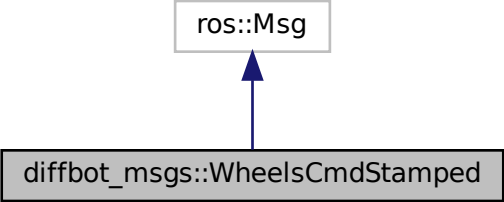


ros::Msg



```
graph BT; A[diffbot_msgs::WheelsCmdStamped] --> B[ros::Msg]
```

The diagram illustrates a relationship between two ROS message types. At the bottom, a gray rectangular box contains the text 'diffbot_msgs::WheelsCmdStamped'. A blue arrow points vertically upwards from the top center of this box to the bottom center of a white rectangular box above it. The white box contains the text 'ros::Msg'. This indicates that 'diffbot_msgs::WheelsCmdStamped' inherits from or is a specialization of 'ros::Msg'.

diffbot_msgs::WheelsCmdStamped