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# Long-Term Simulation of Power System Dynamics using Time Sequenced Power Flows

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Montana Tech - Master's Thesis Research Project

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## Overview of Project

**TODO:**

What is LTD - why use it  
system assumptions/main methods of LTD  
goals of research/ code

## TODO:

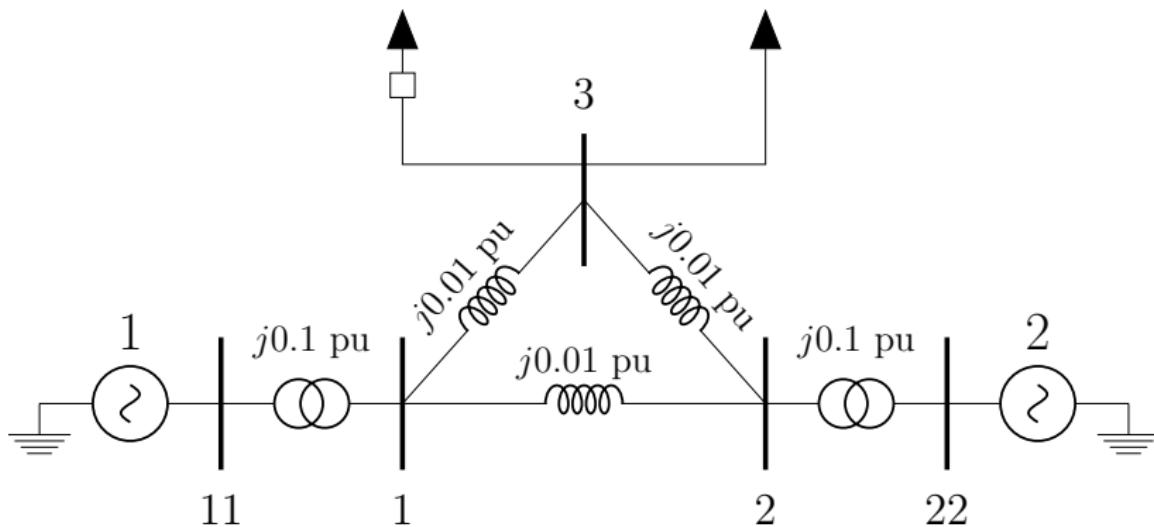
Overview of parts involved in simulation  
(sequence diagram)

other explanations about computery stuff:  
ipy vs py?

flow chart of predicted work flow.

System Used for Initial Frequency Validation

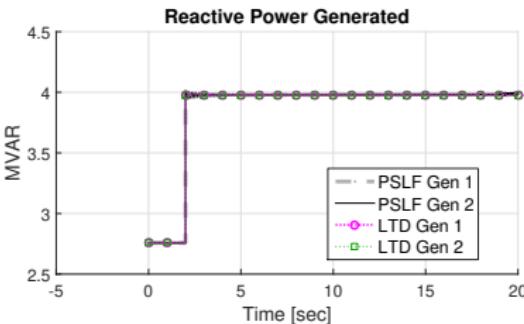
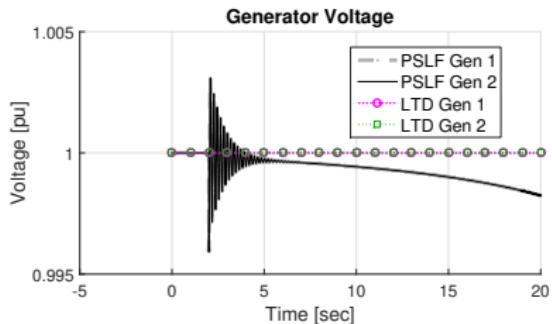
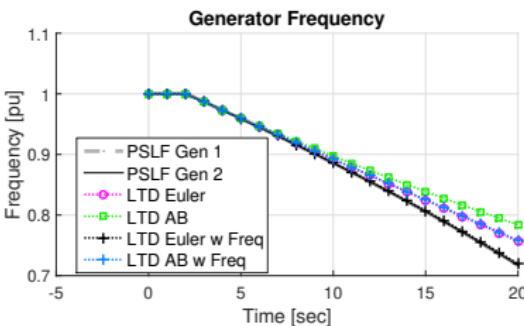
## EE554.sav test system:



Generators are identical.  
PSLF models have exciters.

