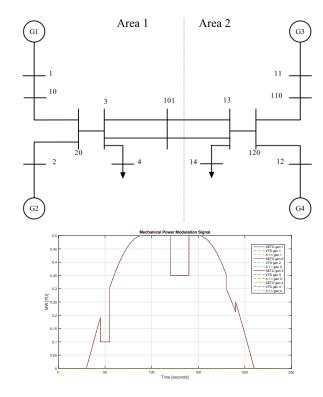
#### Scenario

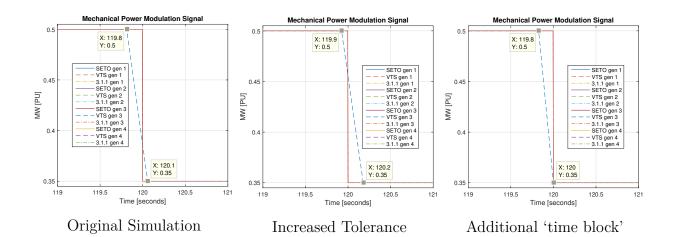


- Kundur 4 machine system packaged with PST
- Constant Z load model
- System has governors, exciters, and PSS.
- Governor of generator being perturbed by pm sig removed
- Perturbance was meant to mimic a solar ramp with various situations of cloud cover: (larger plot of pm\_sig on Page 6)

### Summary

- 1. Delay in executing pm sig caused by VTS created a noticeable delay in VTS dynamics.
- 2. Increasing ODE solver tolerances did not resolve the issue.
- 3. Creating a new time block near the event in question did resolve the issue.

As shown below, VTS may result with event start times ending up between computed time steps without additional user action/foresight.



## sw\_con Changes

The original switching array is shown below.

```
ts = 0.004;
sw_con = [...
. 1
        0
                    0
                                0
                                      0
                                           0
                                                 ts;
                                                       % sets intitial time step
                    3
0.2
        101
                                0
                                      0
                                           6
                                                       % Do Nothing
                                                 ts;
30.0
                    0
                                      0
                                                       % Do Nothing
        0
                                0
                                           0
                                                 ts;
240.0
                    0
                                                 0];
                                                       % end simulation
                                0
                                      0
```

The altered switching array adds a null event at t = 120 to ensure the pm\_sig step is processed at the designed starting time.

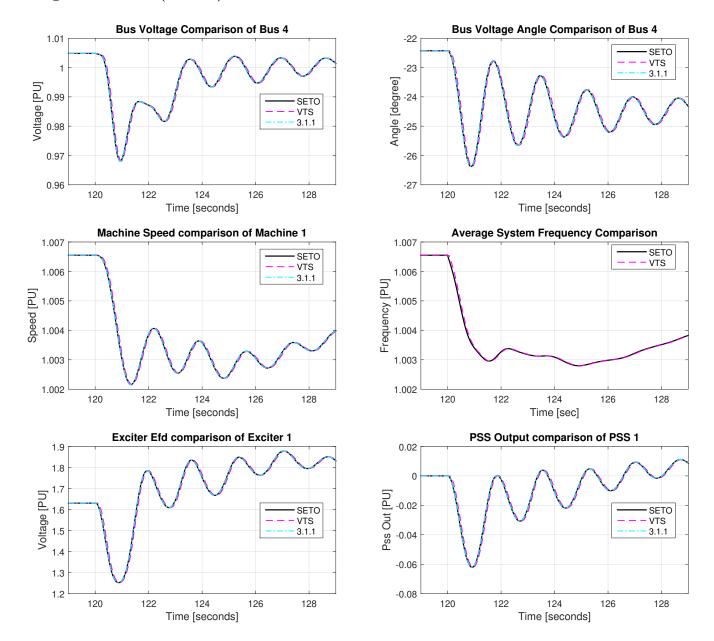
```
ts = 0.004;
sw_con = [...
.1
        0
                                                      % sets intitial time step
                    0
                                0
                                     0
                                          0
                                                ts;
0.2
        101
                    3
                                0
                                     0
                                                      % Do Nothing
                                          6
                                                ts;
30.0
        0
                    0
                                                      % Do Nothing
                                0
                                     0
                                          0
                                                ts;
120.0
                    0
                                                      % Do Nothing
        0
                                0
                                     0
                                          0
                                                ts;
240.0
                    0
                                0
                                     0
                                                0];
                                                      % end simulation
        0
```

### **Performance Effects**

The increased tolerance case (VTS 1) took more time to simulate as it took many more steps. VTS 2, with altered sw\_con, performed slightly slower than the original (VTS 0) case.

	Step Size [seconds]					Solutions Per Step				
Version	Max.	Min.	Ave.	Total Steps	Ave.	Max.	Total Slns.	Sim. Time	Speed Up	
VTS 0	2.32E+01	2.68E-04	2.58E-02	9,315	2	97	17,006	61.73	1.00	
VTS 1	2.32E+01	1.36E-04	1.38E-02	17,353	2	96	27,243	106.09	0.58	
$VTS\ 2$	2.00E+01	2.19E-05	2.58E-02	9,504	2	100	17,927	66.59	0.93	

# Original Results (VTS 0)



# Altered sw\_con Results (VTS 2)

