

Heap

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0.1 Heap

- It is basically a binary tree
- Two main binary heap types: min and max heap
- In a max heap, the keys of parent nodes are always greater than or equal to those of the children -> the highest key is in the root node.
- In a min heap, the keys of parent nodes are less than or equals to those of the children -> the lowest key is in the root node
- It is complete: it cannot be unbalanced !!! we insert every new item to the next available place
- Applications: Dijkstra's algorithm, Prim's algorithm
- The heap is one maximally efficient implementation of a priority queue abstract data type
- It has nothing to do with the pool of memory from which dynamically allocated memory is allocated.

0.2 Heap properties

- 1) Complete -> we construct the heap from left to right across each row // of course the last row may not be completely full. There is no missing node from left to right in a layer
- 2) In a binary heap every node can have 2 children, left child and right child
- 3)
 - Min heap -> the parent is always smaller than the values of the children
 - Max heap -> the parent is always greater
 - So: the root node will the smallest/greatest value in the heap. // $O(1)$ access !!!
 - It is an $O(n)$ process to construct a heap
 - We have to reconstruct it if the heap properties are violated but it takes $O(\log N)$ time --> $O(N) + O(\log N) - O(N)$
 - inserting an item to the heap is just adding the data to the array with incremented index!!! $O(1)$

0.3 Deleting an item

- We just get rid of the item we want to delete. But there will be a hold in the tree. So we put the last item there, and make sure the heap properties are valid // with reconstructions!!!
- So: we have managed to get rid of the root node and to make some reconstructions in order to end up with a valid heap again!!!
- Operation: deleting the root node $O(1)$ + reconstruction $O(\log N) = O(\log N)$
- Operation: deleting the arbitrary node $O(N)$ + reconstruction $O(\log N) = O(N)$!!!

0.4 Heapsort

- Comparison-based sorting algorithm
- Use Heap data structure rather than a linear-time search to find the maximum
- A bit slower in practice on most machines than a well-implemented quicksort, it has the advantage of a more favorable worst-case $O(N \log N)$ runtime
- It is an in-place algorithm, but it is not a stable sort
- **Does NOT NEED ADDITIONAL MEMORY**
- Problem: first we have to construct the heap itself from the numbers we want to sort -> $O(N)$ time complexity!!!

0.5 Running time

- Running time: we have to consider N items + have to make some swappings if necessary
 $O(N \log N)$
- Memory complexity: we have N items we want to store in the heap. We have to allocate memory for an array with size N --> $O(N)$ memory complexity
- Find the minimum / maximum: $O(1)$ very fast. Because in a heap the highest priority item is at the root node, it is easy heapArray[0] will be the item we are looking for
- Insert new items: we can insert at the next available place, so increment the array index and insert it -> $O(1)$ fast. But we have to make sure the heap properties are met.. it may take $O(\log N)$ time
- $O(\log_2 N)$ why? because a node has at most $\log_2 N$ parents so at most $\log_2 N$ swaps are needed
- Remove item: We usually remove the root node. Removing it is quite fast: just delete it in $O(1)$ time. But we have to make sure we met the heap properties $O(\log N)$ time to reconstruct the heap!!!

```
In [13]: class Heap(object):
          HEAP_SIZE = 10

          def __init__(self):
              self.heap = [0]* Heap.HEAP_SIZE
              self.currentPosition = -1

          def insert(self, item):
```

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if self.isFull():
    print("Heap is full...")
    return

self.currentPosition = self.currentPosition + 1
self.heap[self.currentPosition] = item
self.fixUp(self.currentPosition)

def fixUp(self, index):
    parentIndex = int((index - 1)/2)

    while parentIndex >= 0 and self.heap[parentIndex] < self.heap[index]:
        temp = self.heap[index]
        self.heap[index] = self.heap[parentIndex]
        self.heap[parentIndex] = temp;
        parentIndex = (int)((index-1)/2)

def heapsort(self):

    for i in range(0, self.currentPosition + 1):
        temp = self.heap[0]
        print("%d " % temp)
        self.heap[0] = self.heap[self.currentPosition - i]
        self.heap[self.currentPosition - i] = temp
        self.fixDown(0, self.currentPosition - i - 1)

def fixDown(self, index, upto):

    while index <= upto:
        leftChild = 2*index + 1
        rightChild = 2*index + 2

        if leftChild < upto:
            childToSwap = None

            if rightChild > upto:
                childToSwap = leftChild
            else:
                if self.heap[leftChild] > self.heap[rightChild]:
                    childToSwap = leftChild
                else:
                    childToSwap = rightChild

            if self.heap[index] < self.heap[childToSwap]:
                temp = self.heap[index]
                self.heap[index] = self.heap[childToSwap]
                self.heap[childToSwap] = temp
            else:

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        break

    index = childToSwap

    else:
        break

    def isFull(self):
        if self.currentPosition == Heap.HEAP_SIZE:
            return True
        else:
            return False

```

```

In [14]: heap = Heap()
        heap.insert(10)
        heap.insert(-20)
        heap.insert(0)
        heap.insert(2)

        heap.heapsort()

```

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TypeError Traceback (most recent call last)

```

<ipython-input-14-458ada994925> in <module>()
      5 heap.insert(2)
      6
----> 7 heap.heapsort()

<ipython-input-13-f70e9428940e> in heapsort(self)
    31     self.heap[0] = self.heap[self.currentPosition - i]
    32     self.heap[self.currentPosition - i] = temp
----> 33     self.fixDown(0, self.currentPosition - i - 1)
    34
    35     def fixDown(self, index, upto):

<ipython-input-13-f70e9428940e> in fixDown(self, index, upto)
    50         childToSwap = rightChild
    51
----> 52         if self.heap[index] < self.heap[childToSwap]:

```

```
53         temp = self.heap[index]
54         self.heap[index] = self.heap[childToSway]
```

TypeError: list indices must be integers or slices, not NoneType

In []: