# Week 5: Modelling in STRIPS and PDDL

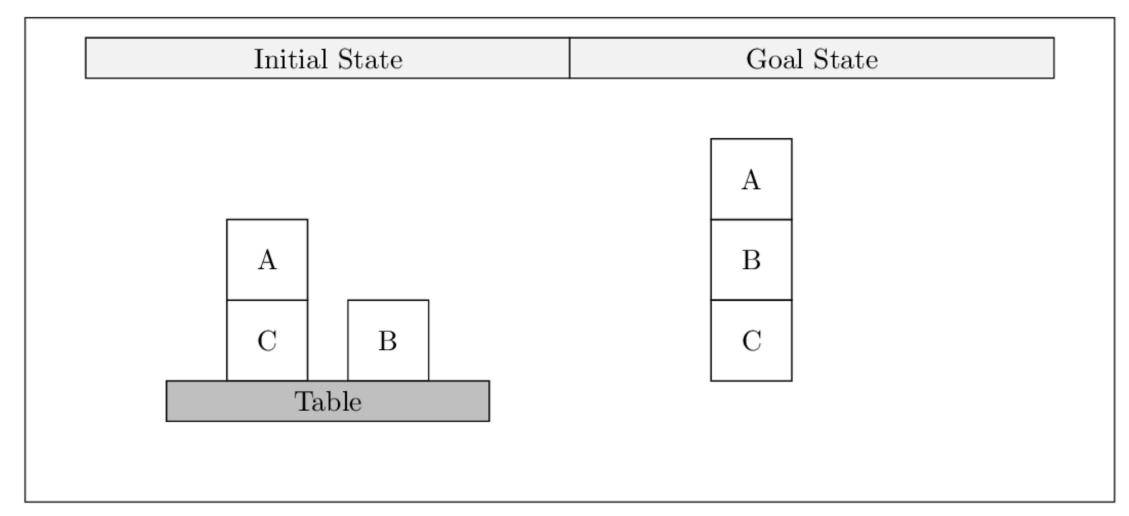
COMP90054 – Al Planning for Autonomy

# Key concepts

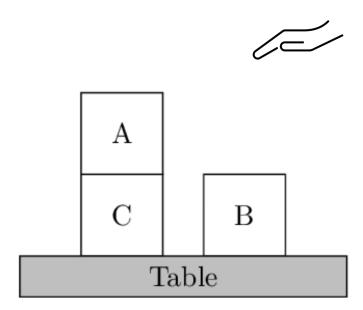
- How to model a problem in STRIPS
- PDDL (Problem Domain Definition Language)

## Problem 1: STRIPS

Model Blocks-World as a STRIPS problem  $P = \langle F, O, I, G \rangle$ . You need to define the set of facts F, the set of operators O, the goal facts G and the initial facts I. You must also define the pre, add, and del functions.

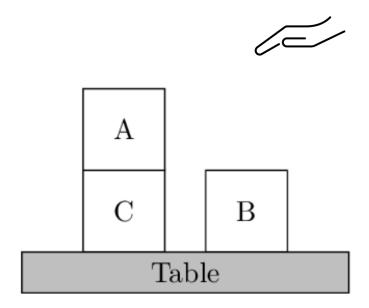


## Initial State



```
P = <F, O, I, G>
F = \{ on(x, y), 
     onTable(x),
     clear(x),
     holding(x),
     handEmpty |
            \mathsf{x},\mathsf{y}\in\{A,B,C\}
```

### Initial State



```
P = \langle F, O, I, G \rangle
F = \{ on(x, y), \\ onTable(x), \\ clear(x), \\ holding(x), \\ handEmpty \mid \\ x, y \in \{A, B, C\} \}
```

I = {on(A, C), onTable(C), onTable(B), clear(A), clear(B), handEmpty}

## Goal State

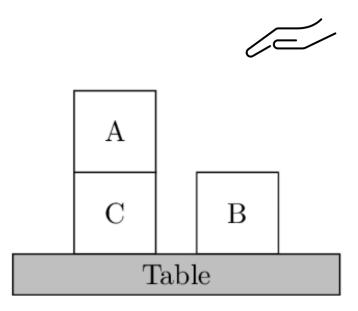
A

В

 $\mathbf{C}$ 

```
P = <F, O, I, G>
F = \{ on(x, y), 
     onTable(x),
     clear(x),
     holding(x),
     handEmpty |
           \mathsf{x},\mathsf{y}\in\{A,B,C\}
G = \{on(A,B), on(B,C)\}
```

