

Week 6: Delete Relaxation

COMP90054 – AI Planning for Autonomy

Key concepts

- Delete relaxation heuristic h^+
- The relationship between h^{max} , h^{add} and h^+

Problem 1

What is the (optimal) delete relaxation heuristic h^+ ?

Relaxing by ignoring delete lists “What was once true remains true forever”

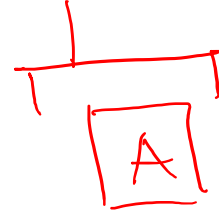
prec:
add:
~~del:~~

Definition (Delete Relaxation).

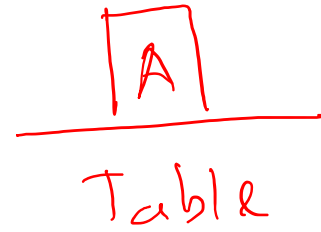
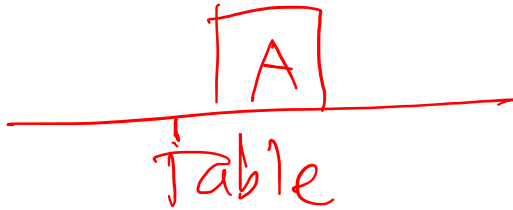
① For a STRIPS action a , by a^+ we denote the corresponding *delete relaxed action*, or short *relaxed action*, defined by $pre_{a^+} := pre_a$, $add_{a^+} := add_a$, and $del_{a^+} :=$

$P = \langle F, O, I, G \rangle$

$P = \langle F, O^+, I, G \rangle$



pickup (A)

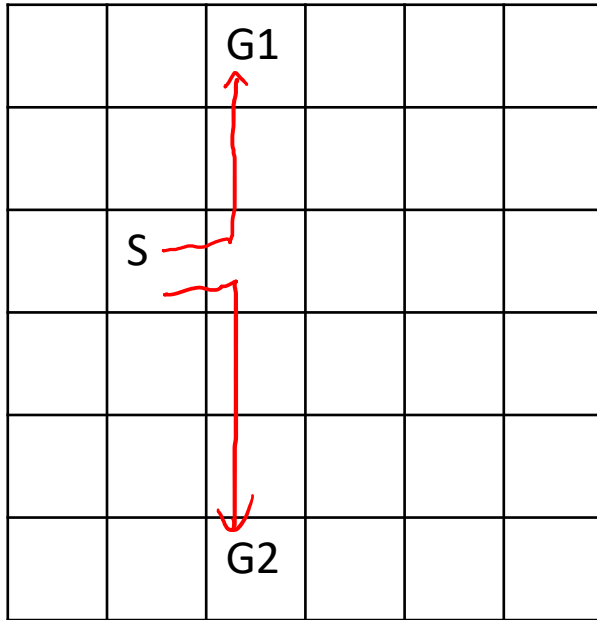


once true \rightarrow forever true.

Problem 1

$$h(s) = d(s, G1) + d(s, G2) = 3 + 4 = 7$$

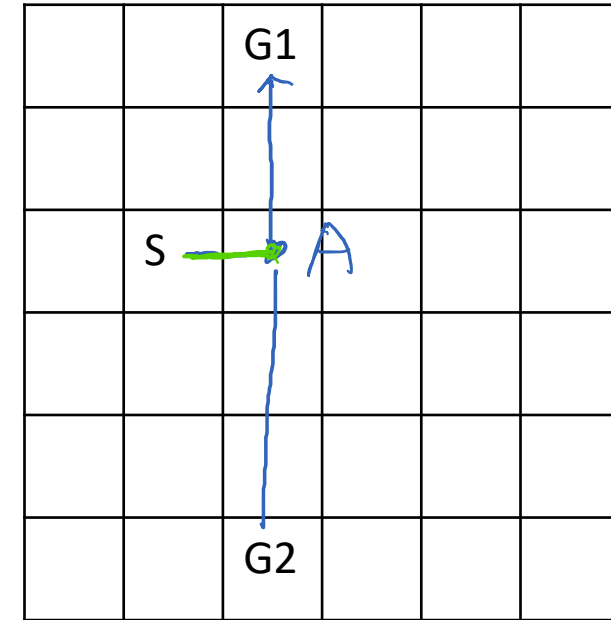
How would it be interpreted in pacman?



