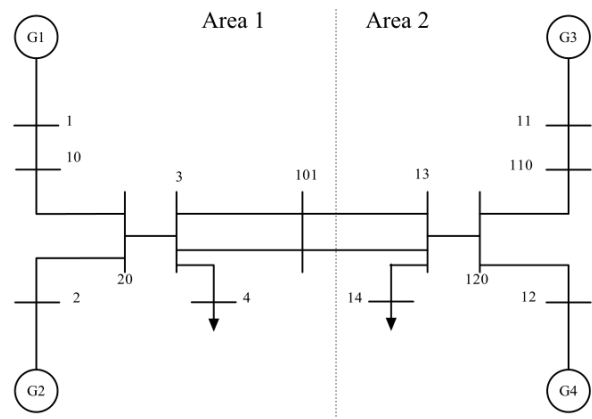


Scenario



- Kundur 4 machine system packaged with PST
- Constant Z load model
- System has governors, exciters, and PSS.
- +50 MW (0.5 PU) step of load on bus 4 at t=1
- VTS mixed method:  
  huens switches to ode23t when t=10
- AGC and VTS available in pstSETO only

Summary

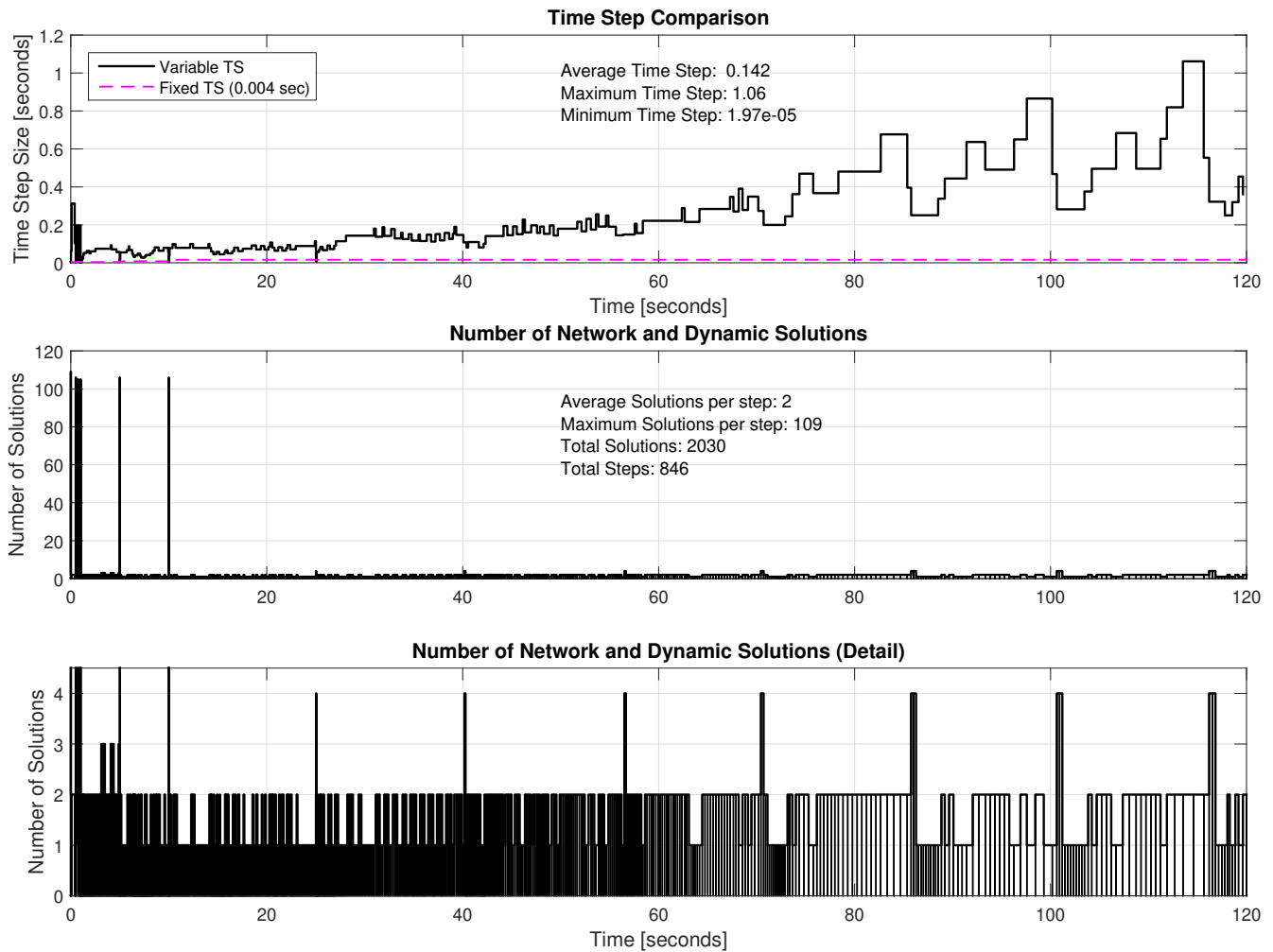
1. AGC works in variable time step simulation.
2. VTS takes larger steps, which often means fewer network and dynamic solutions.  
  This leads to a noticeable speed up.
3. AGC action was accounted for without VTS requiring a ‘time block break’.
4. Variable step network and dynamic values seem to match fixed results well.

