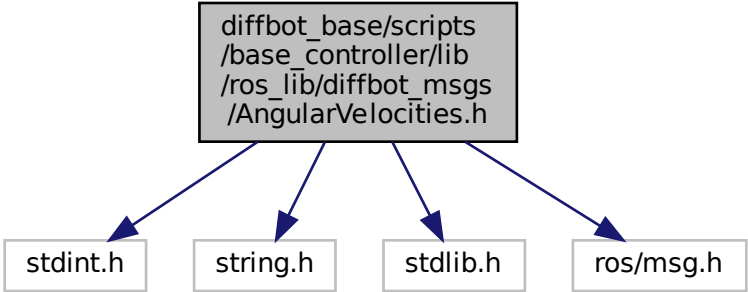


diffbot_base/scripts
/base_controller/lib
/ros_lib/diffbot_msgs
/AngularVelocities.h



```
graph TD; A["diffbot_base/scripts<br>/base_controller/lib<br>/ros_lib/diffbot_msgs<br>/AngularVelocities.h"] --> B["stdint.h"]; A --> C["string.h"]; A --> D["stdlib.h"]; A --> E["ros/msg.h"];
```

stdint.h

string.h

stdlib.h

ros/msg.h