## Maskrcnn seven class 5 (2)

December 31, 2019

```
[4]: from google.colab import drive drive.mount('/content/drive')
```

Go to this URL in a browser: https://accounts.google.com/o/oauth2/auth?client\_id =947318989803-6bn6qk8qdgf4n4g3pfee6491hc0brc4i.apps.googleusercontent.com&redire ct\_uri=urn%3aietf%3awg%3aoauth%3a2.0%3aoob&response\_type=code&scope=email%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdocs.test%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive%20https%3a%2f%2fwww.googleapis.com%2fauth%2fdrive.photos.readonly%20https%3a%2f%2fwww.googleapis.com%2fauth%2fpeopleapi.readonly

```
Enter your authorization code:
.....
Mounted at /content/drive
```

```
[0]: import os
  import sys
  import json
  import numpy as np
  import time
  from PIL import Image, ImageDraw
  import tensorflow.compat.v1 as tf
  tf.disable_v2_behavior()
```

```
[6]: # Set the ROOT_DIR variable to the root directory of the Mask_RCNN git repo
ROOT_DIR = '/content/drive/My Drive/'
assert os.path.exists(ROOT_DIR), 'ROOT_DIR does not exist. Did you forget to
→read the instructions above? ;)'

# Import mrcnn libraries
sys.path.append(ROOT_DIR)
from mrcnn.config import Config
import mrcnn.utils as utils
from mrcnn import visualize
import mrcnn.model as modellib
```

Using TensorFlow backend.

```
[0]: # Directory to save logs and trained model
MODEL_DIR = os.path.join(ROOT_DIR, "cervic_logs")

# Local path to trained weights file
# COCO_MODEL_PATH = os.path.join(ROOT_DIR, "mask_rcnn_cig_butts_0008.h5")

COCO_MODEL_PATH = os.path.join(ROOT_DIR, "mask_rcnn_coco.h5")

# Download COCO trained weights from Releases if needed
if not os.path.exists(COCO_MODEL_PATH):
    utils.download_trained_weights(COCO_MODEL_PATH)
```

```
[8]: print(MODEL_DIR )
print(COCO_MODEL_PATH)
```

/content/drive/My Drive/cervic\_logs
/content/drive/My Drive/mask\_rcnn\_coco.h5

```
[9]: class Cervic_seven_classConfig(Config):
         """Configuration for training on the cigarette butts dataset.
         Derives from the base Config class and overrides values specific
         to the cigarette butts dataset.
         # Give the configuration a recognizable name
         NAME = "Cervic seven class"
         # Train on 1 GPU and 1 image per GPU. Batch sizoure is 1 (GPUs * images/
      \hookrightarrow GPU).
         GPU COUNT = 1
         IMAGES_PER_GPU = 1
         # Number of classes (including background)
         NUM CLASSES = 1 + 7 # background + 1 (cig butt)
         # All of our training images are 512x512
         IMAGE_MIN_DIM = 512
         IMAGE_MAX_DIM = 512
         # You can experiment with this number to see if it improves training
         STEPS_PER_EPOCH = 500
         LEARNING_RATE= 5e-4
         # This is how often validation is run. If you are using too much hard drive,
      \hookrightarrowspace
         # on saved models (in the MODEL DIR), try making this value larger.
         VALIDATION_STEPS = 5
```

```
# Matterport originally used resnet101, but I downsized to fit it on my_
graphics card

BACKBONE = 'resnet50'

# To be honest, I haven't taken the time to figure out what these do
RPN_ANCHOR_SCALES = (8, 16, 32, 64, 128)
TRAIN_ROIS_PER_IMAGE = 32
MAX_GT_INSTANCES = 50
POST_NMS_ROIS_INFERENCE = 500
POST_NMS_ROIS_TRAINING = 1000

config = Cervic_seven_classConfig()
config.display()
```

```
Configurations:
BACKBONE
                                resnet50
BACKBONE_STRIDES
                                [4, 8, 16, 32, 64]
BATCH_SIZE
                                [0.1 0.1 0.2 0.2]
BBOX_STD_DEV
COMPUTE_BACKBONE_SHAPE
                                None
DETECTION_MAX_INSTANCES
                                100
DETECTION MIN CONFIDENCE
                                0.7
DETECTION_NMS_THRESHOLD
                                0.3
FPN CLASSIF FC LAYERS SIZE
                                1024
GPU COUNT
                                5.0
GRADIENT CLIP NORM
IMAGES_PER_GPU
                                1
                                3
IMAGE_CHANNEL_COUNT
IMAGE_MAX_DIM
                                512
IMAGE_META_SIZE
                                20
                                512
IMAGE_MIN_DIM
IMAGE_MIN_SCALE
IMAGE_RESIZE_MODE
                                square
IMAGE_SHAPE
                                [512 512
                                           3]
LEARNING_MOMENTUM
                                0.9
LEARNING_RATE
                                0.0005
LOSS WEIGHTS
                                {'rpn_class_loss': 1.0, 'rpn_bbox_loss': 1.0,
'mrcnn_class_loss': 1.0, 'mrcnn_bbox_loss': 1.0, 'mrcnn_mask_loss': 1.0}
MASK POOL SIZE
                                14
MASK SHAPE
                                [28, 28]
MAX_GT_INSTANCES
                                50
MEAN_PIXEL
                                [123.7 116.8 103.9]
                                (56, 56)
MINI_MASK_SHAPE
                                Cervic_seven_class
NAME
NUM_CLASSES
                                8
POOL_SIZE
                                7
```

