

DATA 201: Time Series Analysis

Linear Regression Model

Lecture 11: The Auto-Regressive (AR) Model

Lulu Wang

Data Analytics
Dickinson College

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The Auto-Regressive (AR) Model

Estimation

Order selection

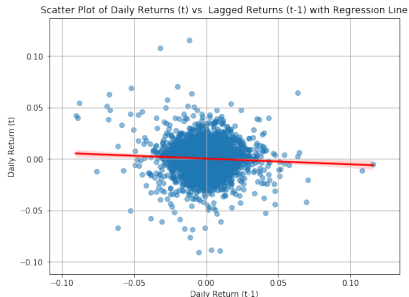
Auto-Regressive (AR) model

- The AutoRegressive model of order 1, denoted by **AR(1)**, is given by:

$$Y_t = \beta_0 + \beta_1 Y_{t-1} + \epsilon_t$$

where β_0 and β_1 are parameters to be estimated and ϵ_t has mean zero and variance σ_ϵ^2 .

- A scatter plot of Y_{t-1} and Y_t shows little dependence between the current and past value.
- The red line represents $E(Y_t|Y_{t-1}) = \beta_0 + \beta_1 Y_{t-1}$.



Auto-Regressive (AR) Model

- In general, an **AR(p)** model is defined as:

$$Y_t = \beta_0 + \beta_1 Y_{t-1} + \cdots + \beta_p Y_{t-p} + \epsilon_t$$

where:

- $\beta_0, \beta_1, \dots, \beta_p$ are parameters to be estimated.
- ϵ_t is a white noise error term with mean zero and variance σ_ϵ^2 .

Conditional Expectation in AR(p) Model

Property 1: Conditional Expectation

$$E(Y_t | Y_{t-1}, \dots, Y_{t-p}) = \beta_0 + \beta_1 Y_{t-1} + \dots + \beta_p Y_{t-p}$$

It can be interpreted as a **forecast** since only past information is used to produce an expectation of the variable today.

Property 2: Unconditional Expectation

$$E(Y_t) = \frac{\beta_0}{1 - \sum_{j=1}^p \beta_j}$$

since:

$$E(Y_t) = \beta_0 + \beta_1 E(Y_{t-1}) + \dots + \beta_p E(Y_{t-p}) + E(\epsilon_t)$$

Assuming that $E(Y_t) = E(Y_{t-k})$ for all values of k .

It represents the long-run mean of Y_t

Conditional Expectation in AR(p) Model

Proof of Property 1: Conditional Expectation

The AR(p) model is given by:

$$Y_t = \beta_0 + \beta_1 Y_{t-1} + \cdots + \beta_p Y_{t-p} + \varepsilon_t \quad (1)$$

Taking the expectation conditional on past values:

$$E(Y_t | Y_{t-1}, \dots, Y_{t-p}) = E \left(\beta_0 + \sum_{j=1}^p \beta_j Y_{t-j} + \varepsilon_t \mid Y_{t-1}, \dots, Y_{t-p} \right) \quad (2)$$

Since $E(\varepsilon_t | Y_{t-1}, \dots, Y_{t-p}) = 0$, we obtain:

$$E(Y_t | Y_{t-1}, \dots, Y_{t-p}) = \beta_0 + \sum_{j=1}^p \beta_j Y_{t-j} \quad (3)$$

Variance of AR(p) Model

Property 3: Variance

$$\text{Var}(Y_t) = \frac{\sigma_\epsilon^2}{1 - \sum_{j=1}^p \beta_j^2}$$

since:

$$\text{Var}(Y_t) = \beta_1^2 \text{Var}(Y_{t-1}) + \cdots + \beta_p^2 \text{Var}(Y_{t-p}) + \text{Var}(\epsilon_t)$$

$$= \left(\sum_{j=1}^p \beta_j^2 \right) \text{Var}(Y_t) + \sigma_\epsilon^2$$

This shows how past values contribute to the variance of the current value.

Persistence and Mean Reversion in AR(p)

Property 4: Persistence and Mean Reversion

$$\sum_{i=1}^p \beta_i$$

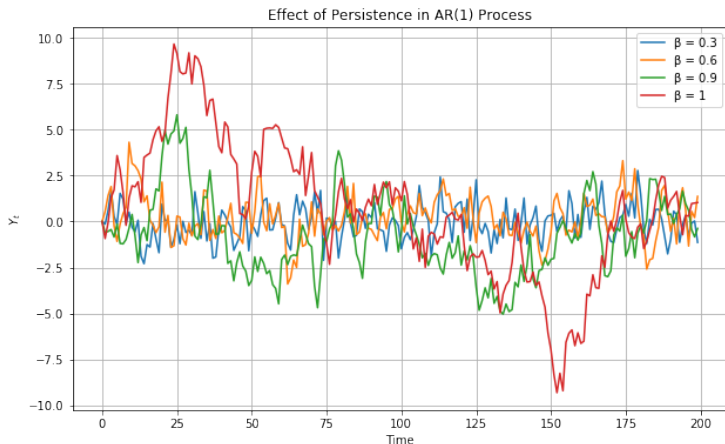
measures the **persistence** of the time series. Persistence can also be interpreted as **mean reversion**, which represents how quickly a time series reverts back to its mean.