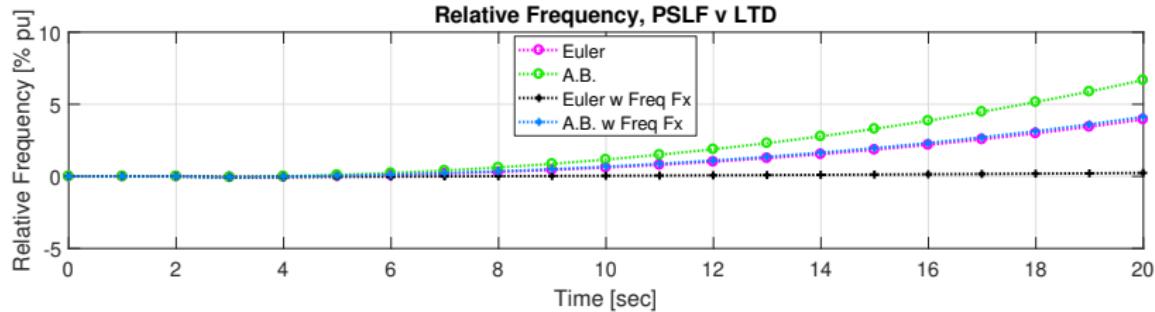
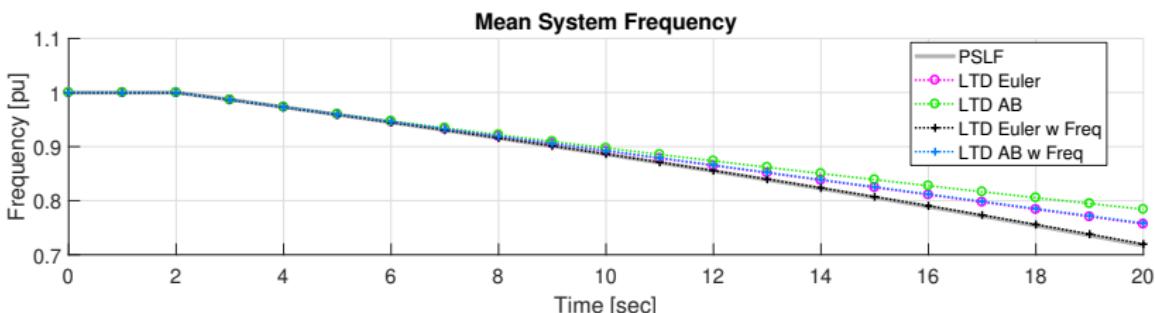
+20 MW Load Step at t=2

# System Response



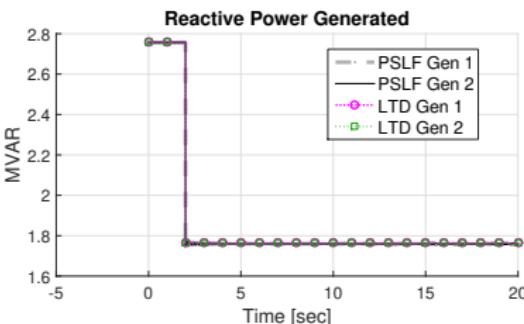
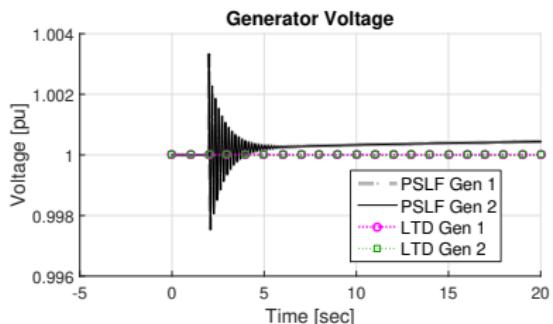
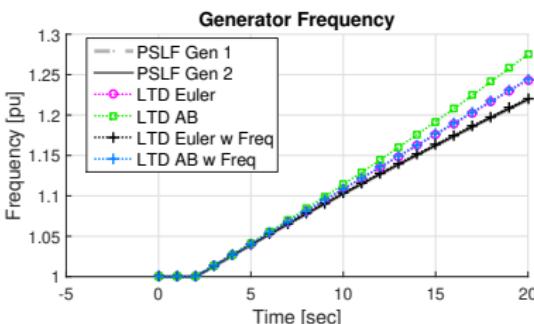
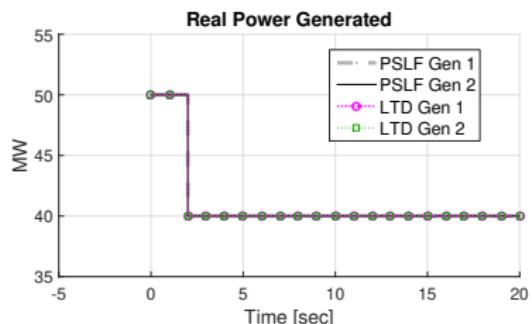
+20 MW Load Step at t=2