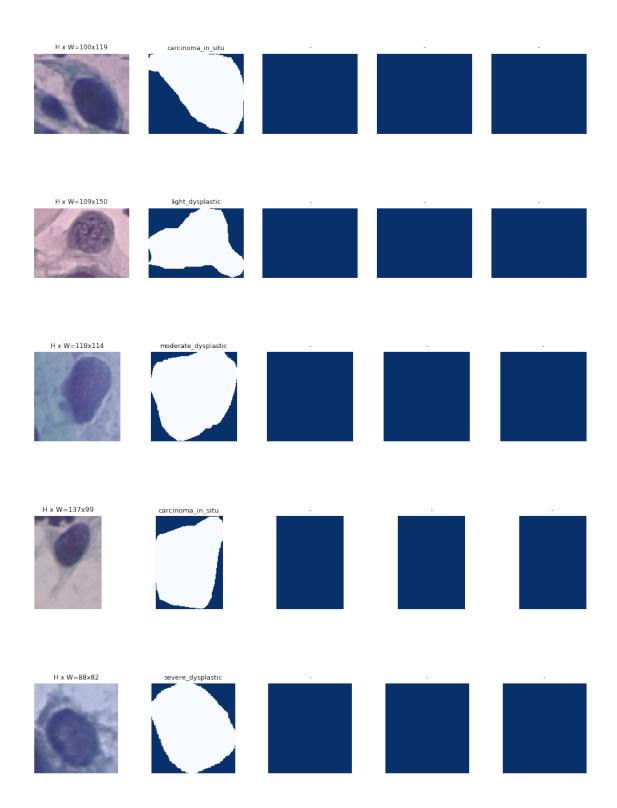
```
POST_NMS_ROIS_INFERENCE
                                500
                                1000
POST_NMS_ROIS_TRAINING
PRE_NMS_LIMIT
                                6000
ROI_POSITIVE_RATIO
                                0.33
RPN ANCHOR RATIOS
                                [0.5, 1, 2]
RPN_ANCHOR_SCALES
                                (8, 16, 32, 64, 128)
RPN ANCHOR STRIDE
RPN_BBOX_STD_DEV
                                [0.1 \ 0.1 \ 0.2 \ 0.2]
RPN NMS THRESHOLD
                                0.7
RPN_TRAIN_ANCHORS_PER_IMAGE
                                256
STEPS_PER_EPOCH
                                500
TOP_DOWN_PYRAMID_SIZE
                                256
TRAIN_BN
                                False
                                32
TRAIN_ROIS_PER_IMAGE
USE_MINI_MASK
                                True
USE_RPN_ROIS
                                True
VALIDATION_STEPS
                                0.0001
WEIGHT_DECAY
```

```
[0]: class CocoLikeDataset(utils.Dataset):
        \hookrightarrowstyle of the COCO dataset.
            See http://cocodataset.org/#home for more information.
        def load_data(self, annotation_json, images_dir):
            """ Load the coco-like dataset from json
            Args:
                annotation_json: The path to the coco annotations json file
                images_dir: The directory holding the images referred to by the ___
     \hookrightarrow json file
            11 11 11
            # Load json from file
            json_file = open(annotation_json)
            coco_json = json.load(json_file)
            json_file.close()
            # Add the class names using the base method from utils.Dataset
            source name = "coco like"
            for category in coco_json['categories']:
                class_id = category['category_id']
                \# class_id = 4
                class_name = category['name']
                # class_name = 'Severe_dysplastic'
                if class_id < 1:</pre>
```

```
print('Error: Class id for "{}" cannot be less than one. (0 is_{\sqcup}
→reserved for the background)'.format(class_name))
               return
           self.add_class(source_name, class_id, class_name)
       # Get all annotations
       annotations = {}
       for annotation in coco_json['annotations']:
           image_id = annotation['image_id']
           if image_id not in annotations:
               annotations[image_id] = []
           annotations[image_id].append(annotation)
       # Get all images and add them to the dataset
       seen_images = {}
       for image in coco_json['images']:
           image_id = image['id']
           if image_id in seen_images:
               print("Warning: Skipping duplicate image id: {}".format(image))
           else:
               seen_images[image_id] = image
               try:
                   image_file_name = image['filename']
                   image_width = image['width']
                   image_height = image['height']
               except KeyError as key:
                   print("Warning: Skipping image (id: {}) with missing key:
→{}".format(image_id, key))
               image_path = os.path.abspath(os.path.join(images_dir,_
→image_file_name))
               image_annotations = annotations[image_id]
               # Add the image using the base method from utils.Dataset
               self.add_image(
                   source=source_name,
                   image_id=image_id,
                   path=image_path,
                   width=image_width,
                   height=image_height,
                   annotations=image_annotations
               )
  def load_mask(self, image_id):
       """ Load instance masks for the given image.
```

```
MaskRCNN expects masks in the form of a bitmap [height, width, ]
       \hookrightarrow instances].
              Args:
                  image_id: The id of the image to load masks for
              Returns:
                  masks: A bool array of shape [height, width, instance count] with
                      one mask per instance.
                  class_ids: a 1D array of class IDs of the instance masks.
              image_info = self.image_info[image_id]
              annotations = image_info['annotations']
              instance_masks = []
              class_ids = []
              for annotation in annotations:
                  class_id = annotation['category_id']
                  mask = Image.new('1', (image_info['width'], image_info['height']))
                  mask_draw = ImageDraw.ImageDraw(mask, '1')
                  for segmentation in annotation['segmentation']:
                      mask_draw.polygon(segmentation, fill=1)
                      bool array = np.array(mask) > 0
                      instance masks.append(bool array)
                      class_ids.append(class_id)
              mask = np.dstack(instance_masks)
              class_ids = np.array(class_ids, dtype=np.int32)
              return mask, class_ids
[0]: dataset train = CocoLikeDataset()
      dataset_train.load_data('/content/drive/My Drive/cervic_train/
      →cervic_all_class_train1.json', '/content/drive/My Drive/')
      dataset_train.prepare()
      dataset_val = CocoLikeDataset()
      dataset_val.load_data('/content/drive/My_Drive/cervic_validation/

→cervic_all_class_validation1.json', '/content/drive/My Drive/')
      dataset val.prepare()
[12]: dataset = dataset_train
      image_ids = np.random.choice(dataset.image_ids,6)
      for image id in image ids:
          image = dataset.load_image(image_id)
          mask, class ids = dataset.load mask(image id)
          visualize.display_top_masks(image, mask, class_ids, dataset.class_names)
```





WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:541: The name tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:66: The name tf.get\_default\_graph is deprecated. Please use tf.compat.v1.get\_default\_graph instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:4432: The name tf.random\_uniform is deprecated. Please use tf.random.uniform instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:2139: The name tf.nn.fused\_batch\_norm is deprecated. Please use tf.compat.v1.nn.fused\_batch\_norm instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:4267: The name tf.nn.max\_pool is deprecated. Please use tf.nn.max\_pool2d instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:2239: The name tf.image.resize\_nearest\_neighbor is deprecated. Please use tf.compat.v1.image.resize\_nearest\_neighbor instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow\_core/python/ops/array\_ops.py:1475: where (from tensorflow.python.ops.array\_ops) is deprecated and will be removed in a future version.

Instructions for updating:

Use tf.where in 2.0, which has the same broadcast rule as np.where WARNING:tensorflow:From /content/drive/My Drive/mrcnn/model.py:553: The name tf.random\_shuffle is deprecated. Please use tf.random.shuffle instead.

WARNING:tensorflow:From /content/drive/My Drive/mrcnn/utils.py:202: The name tf.log is deprecated. Please use tf.math.log instead.

WARNING:tensorflow:From /content/drive/My Drive/mrcnn/model.py:600: calling crop\_and\_resize\_v1 (from tensorflow.python.ops.image\_ops\_impl) with box\_ind is deprecated and will be removed in a future version.

Instructions for updating:

box\_ind is deprecated, use box\_indices instead

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:197: The name tf.ConfigProto is deprecated. Please use tf.compat.v1.ConfigProto instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:203: The name tf.Session is deprecated. Please use tf.compat.v1.Session instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:207: The name tf.global\_variables is deprecated. Please use tf.compat.v1.global\_variables instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:216: The name

```
tf.compat.v1.is_variable_initialized instead.
     WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
     packages/keras/backend/tensorflow backend.py:223: The name
     tf.variables_initializer is deprecated. Please use
     tf.compat.v1.variables initializer instead.
[15]: # Train the head branches
      # Passing layers="heads" freezes all layers except the head
      # layers. You can also pass a regular expression to select
      # which layers to train by name pattern.
      start_train = time.time()
      model.train(dataset_train, dataset_val,
                  learning_rate=config.LEARNING_RATE,
                  epochs=20,
                  layers='heads')
      end train = time.time()
      minutes = round((end_train - start_train) / 60, 2)
      print(f'Training took {minutes} minutes')
     Starting at epoch 0. LR=0.0005
     Checkpoint Path: /content/drive/My Drive/cervic_logs/cervic_seven_class20191231T
     0757/mask_rcnn_cervic_seven_class_{epoch:04d}.h5
     Selecting layers to train
     fpn_c5p5
                             (Conv2D)
     fpn_c4p4
                             (Conv2D)
     fpn_c3p3
                             (Conv2D)
     fpn_c2p2
                             (Conv2D)
     fpn_p5
                             (Conv2D)
     fpn_p2
                             (Conv2D)
     fpn_p3
                             (Conv2D)
     fpn_p4
                             (Conv2D)
     In model: rpn_model
         rpn_conv_shared
                                 (Conv2D)
         rpn_class_raw
                                 (Conv2D)
         rpn_bbox_pred
                                 (Conv2D)
     mrcnn_mask_conv1
                             (TimeDistributed)
     mrcnn_mask_bn1
                             (TimeDistributed)
                             (TimeDistributed)
     mrcnn mask conv2
     mrcnn_mask_bn2
                             (TimeDistributed)
     mrcnn_class_conv1
                             (TimeDistributed)
                             (TimeDistributed)
     mrcnn_class_bn1
     mrcnn_mask_conv3
                             (TimeDistributed)
     mrcnn_mask_bn3
                             (TimeDistributed)
```

tf.is\_variable\_initialized is deprecated. Please use

(TimeDistributed) mrcnn\_class\_conv2 mrcnn\_class\_bn2 (TimeDistributed) mrcnn\_mask\_conv4 (TimeDistributed) mrcnn\_mask\_bn4 (TimeDistributed) mrcnn bbox fc (TimeDistributed) mrcnn mask deconv (TimeDistributed) mrcnn class logits (TimeDistributed) mrcnn mask (TimeDistributed)

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-

packages/keras/optimizers.py:793: The name tf.train.Optimizer is deprecated.

Please use tf.compat.v1.train.Optimizer instead.