#### Initial State



$$P = \langle F, O, I, G \rangle$$

 $F = \{ on(x, y), onTable(x), clear(x), holding(x), armFree | x, y \in \{A, B, C\} \}$ 

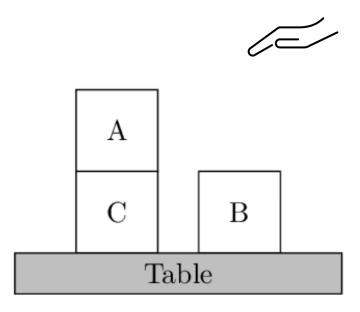
Operator o ∈ O represented by

- 1. the **Add** list  $Add(o) \subseteq F$
- 2. the **Delete** list  $Del(o) \subseteq F$
- 3. the **Precondition** list  $Pre(o) \subseteq F$

#### **Define Operators**

- 1. Pick up a block from the table pickup(x)
- 2. Pick up a block from another block unstack(x)
- 3. Put down a block on the table putdown(x)
- 4. Put down a block on another block **stack(x, y)**

#### Initial State



 $F = \{ on(x, y), onTable(x), clear(x), holding(x), handEmpty | x, y \in \{A, B, C\} \}$ 

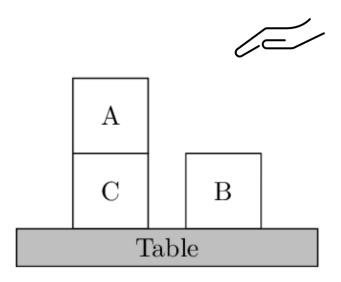
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- 1. the **Add** list  $Add(o) \subseteq F$
- 2. the **Delete** list  $Del(o) \subseteq F$
- 3. the **Precondition** list  $Pre(o) \subseteq F$

#### **Define Operators**

- 1. Pick up a block from the table pickup(x)
- Prec: onTable(x), clear(x), handEmpty
- Add: holding(x)
- Del: onTable(x), clear(x), handEmpty

#### Initial State



F = { on(x, y), onTable(x), clear(x), holding(x), handEmpty |  $x, y \in \{A, B, C\}$ }

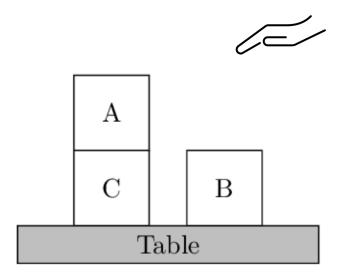
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- 1. the **Add** list  $Add(o) \subseteq F$
- 2. the **Delete** list  $Del(o) \subseteq F$
- 3. the **Precondition** list  $Pre(o) \subseteq F$

#### **Define Operators**

- 2. Pick up a block from another block unstack(x)
- Prec: on(x, y), clear(x), handEmpty
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handEmpty

#### Initial State



 $F = \{ on(x, y), onTable(x), clear(x), holding(x), handEmpty | x, y \in \{A, B, C\} \}$ 

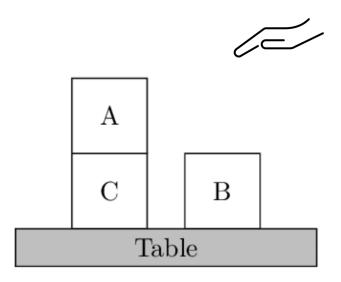
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- 1. the **Add** list  $Add(o) \subseteq F$
- 2. the **Delete** list  $Del(o) \subseteq F$
- 3. the **Precondition** list  $Pre(o) \subseteq F$

#### **Define Operators**

- 3. Put down a block on the table putdown(x)
- Prec: holding(x)
- Add: clear(x), onTable(x), handEmpty
- Del: holding(x)

