

THAI P. DUONG

Email: tduong@ucsd.edu | Website: <https://thaipduong.github.io> | [Google Scholar](#)

RESEARCH INTERESTS

Robot Dynamics Learning, Planning and Control; Model-based Reinforcement Learning; Robot Perception and Environment Representation; Robot Exploration and Safety; Decision Making under Uncertainty.

EDUCATION

Ph.D. Electrical and Computer Engineering. Track: Intelligent Systems, Robotics & Control.	University of California, San Diego La Jolla, CA	2018 - 2024 (expected)
M.S. Electrical Engineering and Computer Science.	Oregon State University Corvallis, OR	2015
B.S. Electronics and Telecommunications. Honors Program.	Hanoi University of Science & Technology Hanoi, Vietnam	2011

EXPERIENCE

Graduate Researcher Advisor: Prof. Nikolay Atanasov , Existential Robotics Laboratory Working on machine learning for robotics: robot dynamics learning, planning and control, robot exploration and safety, robot perception, decision making under uncertainty, etc. (ROS, C++, python, pytorch, tensorflow, quadrotors, cars)	University of California, San Diego La Jolla, CA	2018 – Present
R&D Intern Working on optimization-based motion planning for robot manipulators.	Amazon Robotics	2022
Software Engineer I/II Working on bugs/anomalies detection and power optimizations (C++/C#).	Microsoft Corporation, Office Performance Team	2015 – 2018

PROJECTS

Robot dynamics learning and control <i>neural ODE, python, pytorch, quadrotors, cars</i> <ul style="list-style-type: none">Encoding physics knowledge and Lie group constraints in machine learning models for dynamics learning and control. <i>Papers</i>: [7] [4] [2].Adaptive control with disturbance features learned from data. <i>Papers</i> [10][12].Safe navigation using physics-guided dynamics learning. <i>Papers</i> [6] [11].Learning distributed control policies from demonstration. <i>Papers</i> [5].	2020 - Present
Environment understanding for robot navigation <i>ROS, C++, cars</i> <ul style="list-style-type: none">Sparse online Bayesian occupancy map of the environment using relevance vector machine and efficient collision checking algorithms for autonomous navigation. <i>Papers</i> [8] [9].Optimal planning with large language model guidance. <i>Papers</i> [1].	2018 - Present

SELECTED PUBLICATIONS

Preprints

- [1] Z. Dai, A. Asgharivaskasi, **T. Duong**, S. Lin, M. Tzes, G. Pappas, N. Atanasov, “*Optimal Scene Graph Planning with Large Language Model Guidance*”, submitted to IEEE International Conference on Robotics and Automation (ICRA), 2024 [\[arxiv\]](#).
- [2] A. Altawaitan, J. Stanley, S. Ghosal, **T. Duong**, N. Atanasov, “*Hamiltonian Dynamics Learning from Point Cloud Observations for Nonholonomic Mobile Robot Control*”, submitted to IEEE International Conference on Robotics and Automation (ICRA), 2024 [\[arxiv\]](#).

Conferences

- [3] E. Sebastian, **T. Duong**, N. Atanasov, E. Montijano and C. Sagues, “*Learning to Identify Graphs from Node Trajectories in Multi-Robot Networks*”, International Symposium on Multi-Robot & Multi-Agent Systems (MRS), 2023 [\[website\]](#)[\[arxiv\]](#).
- [4] V. Duruisseaux, **T. Duong**, N. Atanasov, M. Leok, “*Lie Group Forced Variational Integrator Networks for Learning and Control of Robot Systems*”, Learning for Dynamics & Control Conference (L4DC), 2023 [\[website\]](#)[\[arxiv\]](#).
- [5] E. Sebastian, **T. Duong**, N. Atanasov, E. Montijano and C. Sagues, “*LEMURS: Learning Distributed Multi-robot Interactions*”, IEEE International Conference on Robotics and Automation, 2023 [\[website\]](#)[\[arxiv\]](#).
- [6] Z. Li*, **T. Duong***, N. Atanasov, “*Safe Autonomous Navigation for Systems with Learned SE(3) Hamiltonian Dynamics*”, Learning for Dynamics & Control Conference (L4DC), 2022 [\[pdf\]](#) [\[website\]](#) (*equal contribution).
- [7] **T. Duong**, N. Atanasov, “*Hamiltonian-based Neural ODE Networks on the SE(3) Manifold For Dynamics Learning and Control*”, Robotics: Science and Systems (RSS), Virtual, 2021 [\[code\]](#)[\[pdf\]](#) [\[website\]](#).
- [8] **T. Duong**, N. Das, M. Yip, N. Atanasov, “*Autonomous Navigation in Unknown Environments using Sparse Kernel-based Occupancy Mapping*”, International Conference on Robotics and Automation (ICRA), Virtual, 2020 [\[code\]](#)[\[pdf\]](#) [\[website\]](#).