## /usr/local/lib/python3.6/dist-

packages/tensorflow\_core/python/framework/indexed\_slices.py:424: UserWarning: Converting sparse IndexedSlices to a dense Tensor of unknown shape. This may consume a large amount of memory.

"Converting sparse IndexedSlices to a dense Tensor of unknown shape. " /usr/local/lib/python3.6/dist-

packages/tensorflow\_core/python/framework/indexed\_slices.py:424: UserWarning: Converting sparse IndexedSlices to a dense Tensor of unknown shape. This may consume a large amount of memory.

"Converting sparse IndexedSlices to a dense Tensor of unknown shape. " /usr/local/lib/python3.6/dist-

packages/tensorflow\_core/python/framework/indexed\_slices.py:424: UserWarning: Converting sparse IndexedSlices to a dense Tensor of unknown shape. This may consume a large amount of memory.

"Converting sparse IndexedSlices to a dense Tensor of unknown shape. "

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:1033: The name tf.assign\_add is deprecated. Please use tf.compat.v1.assign\_add instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow\_backend.py:1020: The name tf.assign is deprecated. Please use tf.compat.v1.assign instead.

/usr/local/lib/python3.6/dist-packages/keras/engine/training\_generator.py:49: UserWarning: Using a generator with `use\_multiprocessing=True` and multiple workers may duplicate your data. Please consider using the `keras.utils.Sequence class.

UserWarning('Using a generator with `use multiprocessing=True`'

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/callbacks.py:1122: The name tf.summary.merge\_all is deprecated. Please use tf.compat.v1.summary.merge\_all instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/callbacks.py:1125: The name tf.summary.FileWriter is deprecated.