#### Initial State



 $F = \{ on(x, y), onTable(x), clear(x), holding(x), handEmpty | x, y \in \{A, B, C\} \}$ 

Operator o ∈ O represented by

- 1. the **Add** list  $Add(o) \subseteq F$
- 2. the **Delete** list  $Del(o) \subseteq F$
- 3. the **Precondition** list  $Pre(o) \subseteq F$

#### **Define Operators**

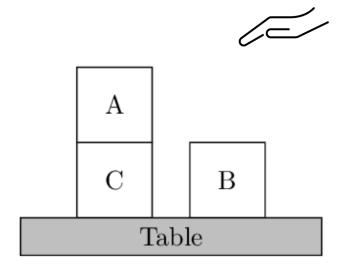
4. Put down a block on another block **stack(x, y)** 

Prec: holding(x), clear(y)

- Add: clear(x), on(x,y), handEmpty

Del: clear(y), holding(x)

#### Initial State



#### **Define Operators**

## O = { pickup(x)

- Prec: onTable(x), clear(x), handEmpty
- Add: holding(x)
- Del: onTable(x), clear(x), handEmpty

#### unstack(x)

- Prec: on(x, y), clear(x), handEmpty
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handEmpty

#### putdown(x)

- Prec: holding(x)
- Add: clear(x), onTable(x), handEmpty
- Del: holding(x)

#### stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handEmpty
- Del: clear(y), holding(x)

## Problem 2: PDDL

- 1. A domain file that has predicates and actions
- 2. A problem file that has objects, initial state and goal

TSP: <a href="https://editor.planning.domains/#read\_session=zp1j883xR9">https://editor.planning.domains/#read\_session=zp1j883xR9</a>

## Problem 2: PDDL

```
(define (domain tsp)
        (:requirements :typing)
        (:types node)
        ;; Define the facts in the problem
        ;; "?" denotes a variable, "-" a type
        (:predicates
            (at ?pos - node)
            (connected ?start ?end - node)
            (visited ?end - node)
11
12
13
        ;; Define the action(s)
14 -
        (:action move
15
            :parameters (?start ?end - node)
16 -
            :precondition (and
17
                (at ?start)
                (connected ?start ?end)
19
20 -
             :effect (and
                (at ?end)
                (visited ?end)
22
23
                (not (at ?start))
24
25
26
```

```
1 (define (problem tsp-01)
        (:domain tsp)
        (:objects Sydney Adelade Brisbane Perth Darwin - node)
        ;; Define the initial situation
        (:init (connected Sydney Brisbane)
                (connected Brisbane Sydney)
                (connected Adelade Sydney)
 9
                (connected Sydney Adelade)
10
                (connected Adelade Perth)
                (connected Perth Adelade)
12
                (connected Adelade Darwin)
13
                (connected Darwin Adelade)
14
                (at Sydney)
15
16 -
        (:goal
17 -
                (and
18
                    (at Sydney)
19
                    (visited Sydney)
                    (visited Adelade)
21
                    (visited Brisbane)
22
                    (visited Perth)
23
                    (visited Darwin)
24
```

TSP: <a href="https://editor.planning.domains/#read">https://editor.planning.domains/#read</a> session=zp1j883xR9

## Problem 2

```
F = \{ on(x, y), 
      onTable(x),
      clear(x),
      holding(x),
      handEmpty | x, y \in \{A, B, C\}
I = {on(A, C), onTable(C), onTable(B), clear(A), clear(B), handEmpty}
G = \{on(A,B), on(B,C)\}
```

```
O = {
pickup(x)
```

- Prec: onTable(x), clear(x), handEmpty
- Add: holding(x)
- Del: onTable(x), clear(x), handEmpty

#### unstack(x)

- Prec: on(x, y), clear(x), handEmpty
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handEmpty

#### putdown(x)

- Prec: holding(x)
- Add: clear(x), onTable(x), handEmpty
- Del: holding(x)

#### stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handEmpty
- Del: clear(y), holding(x)

## Planimation Plugin

https://github.com/planimation/documentation

## Solution with 4 actions

http://editor.planning.domains/#read session=iOEg2OeV24