

# RSVP: ROBOT SCENARIO VISUAL PLANNING

CISC1003

Exploring Robotics

# RSVP: ROBOT SCENARIO VISUAL PLANNING

- Making a picture or a “visual representation” of the scenario and instructions you want the robot to perform
  - can be great way to ensure your robot performs the tasks properly
- A picture of the instructions the robot will perform allows you to think through the steps before translating them to the code

# RSVP: ROBOT SCENARIO VISUAL PLANNING

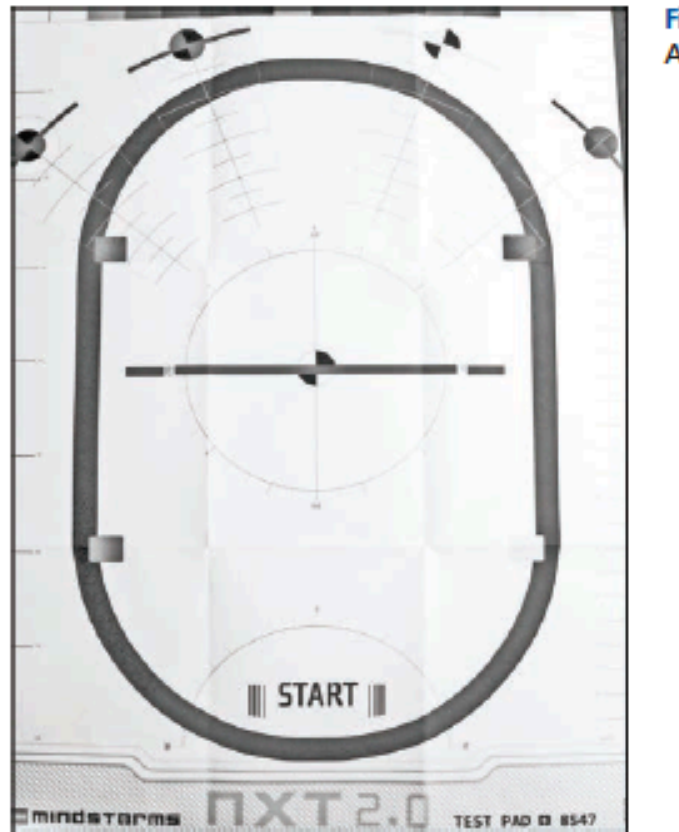
- The RSVP is composed of three types of visuals:
  - A floorplan of the physical environment of the scenario
  - A statechart of the robot and object's states
  - Flowcharts of the instructions for the tasks

# Mapping the Scenario

- The first part of the RSVP is a map of the scenario
- A map is a symbolic representation of the environment
  - where the tasks and situations will take place
  - The environment for the scenario is the world in which the robots operate

# Mapping Example

A robot world for NXT Mindstorms Test Pad



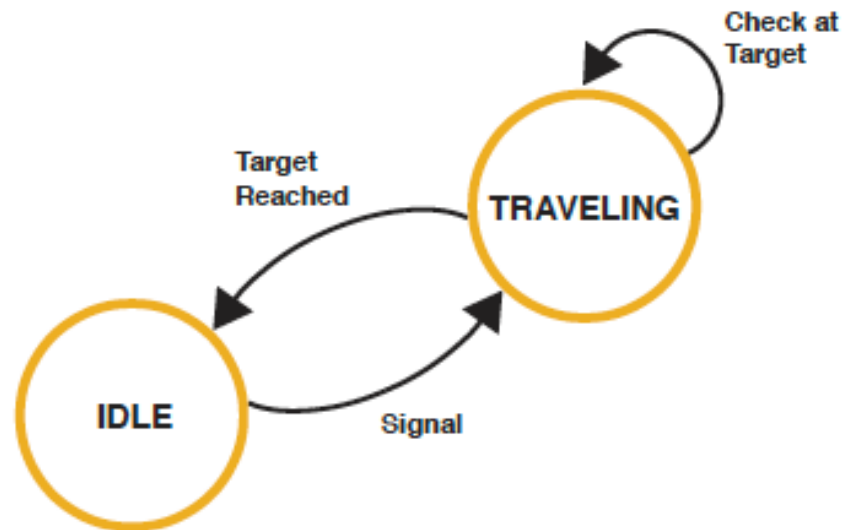
# State Chart

- A statechart is one way to visualize a state machine.
- For example , a “change of state” can be as simple as a change of location.
  - When the robot travels from its initial location to the location next to the table, this is a change of the robot’s state.
  - Another example is that the birthday candles change from an unlit state to a lit state.