Please use tf.compat.v1.summary.FileWriter instead.

```
Epoch 1/20
500/500 [============ ] - 134s 269ms/step - loss: 4.0954 -
rpn class loss: 0.0622 - rpn bbox loss: 2.3489 - mrcnn class loss: 0.5738 -
mrcnn_bbox_loss: 0.4957 - mrcnn_mask_loss: 0.6148 - val_loss: 2.0337 -
val rpn class loss: 0.0147 - val rpn bbox loss: 0.9678 - val mrcnn class loss:
0.2840 - val_mrcnn_bbox_loss: 0.3038 - val_mrcnn_mask_loss: 0.4633
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-
packages/keras/callbacks.py:1265: The name tf.Summary is deprecated. Please use
tf.compat.v1.Summary instead.
Epoch 2/20
500/500 [============= ] - 103s 206ms/step - loss: 2.5473 -
rpn_class_loss: 0.0233 - rpn_bbox_loss: 1.2546 - mrcnn_class_loss: 0.4810 -
mrcnn_bbox loss: 0.2867 - mrcnn_mask_loss: 0.5016 - val_loss: 2.4901 -
val_rpn_class_loss: 0.0126 - val_rpn_bbox_loss: 0.8211 - val_mrcnn_class_loss:
0.7781 - val mrcnn bbox_loss: 0.3889 - val_mrcnn mask_loss: 0.4894
Epoch 3/20
500/500 [========== ] - 109s 219ms/step - loss: 1.9999 -
rpn_class_loss: 0.0173 - rpn_bbox_loss: 0.9498 - mrcnn_class_loss: 0.3921 -
mrcnn bbox loss: 0.2048 - mrcnn mask loss: 0.4359 - val loss: 2.0480 -
val_rpn_class_loss: 0.0126 - val_rpn_bbox_loss: 0.9769 - val_mrcnn_class_loss:
0.2942 - val_mrcnn_bbox_loss: 0.1474 - val_mrcnn_mask_loss: 0.6169
Epoch 4/20
500/500 [============ ] - 94s 189ms/step - loss: 1.6074 -
rpn_class_loss: 0.0142 - rpn_bbox_loss: 0.6948 - mrcnn_class_loss: 0.3453 -
mrcnn_bbox_loss: 0.1524 - mrcnn_mask_loss: 0.4008 - val_loss: 1.9176 -
val_rpn_class_loss: 0.0104 - val_rpn_bbox_loss: 0.6169 - val_mrcnn_class_loss:
0.5143 - val_mrcnn_bbox_loss: 0.2485 - val_mrcnn_mask_loss: 0.5275
Epoch 5/20
rpn_class loss: 0.0135 - rpn bbox loss: 0.6207 - mrcnn_class loss: 0.3200 -
mrcnn_bbox_loss: 0.1323 - mrcnn_mask_loss: 0.4077 - val_loss: 1.4026 -
val rpn class loss: 0.0160 - val rpn bbox loss: 0.6563 - val mrcnn class loss:
0.3307 - val_mrcnn_bbox_loss: 0.1078 - val_mrcnn_mask_loss: 0.2917
Epoch 6/20
rpn_class_loss: 0.0134 - rpn_bbox_loss: 0.5228 - mrcnn_class_loss: 0.2970 -
mrcnn_bbox_loss: 0.1048 - mrcnn_mask_loss: 0.3872 - val_loss: 1.3212 -
val_rpn_class_loss: 0.0236 - val_rpn_bbox_loss: 0.4646 - val_mrcnn_class_loss:
0.3977 - val mrcnn bbox_loss: 0.1247 - val_mrcnn mask_loss: 0.3106
500/500 [============ ] - 95s 190ms/step - loss: 1.2205 -
rpn_class_loss: 0.0127 - rpn_bbox_loss: 0.4830 - mrcnn_class_loss: 0.2688 -
mrcnn_bbox loss: 0.1022 - mrcnn_mask_loss: 0.3539 - val_loss: 1.5851 -
val_rpn_class_loss: 0.0089 - val_rpn_bbox_loss: 0.5821 - val_mrcnn_class_loss:
0.3762 - val_mrcnn_bbox_loss: 0.2059 - val_mrcnn_mask_loss: 0.4120
```

```
Epoch 8/20
rpn_class loss: 0.0113 - rpn bbox_loss: 0.4258 - mrcnn_class_loss: 0.2649 -
mrcnn_bbox_loss: 0.0965 - mrcnn_mask_loss: 0.3605 - val_loss: 1.3826 -
val rpn class loss: 0.0061 - val rpn bbox loss: 0.5371 - val mrcnn class loss:
0.3687 - val_mrcnn_bbox_loss: 0.1073 - val_mrcnn_mask_loss: 0.3635
Epoch 9/20
rpn_class_loss: 0.0104 - rpn_bbox_loss: 0.3910 - mrcnn_class_loss: 0.2135 -
mrcnn_bbox_loss: 0.0879 - mrcnn_mask_loss: 0.3381 - val_loss: 1.7972 -
val rpn_class_loss: 0.0151 - val rpn_bbox_loss: 0.8911 - val mrcnn_class_loss:
0.4202 - val_mrcnn_bbox_loss: 0.1669 - val_mrcnn_mask_loss: 0.3039
Epoch 10/20
500/500 [============= ] - 95s 190ms/step - loss: 1.0067 -
rpn_class_loss: 0.0107 - rpn_bbox_loss: 0.3545 - mrcnn_class_loss: 0.2365 -
mrcnn_bbox loss: 0.0815 - mrcnn_mask_loss: 0.3234 - val_loss: 1.2262 -
val_rpn_class_loss: 0.0056 - val_rpn_bbox_loss: 0.4851 - val_mrcnn_class_loss:
0.2992 - val_mrcnn_bbox_loss: 0.1335 - val_mrcnn_mask_loss: 0.3028
Epoch 11/20
500/500 [============= ] - 94s 189ms/step - loss: 0.8978 -
rpn_class_loss: 0.0104 - rpn_bbox_loss: 0.3133 - mrcnn_class_loss: 0.1941 -
mrcnn_bbox_loss: 0.0688 - mrcnn_mask_loss: 0.3112 - val_loss: 1.6351 -
val_rpn_class_loss: 0.0247 - val_rpn_bbox_loss: 0.4569 - val_mrcnn_class_loss:
0.6768 - val_mrcnn_bbox_loss: 0.0973 - val_mrcnn_mask_loss: 0.3794
Epoch 12/20
rpn_class_loss: 0.0100 - rpn_bbox_loss: 0.3084 - mrcnn_class_loss: 0.1900 -
mrcnn_bbox_loss: 0.0719 - mrcnn_mask_loss: 0.3049 - val_loss: 1.5411 -
val rpn_class_loss: 0.0180 - val rpn_bbox_loss: 0.4866 - val_mrcnn_class_loss:
0.6242 - val_mrcnn_bbox_loss: 0.1031 - val_mrcnn_mask_loss: 0.3091
Epoch 13/20
rpn_class loss: 0.0084 - rpn bbox loss: 0.2894 - mrcnn_class loss: 0.2089 -
mrcnn_bbox_loss: 0.0691 - mrcnn_mask_loss: 0.2860 - val_loss: 0.9672 -
val rpn class loss: 0.0187 - val rpn bbox loss: 0.5200 - val mrcnn class loss:
0.0644 - val_mrcnn_bbox_loss: 0.1276 - val_mrcnn_mask_loss: 0.2364
Epoch 14/20
500/500 [============ ] - 95s 190ms/step - loss: 0.7908 -
rpn_class_loss: 0.0091 - rpn_bbox_loss: 0.2474 - mrcnn_class_loss: 0.1797 -
mrcnn_bbox_loss: 0.0582 - mrcnn_mask_loss: 0.2964 - val_loss: 1.4010 -
val_rpn_class_loss: 0.0122 - val_rpn_bbox_loss: 0.5037 - val_mrcnn_class_loss:
0.4676 - val mrcnn bbox_loss: 0.1205 - val_mrcnn mask_loss: 0.2971
Epoch 15/20
500/500 [============ ] - 95s 190ms/step - loss: 0.7719 -
rpn_class_loss: 0.0090 - rpn_bbox_loss: 0.2511 - mrcnn_class_loss: 0.1717 -
mrcnn_bbox loss: 0.0606 - mrcnn_mask_loss: 0.2796 - val_loss: 1.1897 -
val_rpn_class_loss: 0.0124 - val_rpn_bbox_loss: 0.6217 - val_mrcnn_class_loss:
0.1832 - val_mrcnn_bbox_loss: 0.1333 - val_mrcnn_mask_loss: 0.2392
```

```
rpn_class loss: 0.0096 - rpn bbox loss: 0.2297 - mrcnn_class loss: 0.1570 -
   mrcnn_bbox_loss: 0.0515 - mrcnn_mask_loss: 0.2577 - val_loss: 1.2566 -
   val rpn class loss: 0.0078 - val rpn bbox loss: 0.4970 - val mrcnn class loss:
   0.3387 - val_mrcnn_bbox_loss: 0.1028 - val_mrcnn_mask_loss: 0.3104
   Epoch 17/20
   rpn_class_loss: 0.0092 - rpn_bbox_loss: 0.2096 - mrcnn_class_loss: 0.1396 -
   mrcnn_bbox_loss: 0.0545 - mrcnn_mask_loss: 0.2733 - val_loss: 1.1768 -
   val rpn_class_loss: 0.0119 - val rpn_bbox_loss: 0.2957 - val mrcnn_class_loss:
   0.5916 - val_mrcnn_bbox_loss: 0.0587 - val_mrcnn_mask_loss: 0.2190
   Epoch 18/20
   500/500 [============ ] - 95s 189ms/step - loss: 0.6804 -
   rpn_class_loss: 0.0090 - rpn_bbox_loss: 0.2142 - mrcnn_class_loss: 0.1412 -
   mrcnn_bbox loss: 0.0519 - mrcnn_mask_loss: 0.2640 - val_loss: 1.0045 -
   val_rpn_class_loss: 0.0044 - val_rpn_bbox_loss: 0.5210 - val_mrcnn_class_loss:
   0.1510 - val mrcnn bbox_loss: 0.1010 - val_mrcnn mask_loss: 0.2272
   Epoch 19/20
   500/500 [============== ] - 95s 189ms/step - loss: 0.6162 -
   rpn_class_loss: 0.0084 - rpn_bbox_loss: 0.1855 - mrcnn_class_loss: 0.1212 -
   mrcnn_bbox_loss: 0.0475 - mrcnn_mask_loss: 0.2535 - val_loss: 1.1202 -
   val_rpn_class_loss: 0.0073 - val_rpn_bbox_loss: 0.3786 - val_mrcnn_class_loss:
   0.4194 - val_mrcnn_bbox_loss: 0.0770 - val_mrcnn_mask_loss: 0.2379
   Epoch 20/20
   500/500 [============ ] - 95s 190ms/step - loss: 0.6365 -
   rpn_class_loss: 0.0078 - rpn_bbox_loss: 0.1795 - mrcnn_class_loss: 0.1370 -
   mrcnn_bbox_loss: 0.0480 - mrcnn_mask_loss: 0.2641 - val_loss: 1.0999 -
   val rpn_class_loss: 0.0116 - val rpn_bbox_loss: 0.5544 - val mrcnn_class_loss:
   0.0828 - val_mrcnn_bbox_loss: 0.1083 - val_mrcnn_mask_loss: 0.3428
   Training took 33.44 minutes
[0]: # Fine tune all layers
    # Passing layers="all" trains all layers. You can also
    # pass a regular expression to select which layers to
    # train by name pattern.
    # start_train = time.time()
    # model.train(dataset train, dataset val,
                 learning_rate=config.LEARNING_RATE / 10,
    #
                 epochs=8.
                 layers="all")
    # end_train = time.time()
    # minutes = round((end_train - start_train) / 60, 2)
    # print(f'Training took {minutes} minutes')
```

