# Week 6: Delete Relaxation

COMP90054 – Al Planning for Autonomy

# Key concepts

- Delete relaxation heuristic  $h^+$
- The relationship between  $h^{max}$ ,  $h^{add}$  and  $h^+$

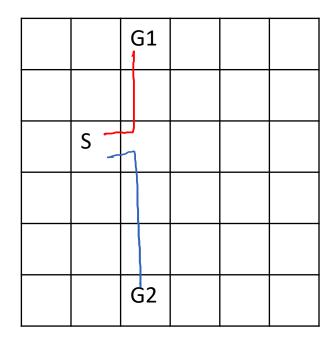
What is the (optimal) delete relaxation heuristic  $h^+$ ?

Relaxing by **ignoring delete lists** 

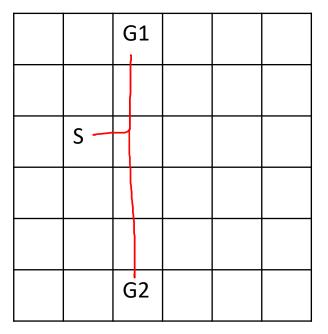
**Definition (Delete Relaxation).** (i) For a STRIPS action a, by  $a^+$  we denote the corresponding delete relaxed action, or short relaxed action, defined by  $pre_{a^+} := pre_a$ ,  $add_{a^+} := add_a$ , and  $del_{a^+} :=$ 

$$P = \langle F, O, I, G \rangle$$
  $P = \langle F, O^+, I, G \rangle$ 

### How would it be interpreted in pacman?



Minimum spanning tree: Admissible, Not consistent



Minimum Steiner tree: Admissible, consistent

What is the relationship between  $h^{max}$ ,  $h^{add}$  and  $h^+$ ? What about  $h^*$ ?

h\* is the perfect heuristic (the optimal cost from the current state to the goal state)

 $h^+$  is the **optimal delete relaxation** heuristic (not easy to compute)  $h^+$  is admissible

 $h^{max}$  is an approximation of  $h^+$   $h^{max}$  is admissible.  $h^{max}$  is very small.  $h^{max} <= h^+ <= h^*$ 

 $h^{add}$  is an approximation of  $h^+$  $h^{add}$  is not admissible  $h^{add} >= h^+$ 

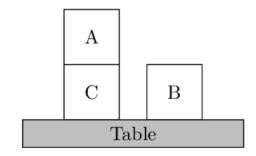
#### **Initial state**

I = {on(A, C), onTable(C), onTable(B), clear(A), clear(B), handFree}

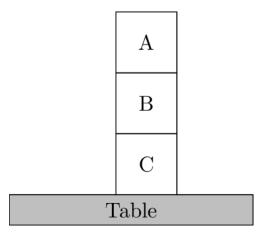
#### **Goal state**

 $G = \{on(A,B), on(B,C), onTable(C)\}$ 

#### Initial State



#### Goal State



**Definition** ( $h^{\text{add}}$ ). Let  $\Pi = (F, A, c, I, G)$  be a STRIPS planning task. The additive heuristic  $h^{\text{add}}$  for  $\Pi$  is the function  $h^{\text{add}}(s) := h^{\text{add}}(s, G)$  where  $h^{\text{add}}(s, g)$  is the point-wise greatest function that satisfies  $h^{\text{add}}(s, g) =$ 

$$\begin{cases} 0 & g \subseteq s \\ \min_{a \in A, g \in add_a} c(a) + h^{\text{add}}(s, pre_a) & |g| = 1 \\ \sum_{g' \in g} h^{\text{add}}(s, \{g'\}) & |g| > 1 \end{cases}$$

**Definition** ( $h^{\text{max}}$ ). Let  $\Pi = (F, A, c, I, G)$  be a STRIPS planning task. The max heuristic  $h^{\text{max}}$  for  $\Pi$  is the function  $h^{\text{max}}(s) := h^{\text{max}}(s, G)$  where  $h^{\text{max}}(s, g)$  is the point-wise greatest function that satisfies  $h^{\text{max}}(s, g) =$ 

$$\begin{cases} 0 & g \subseteq s \\ \min_{a \in A, g \in add_a} c(a) + h^{\max}(s, pre_a) & |g| = 1 \\ \max_{g' \in g} h^{\max}(s, \{g'\}) & |g| > 1 \end{cases}$$

\*This table is not complete. Please refer to the solution notebook to see the complete table.

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	8	8	0	0	8	0	∞	8	8	∞	0
1													
2													

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	8	$\infty$	0	0	$\infty$	0	$\infty$	8	$\infty$	8	0
1	0	0	?		0	0		0					0
2													

Which actions can we take to make **clear(C)** True?