- **Low persistence** \Rightarrow quick mean reversion.
- **High persistence** \Rightarrow slow mean reversion.

Key Insight: The closer the sum of β_i is to 1, the more persistent the process, meaning past values strongly influence future values.

Persistence and Mean Reversion in AR(1)

The plot below shows the **effect of persistence** in an **AR(1) process** with different values of β :



Persistence and Mean Reversion in AR(1)

Low Persistence ($\beta = 0.3, 0.6$)

- The process exhibits **quick mean reversion**, meaning that shocks **fade away quickly**.
- The series remains **close to zero**, with less variability over time.

High Persistence ($\beta = 0.9$)

- The process takes **longer to revert to the mean**, meaning past values strongly influence future values.
- Large deviations **persist longer** before dying out.

Unit Root ($\beta = 1.0$)

- This is a **random walk**, meaning the process **never mean-reverts**.
- Variance **grows indefinitely**, and the series **does not stabilize**.

Estimation of AR models

- Auto-regressive models $AR(P)$ can be estimated consistently using OLS.
- More general time series models (e.g., MA, ARMA) need to be estimated by *Maximum Likelihood* (ML).
- There are several functions to estimate time series models that allow choosing the estimation method.
 - In practice, we can go with the default option since for moderate and large sample sizes, the results are nearly identical.
- We will discuss three functions (first two today):
 - Using `statsmodels.OLS()`: This method applies Ordinary Least Squares (OLS) estimation. **Make sure you use the Newey-West method!**
 - Using `statsmodels.tsa.ar_model.AutoReg()`: It uses Conditional Maximum Likelihood which is Ordinary Least Squares (OLS).
 - Using `statsmodels.tsa.arima.model.ARIMA()`: This function estimates AR, MA, and ARIMA models using ML.

How Correlated Observations Lead to Dependent Errors

Consider a simple first-order autoregressive model $AR(1)$:

$$y_t = \beta y_{t-1} + \varepsilon_t \quad (4)$$

where:

- y_t is the observation at time t ,
- β is the autoregressive coefficient, where $|\beta| < 1$ for stationarity,
- ε_t is a white noise error term.

By recursively substituting:

$$y_{t-1} = \beta y_{t-2} + \varepsilon_{t-1} \quad (5)$$

$$y_t = \beta(\beta y_{t-2} + \varepsilon_{t-1}) + \varepsilon_t = \beta^2 y_{t-2} + \beta \varepsilon_{t-1} + \varepsilon_t \quad (6)$$

Autocovariance of the Errors

The error term at time t is:

$$\varepsilon_t = y_t - \beta y_{t-1} \quad (7)$$

Similarly, the error at $t - 1$ is:

$$\varepsilon_{t-1} = y_{t-1} - \beta y_{t-2} \quad (8)$$

Computing the covariance:

$$\text{Cov}(\varepsilon_t, \varepsilon_{t-1}) = \text{Cov}(y_t - \beta y_{t-1}, y_{t-1} - \beta y_{t-2}) \quad (9)$$

Expanding using linearity of covariance:

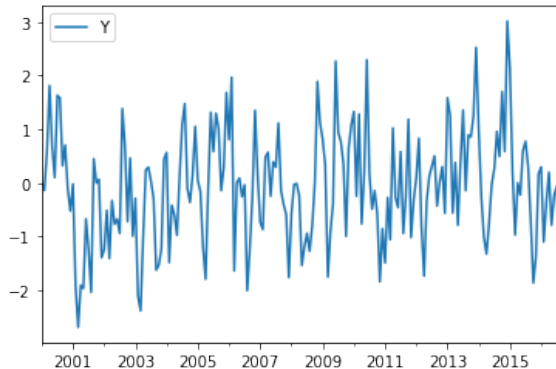
$$\begin{aligned} \text{Cov}(\varepsilon_t, \varepsilon_{t-1}) &= \text{Cov}(y_t, y_{t-1}) - \beta \text{Cov}(y_t, y_{t-2}) \\ &\quad - \beta \text{Cov}(y_{t-1}, y_{t-1}) + \beta^2 \text{Cov}(y_{t-1}, y_{t-2}) \end{aligned} \quad (10)$$

This results in a non-zero covariance, meaning the errors are correlated over time.