Epoch 16/20

```
[0]: class InferenceConfig(Cervic_seven_classConfig):
          GPU_COUNT = 1
          IMAGES_PER_GPU = 1
          IMAGE_MIN_DIM = 512
          IMAGE_MAX_DIM = 512
          # DETECTION_MIN_CONFIDENCE = 0.85
          DETECTION_MIN_CONFIDENCE = 0.65
      inference_config = InferenceConfig()
 [0]: # Set the ROOT DIR variable to the root directory of the Mask RCNN git repo
      ROOT_DIR = '/content/drive/My Drive/'
      assert os.path.exists(ROOT_DIR), 'ROOT_DIR does not exist. Did you forget tou
      →read the instructions above? ;)'
      # Import mrcnn libraries
      sys.path.append(ROOT DIR)
      from mrcnn.config import Config
      import mrcnn.utils as utils
      from mrcnn import visualize
      import mrcnn.model as modellib
 [0]: # Recreate the model in inference mode
      model = modellib.MaskRCNN(mode="inference",
                                config=inference_config,
                                model dir=MODEL DIR )
[33]: # Get path to saved weights
      # Either set a specific path or find last trained weights
      COCO_MODEL_PATH= '/content/drive/My Drive/cervic_logs/
      ⇔mask_rcnn_cervic_seven_class_0020.h5'
      model_path = os.path.join(ROOT_DIR, COCO_MODEL_PATH )
      #model_path = model.find_last()
      # Load trained weights (fill in path to trained weights here)
      assert model_path != "", "Provide path to trained weights"
      print("Loading weights from ", model_path)
      model.load_weights(model_path, by_name=True)
     Loading weights from /content/drive/My
     Drive/cervic_logs/mask_rcnn_cervic_seven_class_0020.h5
 [0]:
        def class_find(cl_id):
            names= {
```

```
'1': 'normal_intermediate',

'2': 'light_dysplastic',

'3': 'moderate_dysplastic',

'4': 'severe_dysplastic',

'5': 'normal_columnar',

'6': 'carcinoma_in_situ',

'7': 'normal_superficiel'

}

return names.get(cl_id)
```

```
[55]: import skimage
     real_test_dir = '/content/drive/My Drive/cervic_test/normal_intermediate'
     acc=0
     image_paths = []
     file count=0
     for filename in os.listdir(real test dir):
          if os.path.splitext(filename)[1] in ['.png', '.jpg', '.jpeg','.BMP']:
              image_paths.append(os.path.join(real_test_dir, filename))
              file_count=file_count+1
     for image_path in image_paths:
         print('filename:'+image_path)
          img = skimage.io.imread(image_path)
         img_arr = np.array(img)
         results = model.detect([img_arr], verbose=1)
         r = results[0]
         print(r['class_ids'][0])
         class_name=class_find(str(r['class_ids'][0]))
         actual_class= real_test_dir.rsplit('/', 1)[1]
         if class_name==actual_class:
            acc=acc+1
         print('Predicted class :' +class_name + ' Actual class :'+actual_class)
         visualize.display_instances(img, r['rois'], r['masks'], r['class_ids'],
                                      dataset_val.class_names, r['scores'], __
      \rightarrowfigsize=(5,5))
     print('Total no. of images in ',actual_class, ' is ', file_count)
     print('No. of images correctly classified is ', acc)
     accper=(acc/file_count) *100
     print('Accuracy of class: ', actual_class, 'is', str(accper))
```

```
filename:/content/drive/My
Drive/cervic_test/normal_intermediate/209565698-209565772-001.BMP
Processing 1 images
image shape: (278, 331, 3) min: 7.00000 max: 230.00000 uint8
molded_images shape: (1, 512, 512, 3) min: -123.70000 max:
```

