

Long Term Simulation of Power System Dynamics using Time Sequenced Power Flows

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Montana Tech - Master's Thesis Research Project

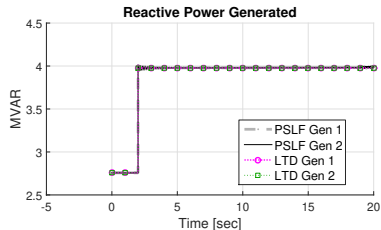
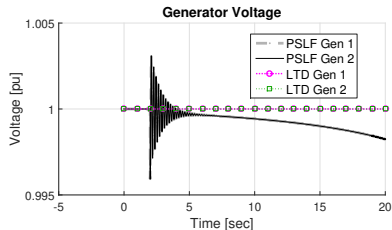
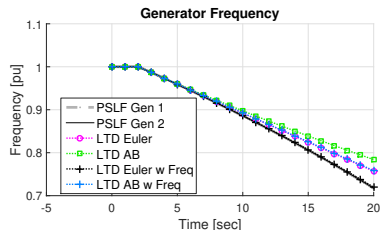
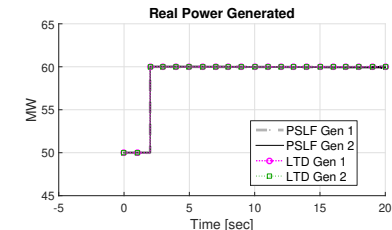
February 5th, 2019

Overview of what the plan is system assumptions goals

Overview of parts involved in simulation
(sequence diagram)
other explanations about computery stuff

