



$$g_{AB} = \begin{bmatrix} R_{AB} & p_{AB} \\ \vec{0}^T & 1 \end{bmatrix}$$

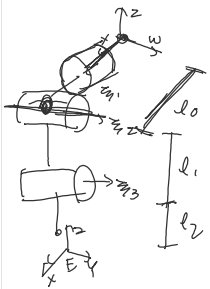
$$p_{AB} = [l_0 \ 0 \ 0]^T$$

$$R_{AB} = R_x(\pi/2)$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & -\sin\theta \\ 0 & \sin\theta & \cos\theta \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$g_{AB} = \begin{bmatrix} 1 & 0 & 0 & l_0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$\dot{z}_1 = \begin{bmatrix} -\omega \times q \\ \omega \end{bmatrix}$$

$$\omega = [1 \ 0 \ 0]^T$$

$$q = [0 \ 0 \ 0]^T$$

$$\dot{z}_1 = [0 \ 0 \ 0 \ 1 \ 0 \ 0]^T$$

$$\dot{z}_2 = [-\omega \times q \ \omega]^T$$

$$\omega = [0 \ 1 \ 0]^T$$

$$q = [l_0 \ 0 \ 0]^T$$

$$-\omega \times q = [0 \ 0 \ l_0]^T$$

$$\dot{z}_2 = [0 \ 0 \ l_0 \ 0 \ 1 \ 0]^T$$

$$\dot{z}_3 = [-\omega \times q \ \omega]^T$$

$$\omega = [0 \ 1 \ 0]^T$$

$$q = [l_0 \ 0 \ -l_1]^T$$

$$-\omega \times q = [l_1 \ 0 \ l_0]^T$$

$$\dot{z}_3 = [l_1 \ 0 \ l_0 \ 0 \ 1 \ 0]^T$$

$$g_{WE}(\theta) = e^{\hat{z}_1 \theta_1} e^{\hat{z}_2 \theta_2} e^{\hat{z}_3 \theta_3} g_{WE}(0)$$

$$e^{\hat{z}_1 \theta_1} = \begin{bmatrix} e^{\hat{\omega}_1 \theta_1} & (1 - e^{\hat{\omega}_1 \theta_1})(\omega_1 \times v_1) + \omega_1 \omega_1^T v_1 \theta_1 \\ \vec{0}^T & 1 \end{bmatrix}$$

$$e^{\hat{z}_1 \theta_1} = \begin{bmatrix} R_x(\theta_1) & (1 - e^{\hat{\omega}_1 \theta_1})(\omega_1 \times v_1) \\ \vec{0}^T & 1 \end{bmatrix}$$

$$R_x(\theta_1) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta_1 & -\sin\theta_1 \\ 0 & \sin\theta_1 & \cos\theta_1 \end{bmatrix} \quad \omega_1 \times v_1 = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$e^{\hat{\omega}_1 \theta_1} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$q' = Rq + p$$

$$R' = R^{-1} = R^T$$

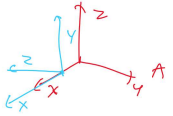
$$q = R'q' + p'$$

$$q = R'(Rq + p) + p'$$

$$\bar{p} = R' R q + R' p + p'$$

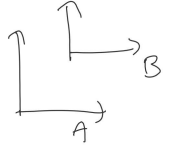
$$p' + R' p = 0$$

$$p' = -R' p$$



$$g_{AB} = \begin{bmatrix} R_{AB} & P_{AB} \\ \vec{0}^T & 1 \end{bmatrix}$$

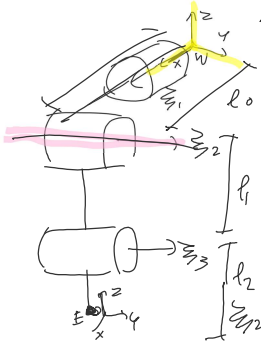
$$P_{AB} = [l_0 \ 0 \ 0]^T$$



$$R_{AB} = R_x(\theta/2)$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & -\sin \theta \\ 0 & \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$g_{AB} = \begin{bmatrix} 1 & 0 & 0 & l_0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$\dot{q}_1 = \begin{bmatrix} -\omega \times q \\ \omega \end{bmatrix}$$

$$\omega = [1 \ 0 \ 0]^T$$

$$v = -\omega \times q$$

$$= 0$$

$$\dot{q}_1 = [0 \ 0 \ 0 \ 1 \ 0 \ 0]^T$$

$$\dot{q}_2 = [-\omega \times q \ \omega]^T$$

$$\begin{bmatrix} 1 & 0 & 0 & l_0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\omega = [0 \ 1 \ 0]^T$$

$$q = [l_0 \ 0 \ 0]^T$$

$$\omega \times q = -\dot{\omega} q = [0 \ 0 \ l_0]^T$$

$$\dot{q}_2 = [0 \ 0 \ l_0 \ 0 \ 1 \ 0]^T$$

$$\dot{q}_3: \omega = [0 \ 1 \ 0]^T$$

$$q = [l_0 \ 0 \ -l_1]^T$$

$$-\omega \times q = [l_1 \ 0 \ l_0]^T$$

$$\dot{q}_3 = [l_1 \ 0 \ l_0 \ 0 \ 1 \ 0]^T$$

$$g_{WE}(\theta_1, \theta_2, \theta_3) = e^{\hat{\xi}_1 \theta_1} e^{\hat{\xi}_2 \theta_2} e^{\hat{\xi}_3 \theta_3} g_{WE}(0)$$

given: $g = \begin{bmatrix} R & p \\ \vec{0}^T & 1 \end{bmatrix}$, what is g^{-1} ?

