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Step ③

Determination of Cone distance (R).

Page NO: - 8.13 ; Table 8;

$$\text{Cone distance } R \approx \psi_y \sqrt{i^2 + 1} \sqrt[3]{\left[ \frac{0.72}{(\psi_y - 0.5) [C_e]} \right]^2 \frac{E [M_t]}{i}}$$

P.NO: - 8.1  $\psi_y = R/b$  (Table-13).

From P.NO: - 8.15; Table 13 for  $i = 1$  to 4. ( $i = 3$ ).

$$\boxed{\psi_y = R/b = 3}$$

Design twisting Moment  $[M_t]$  (P.NO: 8.15).

$$[M_t] = M_t k_d k$$

for initial calculation assume  $k_d k = 1.3$ .

$$\text{Power } P = \frac{2\pi N M_t}{60}$$

$$M_t = \frac{7.36 \times 10^3 \times 60}{2 \times \pi \times 1440}$$

$$\boxed{M_t = 48.807 \text{ N-m}}$$

Design Torque  $[M_t] = M_t k_d k$

$$= 48.807 \times 1.3$$

$$\boxed{[M_t] = 63.45 \text{ N-m}}$$

Young's Modulus: (E)

$$[M_t] = 63.45 \times 10^3 \text{ N-mm}$$

From P.NO: - 8.14; Table: (9) (Pinion & gears are same material C45 steel).

Equivalent Young's Modulus  $E = 2.15 \times 10^6 \text{ kgf/cm}^2$ .

$$E = \frac{2.15 \times 10^6 \times 10}{100}$$

$$\boxed{E = 2.15 \times 10^5 \text{ N/mm}^2}$$



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$$\therefore \text{Cone distance } R = \psi_y \sqrt{i^2 + 1} \sqrt[3]{\left[ \frac{0.72}{(\psi_y - 0.5) \left( \frac{E}{i} \right)} \right]^2 \frac{E [M_H]}{i}}$$

$$= 3 \sqrt{(3^2 + 1)} \sqrt[3]{\left[ \frac{0.72}{(3 - 0.5) \left( \frac{2.15 \times 10^5 \times 63.45 \times 10^3}{500} \right)} \right]^2 \frac{2.15 \times 10^5 \times 63.45 \times 10^3}{500}}$$

$$R = 108.8 \text{ mm}$$

Step ④ Determination of Module ( $m_t$ ).

From p. NO:- 8.38; Table 31

$$\text{Cone Distance } R = 0.5 m_t Z_1 \sqrt{i^2 + 1}$$

$$\text{Transverse module } m_t Z_1 \quad Z_1 = 18$$

$$108.8 = 0.5 m_t \times 18 \times \sqrt{3^2 + 1}$$

$$m_t = 3.822$$

from ~~Table~~ p. NO: 8.2, Table 1

the Standard Module  $m_t = 4$

Step ⑤ Revis the Cone distance and face width based on new standard module  $m_t = 4$ .

$$R = 0.5 m_t Z_1 \sqrt{i^2 + 1}$$

$$\text{Cone distance: } R = 0.5 \times 4 \times 18 \sqrt{3^2 + 1}$$

$$R = 113.84 \text{ mm}$$

$$\psi_y = R/b = 3$$

$$b = \frac{113.84}{3}$$

$$\text{face width } b = 37.95 \text{ mm}$$

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step 6 Revise ~~the~~ design Torque  $[M_t]$ ,  $k_d$ , &  $k$ .

from P.NO:- 8.38, Table 3,

Transverse module  $m_t = m_m + \frac{b \sin \delta_1}{z_1}$  (for pinion use  $z_1$ ).

$\therefore$  Mean Module  $m_m = m_t - \frac{b \sin \delta_1}{z_1}$

From P.NO:- 8.39, Reference angle

$\tan \delta_2 = i$ ;  $\delta_1 = 90^\circ - \delta_2$ .