Method	Step Size [seconds]			Total Steps	Solutions Per Step		Total Slns.	Sim. time	Speed Up
	Max.	Min.	Ave.		Ave.	Max.			
Huen’s	0.016	0.004	0.014	8,749	2	2	17,498	57.45	1
ode23t	1.060	1.97E-5	0.142	846	2	109	2,030	9.31	6.17
Mixed	1.030	0.004	0.048	2,483	2	106	4,780	15.86	3.62

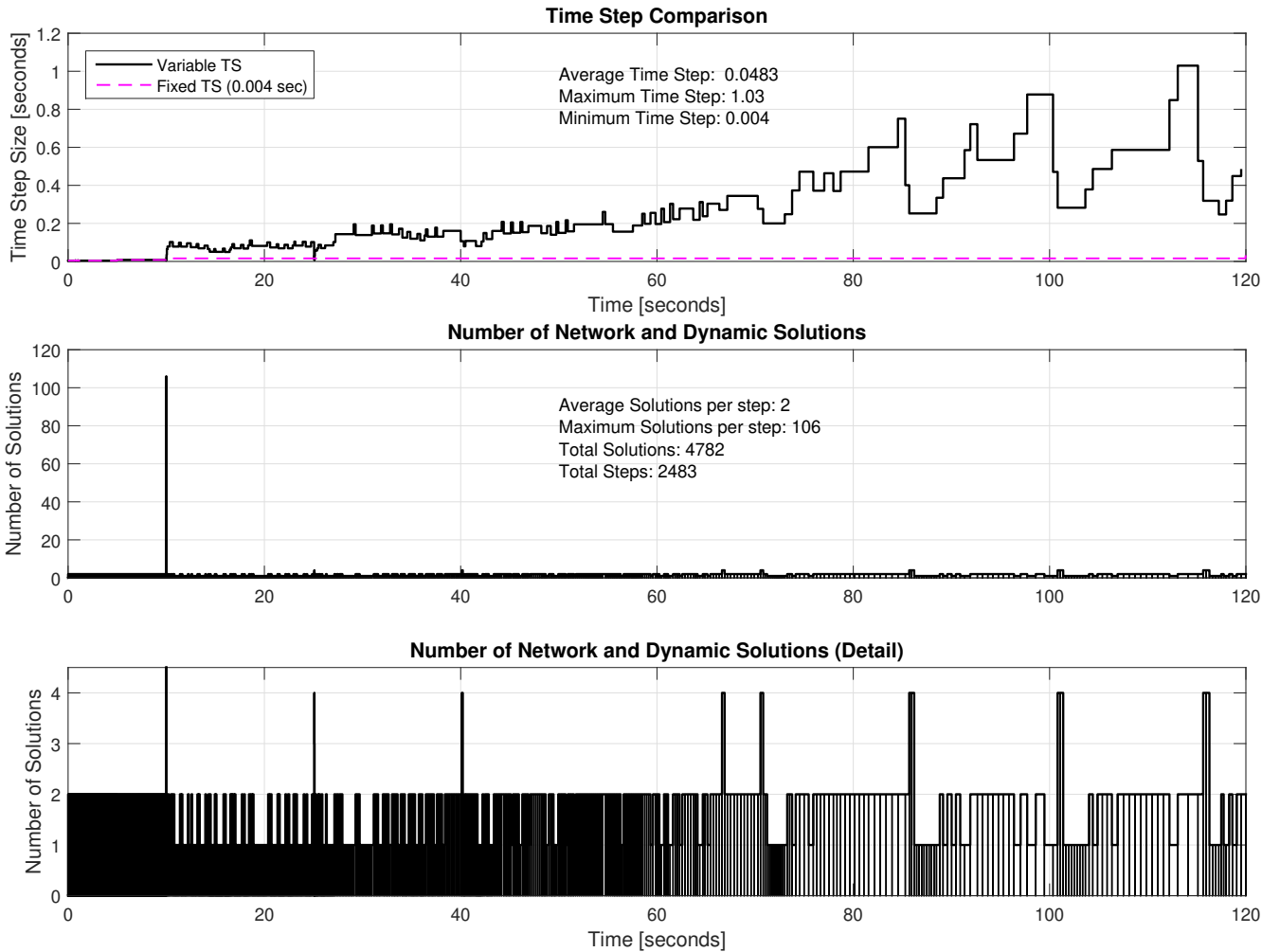
Observations of Note

5. Mixed solutions may be more efficient if fixed steps are used for initialization and all faulting condition switches then switching to a variable step method.
6. Solution tolerances of ODE solver were: 'RelTol',1e-3,'AbsTol',1e-6,
7. mtg\_sig must set tg\_sig to zero (or other desired modulated value).  
  i.e. mtg\_sig cannot just be empty.

## ode23t Results



Mixed Results (Huen's and ode23t)



**Both/Either Method** (visually undifferentiable)