# Detailed Frequency Response



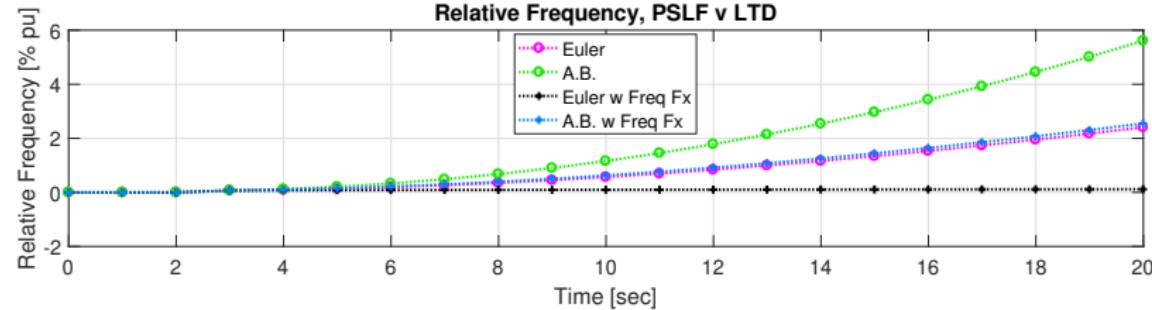
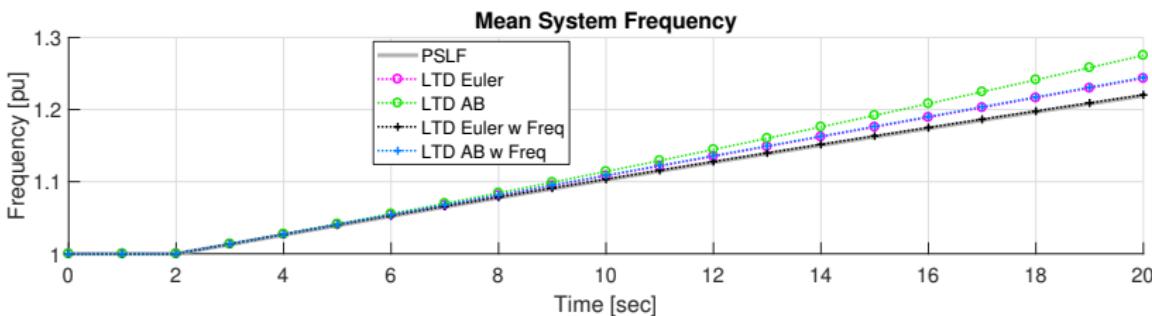
-20 MW Load Step at t=2