$\tan \delta_2 = 3$ ;

$\delta_2 = 71.57^\circ$

$\delta_1 = 90^\circ - 71.57$

$\delta_1 = 18.43^\circ$

$\therefore m_m = 4 - \frac{37.95 \sin 18.41}{8}$

$m_m = 3.333 \text{ mm}$

Pitch line velocity. (P.NO: 8.15; below Table 14).

$V = \frac{\pi \text{ dia } n_1}{60 \times 1000} \text{ m/sec.}$   $n_1 = \text{Speed in rpm.}$

Reference dia  $d_1 = m_t z_1$  (P.NO:- 8.38; Table 3)

Similarly reference dial dia  $d_{1av}$ .

$d_{1av} = m_m z_1$

$= 3.333 \times 18$

$= 59.9945$

$d_{1av} = 60 \text{ mm.}$

Pitch line velocity  $\otimes V = \frac{\pi \times 60 \times 1440}{60 \times 1000}$

$V = 4.524 \text{ m/sec}$



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From ~~Table~~ P.NO:- 8.3; Table 2 (Bevel gear).

Is Quality grade for  $v = 4.52 \text{ m/sec}$ . (straight bevel gear)  
speed up to  $6 \text{ m/sec} \Rightarrow$  Quality grade is 6

Load concentration factor (k) (From P.NO:- 8.15 Table 14).

$$HB \geq 350; \quad b/d_{\text{div}} = \frac{37.95}{60} = 0.6325.$$

Surface hardened  $HB > 350$  ~~and~~  $b/d_{\text{div}} \leq 1$  (Bevel gear).

$k = 1.6$

Dynamic load factor (kd)

From P.NO:- 8.16; Table 15.

Conical gear / Is Quality 6; pitch line velocity  
up to  $8 \text{ m/sec}$  ( $v = 4.25 \text{ m/sec}$ );  $HB > 350$ .

$k_d = 1.4$

$$\therefore \text{Revised } [M_t] = M_t k_d k.$$

$$= 48.807 \times 1.4 \times 1.6.$$

$[M_t] = 109.33 \text{ N-m}$

$[M_t] = 109.33 \times 10^3 \text{ N-mm}$

step 7 Calculation of Induced stress.

step 7.1 Induced Bending stresses.

P.NO:- 8.13A (Table 8 Contd).

for straight bevel gear.

$$\sigma_b = \frac{R \sqrt{i^2 + 1} [M_t]}{(R - 0.5b)^2 b m_t y_v} \times \frac{1}{\cos \alpha} \leq \sigma_b.$$

$\alpha = 20^\circ$ ; Pressure angle. (59)

~~the~~ Virtual Number of teeth ( $Z_v$ ) (Tredgold's approximation)

$$Z_v = \frac{Z}{\cos \beta} = \frac{18}{\cos 18.44} = 18.97$$

$$Z_v \approx 19 \text{ teeth}$$

for Calculating tooth form factor  $\alpha = 20^\circ$

From P.N.O: 8.18; Table 18. [Addendum Modification  $X=0$ ]

Form factor  $y_v$ .

	$Z_v$	$y_v$
for	18	0.377
for	20	0.389

for  $Z_v = 19 \Rightarrow y_v = \frac{0.377 + 0.389}{2} = 0.383$

$$y_v = 0.383$$

Bending stress  $\sigma_b = \frac{R \sqrt{i^2 + 1} [M_t]}{(R - 0.5b)^2 b m_t y_v \cos \alpha}$

$$= \frac{113.84 \sqrt{3^2 + 1} \times 10^4}{[113.84 - (0.5 \times 37.95)]^2 \times 37.95 \times 4 \times 0.383 \times \cos 20}$$

$$= \frac{39358110}{491663.9705}$$

$$[\sigma_b = 80 \text{ N/mm}^2] \cdot \sigma_b = 80.05 \text{ N/mm}^2$$

$$\sigma_b = 80 \text{ N/mm}^2 < [\sigma_b] = 140 \text{ N/mm}^2$$

The induced bending stress  $\sigma_b = 80 \text{ N/mm}^2$  is less than the Material bending strength  $[\sigma_b] = 140 \text{ N/mm}^2$ .

