

## 7.2 Line Integrals

Motivation

$$W = (\text{force}) \cdot \cancel{\text{distance}} \quad (\text{displacement in the direction of force}).$$

over the short distance:  $W \approx \vec{F} \cdot \vec{ds}$

total work over long distance along trajectory  $C$ :

$$W \approx \sum_i \vec{F}(t_i) \cdot (\Delta \vec{s})_i \rightarrow \int_C \vec{F} \cdot d\vec{s}.$$

$$\Rightarrow W = \int_C \vec{F} \cdot d\vec{s}.$$

Def: Let  $\vec{F}$  be a vector field in  $\mathbb{R}^3$ , continuous on  $\vec{c}: [a, b] \rightarrow \mathbb{R}^3$ . The line integral of  $\vec{F}$  along  $\vec{c}$  is defined as

$$\int_C \vec{F} \cdot d\vec{s} = \int \vec{F}(x(t), y(t), z(t)) \cdot \vec{c}'(t) dt.$$

E.g.  $\vec{c}(t) = (\cos t, \sin t, t)$ ,  $0 \leq t \leq 2\pi$ .

$$\vec{F}(x, y, z) = x^2 \vec{i} + y^2 \vec{j} + z \vec{k}.$$

Compute  $\int_C \vec{F} \cdot d\vec{s}$ .

Sol: Along  $\vec{c}$ ,

$$\begin{aligned} \vec{F}(x, y, z) &= \vec{F}(\cos t, \sin t, t) \\ &= \cos^2 t \vec{i} + \sin^2 t \vec{j} + t \vec{k}. \end{aligned}$$

then and

$$\vec{c}(t) = (-\sin t \vec{i} + \cos t \vec{j} + t \vec{k}).$$

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$$\begin{aligned}
 \int_{\vec{C}} \vec{F} \cdot d\vec{s} &= \int_0^{2\pi} (\cos^2 t \vec{i} + \sin^2 t \vec{j} + t \vec{k}) \cdot (-\sin t \vec{i} + \cos t \vec{j} + \vec{k}) dt \\
 &= \int_0^{2\pi} -\cos^2 t \sin t + \sin^2 t \cos t + t dt \\
 &= \int_0^{2\pi} -\cos^2 t \sin t dt + \int_0^{2\pi} \sin^2 t \cos t dt + \int_0^{2\pi} t dt \\
 &= \left. \frac{\cos^3 t}{3} \right|_0^{2\pi} + \left. \frac{\sin^3 t}{3} \right|_0^{2\pi} + \left. \frac{t^2}{2} \right|_0^{2\pi} \\
 &= 0 + 0 + \frac{4\pi^2}{2} \\
 &= 2\pi^2.
 \end{aligned}$$

New notation: for the line integral

$$\vec{F} = (P, Q, R)$$

$$\text{and } d\vec{s} = (dx, dy, dz)$$

We write

$$\begin{aligned}
 \int_{\vec{C}} \vec{F} \cdot d\vec{s} &= \int_{\vec{C}} P dx + Q dy + R dz \\
 &= \int_a^b \left( P \frac{dx}{dt} + Q \frac{dy}{dt} + R \frac{dz}{dt} \right) dt
 \end{aligned}$$

Remark: This is not the sum of 3 integrals. It is just another way to write  $\int_{\vec{C}} \vec{F} \cdot d\vec{s}$ . We still need to

parametrize and express everything in terms of the parameter.

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E.g.  $\vec{c}(t) = (\cos t, \sin t, t) \quad 0 \leq t \leq 2\pi$

$$\vec{F}(x, y, z) = \underset{P}{\overset{x^2}{\uparrow}} \vec{i} + \underset{Q}{\overset{y^2}{\uparrow}} \vec{j} + \underset{R}{\overset{z}{\uparrow}} \vec{k}$$

$$\begin{aligned} \text{So } \int_{\vec{C}} \vec{F} \cdot d\vec{s} &= \int_C x^2 dx + \int_C y^2 dy + \int_C z dz \\ &= \int_a^{2\pi} \left( x^2(t) \frac{dx}{dt} + y^2(t) \frac{dy}{dt} + z^2(t) \frac{dz}{dt} \right) dt \\ &= \int_0^{2\pi} (\cos^2 t (-\sin t) + \sin^2 t \cos t + t) dt \\ &= 2\pi^2. \end{aligned}$$

