```
**P1.3** x_{\mathsf{new}} = (1 - \alpha)x_{\mathsf{old}} + \alpha x_{\mathsf{update}} Rewrite the update equation: x_{\mathsf{n}} = (1 - \alpha)x_{\mathsf{n-1}} + \alpha x_{\mathsf{update}} The same equation can be applied to x_{\mathsf{n-1}} x_{\mathsf{n-1}} = (1 - \alpha)x_{\mathsf{n-2}} + \alpha x_{\mathsf{update}} ... x_1 = (1 - \alpha)x_0 + \alpha x_{\mathsf{update}} \Rightarrow x_{\mathsf{k}} consists of an element A scaled by \alpha and A scaled by
```

 $\Rightarrow x_k$  consists of an element A scaled by  $\alpha$  and an element B scaled by  $1-\alpha$ . However, formula of A contains element scaled by  $\alpha$  and an element scaled by  $1-\alpha$ .

 $\Rightarrow x_n$  contains element scaled by  $\alpha^k (1-\alpha)^{n-k} \ \forall k < n, k \in \mathbb{N}$ Hence  $x_{\mathsf{new}} = (1-\alpha)x_{\mathsf{old}} + \alpha x_{\mathsf{update}}$  is exponentially weighted

\*\*P1.4\*\*

1. Addition of 2 vectors in  $\mathbb{R}^n$ 

 $[a_{\mathsf{n}}, a_{\mathsf{n-1}}, ..., a_1] + [b_{\mathsf{n}}, b_{\mathsf{n-1}}, ..., b_1] = [a_{\mathsf{n}} + b_{\mathsf{n}}, a_{\mathsf{n-1}} + b_{\mathsf{n-1}}, ..., a_1 + b_1]$  And scalar multiplication of a vector in  $R^n$ 

 $\alpha[a_{\mathsf{n}}, a_{\mathsf{n}-1}, ..., a_1] = [\alpha a_{\mathsf{n}}, \alpha a_{\mathsf{n}-1}, ..., \alpha a_1]$ 

result in a vector living in  $\mathbb{R}^n$  , hence  $\mathbb{R}^n$  is closed under addition and scalar multiplication .

Therefore,  $R^n$  is a vector space.

2.

Addition of 2 tensors in  $R^{m*n*...*q}$  is element-wise addition, thus the output tensors will retain the old dimesion, thus be an element of  $R^{m*n*...*q}$ 

The same to scalar multiplication , which is element-wise multiplication of every elements in the tensor with a scalar.

Hence  $R^{m*n*...*q}$  is closed under addition and scalar multiplication. Therefore,  $R^{m*n*...*q}$  is a vector space.

3.

Given 2 functions f(x) and g(x) in C[a,b], we have f(x)+g(x)=(f+g)(x), resulting in a continuous function with domain  $D_f \cap D_g = [a,b]$ 

Similarly, f(x) \* g(x) = (f \* g)(x), resulting in a continuous function with domain  $D_f \cap D_g = [a, b]$ 

Hence C[a, b] is a vector space.

4

Obviously sum of 2 polynomials with degree at most n will result in another polynomial with degree at most n.

And also multiplying a polynomial by a scalar will not increase nor decrease the degree, thus the output still stay in  $P_n(R) := \{\sum_{i=0}^n a_i x^i\}$ 

Hence  $P_n(R) := \{\sum_{i=0}^n a_i x^i\}$  is closed under addition and scalar multiplication, thus is a vector space.