$$g^{-1} = \begin{bmatrix} R' & p' \\ \vec{0}^T & 1 \end{bmatrix}$$

$$q' = R q + p$$

$$q = R' q' + p'$$

$$q = R'(R q + p) + p'$$

$$q = R' R q + R' p + p'$$

$$R' = R^T = R^{-1}$$

$$0 = R' p + p'$$

$$p' = -R' p$$

$$g^{-1} = \begin{bmatrix} R^T & -R^T p \\ \vec{0}^T & 1 \end{bmatrix}$$

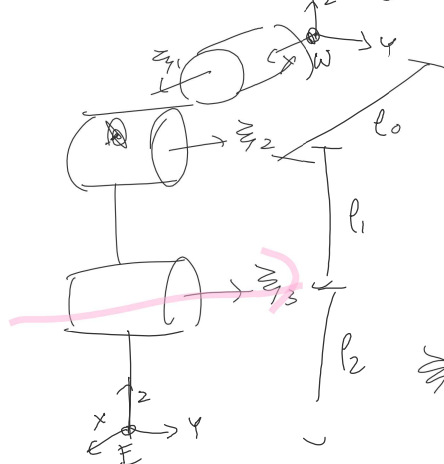
$$① \quad g_{AB} = \begin{bmatrix} R_{AB} & p_{AB} \\ \vec{0}^T & 1 \end{bmatrix}$$

$$p_{AB} = [l_0 \ 0 \ 0]^T$$

$$R_{AB} = R_x(\pi/2) = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos \pi/2 & -\sin \pi/2 \\ 0 & \sin \pi/2 & \cos \pi/2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$g_{AB} = \begin{bmatrix} 1 & 0 & 0 & l_0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$



$$\vec{z}_1 = \begin{bmatrix} -w_1 \times q_1 \\ w_1 \end{bmatrix}$$

$$w_1 = [1 \ 0 \ 0]^T$$

$$q_1 = [l_0 \ 0 \ 0]^T$$

$$\vec{z}_1 = [0 \ 0 \ 0 \ 1 \ 0 \ 0]^T$$

$$\vec{z}_2 \quad w_2 = [0 \ 1 \ 0]^T$$

$$q_2 = [l_0 \ 0 \ 0]^T$$

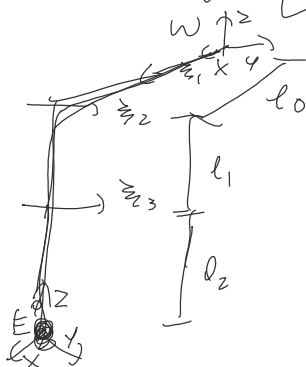
$$\vec{z}_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\vec{z}_3 \quad w_3 = [0 \ 1 \ 0]^T$$

$$q_3 = [l_0 \ 0 \ -l_1]^T$$

$$w_3 \times d_3 = [l_1 \ 0 \ l_0]^T$$

$$\vec{z}_3 = [l_0 \ 0 \ l_0 \ 0 \ 1 \ 0]^T$$



$$g_{WE}(0) = e^{\hat{z}_1 \theta_1} e^{\hat{z}_2 \theta_2} e^{\hat{z}_3 \theta_3} \quad (g_{WE}(0))$$

$$g_{WE}(0) = \begin{bmatrix} R_{WE} & p_{WE} \\ \vec{0}^T & 1 \end{bmatrix}$$

$$p_{WE} = [l_0 \ 0 \ -l_1 - l_2]^T$$

$$R_{WE} = I$$

$$g_{WE}(0) = \begin{bmatrix} 1 & 0 & 0 & l_0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & -l_1 - l_2 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\vec{z} = \begin{bmatrix} v \\ w \end{bmatrix}$$

$$e^{\hat{\omega}_1 \theta_1} = \begin{pmatrix} (e^{\omega_1 \theta_1}) & (1 - e^{\omega_1 \theta_1})(\omega \times v) + \omega \omega^T v \theta \\ 0 & I \end{pmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$e^{\hat{\omega}_1 \theta_1} = R_x(\pi/2) \quad \omega \times v$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{bmatrix}$$

$$e^{\hat{\omega}_2 \theta_2} = I_4$$

$$e^{\hat{\omega}_3 \theta_3} = \dots \quad e^{\hat{\omega}_3 \theta_3} = R_y(\pi/2) = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 0 \end{bmatrix}$$

$$\omega \times v = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \times \begin{bmatrix} l_1 \\ 0 \\ l_0 \end{bmatrix} = \begin{bmatrix} l_0 \\ 0 \\ -l_1 \end{bmatrix}$$

$$I - R_x(\pi/2) = \begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} l_0 \\ 0 \\ -l_1 \end{bmatrix} = \begin{bmatrix} l_0 + l_1 \\ 0 \\ l_0 - l_1 \end{bmatrix}$$

$$e^{\hat{\omega}_3 \theta_3} = \begin{bmatrix} 0 & 0 & 1 & l_0 + l_1 \\ 0 & 1 & 0 & 0 \\ -1 & 0 & 0 & l_0 - l_1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$