E.g. Evaluate  $\int_{\vec{C}} x^2 dx + xy dy$

where  $\vec{c}(t) = (t, t^2), \quad 0 \leq t \leq 1.$

$$\begin{aligned} \int_{\vec{C}} x^2 dx + xy dy &= \int_0^1 \left( x^2(t) \frac{dx}{dt} + x(t) y(t) \frac{dy}{dt} \right) dt \\ &= \int_0^1 (t^2 + t \cdot t^2 \cdot 2t) dt \\ &= \int_0^1 (t^2 + 2t^4) dt \\ &= \left. \frac{t^3}{3} + \frac{2}{5} t^5 \right|_0^1 \\ &= \frac{1}{3} + \frac{2}{5}. \\ &= \frac{11}{15}. \end{aligned}$$

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Remark: line integrals are independent of the parametrization as long as the parametrization is orientation preserving.

E.g. The curve  $y = x^3$  from  $(0,0)$  to  $(1,1)$  can be parametrized as  $\vec{c}(t) = (t, t^3)$   $0 \leq t \leq 1$  or as  $\vec{p}(\theta) = (\sin \theta, \sin^3 \theta)$   $0 \leq \theta \leq \pi/2$ .

$$\text{Let } \vec{F} = x\vec{i} + y\vec{j}.$$

$$\int \vec{F} \cdot d\vec{s} = \int_0^1 (\vec{t}\vec{i} + \vec{t}^3\vec{j}) \cdot \vec{c}'(t) dt$$

$$\text{or } = \int_0^{\pi/2} (\sin \theta \vec{i} + \sin^3 \theta \vec{j}) \cdot \vec{p}'(\theta) d\theta.$$

check!

\* Line integral of gradient field:

$$\text{FTOC: } \int_a^b f'(t) dt = f(b) - f(a).$$

Thm: (Fundamental theorem of line integrals).

$f: \mathbb{R}^3 \rightarrow \mathbb{R}$  differentiable and  $c: [a, b] \rightarrow \mathbb{R}$ .

( $c$  is continuous or piecewise ~~cts~~ cts.)

$$\int_C (\nabla f) \cdot d\vec{s} = f(\vec{c}(b)) - f(\vec{c}(a))$$

Remark: If the field is a gradient field, only the end points matter.

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E.g. Evaluate  $\int_{\vec{c}} \nabla f \cdot d\vec{s}$  where  $f(x, y, z)$

$f(x, y, z) = \cos x + \sin y - xyz$   
 and  $\vec{c}$  is a trajectory that starts at  $(\frac{\pi}{2}, \frac{\pi}{2}, 0)$   
 and ends at  $(\pi, 2\pi, 1)$ .

Sol: Let  $\vec{c}(t)$ ,  $a \leq t \leq b$ , be a path with  
 $\vec{c}(a) = (\frac{\pi}{2}, \frac{\pi}{2}, 0)$  &  $\vec{c}(b) = (\pi, 2\pi, 1)$ .

Then by ~~FROG~~ FTOLI.

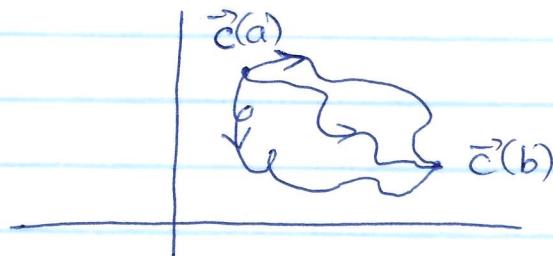
$$\int_{\vec{c}} \nabla f \cdot d\vec{s} = f(\vec{c}(b)) - f(\vec{c}(a))$$

$$= f(\pi, 2\pi, 1) - f(\frac{\pi}{2}, \frac{\pi}{2}, 0)$$

$$= \cos \pi + \sin \frac{2\pi}{2} - \cancel{\frac{\pi^2}{2}} - \cos \frac{\pi}{2} - \sin \frac{\pi}{2}$$

$$= -1 + 0 - \frac{\pi^2}{2} - 0 - 1$$

$$= -2 - \frac{\pi^2}{2}.$$



- Integrals of scalar fields along curves  
 $\Rightarrow$  path integrals

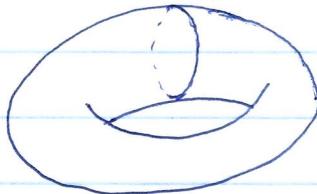
- Integrals of vector fields along curves  
 $\Rightarrow$  line integrals.

### 7.3 Parametrized Surfaces.

E.g. The graph of a function  $f(x, y)$  is a surface.

But we still have surfaces that are not the graph of a function.