Minimum spanning tree:
Admissible, Not consistent

without delete relaxation.

$$\begin{aligned} h^+(s) &= \underline{d(s, G1)} + \underline{d(A, G2)} \\ &= 3 + 3 = 6 \end{aligned}$$



Minimum Steiner tree:
Admissible, consistent

with delete relaxation

Problem 1

approximations of h^+

What is the relationship between h^{max} , h^{add} and h^+ ? What about h^* ?

h^* is the perfect heuristic (the optimal cost from the current state to the goal state)

h^+ is the **optimal delete relaxation** heuristic (not easy to compute)

h^+ is admissible

~~h^{max} is an approximation of h^+~~

h^{max} is admissible. h^{max} is very small.

$h^{max} \leq h^+ \leq h^*$

~~h^{add} is an approximation of h^+~~

h^{add} is not admissible

$h^{add} \geq h^+$

Problem 2: Computing h^{max} and h^{add}

Definition (h^{add}). Let $\Pi = (F, A, c, I, G)$ be a STRIPS planning task. The *additive heuristic* h^{add} for Π is the function $h^{add}(s) := h^{add}(s, G)$ where $h^{add}(s, g)$ is the point-wise greatest function that satisfies $h^{add}(s, g) =$

$$\begin{cases} 0 & g \subseteq s \\ \min_{a \in A, g \in add_a} c(a) + h^{add}(s, pre_a) & |g| = 1 \\ \sum_{g' \in g} h^{add}(s, \{g'\}) & |g| > 1 \end{cases}$$

Definition (h^{max}). Let $\Pi = (F, A, c, I, G)$ be a STRIPS planning task. The *max heuristic* h^{max} for Π is the function $h^{max}(s) := h^{max}(s, G)$ where $h^{max}(s, g)$ is the point-wise greatest function that satisfies $h^{max}(s, g) =$

$$\begin{cases} 0 & g \subseteq s \\ \min_{a \in A, g \in add_a} c(a) + h^{max}(s, pre_a) & |g| = 1 \\ \max_{g' \in g} h^{max}(s, \{g'\}) & |g| > 1 \end{cases}$$

Problem 2: Computing h^{max} and h^{add}

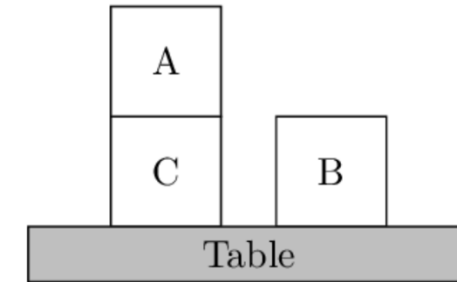
Initial state

$I = \{\text{on}(A, C), \text{onTable}(C), \text{onTable}(B), \text{clear}(A), \text{clear}(B), \text{handFree}\}$

