & \boldsymbol{\Sigma}_{t=0}^{T+1} \boldsymbol{f}^{(t)T}(\boldsymbol{\theta}^{(t)} - \boldsymbol{u}) \\ & \leq \boldsymbol{\Sigma}_{t=0}^{T+1} \boldsymbol{f}^{(t)}(\boldsymbol{\theta}^{(t)}) - \boldsymbol{\Sigma}_{t=0}^{T+1} \boldsymbol{f}^{(t)}(\boldsymbol{\theta}^{(T+2)}) \\ & = \boldsymbol{\Sigma}_{t=0}^{T}(\boldsymbol{f}^{(t)}(\boldsymbol{\theta}^{(t)}) - \boldsymbol{f}^{(t)}(\boldsymbol{\theta}^{(T+2)})) + \boldsymbol{f}^{(T+1)}(\boldsymbol{\theta}^{(T+1)}) - \boldsymbol{f}^{(T+1)}(\boldsymbol{\theta}^{(T+2)}) \end{split}$$