Which actions can we take to make **clear(C)** True?

```
putdown(C)
stack(C, A)
stack(C, B)
unstack(A, C)
unstack(B, C)
```

#### **Define Operators**

# O = { pickup(x)

- Prec: onTable(x), clear(x), handFree
- Add: holding(x)
- Del: onTable(x), clear(x), handFree

#### unstack(x, y)

- Prec: on(x, y), clear(x), handFree
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handFree

#### putdown(x)

- Prec: holding(x)
- Add: clear(x), onTable(x), handFree
- Del: holding(x)

#### stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handFree
- Del: clear(y), holding(x)

<sup>\*</sup>Using the complete table, we need to add 2 more actions here: stack(C, C), unstack(C, C)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	$\infty$	$\infty$	0	0	$\infty$	0	8	8	$\infty$	8	0
1	0	0	?		0	0		0					0
2													

```
h^{add} = action cost + sum(heuristic of preconditions)
h^{max} = action cost + max(heuristic of preconditions)
putdown(C) = 1 + \text{hold}(C) = 1 + \infty = \infty
                 1 + hold(C) = \infty
stack(C, A) = 1 + hold(C) + clear(A) = 1 + \infty + 0 = \infty
                1 + \max(\text{hold}(C), \text{clear}(A)) = 1 + \infty = \infty
stack(C, B) = 1 + hold(C) + clear(B) = 1 + \infty + 0 = \infty
                1 + \max(\text{hold}(C), \text{clear}(B)) = 1 + \infty = \infty
unstack(A, C) = 1 + on(A, C) + clear(A) + handFree = <math>1 + 0 + 0 + 0 = 1
                   1 + \max(on(A, C), clear(A), handFree) = 1
unstack(B, C) = 1 + on(B, C) + clear(B) + handFree = <math>1 + \infty + 0 + 0 = \infty
                   1 + max(on(B, C), clear(B), handFree )
```

#### unstack(x, y)

- Prec: on(x, y), clear(x), handFree
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handFree

#### putdown(x)

- Prec: holding(x)
- Add: clear(x), onTable(x), handFree
- Del: holding(x)

#### stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handFree
- Del: clear(y), holding(x) 11

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	$\infty$	$\infty$	0	0	∞	0	$\infty$	8	$\infty$	$\infty$	0
1	0	0	?		0	0		0					0
2													

putdown(C) =  $\infty$ stack(C, A) =  $\infty$ stack(C, B) =  $\infty$ unstack(A, C) = 1 unstack(B, C) =  $\infty$ 

min(putdown(C), stack(C, A), stack(C, B), unstack(A, C), unstack(B, C)) = 1

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	8	8	0	0	8	0	$\infty$	$\infty$	$\infty$	$\infty$	0
1	0	0	1	8	0	0	8	0	$\infty$	1	1	$\infty$	0
2									?				

#### pickup(x)

Prec: onTable(x), clear(x), handFree

Add: holding(x)

Del: onTable(x), clear(x), handFree

#### unstack(x, y)

Prec: on(x, y), clear(x), handFree

Add: holding(x), clear(y)

Del: on(x, y), clear(x), handFree

#### putdown(x)

Prec: holding(x)

Add: clear(x), onTable(x), handFree

- Del: holding(x)

#### stack(x, y)

Prec: holding(x), clear(y)

- Add: clear(x), on(x,y), handFree

- Del: clear(y), holding(x)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	∞	8	0	0	∞	0	$\infty$	$\infty$	∞	$\infty$	0
1	0	0	1	8	0	0	8	0	$\infty$	1	1	$\infty$	0
2									?				

 $h^{add}$  = action cost + **sum**(heuristic of preconditions)

 $h^{max}$  = action cost + max(heuristic of preconditions)

$$stack(B,C) = 1 + hold(B) + c(C) = 1 + 1 + 1 = 3$$

$$stack(B,C) = 1 + max(hold(B) + c(C)) = 1 + 1 = 2$$

#### stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handFree
- Del: clear(y), holding(x)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	8	8	0	0	∞	0	∞	8	8	$\infty$	0
1	0	0	1	8	0	0	8	0	8	1	1	8	0
2	0	0	1	2	0	0	2	0	3/2	1	1	2	0

 $h^{add}/h^{max}$ 

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	$\infty$	8	0	0	∞	0	$\infty$	8	8	$\infty$	0
1	0	0	1	8	0	0	8	0	∞	1	1	8	0
2	0	0	1	2	0	0	2	0	3/2	1	1	2	0
3	0	0	1	2	0	0	2	0	3/2	1	1	2	0

 $h^{add}/h^{max}$ 

stop when converge (2 rows have the same values)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	$\infty$	8	0	0	∞	0	$\infty$	8	8	$\infty$	0
1	0	0	1	8	0	0	8	0	∞	1	1	8	0
2	0	0	1	2	0	0	2	0	3/2	1	1	2	0
3	0	0	1	2	0	0	2	0	3/2	1	1	2	0

 $h^{add}/h^{max}$ 

$$h^{add}(s0) = 2 + 3 + 0 = 5$$
  
 $h^{max}(s0) = \max(2, 2, 0) = 2$ 

 $G = \{on(A,B), on(B,C), onTable(C)\}$