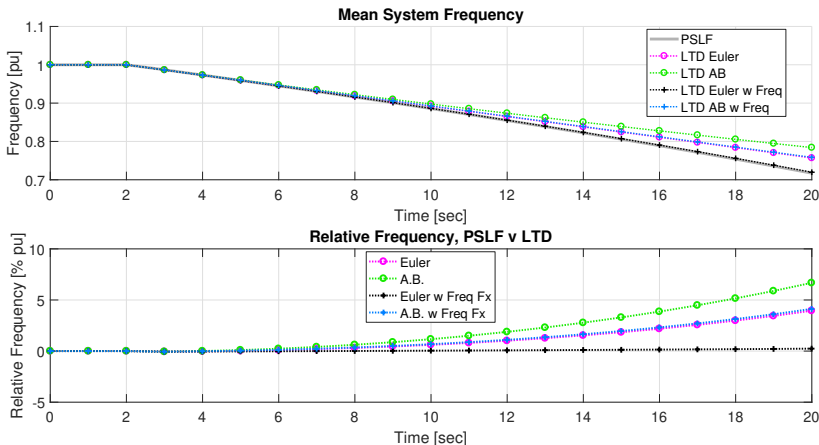
+20 MW Load Step at $t=2$

System Response



+20 MW Load Step at $t=2$

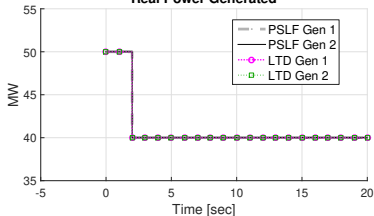
Detailed Frequency Response



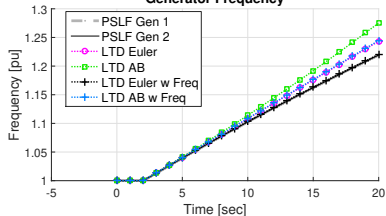
-20 MW Load Step at $t=2$

System Response

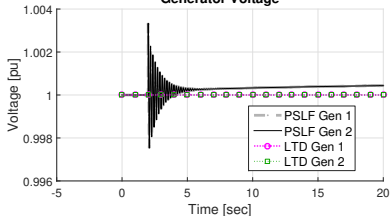
Real Power Generated



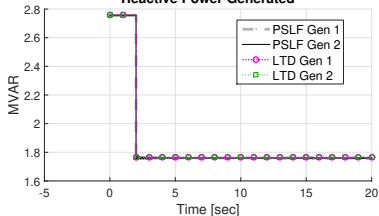
Generator Frequency



Generator Voltage

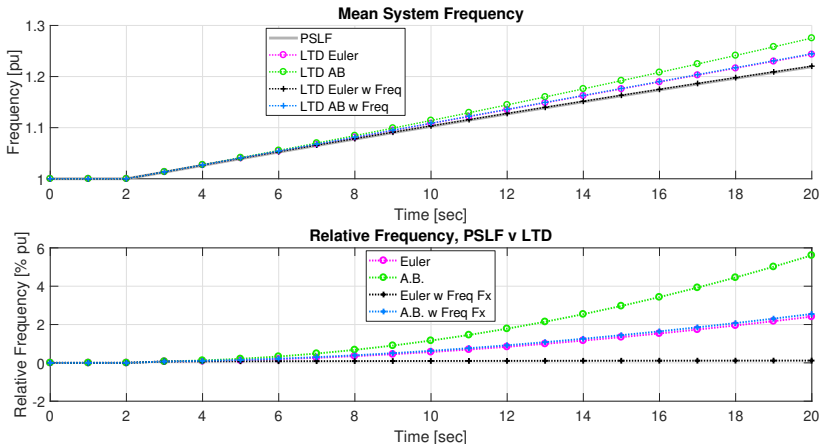


Reactive Power Generated

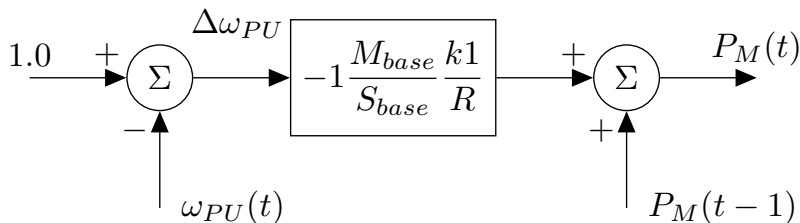


-20 MW Load Step at $t=2$

Detailed Frequency Response



Proportional gain control of generator P_M

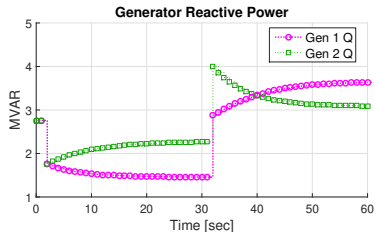
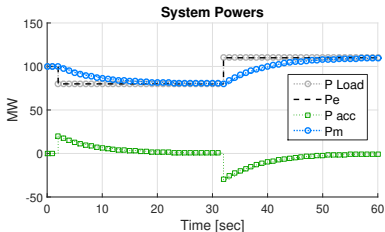
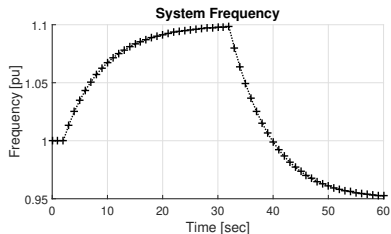
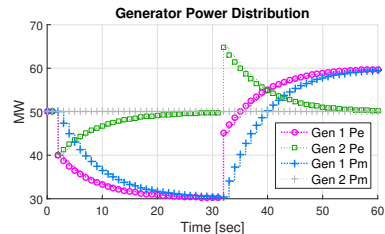


Entered into system via parsed text file:

```
# pgov1 busnum busnam basekv id : #9 mwcap droop k1
#!pgov1 21 "21" 22.00 "1 " : #9 mwcap=100.0 0.05 1.0
```

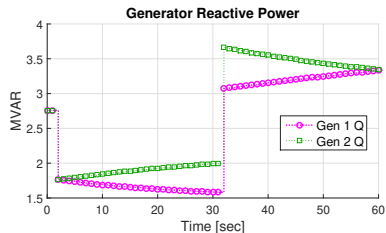
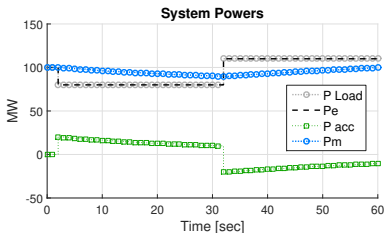
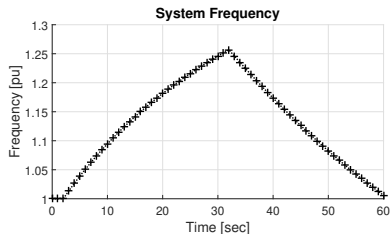
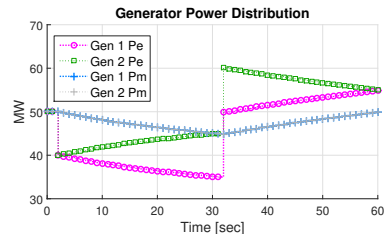
Dynamic model 'pgov1' experiment: -20 MW t=2, +30 MW t=32

pgov1 on Gen 1



Dynamic model 'pgov1' experiment: -20 MW t=2, +30 MW t=32

pgov1 on Gen 1 & Gen 2



- ▶ Frequency effects should be accounted for in swing equation.
- ▶ Euler Integration tracks PSLF mean frequency well.
- ▶ Custom dynamic model implementation seems realizable.