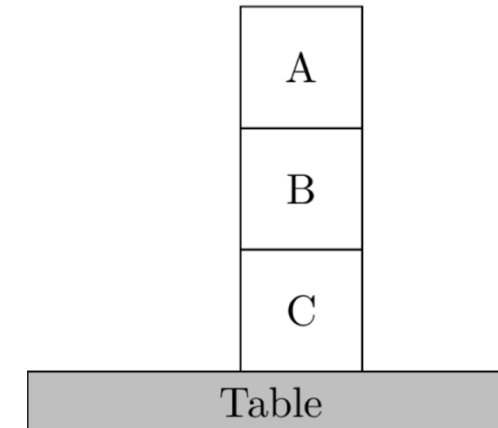
Goal state

$G = \{\text{on}(A,B), \text{on}(B,C), \text{onTable}(C)\}$

Initial State



Goal State

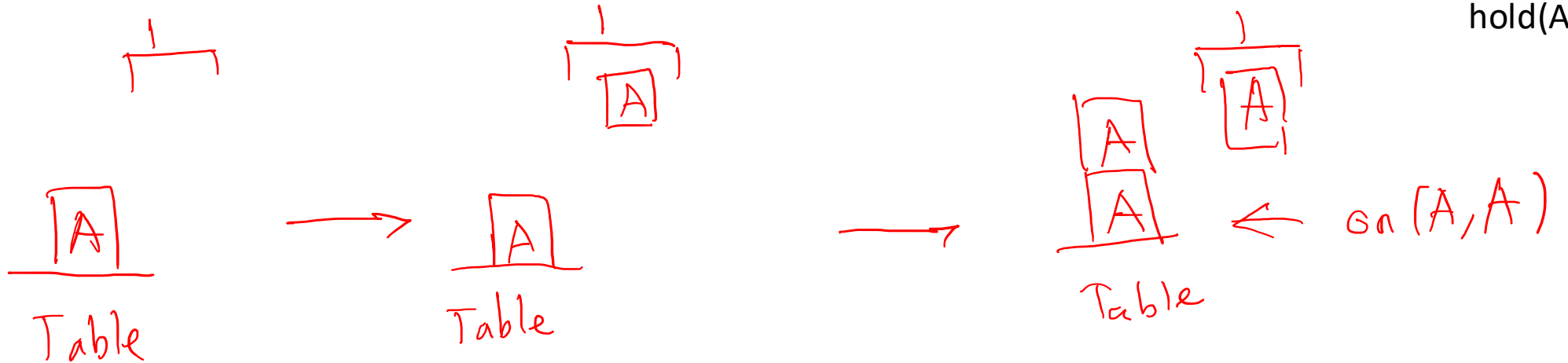


Problem 2: Computing h^{max} and h^{add}

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A, B)	on(A, C)	on(B, A)	on(B, B)	on(B, C)	on(C, A)	on(C, B)	on(C, C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1																			
2																			

$I = \{\text{on}(A, C), \text{onTable}(C), \text{onTable}(B), \text{clear}(A), \text{clear}(B), \text{handFree}\}$

$c(A) = \text{clear}(A)$
 $\text{onTable}(A) = \text{onT}(A)$
 $\text{hold}(A) = \text{holding}(A)$



Problem 2: Computing h^{max} and h^{add}

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	?	0						0								0	0

Which actions can we take to make **clear(C)** True?

Problem 2

Once true \rightarrow forever true

Which actions can we take to make **clear(C)** True?

putdown(C)
stack(C, A)
stack(C, B)
unstack(A, C)
unstack(B, C)
stack(C, C)
unstack(C, C)

• $\text{unstack}(x, C)$ $x \in \{A, B, C\}$
• $\text{putdown}(C)$
• $\text{stack}(C, y)$ $y \in \{A, B, C\}$

Define Operators

$O = \{$

pickup(x)

- Prec: onTable(x), clear(x), handFree
- Add: holding(x)
- Del: onTable(x), clear(x), handFree

unstack(x, y)

- Prec: on(x, y), clear(x), handFree
- \rightarrow Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handFree

putdown(x)

- Prec: holding(x)
- \rightarrow Add: clear(x), onTable(x), handFree
- Del: holding(x)

stack(x, y)

- Prec: holding(x), clear(y)
 - \rightarrow Add: clear(x), on(x, y), handFree
 - Del: clear(y), holding(x)
- }

Problem 2 action cost = 1

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	?	0						0								0	0

h^{add} = action cost + **sum**(heuristic of preconditions) ←

h^{max} = action cost + **max**(heuristic of preconditions)

putdown(C)

stack(C, A)

stack(C, B)

unstack(A, C)

unstack(B, C)

stack(C, C)

unstack(C, C)

unstack(x, y)

- Prec: on(x, y), clear(x), handFree
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handFree

putdown(x)

- Prec: holding(x)
- Add: clear(x), onTable(x), handFree
- Del: holding(x)

stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handFree
- Del: clear(y), holding(x)

Problem 2

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	?	0						0								0	0

$\text{putdown}(C) = 1 + \text{hold}(C) = 1 + \infty = \infty$

$1 + \text{hold}(C) = \infty$

$\text{stack}(C, A) = 1 + \text{hold}(C) + \text{clear}(A) = 1 + \infty + 0 = \infty$

$1 + \max(\text{hold}(C), \text{clear}(A)) = 1 + \infty = \infty$

$\text{stack}(C, B) = 1 + \text{hold}(C) + \text{clear}(B) = 1 + \infty + 0 = \infty$

$1 + \max(\text{hold}(C), \text{clear}(B)) = 1 + \infty = \infty$

$\text{unstack}(A, C) = 1 + \text{on}(A, C) + \text{clear}(A) + \text{handFree} = 1 + 0 + 0 + 0 = 1$

$1 + \max(\text{on}(A, C), \text{clear}(A), \text{handFree}) = 1$

$\text{unstack}(B, C) = 1 + \text{on}(B, C) + \text{clear}(B) + \text{handFree} = 1 + \infty + 0 + 0 = \infty$

$1 + \max(\text{on}(B, C), \text{clear}(B), \text{handFree}) = \infty$

$\text{stack}(C, C) = 1 + \text{hold}(C) + \text{clear}(C) = 1 + \infty + \infty = \infty$

$1 + \max(\text{hold}(C), \text{clear}(C)) = 1 + \infty = \infty$

$\text{unstack}(C, C) = 1 + \text{on}(C, C) + \text{clear}(C) + \text{handFree} = 1 + \infty + \infty + 0 = \infty$

$1 + \max(\text{on}(C, C), \text{clear}(C), \text{handFree}) = 1 + \infty = \infty$

unstack(x, y)

- Prec: $\text{on}(x, y), \text{clear}(x), \text{handFree}$
- Add: $\text{holding}(x), \text{clear}(y)$
- Del: $\text{on}(x, y), \text{clear}(x), \text{handFree}$

putdown(x)

- Prec: $\text{holding}(x)$
- Add: $\text{clear}(x), \text{onTable}(x), \text{handFree}$
- Del: $\text{holding}(x)$

stack(x, y)

- Prec: $\text{holding}(x), \text{clear}(y)$
- Add: $\text{clear}(x), \text{on}(x, y), \text{handFree}$
- Del: $\text{clear}(y), \text{holding}(x)$

Problem 2

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	1/1	0						0								0	0

$\text{putdown}(C) = \infty$

$\text{stack}(C, A) = \infty$

$\text{stack}(C, B) = \infty$

$\text{unstack}(A, C) = 1$

$\text{unstack}(B, C) = \infty$

$\text{stack}(C, C) = \infty$

$\text{unstack}(C, C) = \infty$

$\min(\text{putdown}(C), \text{stack}(C, A), \text{stack}(C, B), \text{stack}(C, C), \text{unstack}(A, C), \text{unstack}(B, C), \text{unstack}(C, C)) = 1$

Problem 2

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	1	0						0								0	0

Summary

1. Find all actions that make the predicate become True
2. Calculate h^{add} and h^{max} of all actions

h^{add} = action cost + **sum**(heuristic of preconditions)
 h^{max} = action cost + **max**(heuristic of preconditions)