So the bevel gear is safe for bending strength.

Step 7.2. Induced Contact stress.

P.N.O: 8.13; Table 8.

$$\sigma_c = \frac{0.72}{(R - 0.5b)} \sqrt{\frac{\sqrt{(i^2 + 1)^3}}{b}} E [M_t]$$



$$= \frac{0.72}{[113.84 - (0.5 \times 37.95)]} \cdot \sqrt{\frac{(3^2 + 1)^3}{3 \times 37.95}} \times 2.15 \times 10^5 \times 109.33 \times 10^3$$

$$= \frac{0.72}{94.885} \cdot \sqrt{\frac{1000}{113.85}} \times 2.35 \times 10^{10}$$

$$\sigma_c = 613.66 \text{ N/mm}^2 > [\sigma_c] = 500 \text{ N/mm}^2$$

Design is not safe. because  $\sigma_c > [\sigma_c]$

Trial ②: Revise the transverse module  $m_t = 5$ .  
Repeat the step ⑤ and ⑥ for  $m_t = 5$   
Cone distance.

$$R = 0.5 \times m_t \times \sqrt{i^2 + 1}$$

$$= 0.5 \times 5 \times 18 \sqrt{3^2 + 1}$$

$$R = 142.302 \text{ mm}$$

face width

$$\psi_y = R/b = 3; \quad b = \frac{142.302}{3} = 47.434 \text{ mm}$$

$$\text{mean module } m_m = m_t - \frac{b \sin i_1}{z_1}$$

$$= 5 - \frac{47.434 \times \sin 18.44}{18}$$

$$m_m = 4.166$$

$$\text{diam} = m_m z_1 = 4.166 \times 18 = 74.99 = 75 \text{ mm}$$

$$\text{Pitch line velocity} = \frac{\pi \times 75 \times 1440}{60 \times 1000} = 5.655 \text{ m/sec}$$

for  $v \leq 6 \text{ m/sec}$  ( $v = 5.655$ ) Quality grad = 6.

Load Concentration factor ( $k$ )

$$HB > 350, \quad \frac{b}{\text{diam}} = 0.632 \leq 1$$

$$k = 1.6$$

Dynamic load factor ( $k_d$ )

No change in  $k_d$ .

$$k_d = 1.4$$

No change in  $[M_t]$  also. (6)

$$[M_t] = 109.33 \text{ N-m.}$$

$$[M_t] = 109.33 \times 10^3 \text{ N-mm.}$$

Step 7.1 Induced ~~Bending~~ Contact stress.  $\sigma_c$

$$\begin{aligned}\sigma_c &= \frac{0.72}{(R - 0.5b)} \sqrt{\frac{\sqrt{i^2 + 1}^3}{ib}} E [M_t] \\ &= \frac{0.72}{[142.302 - (0.5 \times 47.434)]^x} \sqrt{\frac{\sqrt{3^2 + 1}^3}{3 \times 47.434}} \times 2.15 \times 10^3 \times 109.33 \times 10^3 \\ &= \frac{0.72 \times 72274.218}{118.585}\end{aligned}$$

$$\sigma_c = 438.82 \text{ N/mm}^2 < [\sigma_c] = 500 \text{ N/mm}^2.$$

The <sup>induced</sup> Contact stress is less than the material Contact stress. So the bevel gear design is safe for Contact strength.

(7.2) Induced Bending stress.

$$\begin{aligned}\sigma_b &= \frac{R \sqrt{i^2 + 1} [M_t]}{(R - 0.5b)^2 b m_t Y_V \cos \alpha} \\ &= \frac{142.302 \times \sqrt{3^2 + 1} \times 109.33 \times 10^3}{[142.302 - (0.5 \times 47.434)]^2 \times 47.434 \times 5 \times 0.383 \times \cos 20^\circ} \\ &= \frac{49198674.7}{1200338.842}\end{aligned}$$

$$\sigma_c = 40.987 \text{ N/mm}^2 < [\sigma_b] = 140 \text{ N/mm}^2.$$

The bevel gear design is safe for Bending strength also.