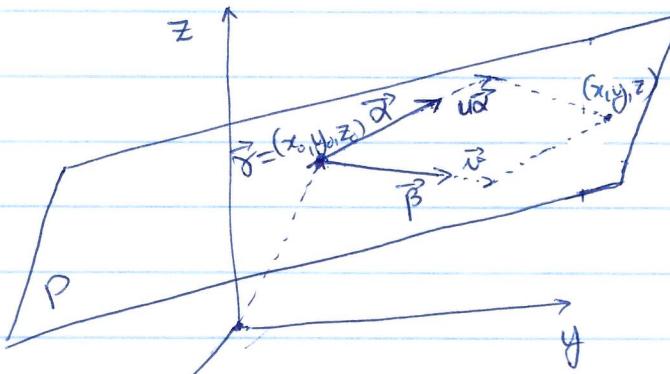
E.g. Torus (surface of a donut).



Def: A parametrization of a surface is a function  $\Phi: D \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3$ . The surface is  $S = \Phi(D)$  and  $\Phi(u, v) = (x(u, v), y(u, v), z(u, v))$ .

If  $x(u, v)$ ,  $y(u, v)$ ,  $z(u, v)$  are differentiable, we call  $S$  a differentiable surface.

#### • Parametrization of a plane:



Let  $P$  be a plane that is parallel to  $\vec{u}$  and  $\vec{v}$ , and passes through  $\vec{r}$ .

For any  $(x, y, z) \in P$ , we can write  $(x, y, z)$  as

$$(x, y, z) = (x_0, y_0, z_0) + u\vec{u} + v\vec{v} \quad \text{for some } u, v \in \mathbb{R}$$

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$$\boxed{\text{So } \Phi(u, v) = \vec{x}u + \vec{y}v + \vec{z}}$$

E.g. Find a parametrization of the plane  $x+y+z=1$

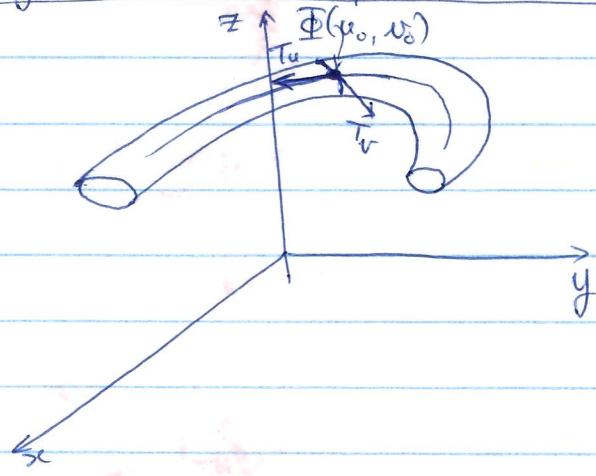
Sol: The point  $(0,0,1)$  is on the plane.

Vectors  $(1, -1, 0)$  and  $(0, 1, -1)$  are parallel to the plane (why?).

Hence,

$$\Phi(u, v) = (1, -1, 0)u + (0, 1, -1)v + (0, 0, 1).$$

\* Tangent vectors to parametrized surfaces:



Suppose that  $\Phi(u, v)$  is diff. at  $(u_0, v_0)$ .

Fix  $v_0$  and look at the map  $t \mapsto \Phi(u_0, t, v_0)$   
(in other words, we have a map  $\mathbb{R} \rightarrow \mathbb{R}^3$ ) which identifies a ~~curve~~ curve on the surface

The vector tangent to this curve at  $(u_0, v_0)$  is given by

$$T_u = \frac{\partial \Phi}{\partial u} = \frac{\partial x}{\partial u}(u_0, v_0) \vec{i} + \frac{\partial y}{\partial u}(u_0, v_0) \vec{j} + \frac{\partial z}{\partial u}(u_0, v_0) \vec{k}.$$

It is also tangent to the surface.

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$$\text{Similarly, } T_w = \frac{\partial \Phi}{\partial v} = \frac{\partial x}{\partial v}(u_0, v_0) \vec{i} + \frac{\partial y}{\partial v}(u_0, v_0) \vec{j} + \frac{\partial z}{\partial v}(u_0, v_0) \vec{k}$$

Both  $T_u$  and  $T_v$  are tangent to the surface.  
so  $T_u \times T_v$  is normal to them (provided  $T_u \times T_v \neq 0$ ).

