

Graph-BFS-DFS

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0.1 BFS

- $O(V + E)$

```
def bfs (vertex):
    Queue queue
    vertex set visited true
    queue.enqueue(vertex)

    while queue not empty:
        actual = queue.dequeue()

        for v in actual neighbours:
            if v is not visited:
                v set visited true
                queue.enqueue(v)
```

```
In [9]: class Node(object):

        def __init__(self, name):
            self.name = name;
            self.adjacencyList = [];
            self.visited = False;
            self.predecessor = None;

        class BreadthFirstSearch(object):

            def bfs(self, startNode):

                queue = [];
                queue.append(startNode)
                startNode.visited = True;

                while queue:

                    actualNode = queue.pop(0);
                    print("%s " % actualNode.name)
```

```

    for node in actualNode.adjacencyList:
        if not node.visited:
            node.visited = True
            queue.append(node);

```

```

In [10]: node1 = Node("A");
        node2 = Node("B");
        node3 = Node("C");
        node4 = Node("D");
        node5 = Node("E");

        node1.adjacencyList.append(node2);
        node1.adjacencyList.append(node3);
        node2.adjacencyList.append(node4);
        node4.adjacencyList.append(node5);

        bfs = BreadthFirstSearch();
        bfs.bfs(node1);

```

A
B
C
D
E

```

In [ ]:

```

```

In [ ]:

```

0.2 DFS

```

def dfs(vertex):
    Stack stack
    vertex set visited True
    stack.push(vertex)

    while stack not empty:
        actual = stack.pop()

        for v in actual neighbours:
            if v is not visited:
                v set visited True
                stack.push(v)

```

```

def dfs(vertex):

```

```

vertex set visisted True
print vertex

for v in vertex neighbours:
    if v is not visited:
        dfs(v)

```

```

In [14]: class Node(object):
        def __init__(self, name):
            self.name = name;
            self.adjacenciesList = [];
            self.visited = False;
            self.predecessor = None;

        class DepthFirstSearch(object):

            def dfs(self, node):

                node.visited = True;
                print("%s" % node.name);

                for n in node.adjacenciesList:
                    if not n.visited:
                        self.dfs(n)

```

```

In [16]: node1 = Node("A");
        node2 = Node("B");
        node3 = Node("C");
        node4 = Node("D");
        node5 = Node("E");

        node1.adjacenciesList.append(node2);
        node1.adjacenciesList.append(node3);
        node2.adjacenciesList.append(node4);
        node4.adjacenciesList.append(node5);

        dfs = DepthFirstSearch();
        dfs.dfs(node1);

```

```

A
B
D
E
C

```

```

In [ ]:

```

0.3 Memory Management

- BFS:
 - *Space complexity: $O(N)$* . Because at the leaves \rightarrow if we have N items stored in the balanced tree \sim then there will be $N/2$ leaf nodes
 - So we have to store $O(N)$ items if we want to traverse a tree that contains N items!!!
- DFS:
 - Here we have to backtrack (pop item from stack): so basically we just have to store as many items in the stack as the height of the tree \rightarrow which is $\log(N)$!!!
 - \sim so the memory complexity will be $O(\log N)$
- That's why depth-first search is preferred most of the times. There may be some situations where BFS is better \sim artificial intelligence, robot movements

In []: