```
#pragma once
#include<string>
#include<vector>
#include<iostream>
class P_ctrl
public:
   P_ctrl(const float& P); // constructor for P controller
   float calc_ctrl_P(float error); // function that calculates control input based on provided error from the
system we aim to control.
   float m_P;
};
class PI_ctrl : public P_ctrl
private:
protected:
public:
   float m_I;
   float m_dT;
   float m_integrator;
   float calc_ctrl_I( float error);
   PI_ctrl(const float& P,
            const float& I,
            const float& dT);
   float calc_ctrl_PI( float error);
};
class PID_ctrl : public PI_ctrl
private:
protected:
public:
    std::string newName;
    std::string getName();
    std::string setName(std::string);
   float m_D;
   float m_dT;
   float m_p_error;
    float calc_ctrl_D( float error);
    //std::string m_ID; // if you'll need to compare two std::string objects you have to use string::compare
    PID_ctrl(float P, float I, float D, float dT, std::string ID);
    float calc_ctrl_PID( float error);
   void setD(const float& P, const float& I, const float& D); //IMPLEMENT! use references to set and get P,I
and D constants.. P and I are set as protected which makes them accessible to PID class
   void getD(float& P, float& I, float& D); //IMPLEMENT!
```