# System Response



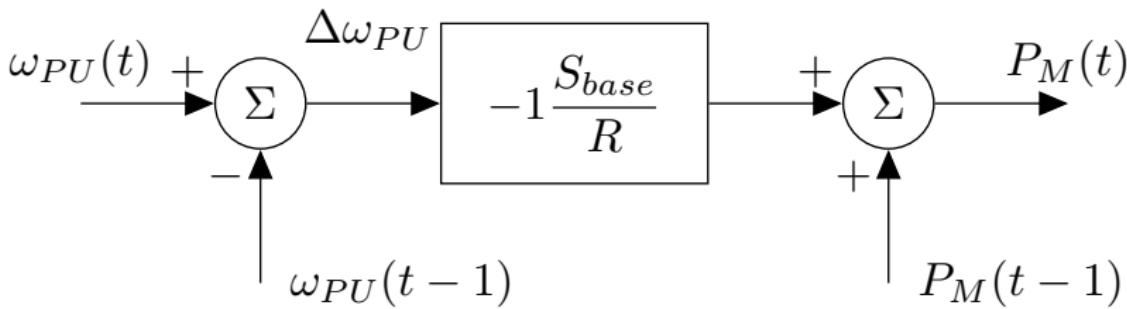
-20 MW Load Step at t=2

# Detailed Frequency Response



Dynamic model 'pgov1' defined

## pgov1 : Proportional gain control of $P_M$

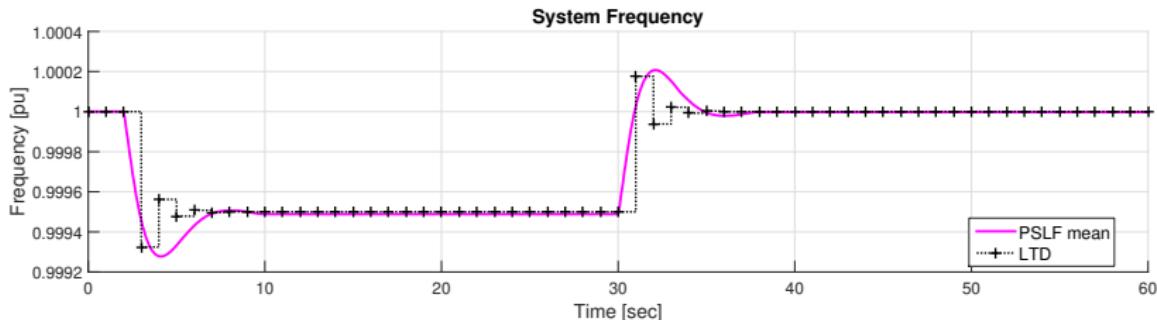
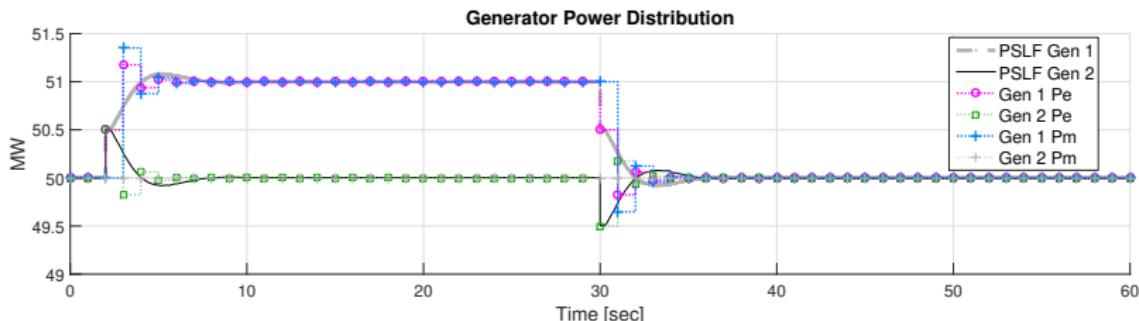


Entered into system via parsed text file:

```
# model busnum busnam basekv id : #9 mwcap droop
#!pgov1 11 "11" 22.00 "1" : #9 mwcap=100.0 0.05
```

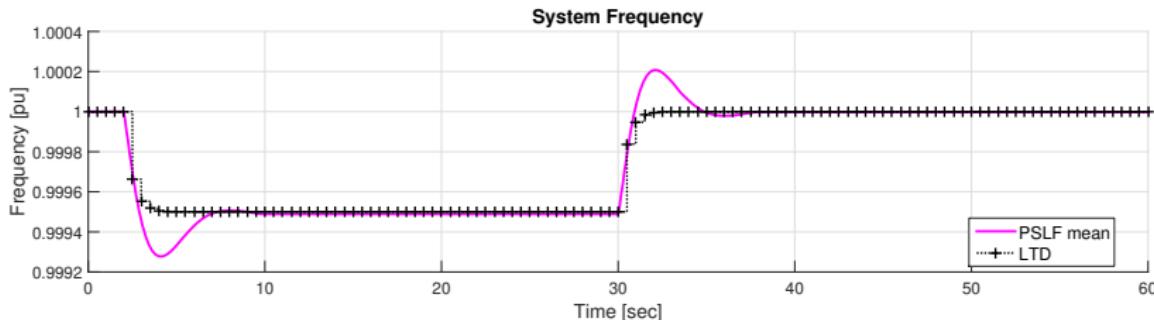
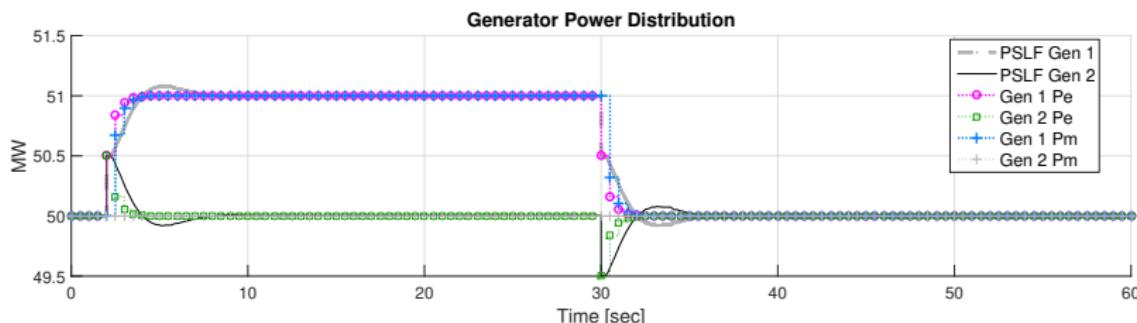
Dynamic model 'pgov1' experiment: +1 MW t=2, -1 MW t=30

