

Things you should know:

1) Aster mid 2 material:

- Eigenvalues & Eigenvectors of matrices.
- If $A\vec{v}_i = \lambda_i \vec{v}_i$ and $\lambda_1, \dots, \lambda_n$ are distinct.
 $\{\vec{v}_1, \dots, \vec{v}_n\}$ are linearly independent.
- Characteristic polynomial of $n \times n$ matrix A :

$$p_A(\lambda) = \det(A - \lambda I)$$

\Rightarrow know how to compute $p_A(\lambda)$

how to find roots of $p_A(\lambda)$

A is diagonalizable if all roots of $p_A(\lambda)$ are distinct.

If there are repeated roots, A may or may not be diagonalizable.

- Know how to find eigenvector/eigenbasis of an eigenvalue, i.e. find a basis for $\text{Nul}(A - \lambda I)$.
- Definition of a diagonalizable $n \times n$ matrix A .

A is diagonalizable \Leftrightarrow algebraic multiplicity of λ_i
 $=$ geometric multiplicity of λ_i
for all λ_i

If A is diagonalizable and $A\vec{v}_i = \lambda_i \vec{v}_i$.

$$P = [\vec{v}_1 \dots \vec{v}_n]$$

$$D = \begin{bmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \ddots \\ & & & \lambda_n \end{bmatrix}$$

$$A = PDP^{-1}$$

$$\Rightarrow A^k = P D^k P^{-1}, \text{ where } D^k = \begin{bmatrix} \lambda_1^k & & \\ & \lambda_2^k & \\ & & \ddots \\ & & & \lambda_n^k \end{bmatrix}.$$

- Know definition of dot/inner product; norm or length of a vector. Know the distance between two vectors.

- ~~Def~~ Meaning of orthogonal sets, orthonormal sets, ~~or~~ orthogonal bases, orthonormal bases.

- Orthogonal projections.

If $B = \{\vec{u}_1, \dots, \vec{u}_n\}$ orthogonal basis for subspace $W \subset \mathbb{R}^m$.

$$\text{proj}_W \vec{v} = \sum_{i=1}^n \frac{\vec{v} \cdot \vec{u}_i}{\|\vec{u}_i\|^2} \vec{u}_i.$$

- If $U = [\vec{u}_1 \dots \vec{u}_n]$ is an $n \times n$ matrix, the following are equivalent:

i) U is an orthogonal matrix

$$U^T U = I = U U^T.$$

ii) the columns of U form an orthonormal basis for \mathbb{R}^n .

- Gram-Schmidt process.

- QR Decomposition.

2) Midterm 2 review material.

- Vector spaces?
- Subspaces and important subspaces (e.g. $\mathbb{P}_n =$ polynomials of degree at most n .)
- How to determine if a set $H \subset V$ a subspace or not.
- linear independence, span of vectors, basis, dimension, and coordinates relative to a basis.
- Can check if vectors in \mathbb{R}^m are a basis or not by putting the vectors in the columns of a matrix and row reducing.
 - if $n > m$ the number of vectors, they are linearly dependent.
 - if $n < m$, they ~~do~~ do not span \mathbb{R}^m .
- Matrix operations.
- Notion of linear transformation. $T: V \rightarrow W$.
 - $\text{Nul}(T) = \{ \vec{v} \in V : T(\vec{v}) = \vec{0} \}$.
 - T is one-to-one iff $\text{Nul}(T) = \{0\}$.
 - if $T(x) = Ax$, be able to find a basis for $\text{Nul}(A)$.
 - $\text{Ran}(T) = \{ T(\vec{v}) \in W : \vec{v} \in V \}$.
 - Know how to find a basis for $\text{Col}(A)$, $\text{Row}(A)$.
 - $\dim \text{Row}(A) = \dim \text{Col}(A) = \text{rank}(A)$.
- Understand the rank-nullity theorem
 - Theorem 14, p. 233.

• Thm: if A not square, A is not invertible.

• Thm: if A $n \times n$, the following are equivalent:

a) A invertible.

b) $\text{col}(A) = \mathbb{R}^n \iff \dim \text{Row } A = n.$

c) $\text{Row}(A) = \mathbb{R}^n.$

d) $\text{Nul}(A) = \{0\}.$

e) $\det(A) \neq 0$

f) $\text{RREF}(A) = I.$

• Can find A^{-1} using $[A|I] \rightsquigarrow [I|A^{-1}]$.

• Know how to compute determinants of matrices.

know the determinants behavior under row ~~and~~ operations.

3) Midterm 1 Review material.

$$A\vec{x} = \vec{b}$$

• Thm: if $A\vec{p} = \vec{b}$, then general solution to $A\vec{x} = \vec{b}$ is $\vec{x} = \vec{p} + \vec{v}_h$, where \vec{v}_h is the ^{generic} solution to $A\vec{v}_h = \vec{0}.$

• Linear independence/dependence.

• Know how to get REF and RREF.

• Can write down the general solution to $A\vec{x} = \vec{b}$ and ~~and~~ find out the condition of \vec{b} such that $A\vec{x} = \vec{b}$ consistent / inconsistent.

Thm: Let A $m \times n$ and $U = \text{RREF}(A)$. Then.

a) $A\vec{x} = \vec{b}$ consistent iff $\text{RREF}([A|\vec{b}])$ does not have a pivot in the last column.

b) $A\vec{x} = \vec{b}$ consistent

iff $U = \text{RREF}(A)$ has a pivot in every row
or i.e. U does not contain a row of zeros.

~~e) $m \geq n$~~

c) $A\vec{x} = \vec{b}$ has at most 1 solution

iff $\text{Nul}(A) = \{\vec{0}\}$.

iff $\{\vec{a}_1, \dots, \vec{a}_n\}$ linearly independent.

iff $\text{RREF}(A)$ has no free variable