Week 6: Delete Relaxation

COMP90054 – Al Planning for Autonomy

Key concepts

- Delete relaxation heuristic h^+
- The relationship between h^{max} , h^{add} and h^+

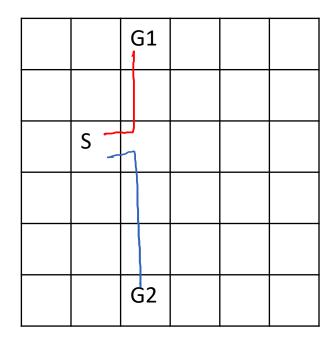
What is the (optimal) delete relaxation heuristic h^+ ?

Relaxing by **ignoring delete lists**

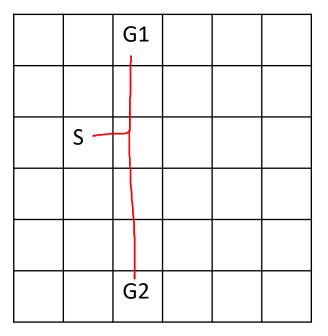
Definition (Delete Relaxation). (i) For a STRIPS action a, by a^+ we denote the corresponding delete relaxed action, or short relaxed action, defined by $pre_{a^+} := pre_a$, $add_{a^+} := add_a$, and $del_{a^+} :=$

$$P = \langle F, O, I, G \rangle$$
 $P = \langle F, O^+, I, G \rangle$

How would it be interpreted in pacman?



Minimum spanning tree: Admissible, Not consistent



Minimum Steiner tree: Admissible, consistent

What is the relationship between h^{max} , h^{add} and h^+ ? What about h^* ?

h* is the perfect heuristic (the optimal cost from the current state to the goal state)

 h^+ is the **optimal delete relaxation** heuristic (not easy to compute) h^+ is admissible

 h^{max} is an approximation of h^+ h^{max} is admissible. h^{max} is very small. $h^{max} <= h^+ <= h^*$

 h^{add} is an approximation of h^+ h^{add} is not admissible $h^{add} >= h^+$

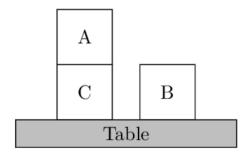
Initial state

I = {on(A, C), onTable(C), onTable(B), clear(A), clear(B), handFree}

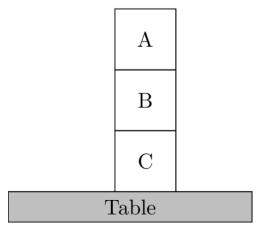
Goal state

 $G = \{on(A,B), on(B,C), onTable(C)\}$

Initial State



Goal State



Definition (h^{add}). Let $\Pi = (F, A, c, I, G)$ be a STRIPS planning task. The additive heuristic h^{add} for Π is the function $h^{\text{add}}(s) := h^{\text{add}}(s, G)$ where $h^{\text{add}}(s, g)$ is the point-wise greatest function that satisfies $h^{\text{add}}(s, g) =$

$$\begin{cases} 0 & g \subseteq s \\ \min_{a \in A, g \in add_a} c(a) + h^{\text{add}}(s, pre_a) & |g| = 1 \\ \sum_{g' \in g} h^{\text{add}}(s, \{g'\}) & |g| > 1 \end{cases}$$

Definition (h^{max}). Let $\Pi = (F, A, c, I, G)$ be a STRIPS planning task. The max heuristic h^{max} for Π is the function $h^{\text{max}}(s) := h^{\text{max}}(s, G)$ where $h^{\text{max}}(s, g)$ is the point-wise greatest function that satisfies $h^{\text{max}}(s, g) =$

$$\begin{cases} 0 & g \subseteq s \\ \min_{a \in A, g \in add_a} c(a) + h^{\max}(s, pre_a) & |g| = 1 \\ \max_{g' \in g} h^{\max}(s, \{g'\}) & |g| > 1 \end{cases}$$

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	8	8	0	0	8	0	∞	8	8	∞	0
1													
2													

I = {on(A, C), onTable(C), onTable(B), clear(A), clear(B), handFree}

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	∞	8	0	0	∞	0	∞	8	× ×	∞	0
1	0	0	?		0	0		0					0
2													

Which actions can we take to make **clear(C)** True?