AR estimated by OLS()

- We will simulate time series data.

$$Y_t = 0.5Y_{t-1} + \epsilon_t$$



AR estimated by OLS()

- Estimation summary of

$$Y_t = 0.5Y_{t-1} + \epsilon_t$$

```

=== OLS Results (HAC/ Newey-West Standard Errors) ===
                        OLS Regression Results
=====
Dep. Variable:          Y      R-squared:                0.170
Model:                  OLS    Adj. R-squared:           0.168
Method:                  Least Squares    F-statistic:       60.83
Date:                    Thu, 27 Feb 2025    Prob (F-statistic): 1.07e-13
Time:                    18:59:17    Log-Likelihood:     -425.08
No. Observations:        298    AIC:                 854.2
Df Residuals:            296    BIC:                 861.5
Df Model:                 1
Covariance Type:         nonrobust
=====

```

| | coef | std err | t | P> t | [0.025 | 0.975] |
|--------|---------|---------|--------|-------|--------|--------|
| const | -0.0145 | 0.059 | -0.247 | 0.805 | -0.130 | 0.101 |
| Y_lag1 | 0.4130 | 0.053 | 7.799 | 0.000 | 0.309 | 0.517 |

```

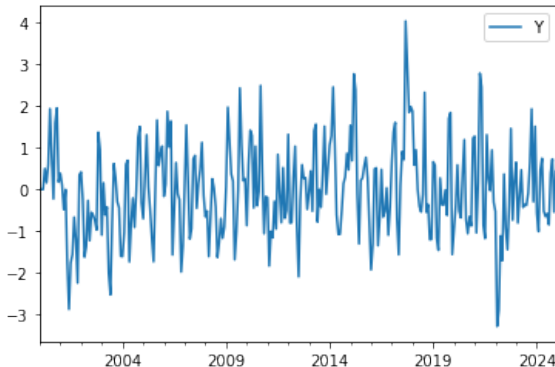
=====
Omnibus:                 3.409    Durbin-Watson:         1.858
Prob(Omnibus):           0.182    Jarque-Bera (JB):       3.090
Skew:                    0.217    Prob(JB):               0.213
Kurtosis:                3.247    Cond. No.               1.11
=====

```

AR estimated by AutoReg()

- Example: estimating a AR(3) model:

$$Y_t = 0.6Y_{t-1} - 0.3Y_{t-2} + 0.2Y_{t-3} + \epsilon_t$$



AR estimated by AutoReg()

- Estimation summary of

$$Y_t = 0.6Y_{t-1} - 0.3Y_{t-2} + 0.2Y_{t-3} + \epsilon_t$$

| AutoReg Model Results | | | | | | |
|-----------------------|------------------|---------------------|----------|-----------|--------|--------|
| ===== | | | | | | |
| Dep. Variable: | Y | No. Observations: | 300 | | | |
| Model: | AutoReg(3) | Log Likelihood | -415.822 | | | |
| Method: | Conditional MLE | S.D. of innovations | 0.981 | | | |
| Date: | Mon, 24 Feb 2025 | AIC | 841.644 | | | |
| Time: | 18:49:08 | BIC | 860.113 | | | |
| Sample: | 04-30-2000 | HQIC | 849.038 | | | |
| | - 12-31-2024 | | | | | |
| ===== | | | | | | |
| | coef | std err | z | P> z | [0.025 | 0.975] |
| ----- | | | | | | |
| const | -0.0137 | 0.057 | -0.240 | 0.810 | -0.125 | 0.098 |
| Y.L1 | 0.5116 | 0.057 | 8.925 | 0.000 | 0.399 | 0.624 |
| Y.L2 | -0.2497 | 0.063 | -3.962 | 0.000 | -0.373 | -0.126 |
| Y.L3 | 0.1625 | 0.057 | 2.829 | 0.005 | 0.050 | 0.275 |
| Roots | | | | | | |
| ===== | | | | | | |
| | Real | Imaginary | Modulus | Frequency | | |
| ----- | | | | | | |
| AR.1 | 1.7486 | -0.0000j | 1.7486 | -0.0000 | | |
| AR.2 | -0.1060 | -1.8730j | 1.8760 | -0.2590 | | |
| AR.3 | -0.1060 | +1.8730j | 1.8760 | 0.2590 | | |
| ----- | | | | | | |

Order selection

- **How do we choose the order p of the AR model?**
- The problem is the same as choosing the best LRM:
 - we use adjusted R^2 to penalize models that include more variables
 - select the model with largest adjusted R^2
- We do the same for time series models, but instead of using adjusted R^2 we use:

1. *Akaike Information Criterion (AIC)* defined as

$$\log(RSS/T) + 2 \cdot \frac{(1+p)}{T}$$

2. *Bayesian Information Criterion (BIC)* defined as

$$\log(RSS/T) + \log(T) \cdot \frac{(1+p)}{T}$$

- For AIC and BIC the best model has the *lowest* value of the criterion

Order selection (Cont.)

- This can be achieved in Python using the `AutoReg` function from `statsmodels` by selecting the model with the lowest AIC or BIC.
- However, a more convenient approach is to use `ar_select_order()`, which automatically determines the optimal lag order based on AIC or BIC.