Journals

- [9] **T. Duong**, M. Yip, N. Atanasov, “*Autonomous Navigation in Unknown Environments with Sparse Bayesian Kernel-based Occupancy Mapping*”, IEEE Transactions on Robotics (T-RO), 2022 [\[code\]](#)[\[pdf\]](#) [\[website\]](#).

- [10] **T. Duong**, N. Atanasov, “*Adaptive Control of $SE(3)$ Hamiltonian Dynamics with Learned Disturbance Features*”, IEEE Control Systems Letters, 2022 [[pdf](#)] [[website](#)].
- [11] Z. Li, **T. Duong**, N. Atanasov, “*Robust and Safe Autonomous Navigation for Systems with Learned $SE(3)$ Hamiltonian Dynamics*”, IEEE Open Journal of Control System, 2022 (*Invited Paper*) [[website](#)].

Workshops

- [12] **T. Duong**, N. Atanasov, “*Physics-guided Learning-based Adaptive Control on the $SE(3)$ Manifold*”, Physical Reasoning and Inductive Biases for the Real World Workshop at NeurIPS, Virtual, 2021 [[pdf](#)].

TALKS

- “Learning and Control of Hamiltonian Dynamics on the $SE(3)$ Manifold”, 2022 SIAM Conference on Mathematics of Data Science ([MDS’22](#))
- “Autonomous Navigation in Unknown Environments with Sparse Bayesian Kernel-based Occupancy Mapping”, 2023 International Conference on Robotics and Automation ([ICRA’23](#))
- “Learning Environment and Dynamics Representations for Autonomous Robot Navigation”, Robograd Seminar, UCSD, 2023

SERVICES

Reviewers: IEEE Transactions on Robotics (T-RO), IEEE Robotics and Automation Letters (RAL), IEEE International Conference on Robotics and Automation (ICRA), IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS), American Control Conference (ACC), Learning for Dynamics and Control (L4DC).

Program Committee:

[AAAI’23](#) workshop “[When Machine Learning meets Dynamical Systems: Theory and Applications](#)”.

TECHNICAL SKILLS

Programming: C++/Python/Matlab, Object-oriented Design.

Operating Systems: Linux, ROS.

Libraries and Toolbox: Tensorflow, Pytorch, Pybullet, Gazebo, Docker.

Hardware Platforms: RaceCar, PX4 Quadrotors.

HONORS AND AWARDS

ICRA 2023 Travel Grant , IEEE Robotics and Automation Society	2023
ECE Department Fellowships , University of California, San Diego	2018-2019
Jacobs Fellowships , University of California, San Diego	2018
First place, Microsoft Coding Competition , Oregon State University	2013
Phi Kappa Phi Society , Oregon State University	2013
President’s Honors List , Hanoi University of Science & Technology	2011
Department’s Honors List , Hanoi University of Science & Technology	2010

TEACHING EXPERIENCE

Teaching Assistant , Planning & Learning in Robotics, University of California, San Diego	Spring 2021
Teaching Assistant , Sensing & Estimation in Robotics, University of California, San Diego	Winter 2020
Teaching Assistant , Stochastic Signals & Systems, Oregon State University	Fall 2014
Teaching Assistant , Discrete Structures in Computer Science, Oregon State University	Summer 2014
Teaching Assistant , Intro. to Probability & Random Signals, Oregon State University	Winter 2014

MENTORING

MS students:

Sambaran Ghosal (UCSD), Rishabh Bhattacharya (UCSD), Quan Luo (UCSD) 2020-present

BS students:

Minh Pham (UCSD), Yuchen Zhang (UCSD), Behrad Rabiei (UCSD), Jiawen Yu (UCSD), Adin Ackerman (UCSD), Anthony Tseng (UCSD), Jason Stanley (UCSD) 2020-present

MAE Women’s Mentoring Program: Dehao Lin(UCSD), Zihang He(UCSD), David Yount(UCSD) 2023

International student office’s mentorship program: Iman Sayyadzadeh (UCSD), Taiga Morioka (UCSD) 2023