# State Chart

- The state machine captures the events, transformations, and responses.
- A statechart is a diagram of these activities.
- The statechart is used to capture the possible situations for that object in that scenario

# Example – State Machine





# Pseudocode and Flowcharting

- Flowcharts are a type of statechart
  - they contain states that are converted to actions and activities
    - Things like decisions and repetitions are easily represented
      - what happens as the result of a branch can be simply depicted.
  - Some suggest flowcharting before writing pseudocode

# Pseudocode and Flowcharting

- Pseudocode has the advantage of being easily converted to a programming language or utilized for documenting a program
  - It can also be easily changed.
- A flowchart requires a bit more work to change when using flowcharting software.

# PseudoCode

- What is the problem we are trying to solve?
  - Identify the behavior you need
  - Write down the sequence of behaviors that is needed
    - To achieve your goals
  - Identify the sub-tasks needed to achieve your goals

# Pseudocode

- As we increase the level of details, we will reach commands we can express directly in programming language
- This is the plan the robot needs to follow
- The steps are written in English
  - So can be understood by the human programmer
- This is called *Pseudocode*

# Pseudocode and Flowcharting

RSVP Type	Advantages	Disadvantages
<p><b>Pseudocode:</b></p> <p>A method of describing computer instructions using a combination of natural language or programming language.</p>	<p>Easily created and modified in any word processor.</p> <p>Implementation is useful in any design.</p> <p>Written and understood easily.</p> <p>Easily converted to a programming language.</p>	<p>Is not visual.</p> <p>No standardized style or format.</p> <p>More difficult to follow the logic.</p>
<p><b>Flowcharting:</b></p> <p>Flow from the top to the bottom of a page. Each command is placed in a box of the appropriate shape, and arrows are used to direct program flow.</p>	<p>Is visual, easier to communicate to others.</p> <p>Problems can be analyzed more effectively.</p>	<p>Can become complex and clumsy for complicated logic.</p> <p>Alterations may require redrawing completely.</p>

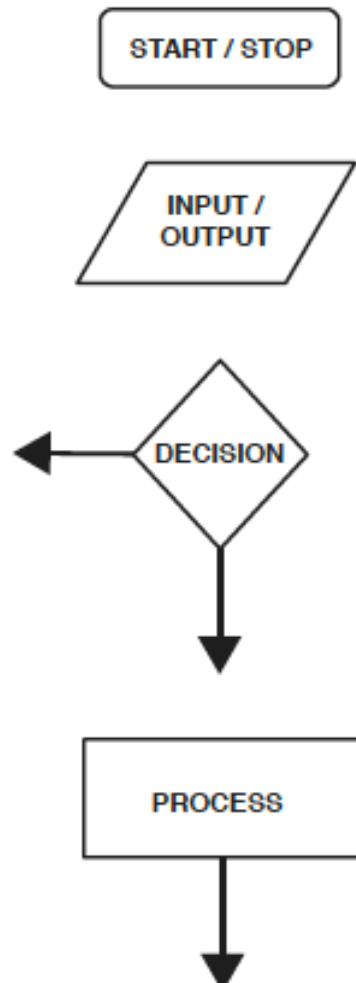
# Flowcharting

- The four common symbols used in flowcharting are
- Start and stop:
  - The start symbol represents the beginning of the flowchart with the label “start” appearing inside the symbol.
  - The stop symbol represents the end of the flowchart with the label “stop” appearing inside the symbol. These are the only symbols with keyword labels.
- Input and output:
  - The input and output symbol contains data that is used for input (e.g., provided by the user)
    - and data that is the result of processing (output)

# Flowcharting

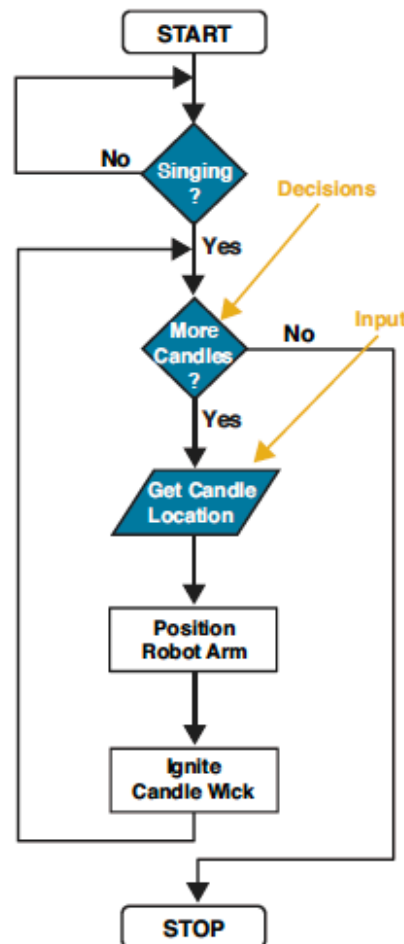
- Decisions:
  - The decision symbol contains a question or a decision that has to be made.
- Process:
  - The process symbol contains brief descriptions (a few words) of a rule or some action taking place .