To find the equation of the tangent plane at  $(u_0, v_0)$   
we calculate

$$\vec{n} = T_u \times T_v = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{vmatrix}_{(u_0, v_0)}$$

Tangent plane is

$$\vec{n} \cdot (x - x_0, y - y_0, z - z_0) = 0.$$

$$\Leftrightarrow n_1(x - x_0) + n_2(y - y_0) + n_3(z - z_0) = 0 \quad \vec{n} = (n_1, n_2, n_3)$$

E.g. Let  $\Phi: \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be given by

$$\Phi(u, v) = (u \cos v, u \sin v, u^2 + v^2)$$

Find the tangent plane at  $\Phi(1, 0)$ .

Sols:  $T_u = (\cos v, \sin v, 2u)$

$$T_v = (-u \sin v, u \cos v, 2v)$$

$$\vec{n} = T_u \times T_v = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos v & \sin v & 2u \\ -u \sin v & u \cos v & 2v \end{vmatrix}_{(1, 0)} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 2 \\ 0 & 1 & 0 \end{vmatrix}$$

$$= \begin{vmatrix} 0 & 2 \\ 1 & 0 \end{vmatrix} \vec{i} - \begin{vmatrix} 1 & 2 \\ 0 & 0 \end{vmatrix} \vec{j} + \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} \vec{k}$$

$$= -2\vec{i} - (0)\vec{j} + 1\vec{k}$$

$$= -2\vec{i} + \vec{k}.$$

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$$(x_0, y_0, z_0) = \Phi(u_0, v_0) = \Phi(1, 0) = (1, 0, 1).$$

The eq. of the tangent plane

$$-2(x-1) + 0(y-0) + 1(z-1) = 0$$

$$-2x + 2 + z - 1 = 0.$$

$$-2x + z = -1.$$

Remark: We say that a surface is regular or smooth, at  $\Phi(u_0, v_0)$  if  $T_u \times T_v \neq 0$  at  $(u_0, v_0)$ . We say that it is regular, if it is regular at all points  $\Phi(u_0, v_0)$ .

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7.4 Area of a surface.

Def: The surface area of a parametrized surface

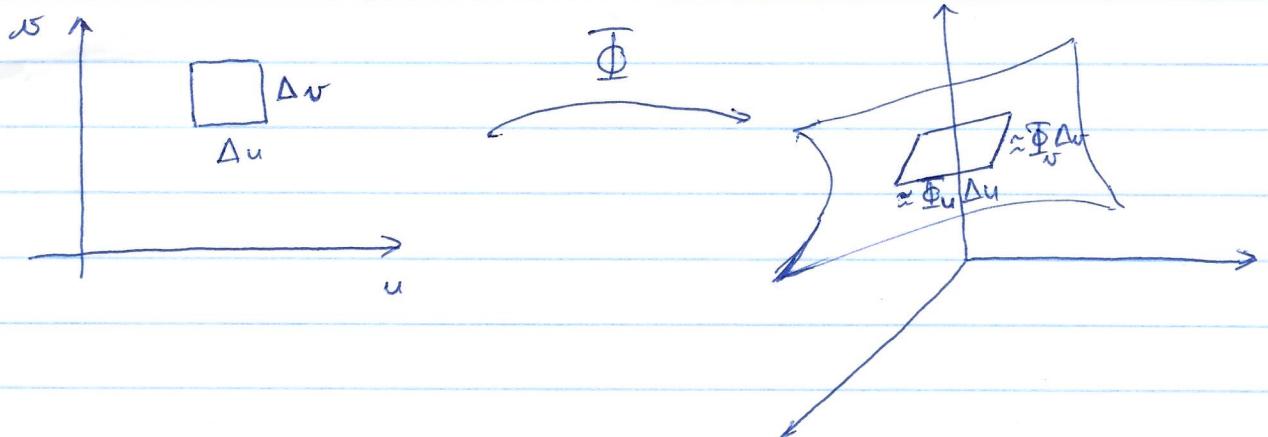
$$A(S) = \iint_D \|\mathbf{T}_u \times \mathbf{T}_v\| du dv.$$

 $S$  is regular $\Phi$  one-to-one and differentiable.Recall:  $\frac{\partial(x,y)}{\partial(u,v)} = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix}$ , then

$$\|\mathbf{T}_u \times \mathbf{T}_v\| = \sqrt{\left[\frac{\partial(x,y)}{\partial(u,v)}\right]^2 + \left[\frac{\partial(y,z)}{\partial(u,v)}\right]^2 + \left[\frac{\partial(x,z)}{\partial(u,v)}\right]^2}$$

So

$$A(S) = \iint_D \sqrt{\left[\frac{\partial(x,y)}{\partial(u,v)}\right]^2 + \left[\frac{\partial(y,z)}{\partial(u,v)}\right]^2 + \left[\frac{\partial(x,z)}{\partial(u,v)}\right]^2} du dv$$



The area of the image of the small rectangle is

$$\|(\Phi_u \Delta u) \times (\Phi_v \Delta v)\| = \|(\mathbf{T}_u \times \mathbf{T}_v)\| \Delta u \Delta v.$$

Summing the areas of all small rectangles as  $\Delta u, \Delta v \rightarrow 0$  gives  $A(S)$ .