The Pinion is safe for both bending and Contact strength.



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Step 8:  
Design for Dynamic load.

same P.W.D.:

$$P.W.D.: 8.52$$

$$\text{static load } F_s = \frac{P_d}{P_d} b Y_v (1 - b/k);$$

$$b = \frac{10}{P_d}$$

$$P_d = \frac{47 \cdot 434}{10}$$

$$= 4743.4$$

$$= [140] \times 47.434 \times 0.383 \left[ 1 - \left( \frac{47.434}{142.302} \right) \right]$$

$P_d$ .

$$P.W.D.: 8.52$$

$$b = \frac{10}{P_d}; \quad 47.434 = \frac{10}{P_d}$$

$$P_d = 0.21082$$

$$\text{Static load } F_s = \frac{[140] \times 47.434 \times 0.383}{0.21082} \left[ 1 - 0.333 \right]$$

$$F_s = 8042.915 \text{ N.}$$

Buckingham's Dynamic load use

Buckingham's Dynamic load ( $F_d$ )

P.W.D. 8.52 Not (For Buckingham's dynamic load use the

Equation for spur gear taking  $V_m$  for the largest pitch circle.

$$P.W.D.: 8.51,$$

$$F_d = F_t + \left[ \frac{0.164 V_m (C_b + F_t)}{0.164 V_m + 1.485 (\sqrt{C_b + F_t})} \right]$$

$$\text{for } V_m = \frac{\pi d n}{60 \times 1000} \text{ m/sec.}$$

$$d_1 = m_t Z_1 = 5 \times 18 = 90 \text{ mm (largest Value)}$$

$$V_m = \frac{\pi \times 90 \times 1440}{60 \times 1000} = 6.786 \text{ m/sec.}$$

$$V_m = 6.786 \text{ m/sec.}$$

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velocity factor ( $C_v$ ) for straight bevel gear.

P.NO: 8.52;  $C_v = \frac{3.5 + \sqrt{V_m}}{3.5}$

$$C_v = 1.744$$

$$F_t = \frac{P_{\text{over}}}{\text{velocity}} \times C_v$$

$$= \frac{7.36 \times 10^3}{6.786} \times 1.744$$

$$F_t = 1891.52 \text{ N}$$

Calculation of C from 41 (P.NO: 8.53)  
for steel.  $\alpha = 20^\circ$  full depth.

$$C = 11860 e$$

Error from graph (P.NO. 8.51).

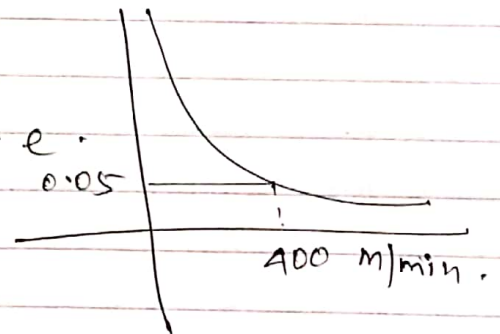
$$V_m = 6.786 \text{ m/sec.}$$

$$= 6.786 \times 60 \text{ m/min.}$$

$$V_m = 407.16 \text{ m/min}$$

$$e = 0.05$$

$$C = 11860 \times 0.05 = 593$$



Dynamic load.

$$F_d = 1891.52 + \frac{0.164 \times 6.786 \left[ (593 \times 47.434) + 1891.52 \right]}{\left[ (0.164 \times 6.786) + 1.485 \left( \sqrt{(593 \times 47.434) + 1891.52} \right) \right]} \times 10^3$$

$$= 1891.52 + \frac{2136.384}{66.176}$$

$$= 1891.52 + 32.283$$

$$F_d = 1923.80 \text{ N.}$$

$$8042.91 > 1923.8$$

$$F_s > F_d$$

Design is safe for Dynamic load.