123.10000 float64

image\_metas shape: (1, 20) min: 0.00000 max:

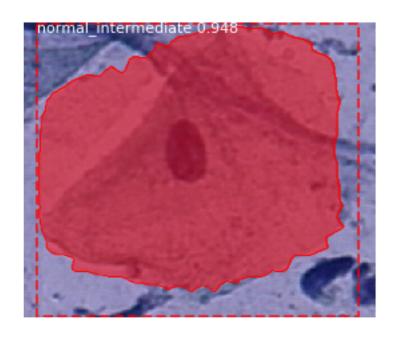
512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1

Predicted class :normal\_intermediate Actual class :normal\_intermediate



filename:/content/drive/My

Drive/cervic\_test/normal\_intermediate/209565864-209565890-001.BMP

Processing 1 images

image shape: (258, 259, 3) min: 21.00000 max:

254.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

149.10000 float64

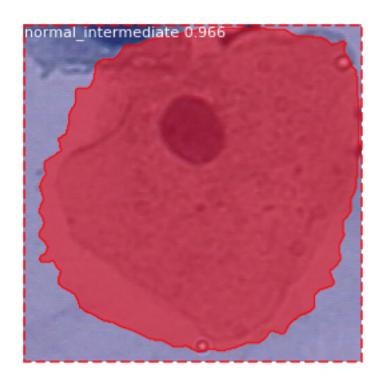
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



 ${\tt Drive/cervic\_test/normal\_intermediate/209565864-209565911-001.BMP}$ 

Processing 1 images

image shape: (230, 335, 3) min: 7.00000 max:

250.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

143.10000 float64

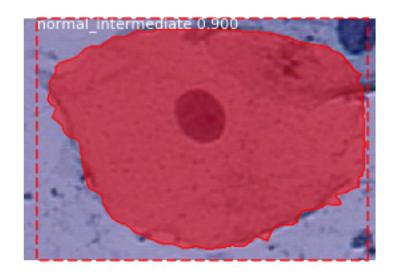
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



Drive/cervic\_test/normal\_intermediate/209565864-209565950-001.BMP

Processing 1 images

image shape: (321, 278, 3) min: 12.00000 max:

249.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

142.10000 float64

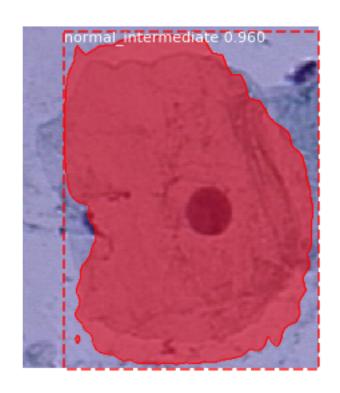
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



 ${\tt Drive/cervic\_test/normal\_intermediate/209566047-209566095-001.BMP}$ 

Processing 1 images

image shape: (248, 286, 3) min: 0.00000 max:

255.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

147.10000 float64

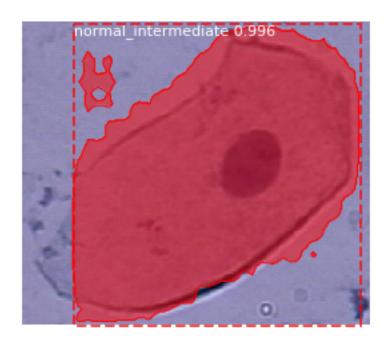
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



 ${\tt Drive/cervic\_test/normal\_intermediate/209566205-209566247-001.BMP}$ 

Processing 1 images

image shape: (300, 208, 3) min: 5.00000 max:

255.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

149.10000 float64

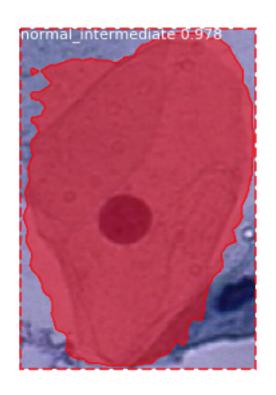
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



Drive/cervic\_test/normal\_intermediate/209566047-209566125-001.BMP

Processing 1 images

image shape: (338, 334, 3) min: 7.00000 max:

251.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

144.10000 float64

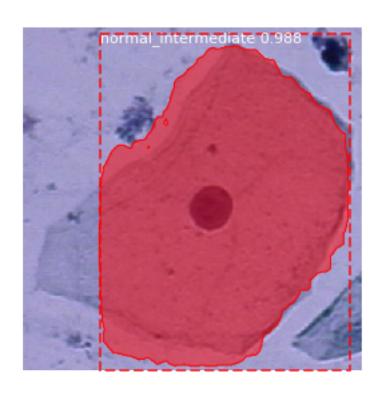
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