Which actions can we take to make **clear(C)** True?

```
putdown(C)
stack(C, A)
stack(C, B)
unstack(A, C)
unstack(B, C)
```

Define Operators

```
O = {
pickup(x)
```

- Prec: onTable(x), clear(x), handFree
- Add: holding(x)
- Del: onTable(x), clear(x), handFree

unstack(x, y)

- Prec: on(x, y), clear(x), handFree
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handFree

putdown(x)

- Prec: holding(x)
- Add: clear(x), onTable(x), handFree
- Del: holding(x)

stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handFree
- Del: clear(y), holding(x)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	∞	∞	0	0	∞	0	∞	∞	o	∞	0
1	0	0	?		0	0		0					0
2													

```
h^{add} = action cost + sum(heuristic of preconditions)
h^{max} = action cost + max(heuristic of preconditions)
putdown(C) = 1 + \text{hold}(C) = 1 + \infty = \infty
                 1 + hold(C) = \infty
stack(C, A) = 1 + hold(C) + clear(A) = 1 + \infty + 0 = \infty
                1 + \max(\text{hold}(C), \text{clear}(A)) = 1 + \infty = \infty
stack(C, B) = 1 + hold(C) + clear(B) = 1 + \infty + 0 = \infty
                1 + \max(\text{hold}(C), \text{clear}(B)) = 1 + \infty = \infty
unstack(A, C) = 1 + on(A, C) + clear(A) + handFree = <math>1 + 0 + 0 + 0 = 1
                   1 + \max(on(A, C), clear(A), handFree) = 1
unstack(B, C) = 1 + on(B, C) + clear(B) + handFree = <math>1 + \infty + 0 + 0 = \infty
                   1 + max(on(B, C), clear(B), handFree )
```

unstack(x, y)

- Prec: on(x, y), clear(x), handFree
- Add: holding(x), clear(y)
- Del: on(x, y), clear(x), handFree

putdown(x)

- Prec: holding(x)
- Add: clear(x), onTable(x), handFree
- Del: holding(x)

stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handFree
- Del: clear(y), holding(x)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	∞	∞	0	0	∞	0	∞	∞	_∞	∞	0
1	0	0	?		0	0		0					0
2													

putdown(C) = ∞ stack(C, A) = ∞ stack(C, B) = ∞ unstack(A, C) = 1 unstack(B, C) = ∞

min(putdown(C), stack(C, A), stack(C, B), unstack(A, C), unstack(B, C)) = 1

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	8	8	0	0	∞	0	∞	8	8	∞	0
1	0	0	1	8	0	0	8	0	∞	1	1	∞	0
2									?				

pickup(x)

Prec: onTable(x), clear(x), handFree

Add: holding(x)

Del: onTable(x), clear(x), handFree

unstack(x, y)

Prec: on(x, y), clear(x), handFree

Add: holding(x), clear(y)

Del: on(x, y), clear(x), handFree

putdown(x)

Prec: holding(x)

Add: clear(x), onTable(x), handFree

Del: holding(x)

stack(x, y)

Prec: holding(x), clear(y)

- Add: clear(x), on(x,y), handFree

- Del: clear(y), holding(x)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	8	8	0	0	∞	0	∞	8	8	∞	0
1	0	0	1	8	0	0	8	0	∞	1	1	∞	0
2									?				

 h^{add} = action cost + **sum**(heuristic of preconditions)

 h^{max} = action cost + max(heuristic of preconditions)

stack(B,C) = 1 + hold(B) + c(C) = 1 + 1 + 1 = 3

stack(B,C) = 1 + max(hold(B) + c(C)) = 1 + 1 = 2

stack(x, y)

- Prec: holding(x), clear(y)
- Add: clear(x), on(x,y), handFree
- Del: clear(y), holding(x)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	8	8	0	0	∞	0	∞	8	8	∞	0
1	0	0	1	8	0	0	8	0	8	1	1	∞	0
2	0	0	1	2	0	0	2	0	3/2	1	1	2	0

 h^{add}/h^{max}

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	∞	8	0	0	∞	0	∞	8	8	∞	0
1	0	0	1	8	0	0	8	0	∞	1	1	∞	0
2	0	0	1	2	0	0	2	0	3/2	1	1	2	0
3	0	0	1	2	0	0	2	0	3/2	1	1	2	0

 h^{add}/h^{max}

stop when converge (2 rows have the same values)

Iter	c(A)	c(B)	c(C)	onT(A)	onT(B)	onT(C)	on(A,B)	on(A,C)	on(B,C)	hold(A)	hold(B)	hold(C)	handFree
0	0	0	∞	8	0	0	∞	0	∞	8	8	∞	0
1	0	0	1	8	0	0	8	0	∞	1	1	8	0
2	0	0	1	2	0	0	2	0	3/2	1	1	2	0
3	0	0	1	2	0	0	2	0	3/2	1	1	2	0

$$h^{add}/h^{max}$$

$$h^{add}(s0) = 2 + 3 + 0 = 5$$

 $h^{max}(s0) = \max(2, 2, 0) = 2$

 $G = \{on(A,B), on(B,C), onTable(C)\}$