3. Get the minimum heuristic value

Definition (h^{add}). Let $\Pi = (F, A, c, I, G)$ be a STRIPS planning task. The **additive heuristic** h^{add} for Π is the function $h^{add}(s) := h^{add}(s, G)$ where $h^{add}(s, g)$ is the point-wise greatest function that satisfies $h^{add}(s, g) =$

$$\begin{cases} 0 & g \subseteq s \\ \min_{a \in A, g \in add_a} c(a) + h^{add}(s, pre_a) & |g| = 1 \\ \sum_{g' \in g} h^{add}(s, \{g'\}) & |g| > 1 \end{cases}$$

Definition (h^{max}). Let $\Pi = (F, A, c, I, G)$ be a STRIPS planning task. The **max heuristic** h^{max} for Π is the function $h^{max}(s) := h^{max}(s, G)$ where $h^{max}(s, g)$ is the point-wise greatest function that satisfies $h^{max}(s, g) =$

$$\begin{cases} 0 & g \subseteq s \\ \min_{a \in A, g \in add_a} c(a) + h^{max}(s, pre_a) & |g| = 1 \\ \max_{g' \in g} h^{max}(s, \{g'\}) & |g| > 1 \end{cases}$$

Problem 2: Computing h^{max} and h^{add}

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	1	0	1	1	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
2													?						

pickup(x)

- Prec: onTable(x), clear(x), handFree
- Add: holding(x)
- Del: onTable(x), clear(x), handFree

unstack(x, y)

- Prec: on(x, y), clear(x), handFree
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handFree

putdown(x)

- Prec: holding(x)
- Add: clear(x), onTable(x), handFree
- Del: holding(x)

stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handFree
- Del: clear(y), holding(x)

Problem 2: Computing h^{max} and h^{add}

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	1	0	1	1	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
2													$\frac{3}{2}$						

h^{add} = action cost + **sum**(heuristic of preconditions)

h^{max} = action cost + **max**(heuristic of preconditions)

$stack(B,C) = 1 + hold(B) + c(C) = 1 + 1 + 1 = 3$

$stack(B,C) = 1 + max(hold(B), c(C)) = 1 + 1 = 2$

- stack(x, y)**
- Prec: holding(x), clear(y)
 - Add: clear(x), on(x,y), handFree
 - Del: clear(y), holding(x)

Problem 2: Computing h^{max} and h^{add}

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	1	0	1	1	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
2	0	0	1	0	1	1	2	2	2	0	2	2	3 / 2	∞	∞	∞	2	0	0

h^{add} / h^{max}

Problem 2: Computing h^{max} and h^{add}

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	1	0	1	1	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
2	0	0	1	0	1	1	2	2	2	0	2	2	$3/2$	∞	∞	∞	2	0	0
3	0	0	1	0	1	1	2	2	2	0	2	2	$3/2$	3	3	$4/3$	2	0	0
4	0	0	1	0	1	1	2	2	2	0	2	2	$3/2$	3	3	$4/3$	2	0	0

h^{add} / h^{max}

stop when converge (2 rows have the same values)

Problem 2: Computing h^{max} and h^{add}

Iter	c(A)	c(B)	c(C)	hand Free	h(A)	h(B)	h(C)	on(A, A)	on(A,B)	on(A,C)	on(B,A)	on(B,B)	on(B,C)	on(C,A)	on(C,B)	on(C,C)	onT(A)	onT(B)	onT(C)
0	0	0	∞	0	∞	∞	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
1	0	0	1	0	1	1	∞	∞	∞	0	∞	∞	∞	∞	∞	∞	∞	0	0
2	0	0	1	0	1	1	2	2	2	0	2	2	3 / 2	∞	∞	∞	2	0	0
3	0	0	1	0	1	1	2	2	2	0	2	2	3 / 2	3	3	4 / 3	2	0	0
4	0	0	1	0	1	1	2	2	2	0	2	2	3 / 2	3	3	4 / 3	2	0	0

h^{add} / h^{max}

$G = \{on(A,B), on(B,C), onTable(C)\}$

$h^{add}(s_0) = 2 + 3 + 0 = 5$

$h^{max}(s_0) = \max(2, 2, 0) = 2$