# pgov1 on Gen 1, 1 second time step



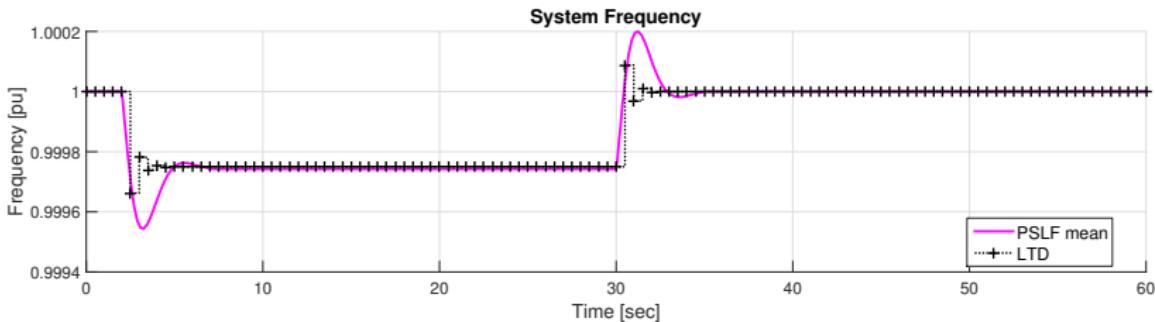
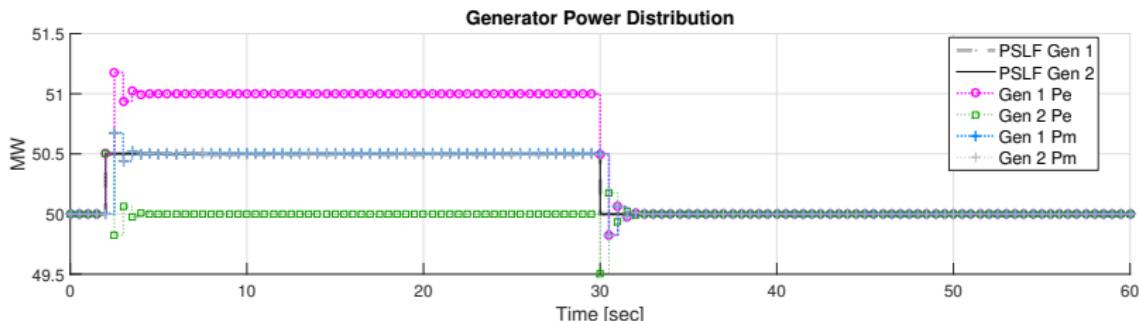
Dynamic model 'pgov1' experiment: +1 MW t=2, -1 MW t=30

# pgov1 on Gen 1, 0.5 second time step



Dynamic model 'pgov1' experiment: +1 MW t=2, -1 MW t=30

## pgov1 on both Gens, 0.5 second time step



- ▶ Much more work to do.
- ▶ Frequency effects should be accounted for in swing equation.
- ▶ Euler Integration tracks PSLF mean frequency well.
- ▶ Custom dynamic model implementation seems realizable.