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**P1.5**
```

1. The space of positive real axis:

Multiplying an element of the positive real axis by a negative scalar will result in an element not belong to the positive real axis.

#### 2.Unit vectors

Addition of 2 unit vectors will result in a vector which is not a unit vector, since unit vectors are linearly independent.

3.Latitude and longitude

 $(90^oN,0^oS)+(50^oN,10^oS)=(140^oN,10^oS)$ , which does not belong to Earth's coordinate anymore, so latitude and longitude space is not closed under addition.

4. Monomials  $\{x^k\}$ 

 $x^{k} + x^{k-1}$  is a sum of 2 monomials but obviously not a monomial.

So the space of monomials is not closed under addition.

#### P1.6

tu is vector u stretched or shrinked by a factor t, so  $tu \ \forall \ t \in R$  will be a line crossing the point u and the origin.

+v means translating the line in a way that move the origin to the point .

Hence  $L_1 = \{ w \in V : w = v + tu, \ \forall t \in R, \ u, v \in V \}$  is a line crossing v in direction of u.

## P1.7

 $w = (1-t)v + tu = t(u-v) + v \ u - v$  is a vector that have a direction from point v to point u

 $\Rightarrow t(u-v)$  is a line crossing the origin that have a direction from point v to point u

+v is a translation that translate the origin to point v. Since the line has a v-to-u direction, the translated line will also cross the point u.

P1.8:

Given 2 random points u and v in a vector space V. The formula of the line D crossing points u and v is:

$$L_2 = \{ w \in V : w = (1 - t)v + tu, \ \forall t \in R, \ u, v \in V \}$$

Thus every point on D and between 2 points u and v is also in vector space  $\mathbf{V}$ 

Recall the formula of line crossing a point:  $L_1 = \{w \in V : w = v + tu, \ \forall t \in R, \ u, v \in V\}$ , with v being the point on D, u being any point in the same space as v, which is V

Since a line only consists of linear combinations of  ${\bf u}$  and  ${\bf v}$ , which are also elements of V, it must be contained in V.

Hence V is flat.

#### P1.9

 $(u-\vec{0})$  is a segment with direction from origin to point u, as  $(u-\vec{0})=u$  so scalar t  $\forall t\in R$  allow the segment to stretch freely, hence, become a line , as t can reach  $+-\infty$ 

# P1.10

```
w = (1-t) v + tu = t(u-v) + v
```

It is similar to the form seen on P1.7, however, t here is restricted from 0 to 1, so the length of t(u-v) is now limited to the distance between u and v So L3 will be only a segment connecting point u and v.

### P1.11:

Since we allow v to move freely on another segment,  $L_3$  will become a set of points inside a triangle with vertices  $u, u_2, v_2$  or only a line if  $u_2, v_2, u$  are aligned.

Repeating the same process, we will consecutively add a point in space and  $L_3$  will be a set of points inside a polyhedron with vertices being the points  $u, u_2, u_3, ...$  introduced in the formula of  $L_3$ 

```
P1.12
```

```
Basis vectors for R_d
-[1,0,0,0,0,...0]
-[0,1,0,0,0,...0]
-[0,0,0,0,0,...1]
associated coordinate vectors: [a_1, a_2, ..., a_d]
    Basis vectors for R_{m*n}
[1, 0, 0, 0, 0, ...0]
0, 0, 0, 0, 0, ...0
[0, 0, 0, 0, 0, ...0]
[0, 1, 0, 0, 0, ...0]
0, 0, 0, 0, 0, ...0
[0, 0, 0, 0, 0, ...0]
[0, 0, 0, 0, 0, ...0]
0, 0, 0, 0, 0, ...0
0, 0, 0, 0, 0, \dots 1
associated coordinate vectors: [a_1, a_2, ..., a_{m*n}]
    Basis vectors for P_n(R)
-[x^n,0,0,0,0,...0]
-[0,x^{n-1},0,0,0,...0]
```

... -  $[0,0,0,0,0,...x^0]$  associated coordinate vectors:  $[a_1,a_2,...,a_d]$ 

P1.13

"linear" in linear combinations means however the input is distorted, the output will be distorted in the same way.

P1.14

Denote (x,y,z) is the coordinate in the standard basis of  $\mathbb{R}^3$ . the coordinates in this basis B is:

$$(\frac{x+y}{\sqrt{2}}, \frac{y-x}{\sqrt{2}}, z)$$