Drive/cervic\_test/normal\_intermediate/209566205-209566266-001.BMP

Processing 1 images

image shape: (295, 291, 3) min: 10.00000 max:

231.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

122.10000 float64

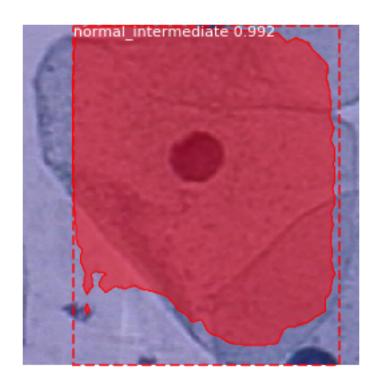
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



 ${\tt Drive/cervic\_test/normal\_intermediate/209566205-209566289-001.BMP}$ 

Processing 1 images

image shape: (209, 476, 3) min: 22.00000 max:

255.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

151.10000 float64

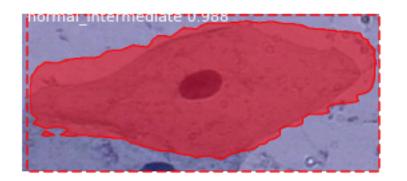
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



Drive/cervic\_test/normal\_intermediate/209566205-209566321-001.BMP

Processing 1 images

image shape: (262, 321, 3) min: 15.00000 max: 255.00000 uint8

255.00000 uint8

 $\verb|molded_images| & shape: (1, 512, 512, 3) & \verb|min: -123.70000 max: \\$ 

149.10000 float64

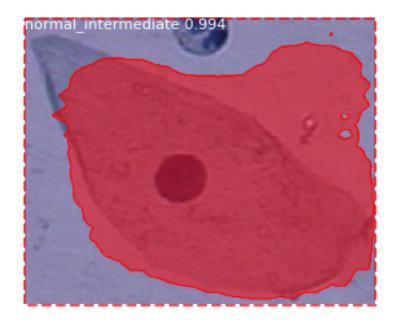
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



Drive/cervic\_test/normal\_intermediate/209566205-209566333-001.BMP

Processing 1 images

image shape: (291, 237, 3) min: 16.00000 max:

205.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

99.10000 float64

image\_metas shape: (1, 20) min: 0.00000 max:

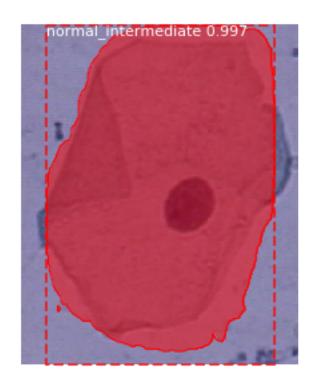
512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1

Predicted class :normal\_intermediate Actual class :normal\_intermediate



filename:/content/drive/My

Drive/cervic\_test/normal\_intermediate/209566399-209566464-001.BMP

Processing 1 images

image shape: (216, 292, 3) min: 3.00000 max:

254.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

150.10000 float64

image\_metas shape: (1, 20) min: 0.00000 max:

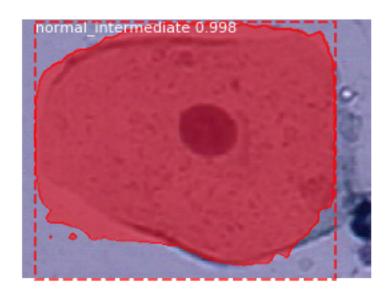
512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1

Predicted class :normal\_intermediate Actual class :normal\_intermediate



filename:/content/drive/My

Drive/cervic\_test/normal\_intermediate/209566399-209566485-001.BMP

Processing 1 images

image shape: (338, 297, 3) min: 22.00000 max:

228.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

121.10000 float64

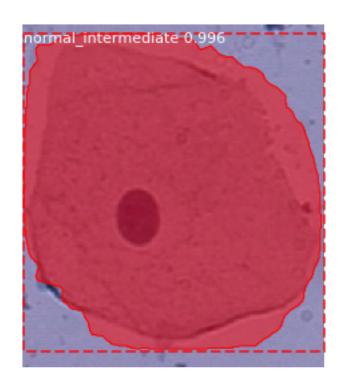
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



 ${\tt Drive/cervic\_test/normal\_intermediate/209566399-209566517-001.BMP}$ 

Processing 1 images

image shape: (263, 324, 3) min: 7.00000 max:

252.00000 uint8

molded\_images shape: (1, 512, 512, 3) min: -123.70000 max:

144.10000 float64

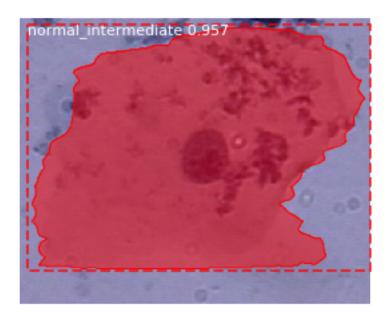
image\_metas shape: (1, 20) min: 0.00000 max:

512.00000 float64

anchors shape: (1, 65472, 4) min: -0.17712 max:

1.05188 float32

1



Total no. of images in normal\_intermediate is 14 No. of images correctly classified is 14 Accuracy of class: normal\_intermediate is 100.0