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E.g. Find the surface area of the cone

$$z = \sqrt{x^2 + y^2}, \quad 0 \leq z \leq 1.$$

Parametrize:

$$\Phi(r, \theta) = (r\cos\theta, r\sin\theta, r), \quad 0 \leq r \leq 1, \quad 0 \leq \theta \leq 2\pi.$$

$$\text{Then } T_r = (\cos\theta, \sin\theta, 1)$$

$$T_\theta = (-r\sin\theta, r\cos\theta, 0).$$

$$T_r \times T_\theta = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \cos\theta & \sin\theta & 1 \\ -r\sin\theta & r\cos\theta & 0 \end{vmatrix} = -r\cos\theta \vec{i} - r\sin\theta \vec{j} + r\vec{k}$$

$$\|T_r \times T_\theta\| = \sqrt{(-r\cos\theta)^2 + (-r\sin\theta)^2 + r^2} \\ = \sqrt{2r^2}$$

$$A(\text{cone}) = \iint_0^{2\pi} \sqrt{2} r dr d\theta = 2\pi \sqrt{2} \frac{r^2}{2} \Big|_0^1 = \sqrt{2}\pi.$$

\* Surface area of the graph of a function  $f(x, y)$ .

We can parametrize  $S$  by  $(x, y, f(x, y))$

$$T_u \times T_v = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & f_u \\ 0 & 1 & f_v \end{vmatrix} \quad \text{or} \quad (u, v, f(u, v)) \\ = -f_u \vec{i} - f_v \vec{j} + \vec{k}.$$

$$A(S) = \iint_D \sqrt{f_u^2 + f_v^2 + 1} \, du dv.$$

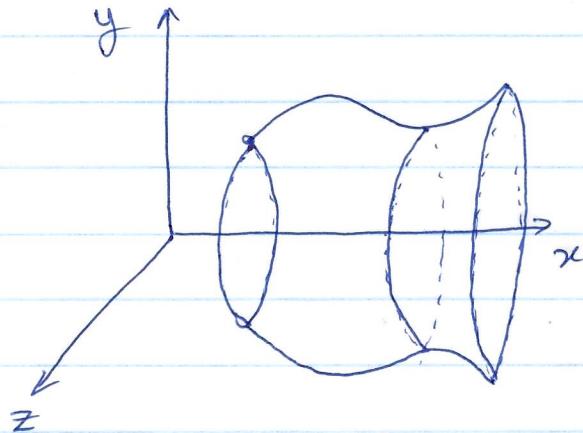
Exercise: use this to find the area of the cone

$$z = \sqrt{x^2 + y^2}$$

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\* Surfaces of revolution.

Suppose  $S$  is obtained by rotating the graph of  $y = f(x)$ ,  $a \leq x \leq b$  around the  $x$ -axis.



We can parametrize  $S$  as  $(u, f(u)\cos v, f(u)\sin v)$   
 $a \leq u \leq b, 0 \leq v \leq 2\pi$ .

$$\text{so } T_u = (1, f(u)\cos v, f(u)\sin v)$$

$$T_v = (0, -f(u)\sin v, f(u)\cos v)$$

$$T_u \times T_v = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & f(u)\cos v & f(u)\sin v \\ 0 & -f(u)\sin v & f(u)\cos v \end{vmatrix}$$

$$= f'(u)f(u) \vec{i} - f(u)\cos v \vec{j} - f(u)\sin v \vec{k}.$$

$$\Rightarrow A(S) = \iint_{a}^{b} \sqrt{f'(u)^2 + \cos^2 v + \sin^2 v} |f(u)| du dv.$$

$$= \iint_{a}^{b} \sqrt{f'(u)^2 + 1} |f(u)| dv du.$$

$$= 2\pi \int_0^b \sqrt{f'(u)^2 + 1} |f(u)| du.$$

Exercise: use this to compute the area of the cone  $z = \sqrt{x^2 + y^2}$ . ( $0 \leq x \leq 1$ ).