# Common Flowchart Symbols





# Example - Candlelighting Flowchart



# Flowcharting

- The task a robot executes can be a series of steps performed one after another
  - a sequential flow of control.
- ***Flow of control*** details the direction the process takes
  - which way program control “flows
- Flow of control determines how a computer responds
  - when given certain conditions and parameters

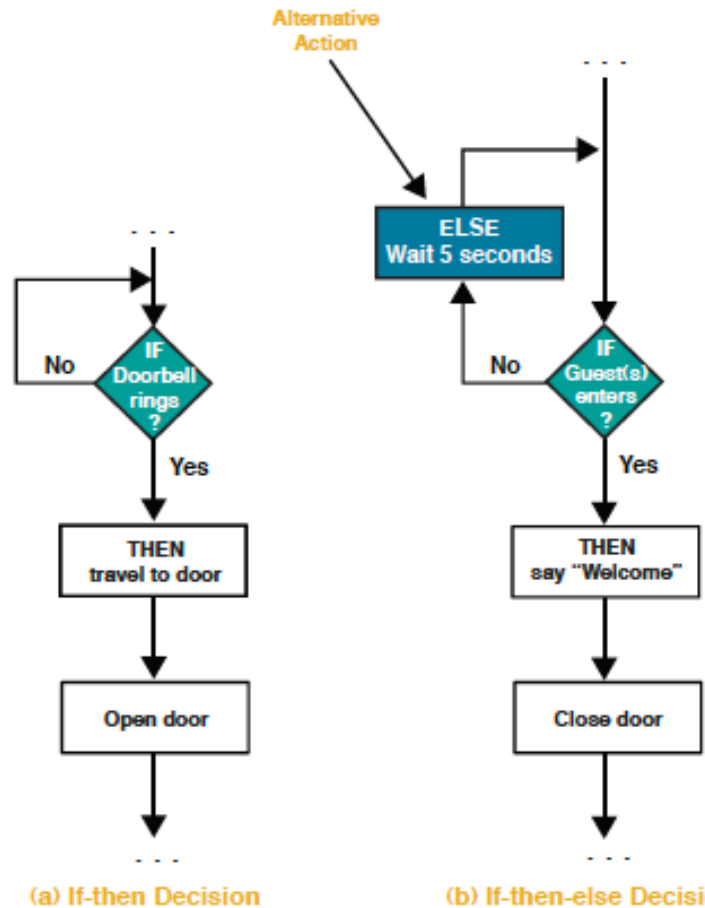
# Example: Sequential Flowchart



# Flowcharting

- A decision symbol is used to construct branching for alternative flow controls.
- Decision symbols can be used to express decision, repetition, and case statements
- A simple decision is structured as an if-then or if-then-else statement

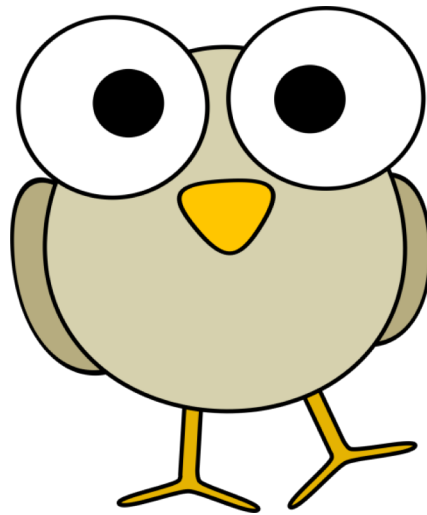
# Example – Guest Welcoming Flowchart



# Summary

- The RSVP is composed of three types of visuals:
  - A floorplan of the physical environment of the scenario
  - A statechart of the robot and object's states
  - Flowcharts of the instructions for the tasks
- These visuals ensure that you have a “clear picture” of what has to be done
  - to program a robot to save the world
    - or light the candles on a cake

- Questions?



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